

Department of Computer Science

THEORY OF COMPUTATION 23MT2014

Topic:
COMPLEXITY CLASSES: P & NP

Session - 24

AIM OF THE SESSION



To make students explain the fundamental concepts of complexity classes P and NP, their significance in computational theory, and the implications of problems classified within these classes.

INSTRUCTIONAL OBJECTIVES



By the end of this course, students will be able to:

1. Explain the definitions of the complexity classes P and NP.
2. Illustrate examples of problems in P and NP, highlighting the differences between them.
3. Discuss the importance of the P vs NP question and its implications for computer science and other fields.

LEARNING OUTCOMES



At the end of this session, you should be able to:

1. Define and distinguish between the complexity classes P and NP.
2. Identify and categorize problems as belonging to P, NP, or NP-complete.
3. Evaluate the significance of the P vs NP problem and its potential impact on computational theory and practical applications.

CLASSIFYING PROBLEMS BY TIME COMPLEXITY

- **Efficiency Analysis:** **How does complexity change with input size?**
- **Resource Management:** **What resources are needed?**
- **Comparative Benchmarking:** **Which algorithm performs best?**
- **Scalability Prediction :** **How does performance change with size?**
- **Theoretical Foundation:** **What is the problem's complexity class?**
- **Optimization guidance:** **Where are the bottlenecks?**

CLASS OF LANGUAGES

- Let $t: \mathbb{N} \rightarrow \mathbb{R}^+$ be a function. Define the *time complexity class*, $TIME(t(n))$, to be the collection of all languages that are decided by an $O(t(n))$ time Turing Machine.

POLYNOMIAL TIME

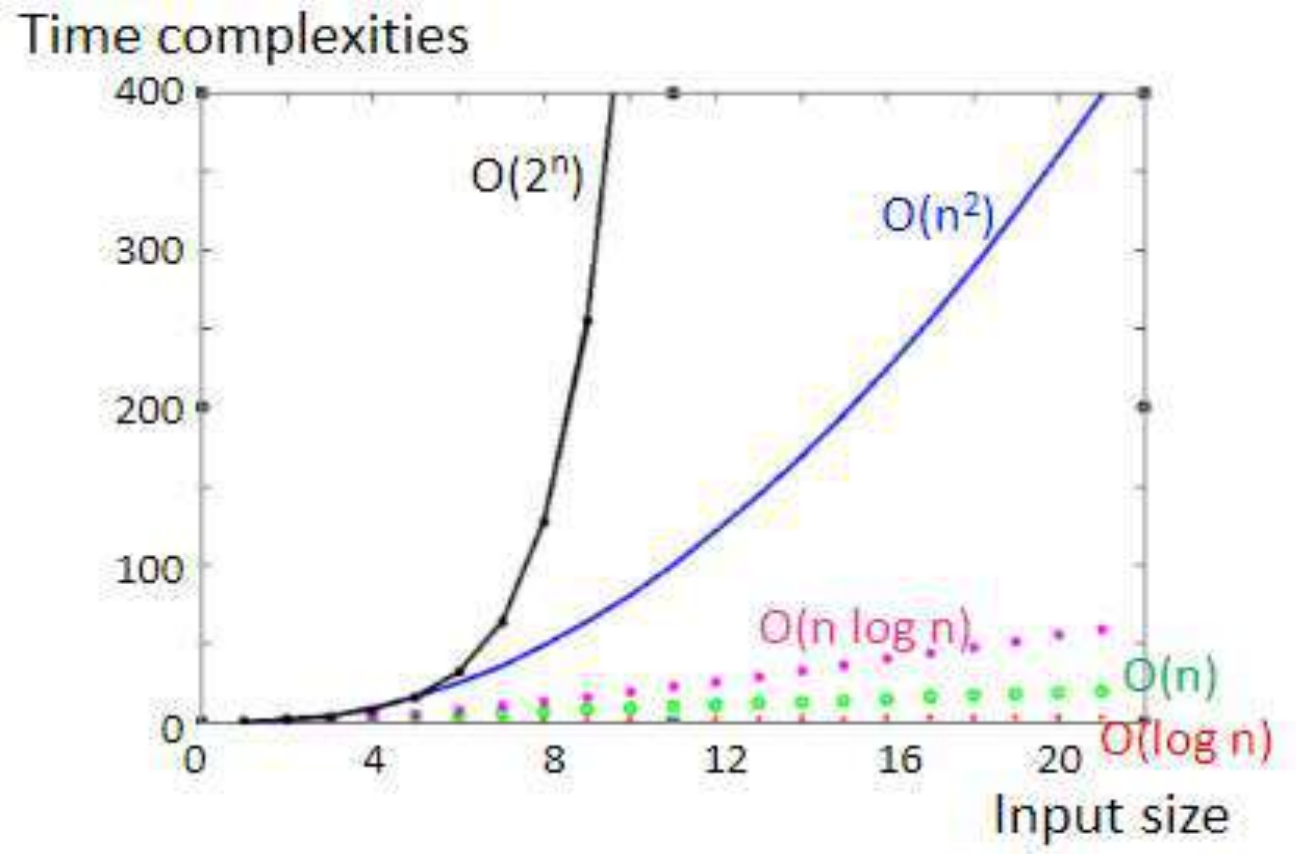
- The time taken by an algorithm (t) increases proportionally to the input size (n) raised to a power, k .
- Ex: n^2 , n^3 , n^4 etc.
- The time complexity is a polynomial function of the input size.

