Ensamble Learning II - Boosting

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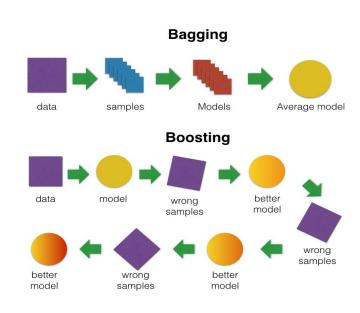
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Introducción

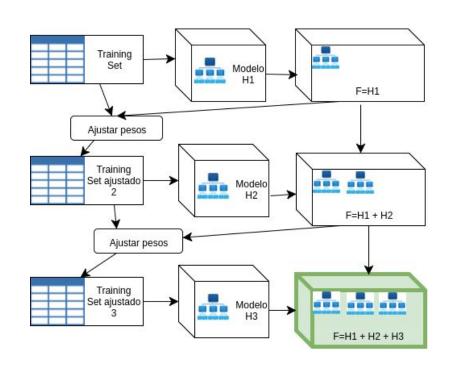
- Bagging y Random Forests: modelos en subsets separados y luego combinamos su predicción
- Paralelizando el entrenamiento y combinando los resultados

 El Boosting es otra técnica de ensamble la cual es secuencial



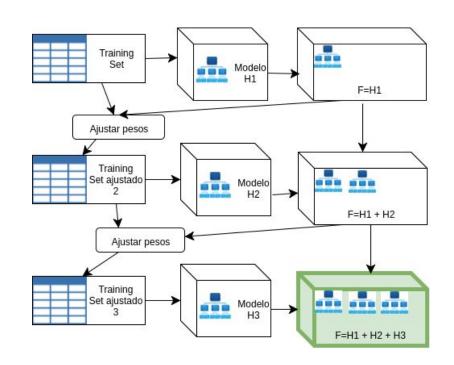
Boosting

- Meta-algoritmo: procedimiento iterativo => el modelo final se construye por pasos
- Aprender de los errores cometidos en los pasos previos.
- Sobre los errores del modelo anterior:
 - cambiar la ponderación en el siguiente modelo
 - entrenando un modelo que prediga los mismos.



AdaBoost

- 1 iteración: pesos uniformes para todos los registros. Luego, los pesos se ajustan para enfatizar los errores en la iteración anterior
- Predicción final: voto ponderado según cada error de entrenamiento, de los distintos modelos base
- Modelo base débil => re-entrenarlo en las muestras mal clasificadas.



- 1. Initialize the observation weights $w_i = 1/N, i = 1, 2, ..., N$.
- 2. For m=1 to M:
 - (a) Fit a classifier $G_m(x)$ to the training data using weights w_i .
 - (b) Compute

Se inicializan todos los pesos iguales.

Habrá un peso Wi asociado a cada uno de los ejemplos Xi del set de entrenamiento. Siendo N la cantidad de ejemplos en el set de entrenamiento

- (c) $compare \alpha_m log((1 clim)/clim)$.
- (d) Set $w_i \leftarrow w_i \cdot \exp[\alpha_m \cdot I(y_i \neq G_m(x_i))], i = 1, 2, \dots, N.$
- 3. Output $G(x) = \operatorname{sign} \left[\sum_{m=1}^{M} \alpha_m G_m(x) \right]$.

El algoritmo entrenará M clasificadores.

- 1. Initialize the observation weights $w_i = 1/N, i = 1, 2, ..., N$.
- 2. For m = 1 to M:
 - (a) Fit a classifier $G_m(x)$ to the training data using weights w_i .
 - (b) Compute

$$err_m = \frac{\sum_{i=1}^{N} w_i I(y_i \neq G_m(x_i))}{\sum_{i=1}^{N} w_i}.$$

- (c) Compute $\alpha_m = \log((1 \operatorname{err}_m)/\operatorname{err}_m)$.
- (d) Set $w_i \leftarrow w_i \cdot \exp[\alpha_m \cdot I(y_i \neq G_m(x_i))], i = 1, 2, \dots, N.$
- 3. Output $G(x) = \operatorname{sign} \left[\sum_{m=1}^{M} \alpha_m G_m(x) \right]$.

