Deep Neural Network for Image Classification: Application

By the time you complete this notebook, you will have finished the last programming assignment of Week 4, and also the last programming assignment of Course 1! Go you!

To build your cat/not-a-cat classifier, you'll use the functions from the previous assignment to build a deep network. Hopefully, you'll see an improvement in accuracy over your previous logistic regression implementation.

After this assignment you will be able to:

Build and train a deep L-layer neural network, and apply it to supervised learning

Let's get started!

Important Note on Submission to the AutoGrader

Before submitting your assignment to the AutoGrader, please make sure you are not doing the following:

- 1. You have not added any extra print statement(s) in the assignment.
- 2. You have not added any extra code cell(s) in the assignment.
- 3. You have not changed any of the function parameters.
- 4. You are not using any global variables inside your graded exercises. Unless specifically instructed to do so, please refrain from it and use the local variables instead.
- 5. You are not changing the assignment code where it is not required, like creating extra variables.

If you do any of the following, you will get something like, Grader Error: Grader feedback not found (or similarly unexpected) error upon submitting your assignment. Before asking for help/debugging the errors in your assignment, check for these first. If this is the case, and you don't remember the changes you have made, you can get a fresh copy of the assignment by following these instructions (https://www.coursera.org/learn/neural-networks-deep-learning/supplement/iLwon/h-ow-to-refresh-your-workspace).

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1 - Packages

Begin by importing all the packages you'll need during this assignment.

- <u>numpy (https://www.numpy.org/)</u> is the fundamental package for scientific computing with Python.
- matplotlib (http://matplotlib.org) is a library to plot graphs in Python.
- h5py (http://www.h5py.org) is a common package to interact with a dataset that is stored on an H5 file.
- PIL (http://www.pythonware.com/products/pil/) and scipy (https://www.scipy.org/) are used here to test your model with your own picture at the end.
- dnn_app_utils provides the functions implemented in the "Building your Deep Neural Network: Step by Step" assignment to this notebook.
- np.random.seed(1) is used to keep all the random function calls consistent. It helps grade your work so please don't change it!

In []:

v1.2

In []:

```
import time
import numpy as np
import h5py
import matplotlib.pyplot as plt
import scipy
from PIL import Image
from scipy import ndimage
from dnn_app_utils_v3 import *
from public_tests import *

%matplotlib inline
plt.rcParams['figure.figsize'] = (5.0, 4.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

%load_ext autoreload
%autoreload 2

np.random.seed(1)
```

2 - Load and Process the Dataset

You'll be using the same "Cat vs non-Cat" dataset as in "Logistic Regression as a Neural Network" (Assignment 2). The model you built back then had 70% test accuracy on classifying cat vs non-cat images. Hopefully, your new model will perform even better!

Problem Statement: You are given a dataset ("data.h5") containing:

- a training set of `m_train` images labelled as cat (1) or non-cat (0)
 a test set of `m_test` images labelled as cat and non-cat
- each image is of shape (num px, num px, 3) where 3 is for the 3 channels (RGB).

Let's get more familiar with the dataset. Load the data by running the cell below.

In []:

```
train_x_orig, train_y, test_x_orig, test_y, classes = load_data()
```

The following code will show you an image in the dataset. Feel free to change the index and re-run the cell multiple times to check out other images.

In []:

```
# Example of a picture
index = 10
plt.imshow(train_x_orig[index])
print ("y = " + str(train_y[0,index]) + ". It's a " + classes[train_y[0,index]].decode("utf-8") + " picture.")
```

In []:

```
# Explore your dataset
m_train = train_x_orig.shape[0]
num_px = train_x_orig.shape[1]
m_test = test_x_orig.shape[0]

print ("Number of training examples: " + str(m_train))
print ("Number of testing examples: " + str(m_test))
print ("Each image is of size: (" + str(num_px) + ", " + str(num_px) + ", 3)")
print ("train_x_orig shape: " + str(train_x_orig.shape))
print ("train_y shape: " + str(train_y.shape))
print ("test_x_orig shape: " + str(test_x_orig.shape))
print ("test_y shape: " + str(test_y.shape))
```

As usual, you reshape and standardize the images before feeding them to the network. The code is given in the cell below.