Ex: Quicksort, Merge sort

EXPONENTIAL TIME

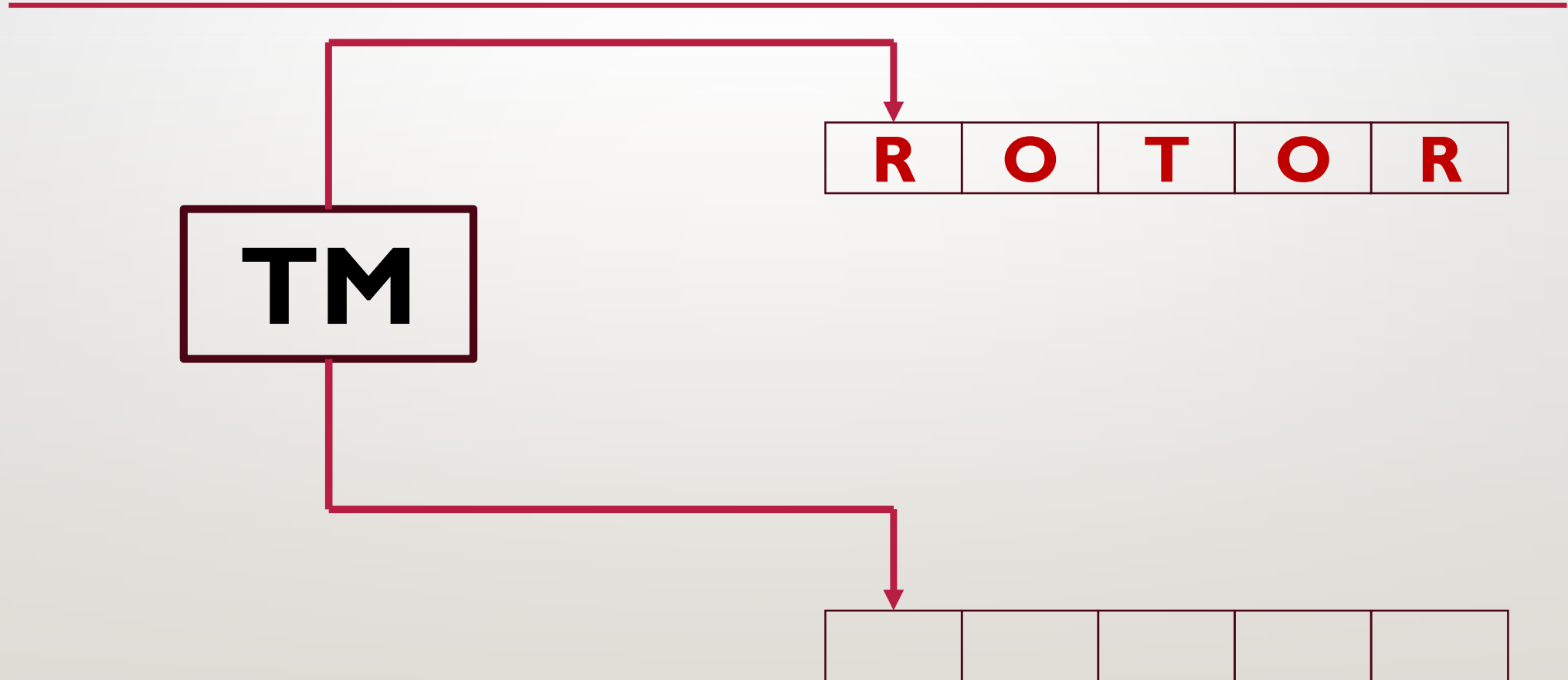
- The time taken by the algorithm (t) increases exponentially with the input size (n).
- Ex: 2^n , 3^n , 5^n etc.
- The time complexity is an exponential function of the input size.
- Example:
 1. Brute-force algorithm for solving Travelling salesperson problem
 2. Solving the knapsack problem using dynamic programming has a time complexity of $O(2^n)$.

POLYNOMIAL VS. EXPONENTIAL TIME



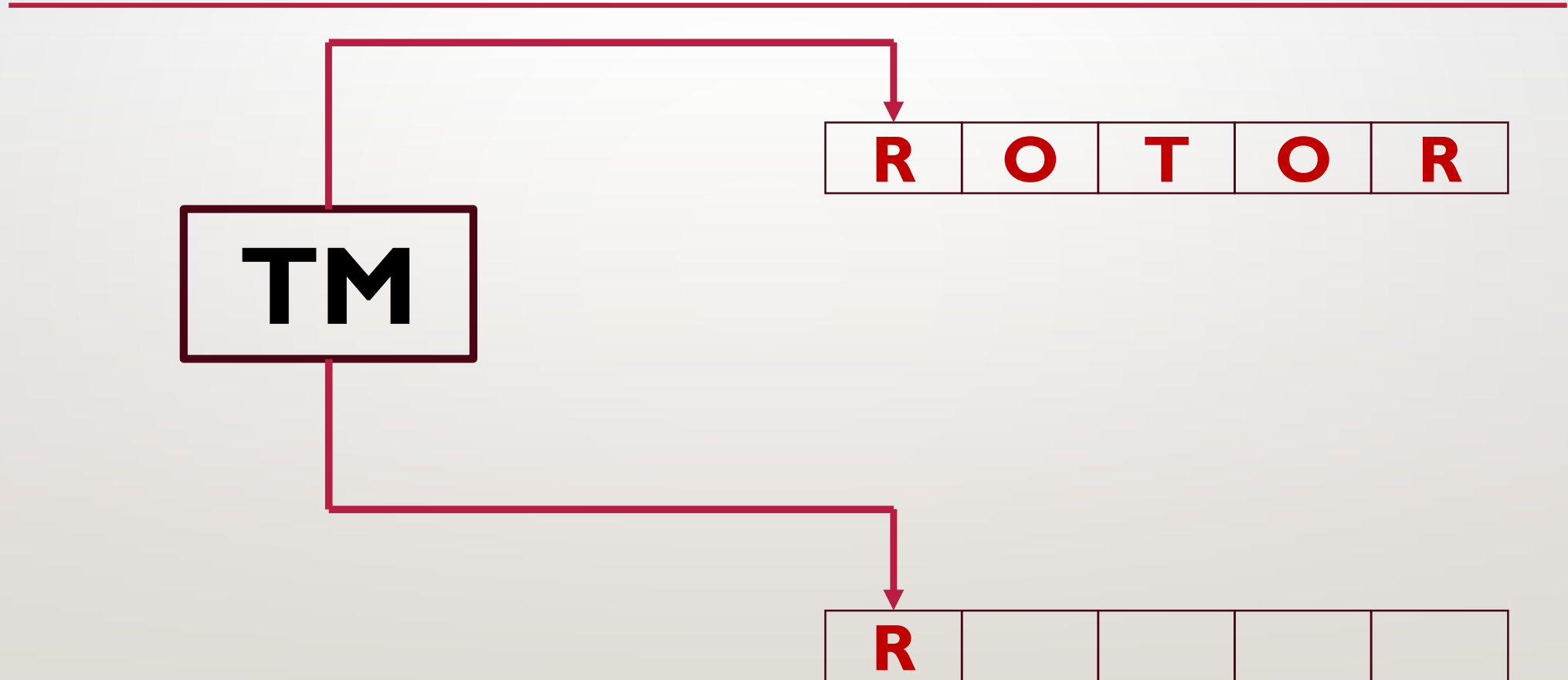
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k-TAPE