Se entrena el clasificador Gm, considerando el set de entrenamiento y el peso wi asignado a cada uno de los ejemplos.

- 1. Initialize the observation weights $w_i = 1/N, i \neq 1, 2, \dots, N$.
- 2. For m=1 to M:
 - (a) Fit a classifier $G_m(x)$ to the training data using weights w_i .
 - (b) Compute

$$err_m = \frac{\sum_{i=1}^{N} w_i I(y_i \neq G_m(x_i))}{\sum_{i=1}^{N} w_i}.$$

- (c) Compute $\alpha_m = \log((1 \operatorname{err}_m)/\operatorname{err}_m)$.
- (d) Set $w_i \leftarrow w_i \cdot \exp[\alpha_m \cdot I(y_i \neq G_m(x_i))], i = 1, 2, \dots, N.$
- 3. Output $G(x) = \operatorname{sign} \left[\sum_{m=1}^{M} \alpha_m G_m(x) \right]$.

Se calcula el error de clasificación ponderado de Gm.

ERRm será la suma del peso de los ejemplos mal clasificados / suma todos los pesos 1. Initialize the Mínimo de 0 cuando no haya errores.

Máximo de 1 cuando sean todos errores.

2. For m=1 Se puede ver que los ejemplos de alto peso mal clasificados influyen más que los de pesos bajos.

- (a) Fit a classifier $G_m(x)$ to the training data using weights w_i .
- (b) Compute

$$err_m = \frac{\sum_{i=1}^{N} w_i I(y_i \neq G_m(x_i))}{\sum_{i=1}^{N} w_i}.$$

- (c) Compute $\alpha_m = \log((1 \text{err}_m)/\text{err}_m)$.
- (d) Set $w_i \leftarrow w_i \cdot \exp[\alpha_m \cdot I(y_i \neq G_m(x_i))], i = 1, 2, \dots, N.$
- 3. Output $G(x) = \operatorname{sign} \left[\sum_{m=1}^{M} \alpha_m G_m(x) \right]$.

Se calcula el coeficiente de aporte de este Clasificador en el ensamble. El valor será mayor cuanto más preciso sea el clasificador Gm, dándole mayor importancia a su voto en el comité.

- 1. Initialize the observation weights $w_i = 1/N$, i = 1, 2/..., N.
- 2. For m=1 to M:
 - (a) Fit a classifier $G_m(x)$ to the training data using weights w_i .
 - (b) Compute

$$err_m = \frac{\sum_{i=1}^{N} w_i L(y_i \neq G_m(x_i))}{\sum_{i=1}^{N} w_i}.$$

- (c) Compute $Q_m = \log((1 \operatorname{err}_m)/\operatorname{err}_m)$.
- (d) Set $w_i \leftarrow w_i \cdot \exp[\alpha_m \cdot I(y_i \neq G_m(x_i))], i = 1, 2, \dots,$
- 3. Output $G(x) = \text{sign}\left[\sum_{m=1}^{M} q_m G_m(x)\right]$.

Observar que este coeficiente es el que determina el peso del voto de este clasificador en el comité resultante

Se recalculan los pesos de los ejemplos del set de entrenamiento. Aumentando los pesos de aquellos ejemplos mal clasificados.

- 1. Initialize the observation weights $w_i = 1/N, \ \not i = 1, 2, \dots, N$.
- 2. For m=1 to M:
 - (a) Fit a classifier $G_m(x)$ to the training
 - (b) Compute

Existen variaciones de este algoritmo donde además se disminuye el peso de los ejemplos bien clasificados. Y se agrega un paso posterior de normalización de los pesos.

$$\operatorname{err}_{m} = \frac{\sum_{i=1}^{N} w_{i} I(y | \operatorname{pesos.})}{\sum_{i=1}^{N} w_{i}}.$$

- (c) Compute $\alpha_m = \log((1 err_m)/err_m)$.
- (d) Set $w_i \leftarrow w_i \cdot \exp[\alpha_m \cdot I(y_i \neq G_m(x_i))], i = 1, 2, \dots, N.$
- 3. Output $G(x) = \operatorname{sign} \left[\sum_{m=1}^{M} \alpha_m G_m(x) \right]$.

