Core Probability Reference

Definition: Empirical Definition of Probability

The probability of any event E can be defined as:

$$\mathrm{P}(E) = \lim_{n o \infty} rac{\mathrm{count}(E)}{n}$$

Where count(E) is the number of times that E occurred in n experiments.

Definition: Core Identities

For an event E and a sample space S

 $0 \leq \mathrm{P}(E) \leq 1$

All probabilities are numbers between 0 and 1.

P(S) = 1

All outcomes must be from the Sample Space.

 $P(E) = 1 - P(E^{^{\mathrm{C}}})$

The probability of an event from its complement.

Definition: Probability of Equally Likely Outcomes

If S is a sample space with equally likely outcomes, for an event E that is a subset of the outcomes in S:

$$P(E) = \frac{\text{number of outcomes in } E}{\text{number of outcomes in } S} = \frac{|E|}{|S|}$$

Definition: Conditional Probability.

The probability of E given that (aka conditioned on) event F already happened:

$$\mathrm{P}(E|F) = rac{\mathrm{P}(E \, \mathrm{and} \, F)}{\mathrm{P}(F)}$$

Definition: Probability of **or** with Mututally Exclusive Events

If two events E and F are mutually exclusive then the probability of E or F occurring is:

$$P(E \operatorname{or} F) = P(E) + P(F)$$

For n events $E_1, E_2, \dots E_n$ where each event is mutually exclusive of one another (in other words, no outcome is in more than one event). Then:

$$\mathrm{P}(E_1 \, \mathrm{or} \, E_2 \, \mathrm{or} \ldots \mathrm{or} \, E_n) = \mathrm{P}(E_1) + \mathrm{P}(E_2) + \cdots + \mathrm{P}(E_n) = \sum_{i=1}^n \mathrm{P}(E_i)$$

Definition: General Probability of **or** (Inclusion-Exclusion)

For any two events E and F:

$$P(E \text{ or } F) = P(E) + P(F) - P(E \text{ and } F)$$

For three events, E, F, and G the formula is:

$$egin{aligned} \mathrm{P}(E \, \mathrm{or} \, F \, \mathrm{or} \, G) &= \mathrm{P}(E) + \mathrm{P}(F) + \mathrm{P}(G) \ &- \mathrm{P}(E \, \mathrm{and} \, F) - \mathrm{P}(E \, \mathrm{and} \, G) - P(F \, \mathrm{and} \, G) \ &+ \mathrm{P}(E \, \mathrm{and} \, F \, \mathrm{and} \, G) \end{aligned}$$

For more than three events see the chapter of probability of or.

Definition: Probability of and for Independent Events.

If two events: E, F are independent then the probability of E and F occurring is:

$$P(E \text{ and } F) = P(E) \cdot P(F)$$

For n events $E_1, E_2, \dots E_n$ that are independent of one another:

$$\operatorname{P}(E_1 \operatorname{and} E_2 \operatorname{and} \ldots \operatorname{and} E_n) = \prod_{i=1}^n \operatorname{P}(E_i)$$

Definition: General Probability of and (The Chain Rule)

For any two events E and F:

$$P(E \text{ and } F) = P(E|F) \cdot P(F)$$

For n events $E_1, E_2, \dots E_n$:

Definition: The Law of Total Probability

For any two events E and F:

$$egin{aligned} \mathrm{P}(E) &= \mathrm{P}(E \, \mathrm{and} \, F) + \mathrm{P}(E \, \mathrm{and} \, F^{\,\,\mathrm{C}}) \ &= \mathrm{P}(E|F) \, \mathrm{P}(F) + \mathrm{P}(E|F^{\,\,\mathrm{C}}) \, \mathrm{P}(F^{\,\,\mathrm{C}}) \end{aligned}$$

For <u>mutually exclusive</u> events: $B_1, B_2, \dots B_n$ such that every outcome in the sample space falls into one of those events:

$$\mathrm{P}(E) = \sum_{i=1}^n \mathrm{P}(E \, \mathrm{and} \, B_i)$$
 Extension of our observation $= \sum_{i=1}^n \mathrm{P}(E|B_i) \, \mathrm{P}(B_i)$ Using chain rule on each term

Definition: Bayes' Theorem

The most common form of Bayes' Theorem is Bayes' Theorem Classic:

$$\mathrm{P}(B|E) = rac{\mathrm{P}(E|B)\cdot\mathrm{P}(B)}{\mathrm{P}(E)}$$

Bayes' Theorem combined with the Law of Total Probability:

$$\mathrm{P}(B|E) = rac{\mathrm{P}(E|B)\cdot\mathrm{P}(B)}{\mathrm{P}(E|B)\cdot\mathrm{P}(B)+\mathrm{P}(E|B^{\mathrm{C}})\cdot\mathrm{P}(B^{\mathrm{C}})}$$