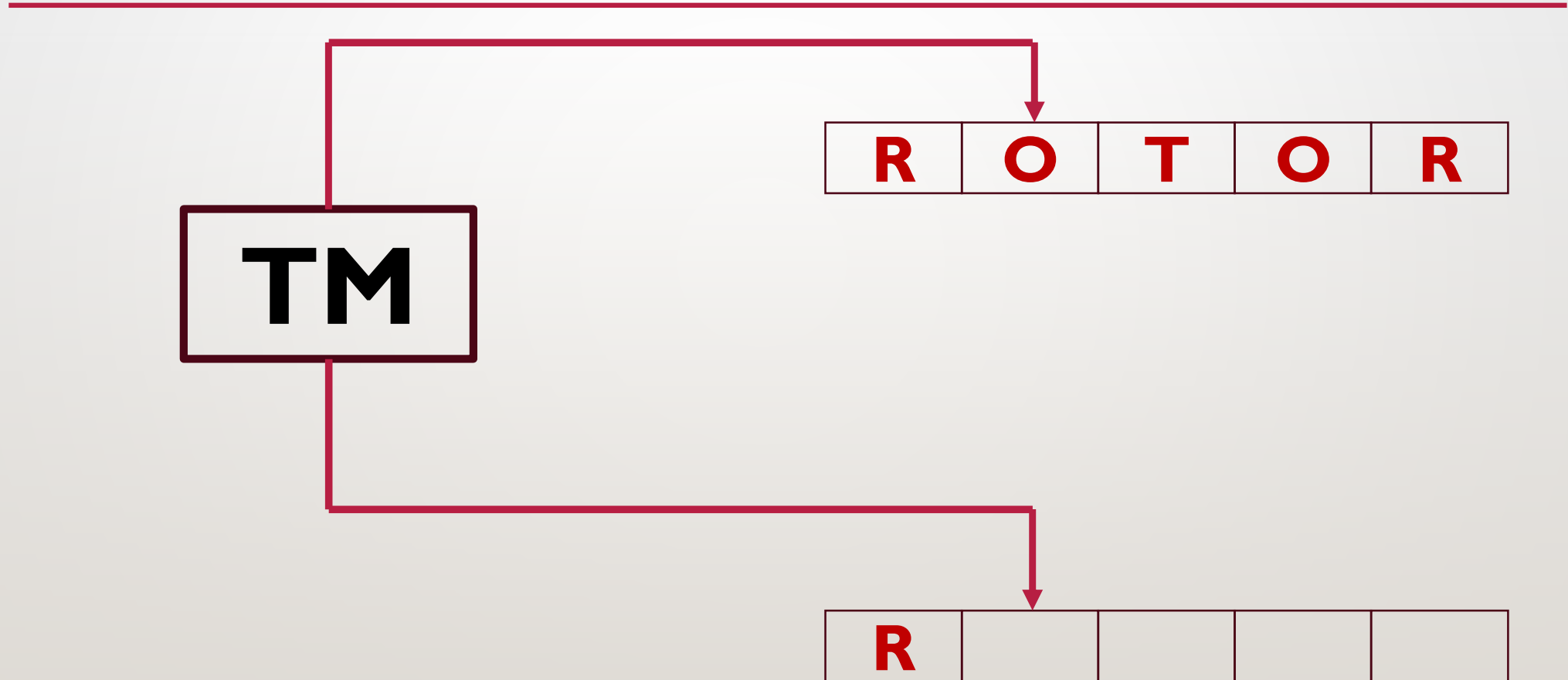
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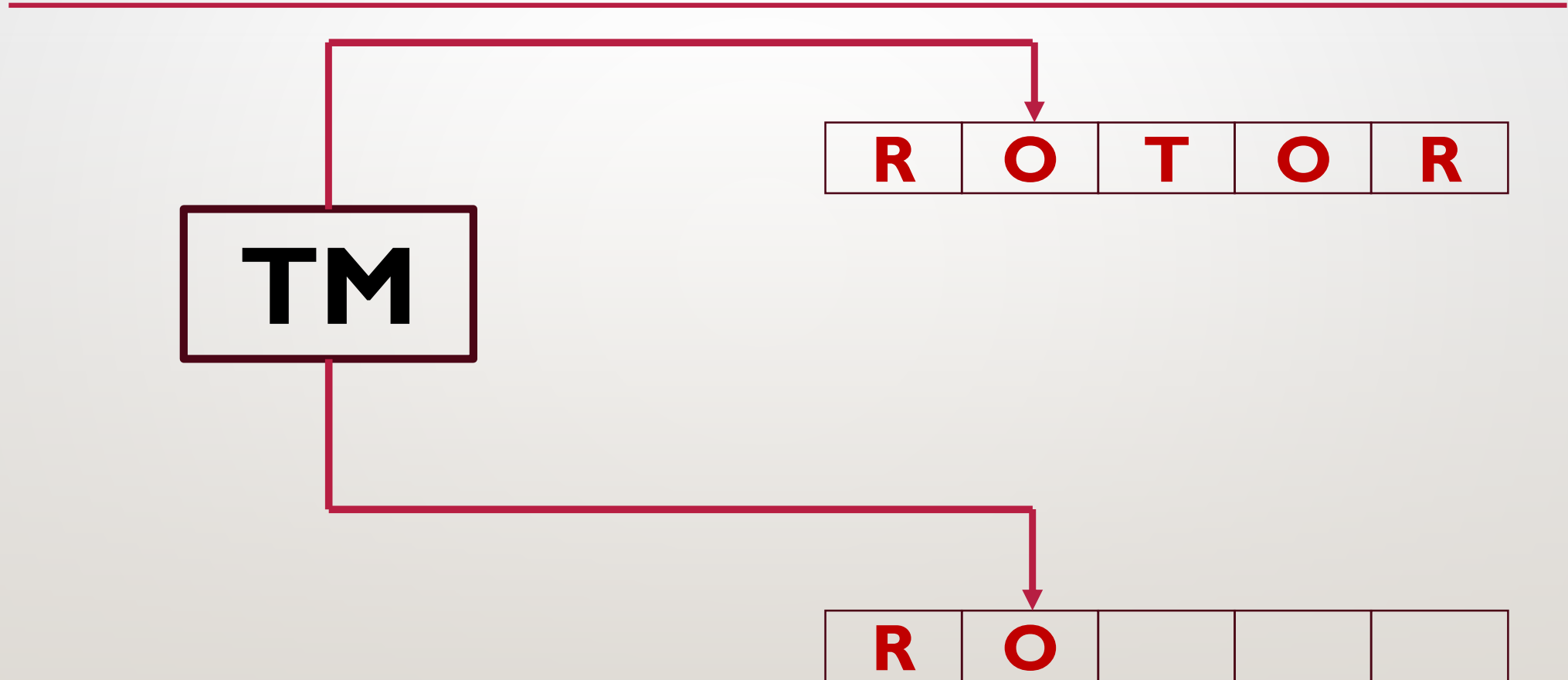