Se obtiene como resultado el ensamble G(x) donde cada Gm(x) hace su aporte con su voto ponderado por su coeficiente Am.

- 1. Initialize the observation weights $w_i = 1/N, i \neq 1, 2, \dots, N$.
- 2. For m=1 to M:
 - (a) Fit a classifier $G_m(x)$ to the training data using weights w_i .
 - (b) Compute

$$\operatorname{err}_{m} = \frac{\sum_{i=1}^{N} \psi_{i} I(y_{i} \neq G_{m}(x_{i}))}{\sum_{i=1}^{N} w_{i}}.$$

- (c) Compute $\alpha_m = \log((1 \operatorname{err}_m)/\operatorname{err}_m)$.
- (d) Set $w_i \leftarrow w_i \cdot \exp[\alpha_m / I(y_i \neq G_m(x_i))], i = 1, 2, \dots, N$.
- 3. Output $G(x) = \operatorname{sign} \left[\sum_{m=1}^{M} \alpha_m G_m(x) \right]$.

Gradient Boosting

 El Gradient Boosting es una generalización de boosting para funciones de pérdida diferenciables.
 Es un procedimiento preciso y efectivo que se puede usar para problemas de regresión y clasificación.

 Modelos de Gradient Boosting de árboles se utilizan en una variedad de áreas, incluyendo ranking de búsqueda web, ecología, etc. Input: training set $\{(x_i, y_i)\}_{i=1}^n$, a differentiable loss function L(y, F(x)), number of iterations M. Algorithm:

1. Initialize model with a constant value:

$$F_0(x) = rg \min_{\gamma} \sum_{i=1}^n L(y_i, \gamma).$$

- 2. For m = 1 to M:
 - 1. Compute so-called pseudo-residuals:

$$r_{im} = -igg[rac{\partial L(y_i,F(x_i))}{\partial F(x_i)}igg]_{F(x)=F_{m-1}(x)} \quad ext{for } i=1,\ldots,n.$$

- 2. Fit a base learner (e.g. tree) $h_m(x)$ to pseudo-residuals, i.e. train it using the training set $\{(x_i, r_{im})\}_{i=1}^n$.
- 3. Compute multiplier γ_m by solving the following one-dimensional optimization problem:

$$\gamma_m = rg \min_{\gamma} \sum_{i=1}^n L\left(y_i, F_{m-1}(x_i) + \gamma h_m(x_i)
ight).$$

4. Update the model:

$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x).$$

Input: training set $\{(x_i,y_i)\}_{i=1}^n$, a differentiable loss fur Algorithm:

Inicializamos el modelo con un valor constante.

1. Initialize model with a constant value:

$$F_0(x) = rg \min_{\gamma} \sum_{i=1}^n \mathcal{I}(y_i, \gamma).$$

- 2. For m = 1 to M:
 - 1. Compute so-called pseudo-residuals:

$$r_{im} = -iggl[rac{\partial L(y_i,F(x_i))}{\partial F(x_i)}iggr]_{F(x)=F_{m-1}(x)} \quad ext{for } i=1,\ldots,n.$$

- 2. Fit a base learner (e.g. tree) $h_m(x)$ to pseudo-residuals, i.e. train it using the training set $\{(x_i, r_{im})\}_{i=1}^n$.
- 3. Compute multiplier γ_m by solving the following one-dimensional optimization problem:

$$\gamma_m = rg \min_{\gamma} \sum_{i=1}^n L\left(y_i, F_{m-1}(x_i) + \gamma h_m(x_i)
ight).$$

4. Update the model:

$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x).$$

Input: training set $\{(x_i,y_i)\}_{i=1}^n$, a differentiable loss function L(y,F(x)), number of iterations M.