Figure 1: Image to vector conversion.

In []:

```
# Reshape the training and test examples
train_x_flatten = train_x_orig.reshape(train_x_orig.shape[0], -1).T  # The "-1" makes reshape flatten the remain
ing dimensions
test_x_flatten = test_x_orig.reshape(test_x_orig.shape[0], -1).T

# Standardize data to have feature values between 0 and 1.
train_x = train_x_flatten/255.
test_x = test_x_flatten/255.

print ("train_x's shape: " + str(train_x.shape))
print ("test_x's shape: " + str(test_x.shape))
```

Note: 12, 288 equals $64 \times 64 \times 3$, which is the size of one reshaped image vector.

3 - Model Architecture

3.1 - 2-layer Neural Network

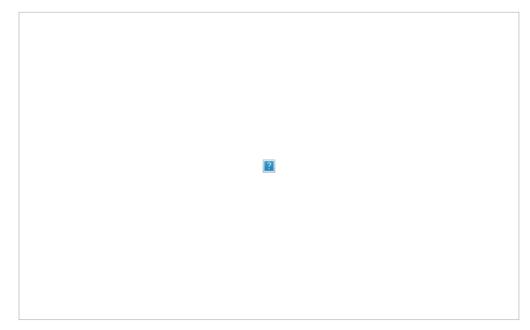
Now that you're familiar with the dataset, it's time to build a deep neural network to distinguish cat images from non-cat images!

You're going to build two different models:

- A 2-layer neural network
- · An L-layer deep neural network

Then, you'll compare the performance of these models, and try out some different values for *L*.

Let's look at the two architectures:



The model can be summarized as: INPUT -> LINEAR -> RELU -> LINEAR -> SIGMOID -> OUTPUT.

Detailed Architecture of Figure 2:

- The input is a (64,64,3) image which is flattened to a vector of size (12288, 1).
- The corresponding vector: $[x_0, x_1, \dots, x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ of size $(n^{[1]}, 12288)$.
- Then, add a bias term and take its relu to get the following vector: $[a_0^{[1]}, a_1^{[1]}, \dots, a_{n^{[1]}-1}^{[1]}]^T$.
- Multiply the resulting vector by $W^{[2]}$ and add the intercept (bias).
- Finally, take the sigmoid of the result. If it's greater than 0.5, classify it as a cat.

3.2 - L-layer Deep Neural Network

It's pretty difficult to represent an L-layer deep neural network using the above representation. However, here is a simplified network representation:



Figure 3: L-layer neural network.

The model can be summarized as: [LINEAR -> RELU] × (L-1) -> LINEAR -> SIGMOID

Detailed Architecture of Figure 3:

- The input is a (64,64,3) image which is flattened to a vector of size (12288,1).
- The corresponding vector: $[x_0, x_1, \dots, x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ and then you add the intercept $b^{[1]}$. The result is called the linear unit.
- Next, take the relu of the linear unit. This process could be repeated several times for each $(W^{[l]}, b^{[l]})$ depending on the model architecture.
- Finally, take the sigmoid of the final linear unit. If it is greater than 0.5, classify it as a cat.

3.3 - General Methodology

As usual, you'll follow the Deep Learning methodology to build the model:

- 1. Initialize parameters / Define hyperparameters
- 2. Loop for num_iterations: a. Forward propagation b. Compute cost function c. Backward propagation d. Update parameters (using parameters, and grads from backprop)
- 3. Use trained parameters to predict labels

Now go ahead and implement those two models!