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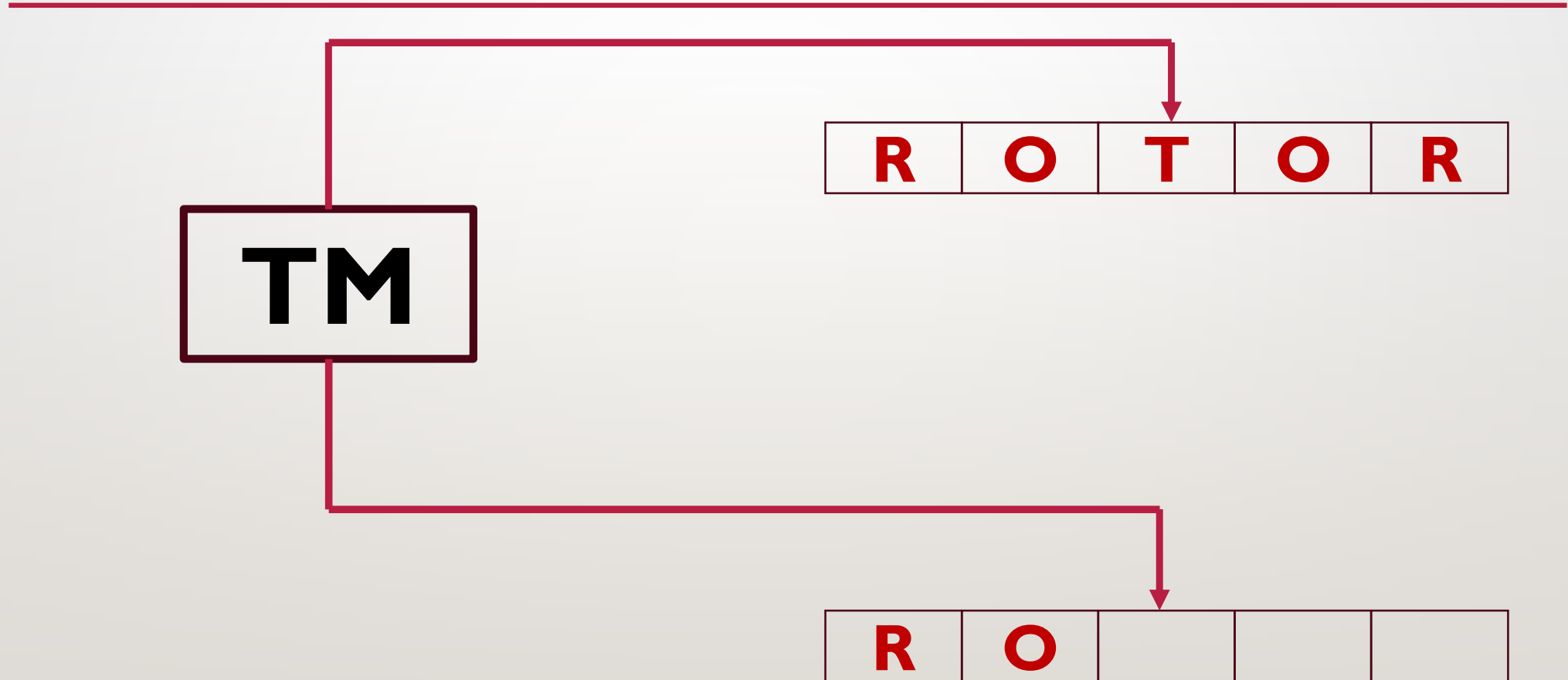
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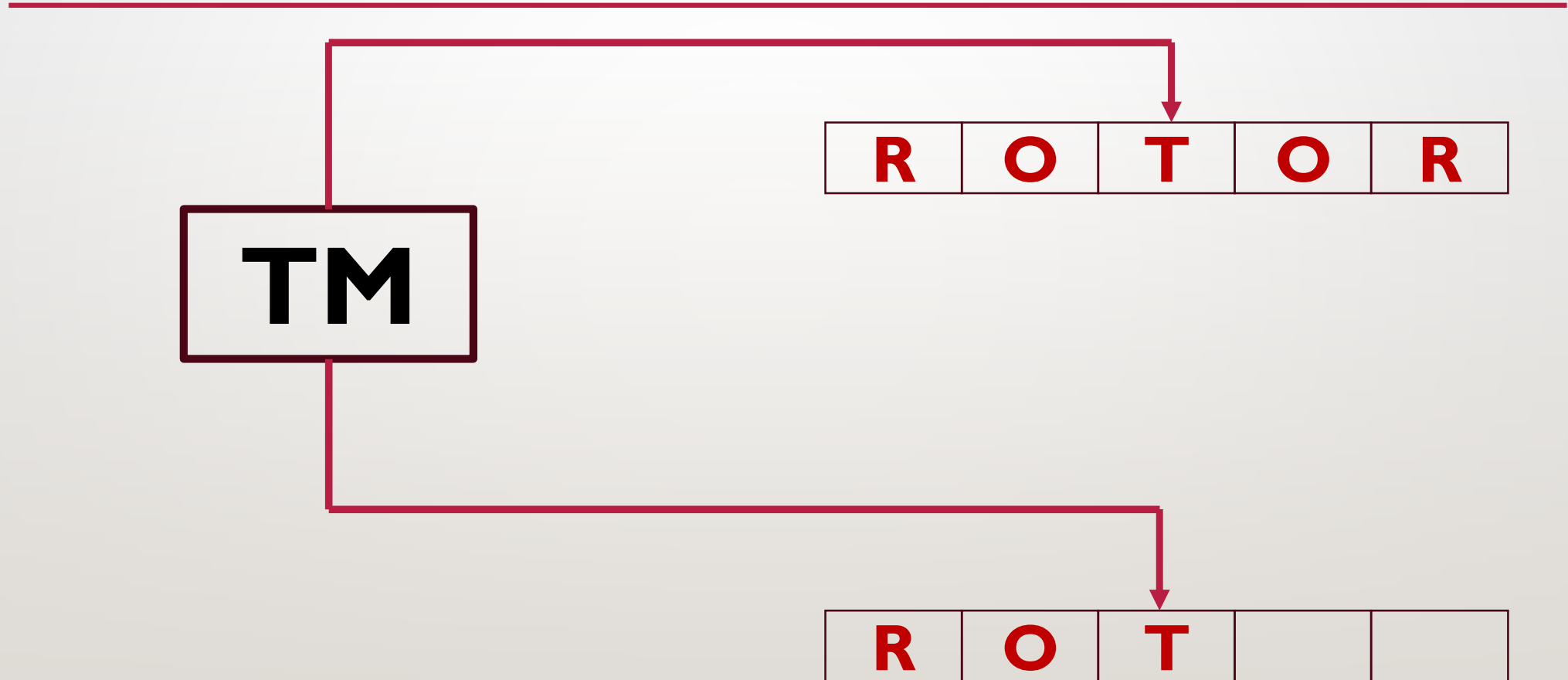
