Core Probability Reference

Definition: Empirical Definition of Probability

The probability of any event E can be defined as:

$$P(E) = \lim_{n \to \infty} \frac{\text{count}(E)}{n}$$

Where count(E) is the number of times that E occurred in n experiments.

Definition: Core Identities

For an event E and a sample space S

 $0 \le \mathrm{P}(E) \le 1$

All probabilities are numbers between 0 and 1.

P(S) = 1

All outcomes must be from the Sample Space.

 $P(E) = 1 - P(E^{^{\mathrm{C}}})$

The probability of an event from its complement.

Definition: Probability of Equally Likely Outcomes

If S is a sample space with equally likely outcomes, for an event E that is a subset of the outcomes in S:

$$\mathrm{P}(E) = \frac{\mathrm{number\ of\ outcomes\ in}\ E}{\mathrm{number\ of\ outcomes\ in}\ S} = \frac{|E|}{|S|}$$

Definition: Conditional Probability.

The probability of E given that (aka conditioned on) event F already happened:

$$P(E|F) = \frac{P(E \text{ and } F)}{P(F)}$$

Definition: Probability of or with Mututally Exclusive Events

If two events E and F are mutually exclusive then the probability of E or F occurring is:

$$P(E \text{ or } F) = P(E) + P(F)$$

For n events $E_1, E_2, \dots E_n$ where each event is mutually exclusive of one another (in other words, no outcome is in more than one event). Then:

$$\mathrm{P}(E_1 \, \mathrm{or} \, E_2 \, \mathrm{or} \ldots \mathrm{or} \, E_n) = \mathrm{P}(E_1) + \mathrm{P}(E_2) + \cdots + \mathrm{P}(E_n) = \sum_{i=1}^n \mathrm{P}(E_i)$$

Definition: General Probability of or (Inclusion-Exclusion)

For any two events E and F:

$$P(E \text{ or } F) = P(E) + P(F) - P(E \text{ and } F)$$

For three events, E, F, and G the formula is:

$$\mathrm{P}(E \, \mathrm{or} \, F \, \mathrm{or} \, G) = \mathrm{P}(E) + \mathrm{P}(F) + \mathrm{P}(G) \\ - \mathrm{P}(E \, \mathrm{and} \, F) - \mathrm{P}(E \, \mathrm{and} \, G) - P(F \, \mathrm{and} \, G) \\ + \mathrm{P}(E \, \mathrm{and} \, F \, \mathrm{and} \, G)$$

For more than three events see the chapter of probability of or.

Definition: Probability of and for Independent Events.

If two events: E, F are independent then the probability of E and F occurring is:

$$P(E \text{ and } F) = P(E) \cdot P(F)$$

For n events $E_1, E_2, \dots E_n$ that are independent of one another:

$$\mathrm{P}(E_1 \, \mathrm{and} \, E_2 \, \mathrm{and} \dots \mathrm{and} \, E_n) = \prod_{i=1}^n \mathrm{P}(E_i)$$

Definition: General Probability of and (The Chain Rule)

For any two events E and F:

$$P(E \text{ and } F) = P(E|F) \cdot P(F)$$

For n events $E_1, E_2, \dots E_n$:

$$P(E_1 \text{ and } E_2 \text{ and } \dots \text{ and } E_n) = P(E_1) \cdot P(E_2|E_1) \cdot P(E_3|E_1 \text{ and } E_2) \dots$$

 $P(E_n|E_1 \dots E_{n-1})$

Definition: The Law of Total Probability

For any two events E and F:

$$P(E) = P(E \text{ and } F) + P(E \text{ and } F^{C})$$
$$= P(E|F) P(F) + P(E|F^{C}) P(F^{C})$$

For <u>mutually exclusive</u> events: $B_1, B_2, \dots B_n$ such that every outcome in the sample space falls into one of those events:

$$\mathrm{P}(E) = \sum_{i=1}^n \mathrm{P}(E \, \mathrm{and} \, B_i)$$
 Extension of our observation $= \sum_{i=1}^n \mathrm{P}(E|B_i) \, \mathrm{P}(B_i)$ Using chain rule on each term

Definition: Bayes' Theorem

The most common form of Bayes' Theorem is Bayes' Theorem Classic:

$$P(B|E) = \frac{P(E|B) \cdot P(B)}{P(E)}$$

Bayes' Theorem combined with the Law of Total Probability:

$$P(B|E) = \frac{P(E|B) \cdot P(B)}{P(E|B) \cdot P(B) + P(E|B^{C}) \cdot P(B^{C})}$$