Algorithm:

1. Initialize model with a constant value:

$$F_0(x) = rg \min_{\gamma} \sum_{i=1}^n L(y_i, \gamma).$$

Para cada iteración (m=1 to M) calculamos los residuos.

- 2. For m = 1 to M:
 - 1. Compute so-called pseudo-residuals:

$$r_{im} = -igg[rac{\partial L(y_i, F(oldsymbol{x_i}))}{\partial F(x_i)}igg]_{F(x) = F_{m-1}(x)} \quad ext{for } i = 1, \dots, n.$$

- 2. Fit a base learner (e.g. tree) $h_m(x)$ to pseudo-residuals, i.e. train it using the training set $\{(x_i, r_{im})\}_{i=1}^n$.
- 3. Compute multiplier γ_m by solving the following one-dimensional optimization problem:

$$\gamma_m = rg \min_{\gamma} \sum_{i=1}^n L\left(y_i, F_{m-1}(x_i) + \gamma h_m(x_i)
ight).$$

4. Update the model:

$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x).$$

Input: training set $\{(x_i, y_i)\}_{i=1}^n$, a differentiable loss function L(y, F(x)), number of iterations M. Algorithm:

1. Initialize model with a constant value:

Para cada iteración (m=1 to M) fiteamos un modelo (por ejemplo, un árbol de decisión) sobre los residuos sobre el training set

- 2 For m = 1 to M:
 - 1. Compute so-called pseudo-residuals:

$$r_{im} = -igg[rac{\partial L(y_i, F(x_i))}{\partial F(x_i)}igg]_{F(x) = F_{m-1}(x)} \quad ext{for } i = 1, \dots, n$$

- 2. Fit a base learner (e.g. tree) $h_m(x)$ to pseudo-residuals, i.e. train it using the training set $\{(x_i,r_{im})\}_{i=1}^n$
- 3. Compute multiplier γ_m by solving the following one-dimensional optimization problem:

$$\gamma_m = rg \min_{\gamma} \sum_{i=1}^n L\left(y_i, F_{m-1}(x_i) + \gamma h_m(x_i)
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4. Update the model:

$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x).$$

Input: training set $\{(x_i,y_i)\}_{i=1}^n$, a differentiable loss function L(y,F(x)), number of iterations M.

Algorithm:

1. Initialize model with a constant value:

$$F_0(x) = rg \min_{\gamma} \sum_{i=1}^n L(y_i, \gamma).$$

- 2. For m = 1 to M:
 - 1. Compute so-called pseu Este es el pase mágico... lo que se busca es encontrar el valor de gamma, que permite calcular la contribución de cada modelo.

$$r_{im} = -igg[rac{\partial L(y_i)}{\partial F(x_i)}igg]_{F(x) = F_{m-1}(x)}$$
 for $i=1,\ldots,n$.

- 2. Fit a base learner (e.g. tree) $h_m(x)$ to pseudo-residuals, i.e. train it using the training set $\{(x_i, r_{im})\}_{i=1}^n$.
- 3. Compute multiplier γ_m by solving the following one-dimensional optimization problem:

$$\gamma_m = rg \min_{\gamma} \sum_{i=1}^n L\left(y_i, F_{m-1}(x_i) + \gamma h_m(x_i)
ight).$$

4. Update the model:

$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x).$$

Input: training set $\{(x_i,y_i)\}_{i=1}^n$, a differentiable loss function L(y,F(x)), number of iterations M.