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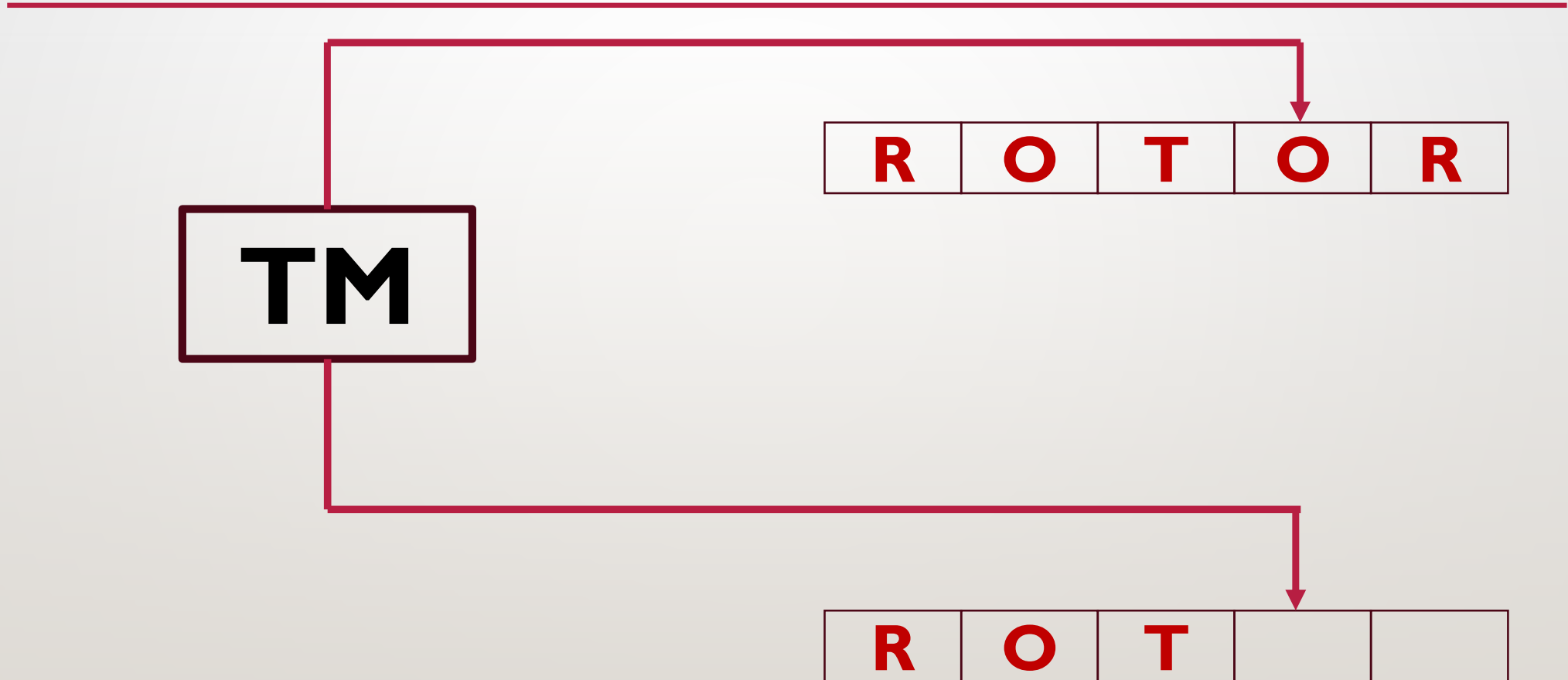
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