4 - Two-layer Neural Network

Exercise 1 - two_layer_model

Use the helper functions you have implemented in the previous assignment to build a 2-layer neural network with the following structure: LINEAR -> RELU -> LINEAR -> SIGMOID. The functions and their inputs are:

```
In [1]:
### CONSTANTS DEFINING THE MODEL ####
n x = 12288
               \# num px * num px * 3
n h = 7
n_y = 1
layers dims = (n \times , n + , n \times )
learning rate = 0.0075
# GRADED FUNCTION: two_layer_model
def two_layer_model(X, Y, layers_dims, learning_rate = 0.0075, num_iterations = 3000, print_cost=False):
    Implements a two-layer neural network: LINEAR->RELU->LINEAR->SIGMOID.
    Arguments:
   X -- input data, of shape (n_x, number of examples) 
Y -- true "label" vector (containing 1 if cat, 0 if non-cat), of shape (1, number of examples)
    layers dims -- dimensions of the layers (n x, n h, n y)
    num iterations -- number of iterations of the optimization loop
    learning_rate -- learning rate of the gradient descent update rule
    print cost -- If set to True, this will print the cost every 100 iterations
    Returns:
    parameters -- a dictionary containing W1, W2, b1, and b2
   np.random.seed(1)
    grads = \{\}
    costs = []
                                              # to keep track of the cost
    m = X.shape[1]
                                               # number of examples
    (n_x, n_h, n_y) = layers_dims
    # Initialize parameters dictionary, by calling one of the functions you'd previously implemented
    #(≈ 1 line of code)
    # parameters = ...
    # YOUR CODE STARTS HERE
    parameters = initialize_parameters(n_x, n_h, n_y)
    # YOUR CODE ENDS HERE
    # Get W1, b1, W2 and b2 from the dictionary parameters.
    W1 = parameters["W1"]
    b1 = parameters["b1"]
    W2 = parameters["W2"
    b2 = parameters["b2"]
    # Loop (gradient descent)
    for i in range(0, num iterations):
        # Forward propagation: LINEAR -> RELU -> LINEAR -> SIGMOID. Inputs: "X, W1, b1, W2, b2". Output: "A1, cac
he1, A2, cache2".
        #(≈ 2 lines of code)
```

```
# A1, cache1 = ...
        \# A2, cache2 = ...
        # YOUR CODE STARTS HERE
        A1, cache1 = linear_activation_forward(X, W1, b1, activation="relu")
        A2, cache2 = linear activation forward(A1, W2, b2, activation="sigmoid")
        # YOUR CODE ENDS HERE
        # Compute cost
        #(≈ 1 line of code)
        # cost = ...
        # YOUR CODE STARTS HERE
        cost = compute cost(A2, Y)
        # YOUR CODE ENDS HERE
        # Initializing backward propagation
        dA2 = - (np.divide(Y, A2) - np.divide(1 - Y, 1 - A2))
        # Backward propagation. Inputs: "dA2, cache2, cache1". Outputs: "dA1, dW2, db2; also dA0 (not used), dW1,
db1".
        \#(\approx 2 \text{ lines of code})
        \# dA1, dW2, db2 = ...
        \# dA0, dW1, db1 = ...
        # YOUR CODE STARTS HERE
        dA1, dW2, db2 = linear_activation_backward(dA2, cache2, activation="sigmoid")
        dA0, dW1, db1 = linear_activation_backward(dA1, cache1, activation="relu")
        # YOUR CODE ENDS HERE
        # Set grads['dWl'] to dW1, grads['db1'] to db1, grads['dW2'] to dW2, grads['db2'] to db2
        grads['dW1'] = dW1
        grads['db1'] = db1
        grads['dW2'] = dW2
        grads['db2'] = db2
        # Update parameters.
        #(approx. 1 line of code)
        \# parameters = .
        # YOUR CODE STARTS HERE
        parameters = update parameters(parameters, grads, learning rate)
        # YOUR CODE ENDS HERE
        # Retrieve W1, b1, W2, b2 from parameters
        W1 = parameters["W1"]
        b1 = parameters["b1"]
        W2 = parameters["W2"]
        b2 = parameters["b2"]
        # Print the cost every 100 iterations and for the last iteration
        if print_cost and (i % 100 == 0 or i == num_iterations - 1):
            print("Cost after iteration {}: {}".format(i, np.squeeze(cost)))
        if i % 100 == 0:
            costs.append(cost)
   return parameters, costs
def plot_costs(costs, learning rate=0.0075):
   plt.plot(np.squeeze(costs))
    plt.ylabel('cost')
    plt.xlabel('iterations (per hundreds)')
   plt.title("Learning rate =" + str(learning rate))
    plt.show()
```

```
In [2]:
```

```
parameters, costs = two_layer_model(train_x, train_y, layers_dims = (n_x, n_h, n_y), num_iterations = 2, print_cost=False)
print("Cost after first iteration: " + str(costs[0]))
two_layer_model_test(two_layer_model)
```

