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Date		Student Name	[@KLWKS_BOT] THANOS

Experiment Title: To implement programs on problem solving using Graph Algorithms.

Aim/Objective: To understand the concept and implementation of programs on Graph Algorithms-based Problems.

Description: The students will understand DFS , BFS, Single Source Shortest Path and All-Pairs Shortest path algorithms. Students will gain experience in implementing these algorithms and applying them to solve real-world problems.

Pre-Requisites:

Knowledge: Before beginning this lab, students should have a foundational understanding of:

- The concepts of DFS , BFS, Single Source Shortest Path, and All-Pairs Shortest path algorithms.
- Mathematical Background: Logarithmic complexity analysis for tree operations.
- Understanding of height-balanced properties.

Tools: Code Blocks/Eclipse IDE.

Pre-Lab:

1. Write a program to find the shortest path from a starting point (e.g., a person's location) to the nearest exit in a building represented as a grid using BFS.

- **Procedure/Program:**

```
import java.util.LinkedList;
import java.util.Queue;
```

```
class Point {
    int x, y;

    Point(int x, int y) {
        this.x = x;
        this.y = y;
    }
}
```

```
public class Main{
    static final int MAX = 100;
```

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```

public static int bfs(int[][] grid, int n, int m, Point start) {
    int[][] directions = {{0, 1}, {1, 0}, {0, -1}, {-1, 0}};
    boolean[][] visited = new boolean[MAX][MAX];
    Queue<Point> q = new LinkedList<>();
    q.add(start);
    visited[start.x][start.y] = true;
    int distance = 0;

    while (!q.isEmpty()) {
        int size = q.size();
        for (int i = 0; i < size; i++) {
            Point current = q.poll();
            if (grid[current.x][current.y] == 2) {
                return distance;
            }
            for (int[] direction : directions) {
                int newX = current.x + direction[0];
                int newY = current.y + direction[1];
                if (newX >= 0 && newX < n && newY >= 0 && newY < m &&
                    grid[newX][newY] != 1 && !visited[newX][newY]) {
                    visited[newX][newY] = true;
                    q.add(new Point(newX, newY));
                }
            }
        }
        distance++;
    }
    return -1;
}

public static void main(String[] args) {
    int[][] grid = {
        {0, 0, 1, 0, 2},
        {0, 1, 0, 0, 0},
        {0, 0, 0, 1, 0},
        {1, 0, 1, 0, 0},
        {0, 0, 0, 0, 0}
    };
}

```

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```

Point start = new Point(0, 0);
int n = 5, m = 5;
int result = bfs(grid, n, m, start);
if (result != -1) {
    System.out.println("Shortest path to exit is: " + result);
} else {
    System.out.println("No exit found.");
}
}
}

```

- **Data and Results:**

Data

A grid represents a building with obstacles and exits.

Result

Shortest path to the nearest exit is determined using BFS.

- **Analysis and Inferences:**

Analysis

Breadth-first search explores paths layer-by-layer, ensuring shortest route.

Inferences

BFS efficiently finds the shortest exit path in grid-based environments.

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In-Lab:

1. You are given a connected, undirected graph representing a network of cities. Each edge represents a road between two cities with a given cost. Write a program to find the Minimum Spanning Tree (MST), which connects all cities with the minimum total cost.

• Procedure/Program:

```
import java.util.Arrays;

public class Main {

    static final int MAX = 100;

    static final int INF = 99999;

    static int[][] graph = new int[MAX][MAX];

    static int[] parent = new int[MAX];

    static int[] key = new int[MAX];

    static boolean[] visited = new boolean[MAX];

    static int numVertices;

    static void primMST() {

        Arrays.fill(key, INF);

        Arrays.fill(visited, false);

        key[0] = 0;

        parent[0] = -1;
```

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```

for (int count = 0; count < numVertices - 1; count++) {

    int minKey = INF, minIndex = -1;

    for (int v = 0; v < numVertices; v++) {

        if (!visited[v] && key[v] < minKey) {

            minKey = key[v];

            minIndex = v;

        }

    }

    visited[minIndex] = true;

    for (int v = 0; v < numVertices; v++) {

        if (graph[minIndex][v] != 0 && !visited[v] && graph[minIndex][v] < key[v]) {

            parent[v] = minIndex;

            key[v] = graph[minIndex][v];

        }

    }

}

static void printMST() {

    System.out.println("Edge \tWeight");

```

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```

for (int i = 1; i < numVertices; i++) {

    System.out.println(parent[i] + " - " + i + "\t" + graph[i][parent[i]]);

}

}

```

```

public static void main(String[] args) {

    numVertices = 5;

    int[][] exampleGraph = {

        {0, 2, 0, 6, 0},

        {2, 0, 3, 8, 5},

        {0, 3, 0, 0, 7},

        {6, 8, 0, 0, 9},

        {0, 5, 7, 9, 0}

    };

```

```

for (int i = 0; i < numVertices; i++) {

    for (int j = 0; j < numVertices; j++) {

        graph[i][j] = exampleGraph[i][j];

    }

}

```

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```
primMST();  
  
printMST();  
  
}  
  
}
```

- **Data and Results:**

Data
Graph with 5 vertices and weighted edges representing city roads.

Result
Minimum Spanning Tree (MST) found with the least total cost.

- **Analysis and Inferences:**

Analysis
Prim’s algorithm selects edges with the smallest weights efficiently.

Inferences
MST connects all cities while minimizing the total connection cost.

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2. You are given a city map represented as a graph. Write a program to determine if there is a path between two given intersections (nodes). Use Depth-First Search (DFS) or Breadth-First Search (BFS) to solve the problem.

• **Procedure/Program:**