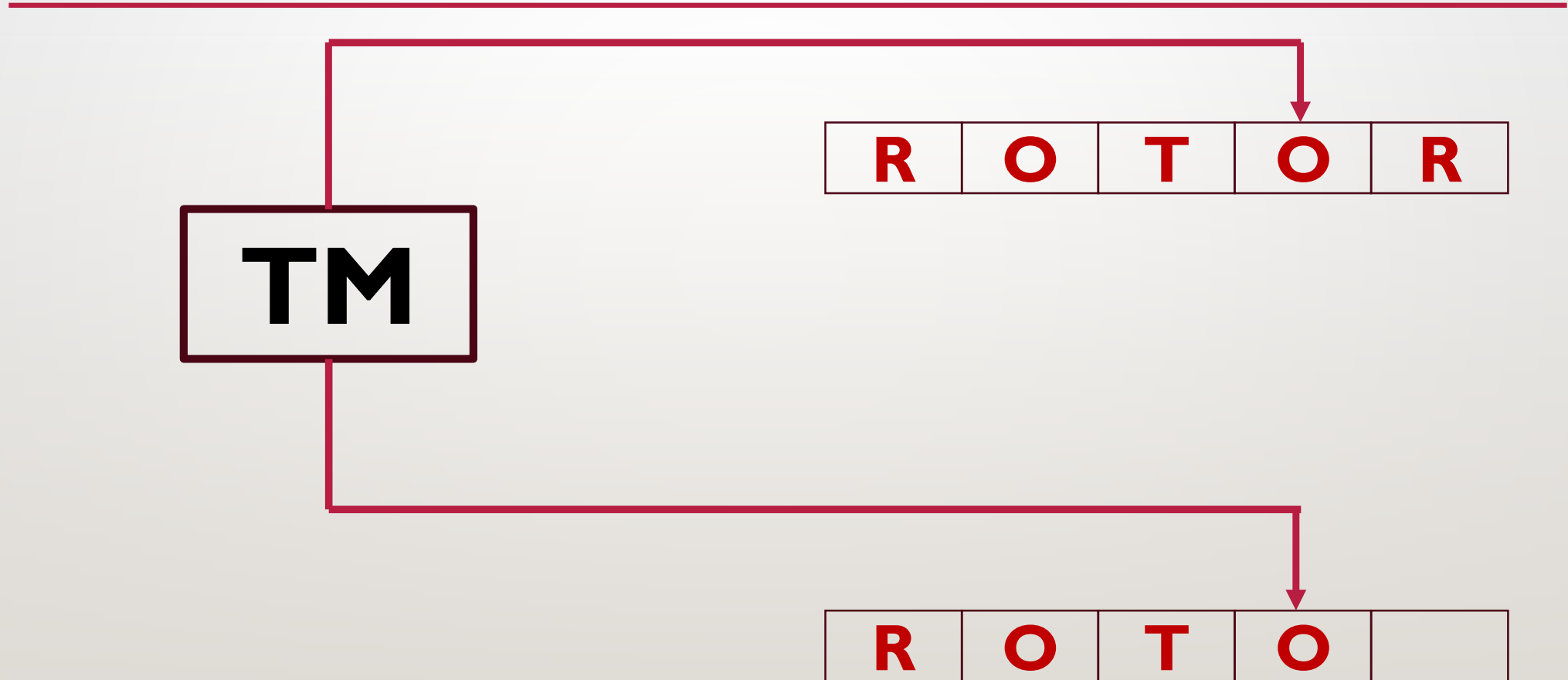
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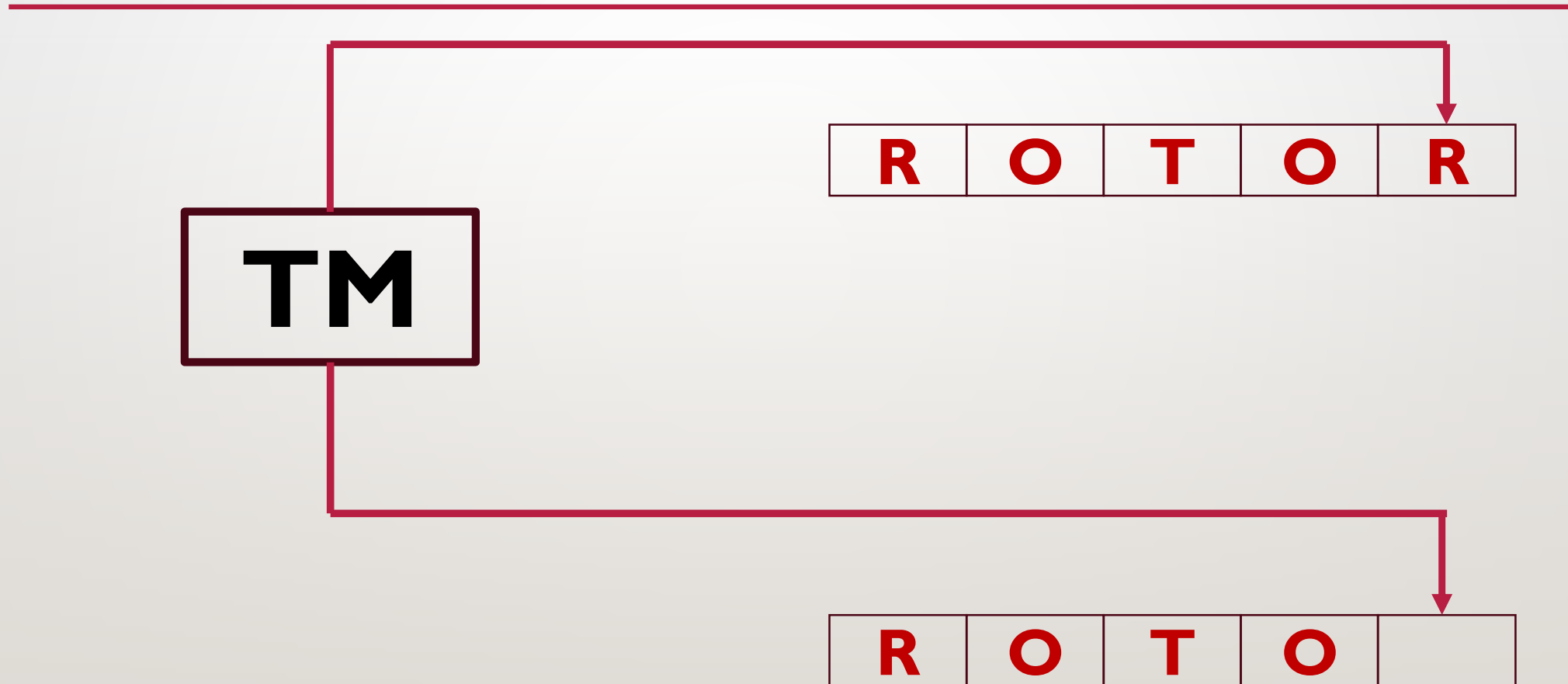