Algorithm:

Actualizamos el modelo agregando el learner nuevo a la predicción

$$F_0(x) = rg \min_{\gamma} \sum_{i=1} L(y_i, \gamma).$$

- 2. For m = 1 to M:
 - 1. Compute so-called pseudo-residuals:

$$r_{im} = -igg[rac{\partial L(y_i, F(x_i))}{\partial F(x_i)}igg]_{F(x) = F_{m-1}(x)} \quad ext{for } i = 1, \dots, n.$$

- 2. Fit a base learner (e.g/tree) $h_m(x)$ to pseudo-residuals, i.e. train it using the training set $\{(x_i, r_{im})\}_{i=1}^n$.
- 3. Compute multiplier γ_m by solving the following one-dimensional optimization problem:

$$\gamma_m = rg \min_{\gamma} \sum_{i=1}^n L\left(y_i, F_{m-1}(x_i) + \gamma h_m(x_i)
ight).$$

4. Update the model:

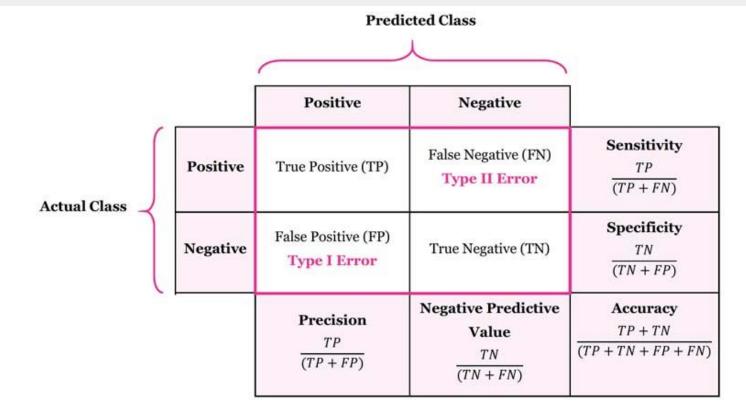
$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x)$$



Síntesis

- Ensambles: herramientas potentes
- Uso de la aleatoriedad para incrementar la capacidad del modelo
- Bagging = Bootstrap Aggregating
- Random Forest = Bagging + random selection de features
- Extra Randomized Trees:
 Random Forest + random splits
- Boosting: entrenamiento secuencial

Evaluando modelos de clasificación



Evaluando modelos de clasificación

| | | True condition | | | | |
|---------------------|------------------------------|---|---|---|--|--|
| | Total population | Condition positive | Condition negative | Prevalence = $\frac{\sum Condition positive}{\sum Total population}$ | Accuracy (ACC) = $\frac{\Sigma \text{ True positive} + \Sigma \text{ True negative}}{\Sigma \text{ Total population}}$ | |
| Predicted condition | Predicted condition positive | True positive | False positive, Type I error | Positive predictive value (PPV), Precision = $\frac{\Sigma \text{ True positive}}{\Sigma \text{ Predicted condition positive}}$ | False discovery rate (FDR) = Σ False positive Σ Predicted condition positive | |
| | Predicted condition negative | False negative, Type II error | True negative | False omission rate (FOR) = Σ False negative Σ Predicted condition negative | Negative predictive value (NPV) = $\frac{\Sigma}{\Gamma}$ True negative $\frac{\Sigma}{\Gamma}$ Predicted condition negative | |
| | | True positive rate (TPR), Recall, Sensitivity, probability of detection, Power = $\frac{\Sigma \text{ True positive}}{\Sigma \text{ Condition positive}}$ | False positive rate (FPR), Fall-out, probability of false alarm = $\frac{\Sigma}{\Sigma}$ False positive $\frac{\Sigma}{\Sigma}$ Condition negative | Positive likelihood ratio (LR+) = TPR FPR | Diagnostic odds | F ₁ score = |
| | | False negative rate (FNR), Miss rate $= \frac{\Sigma \text{ False negative}}{\Sigma \text{ Condition positive}}$ | Specificity (SPC), Selectivity, True negative rate $(TNR) = \frac{\Sigma \text{ True negative}}{\Sigma \text{ Condition negative}}$ | Negative likelihood ratio (LR-) = $\frac{FNR}{TNR}$ | ratio (DOR) = $\frac{LR+}{LR-}$ | 2 · Precision · Recall Precision + Recall |

Evaluando modelos de clasificación