NameError: name 'train_x' is not defined

Expected output:

cost after iteration 1 must be around 0.69

4.1 - Train the model

If your code passed the previous cell, run the cell below to train your parameters.

- The cost should decrease on every iteration.
- It may take up to 5 minutes to run 2500 iterations.

In []:

```
parameters, costs = two_layer_model(train_x, train_y, layers_dims = (n_x, n_h, n_y), num_iterations = 2500, print
_cost=True)
plot_costs(costs, learning_rate)
```

Expected Output:

```
      Cost after iteration 0
      0.6930497356599888

      Cost after iteration 100
      0.6464320953428849

      ...
      ...

      Cost after iteration 2499
      0.04421498215868956
```

Nice! You successfully trained the model. Good thing you built a vectorized implementation! Otherwise it might have taken 10 times longer to train this.

Now, you can use the trained parameters to classify images from the dataset. To see your predictions on the training and test sets, run the cell below.

```
In [ ]:
```

```
predictions_train = predict(train_x, train_y, parameters)
```

Expected Output:

Accuracy 0.999999999999998

```
In [ ]:
```

```
predictions_test = predict(test_x, test_y, parameters)
```

Expected Output:

Accuracy 0.72

Congratulations! It seems that your 2-layer neural network has better performance (72%) than the logistic regression implementation (70%, assignment week 2). Let's see if you can do even better with an L-layer model.

Note: You may notice that running the model on fewer iterations (say 1500) gives better accuracy on the test set. This is called "early stopping" and you'll hear more about it in the next course. Early stopping is a way to prevent overfitting.

5 - L-layer Neural Network

Exercise 2 - L_layer_model

Use the helper functions you implemented previously to build an *L*-layer neural network with the following structure: [LINEAR -> RELU] × (L-1) -> LINEAR -> SIGMOID. The functions and their inputs are:

```
In [7]:
```

```
### CONSTANTS ###
layers_dims = [12288, 20, 7, 5, 1] # 4-layer model
# GRADED FUNCTION: L layer model
def L_layer_model(X, Y, layers_dims, learning_rate = 0.0075, num_iterations = 3000, print_cost=False):
    Implements a L-layer neural network: [LINEAR->RELU]*(L-1)->LINEAR->SIGMOID.
    Arguments:
   X -- input data, of shape (n_x, number of examples) 
Y -- true "label" vector (containing 1 if cat, 0 if non-cat), of shape (1, number of examples)
    layers dims -- list containing the input size and each layer size, of length (number of layers + 1).
    learning_rate -- learning rate of the gradient descent update rule
    num_iterations -- number of iterations of the optimization loop
    print_cost -- if True, it prints the cost every 100 steps
    Returns:
    parameters -- parameters learnt by the model. They can then be used to predict.
    np.random.seed(1)
    costs = []
                                        # keep track of cost
    # Parameters initialization.
    #(≈ 1 line of code)
    # parameters = ...
    # YOUR CODE STARTS HERE
    parameters = initialize parameters deep(layers dims)
    # YOUR CODE ENDS HERE
    # Loop (gradient descent)
    for i in range(0, num_iterations):
        # Forward propagation: [LINEAR -> RELU]*(L-1) -> LINEAR -> SIGMOID.
        #(≈ 1 line of code)
        \# AL, caches = ...
        # YOUR CODE STARTS HERE
        AL, caches = L_model_forward(X, parameters)
        # YOUR CODE ENDS HERE
        # Compute cost.
        #(≈ 1 line of code)
        \# cost = .
        # YOUR CODE STARTS HERE
        cost = compute_cost(AL, Y)
        # YOUR CODE ENDS HERE
        # Backward propagation.
        #(≈ 1 line of code)
        # grads = ...
        # YOUR CODE STARTS HERE
        grads = L model backward(AL, Y, caches)
        # YOUR CODE ENDS HERE
        # Update parameters.
        #(≈ 1 line of code)
        # parameters = ..
        # YOUR CODE STARTS HERE
        parameters = update parameters(parameters, grads, learning rate)
        # YOUR CODE ENDS HERE
        # Print the cost every 100 iterations and for the last iteration
        if print_cost and (i % 100 == 0 or i == num_iterations - 1):
            print("Cost after iteration {}: {}".format(i, np.squeeze(cost)))
        if i % 100 == 0:
            costs.append(cost)
    return parameters, costs
```