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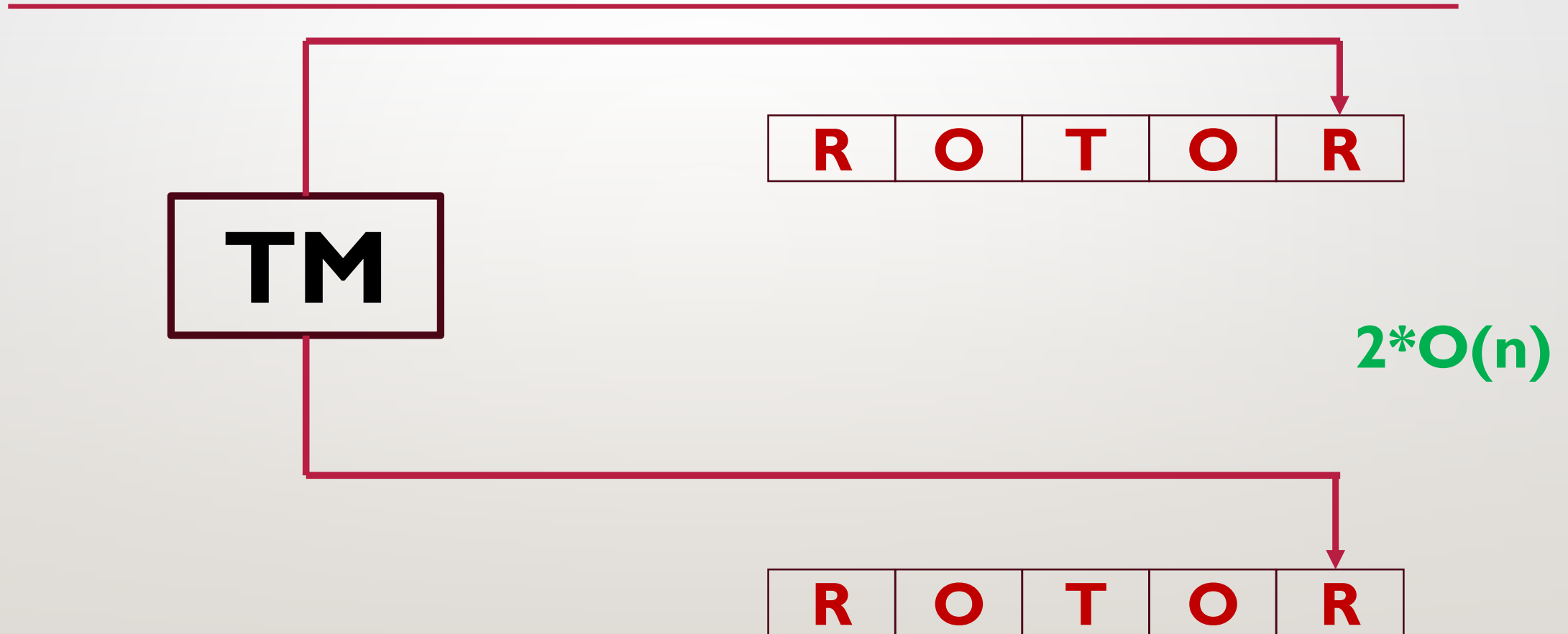
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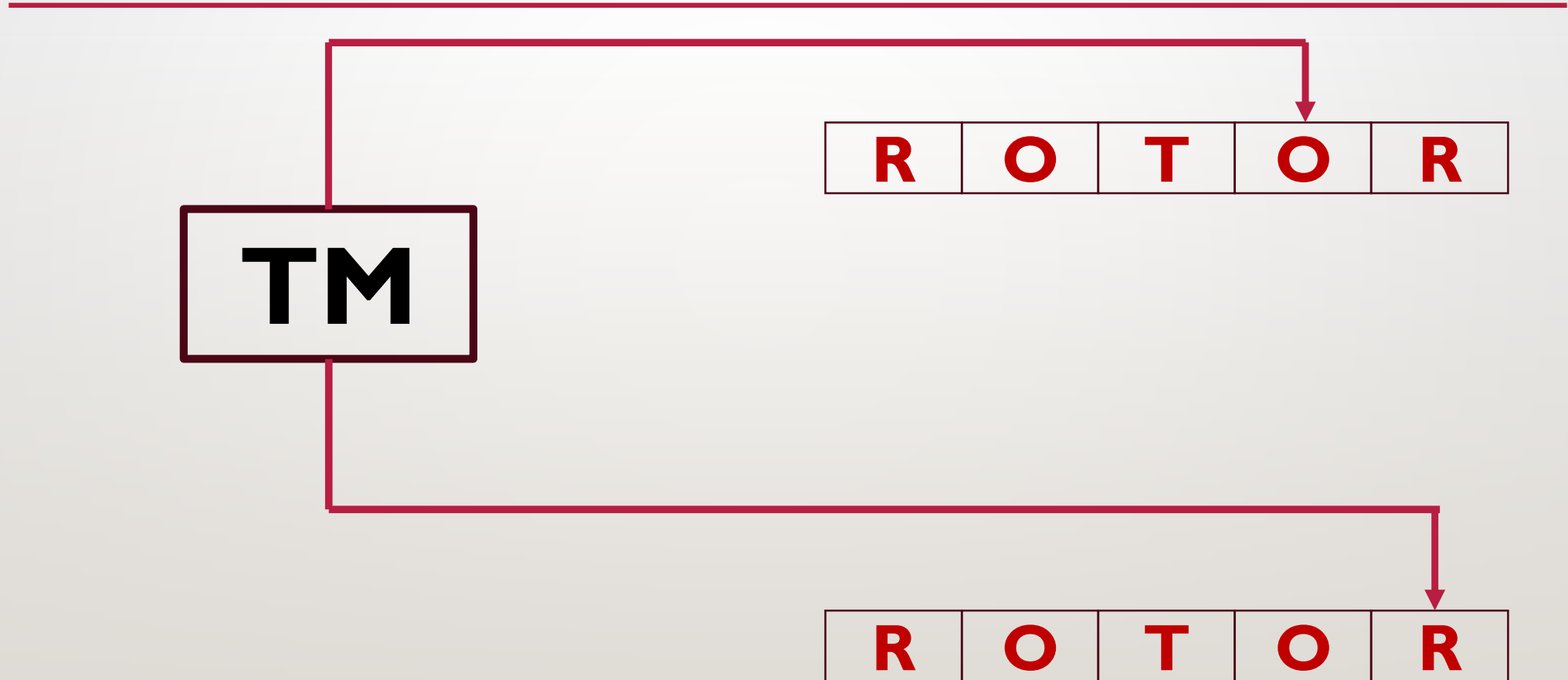
