

GAWM1

rf1	$\begin{matrix} f=[wf1] \\ b=[] \\ c=[] \\ a=[] \\ z=[] \\ y=[wy1] \\ x=[] \end{matrix}$	rc1	$\begin{matrix} f=[wf1] \\ b=[] \\ c=[wc1] \\ a=[] \\ z=[] \\ y=[wy1] \\ x=[wx2] \end{matrix}$	rz1	$\begin{matrix} f=[wf1] \\ b=[] \\ c=[wc1] \\ a=[] \\ z=[wz1] \\ y=[wy1] \\ x=[wx2] \end{matrix}$	ry1	$\begin{matrix} f=[wf1] \\ b=[] \\ c=[wc1] \\ a=[] \\ z=[wz1] \\ y=[wy1] \\ x=[wx2] \end{matrix}$	ra1	$\begin{matrix} f=[wf2,wf1] \\ b=[] \\ c=[wc1] \\ a=[wa1] \\ z=[wz1,wz2] \\ y=[wy1] \\ x=[wx2,wx3] \end{matrix}$	rb1	$\begin{matrix} f=[wf2,wf1] \\ b=[wb1] \\ c=[wc1] \\ a=[wa1] \\ z=[wz1,wz2] \\ y=[wy2,wy1] \\ x=[wx5,wx2,wx3] \end{matrix}$	rx2	$\begin{matrix} f=[wf2,wf1] \\ b=[wb1] \\ c=[wc1] \\ a=[wa1] \\ z=[wz1,wz2] \\ y=[wy2,wy1] \\ x=[wx5,wx2,wx3] \end{matrix}$
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GAWM2

rf1	$\begin{matrix} f=[wf1] \\ b=[] \\ c=[] \\ a=[] \\ z=[] \\ y=[wy1] \\ x=[] \end{matrix}$	rc1	$\begin{matrix} f=[wf1] \\ b=[] \\ c=[wc1] \\ a=[] \\ z=[] \\ y=[wy1] \\ x=[wx2] \end{matrix}$	rz1	$\begin{matrix} f=[wf1] \\ b=[] \\ c=[wc1] \\ a=[] \\ z=[wz1] \\ y=[wy1] \\ x=[wx2] \end{matrix}$	ry1	$\begin{matrix} f=[wf1] \\ b=[] \\ c=[wc1] \\ a=[] \\ z=[wz1] \\ y=[wy1] \\ x=[wx2] \end{matrix}$	ra1	$\begin{matrix} f=[wf2,wf1] \\ b=[] \\ c=[wc1] \\ a=[wa1] \\ z=[wz1,wz2] \\ y=[wy1] \\ x=[wx2,wx3] \end{matrix}$	rb1	$\begin{matrix} f=[wf2,wf1] \\ b=[wb1] \\ c=[wc1] \\ a=[wa1] \\ z=[wz1,wz2] \\ y=[wy2,wy1] \\ x=[wx5,wx2,wx3] \end{matrix}$	rx2	$\begin{matrix} f=[wf1] \\ b=[wb1] \\ c=[wc1] \\ a=[wa1] \\ z=[wz1] \\ y=[wy1] \\ x=[wx2] \end{matrix}$
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0

1

2

3

4