5.1 - Train the model

If your code passed the previous cell, run the cell below to train your model as a 4-layer neural network.

- The cost should decrease on every iteration.
- It may take up to 5 minutes to run 2500 iterations.

```
In [ ]:
```

```
parameters, costs = L_layer_model(train_x, train_y, layers_dims, num_iterations = 2500, print_cost = True)
```

Expected Output:

```
      Cost after iteration 0
      0.771749

      Cost after iteration 100
      0.672053

      ...
      ...

      Cost after iteration 2499
      0.088439
```

```
In [ ]:
```

```
pred_train = predict(train_x, train_y, parameters)
```

Expected Output:

Train Accuracy 0.985645933014

```
In [ ]:
```

```
pred_test = predict(test_x, test_y, parameters)
```

Expected Output:

Test Accuracy 0.8

Congrats! It seems that your 4-layer neural network has better performance (80%) than your 2-layer neural network (72%) on the same test set.

This is pretty good performance for this task. Nice job!

In the next course on "Improving deep neural networks," you'll be able to obtain even higher accuracy by systematically searching for better hyperparameters: learning rate, layers dims, or num iterations, for example.

6 - Results Analysis

First, take a look at some images the L-layer model labeled incorrectly. This will show a few mislabeled images.

```
In [ ]:
```

```
print_mislabeled_images(classes, test_x, test_y, pred_test)
```

A few types of images the model tends to do poorly on include:

- · Cat body in an unusual position
- · Cat appears against a background of a similar color
- · Unusual cat color and species
- Camera Angle
- · Brightness of the picture
- Scale variation (cat is very large or small in image)

Congratulations on finishing this assignment!

You just built and trained a deep L-layer neural network, and applied it in order to distinguish cats from non-cats, a very serious and important task in deep learning.;)

By now, you've also completed all the assignments for Course 1 in the Deep Learning Specialization. Amazing work! If you'd like to test out how closely you resemble a cat yourself, there's an optional ungraded exercise below, where you can test your own image.

Great work and hope to see you in the next course!

7 - Test with your own image (optional/ungraded exercise)

From this point, if you so choose, you can use your own image to test the output of your model. To do that follow these steps:

- 1. Click on "File" in the upper bar of this notebook, then click "Open" to go on your Coursera Hub.
- 2. Add your image to this Jupyter Notebook's directory, in the "images" folder
- 3. Change your image's name in the following code
- 4. Run the code and check if the algorithm is right (1 = cat, 0 = non-cat)!

In []:

```
## START CODE HERE ##
my_image = "my_image.jpg" # change this to the name of your image file
my_label_y = [1] # the true class of your image (1 -> cat, 0 -> non-cat)
## END CODE HERE ##

fname = "images/" + my_image
image = np.array(Image.open(fname).resize((num_px, num_px)))
plt.imshow(image)
image = image / 255.
image = image.reshape((1, num_px * num_px * 3)).T

my_predicted_image = predict(image, my_label_y, parameters)

print ("y = " + str(np.squeeze(my_predicted_image)) + ", your L-layer model predicts a \"" + classes[int(np.squeeze(my_predicted_image)),].decode("utf-8") + "\" picture.")
```

References:

for auto-reloading external module: http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython)
 (http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython)