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SKILLING-7:

Implement Adam and SGD algorithms with only NumPy library and use it to implement DNN classification model

```
import numpy as np
import torch
import torch.nn as nn
from torch.utils.data import DataLoader, TensorDataset
class SGD Numpy:
  def init (self, parameters, lr=0.01):
    self.lr, self.parameters = lr, parameters
  def step(self, grads):
    for p, g in zip(self.parameters, grads):
      p = self.lr * g
class Adam_Numpy:
  def init (self, parameters, lr=0.001, beta1=0.9, beta2=0.999, epsilon=1e-8):
    self.lr, self.beta1, self.beta2, self.epsilon = lr, beta1, beta2, epsilon
    self.m, self.v = [np.zeros like(p.detach().numpy()) for p in parameters],
[np.zeros_like(p.detach().numpy()) for p in parameters]
    self.t, self.parameters = 0, parameters
  def step(self, grads):
    self.t += 1
    for i, (p, g) in enumerate(zip(self.parameters, grads)):
      self.m[i] = self.beta1 * self.m[i] + (1 - self.beta1) * g
      self.v[i] = self.beta2 * self.v[i] + (1 - self.beta2) * (g ** 2)
      m_hat, v_hat = self.m[i] / (1 - self.beta1 ** self.t), self.v[i] / (1 - self.beta2 **
self.t)
      p.data -= self.lr * m hat / (np.sqrt(v hat) + self.epsilon)
class DNN(nn.Module):
  def init (self, input dim, hidden dim, output dim):
```

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    super(DNN, self).__init__()
    self.fc1, self.relu, self.fc2 = nn.Linear(input_dim, hidden_dim), nn.ReLU(),
nn.Linear(hidden dim, output dim)
  def forward(self, x):
    return self.fc2(self.relu(self.fc1(x)))
torch.manual seed(42)
X, y = torch.randn(500, 10), torch.randint(0, 2, (500,))
dataset, dataloader = TensorDataset(X, y), DataLoader(TensorDataset(X, y),
batch size=32, shuffle=True)
input dim, hidden dim, output dim = 10, 16, 2
model = DNN(input dim, hidden dim, output dim) # Initialize model first
params = list(model.parameters()) # Then extract parameters
optimizer, epochs, loss fn = Adam Numpy(params, Ir=0.01), 10, nn.CrossEntropyLoss()
for epoch in range(epochs):
  total loss = 0
  for batch_X, batch_y in dataloader:
    logits, loss = model(batch_X), loss_fn(model(batch_X), batch_y)
    model.zero grad()
```

grads = [p.grad.detach().numpy() for p in model.parameters()]

print(f"Epoch {epoch+1}, Loss: {total loss / len(dataloader)}")

loss.backward()

optimizer.step(grads)
total loss += loss.item()

Output:

Epoch 1, Loss: 0.7037773504853249
Epoch 2, Loss: 0.6819578520953655
Epoch 3, Loss: 0.6730007231235504
Epoch 4, Loss: 0.6657436639070511
Epoch 5, Loss: 0.6607115715742111
Epoch 6, Loss: 0.6507641337811947
Epoch 7, Loss: 0.649769201874733
Epoch 8, Loss: 0.6370874531567097
Epoch 9, Loss: 0.6313175074756145
Epoch 10, Loss: 0.6257837526500225

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