```

public class Main {
    private static final int MAX = 100;
    private int[][] adj = new int[MAX][MAX];
    private int[] visited = new int[MAX];
    private int numNodes;

    public void initGraph(int nodes) {
        this.numNodes = nodes;
        for (int i = 0; i < nodes; i++) {
            visited[i] = 0;
            for (int j = 0; j < nodes; j++) {
                adj[i][j] = 0;
            }
        }
    }

    public void addEdge(int src, int dest) {
        adj[src][dest] = 1;
        adj[dest][src] = 1;
    }

    private void dfs(int node, int target, int[] found) {
        visited[node] = 1;
        if (node == target) {
            found[0] = 1;
            return;
        }
        for (int i = 0; i < numNodes; i++) {
            if (adj[node][i] == 1 && visited[i] == 0) {
                dfs(i, target, found);
            }
        }
    }
}

```

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```

    }
}

public boolean isPath(int start, int end) {
    int[] found = {0};
    dfs(start, end, found);
    return found[0] == 1;
}

public static void main(String[] args) {
    Main g = new Main();
    g.initGraph(5);

    g.addEdge(0, 1);
    g.addEdge(0, 2);
    g.addEdge(1, 3);
    g.addEdge(2, 4);

    int start = 0, end = 3;
    if (g.isPath(start, end)) {
        System.out.println("Path exists between " + start + " and " + end);
    } else {
        System.out.println("No path exists between " + start + " and " + end);
    }
}
}

```

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- **Data and Results:**

Data

Graph with 5 nodes, edges define connectivity between intersections.

Result

DFS determines if a path exists between two intersections.

- **Analysis and Inferences:**

Analysis

Graph traversal explores connected nodes to check reachability efficiently.

Inferences

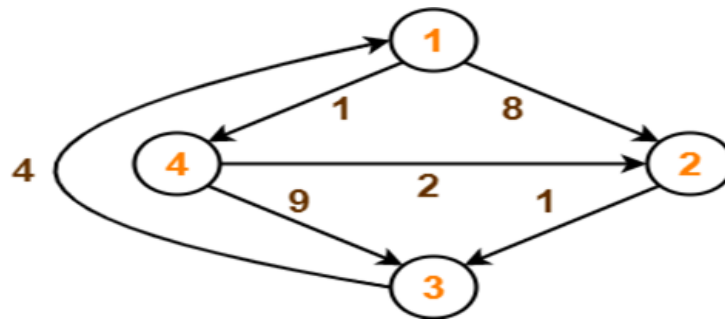
Path existence confirms connectivity; absence indicates graph disconnection.

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Post-Lab:

Consider the following directed weighted graph and Using Floyd-Warshall Algorithm, find the shortest path distance between every pair of vertices.



• Procedure/Program:

Step-01:

- Remove all the self loops and parallel edges (keeping the lowest weight edge) from the graph.
- In the given graph, there are neither self edges nor parallel edges.

Step-02:

- Write the initial distance matrix.
- It represents the distance between every pair of vertices in the form of given weights.
- For diagonal elements (representing self-loops), distance value = 0.
- For vertices having a direct edge between them, distance value = weight of that edge.
- For vertices having no direct edge between them, distance value = ∞ .

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Initial distance matrix for the given graph is-

$$D_0 = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 8 & \infty & 1 \\ \infty & 0 & 1 & \infty \\ 4 & \infty & 0 & \infty \\ \infty & 2 & 9 & 0 \end{bmatrix} \end{matrix}$$

Step-03:

Using Floyd Warshall Algorithm, write the following 4 matrices-

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1

2

3

4

1

2

3

4

0

8

∞

1

∞

0

1

∞

4

12

0

5

∞

2

9

0

1

2

3

4

1

2

3

4

0

8

9

1

∞

0

1

∞

4

12

0

5

∞

2

3

0

1

2

3

4

1

2

3

4

0

8

9

1

5

0

1

6

4

12

0

5

7

2

3

0

1

2

3

4

1

2

3

4

0

3

4

1

5

0

1

6

4

7

0

5

7

2

3

0

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- **Data and Results:**

Data

Graph with weighted edges, vertices, and adjacency matrix representation.

Result

Final shortest path matrix obtained using Floyd-Warshall algorithm.

- **Analysis and Inferences :**

Analysis

Each iteration refines shortest paths by considering intermediate vertices.

Inferences

Algorithm efficiently finds shortest paths between all vertex pairs.

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• **Sample VIVA-VOCE Questions (In-Lab):**

1. What is the time complexity of DFS?

- $O(V + E)$, where V is vertices and E is edges.

2. How can BFS be used to find the shortest path in an unweighted graph?

- Uses level-order traversal, marking shortest distance from the source.

3. How can you implement Dijkstra's Algorithm using a priority queue?

- Uses min-heap to pick the smallest distance vertex, updating neighbors.

4. What is the Floyd-Warshall Algorithm?

- Dynamic Programming approach for all-pairs shortest paths in $O(V^3)$.

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5. How is Prim's Algorithm different from Kruskal's Algorithm?

- Prim's grows MST from a node, Kruskal's sorts edges and merges sets.

Evaluator Remark (if Any):	Marks Secured ____ out of 50
	Signature of the Evaluator with Date

Evaluator MUST ask Viva-voce prior to signing and posting marks for each experiment.

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