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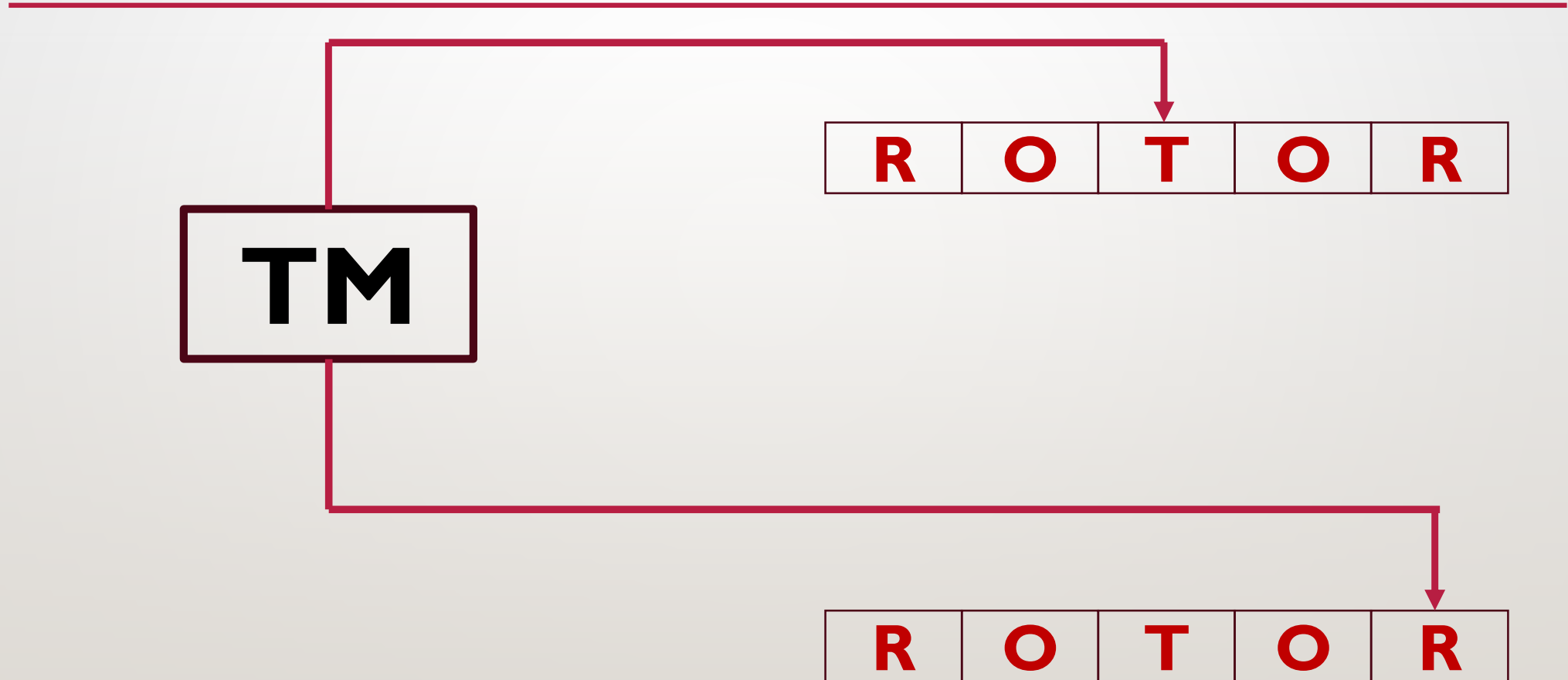
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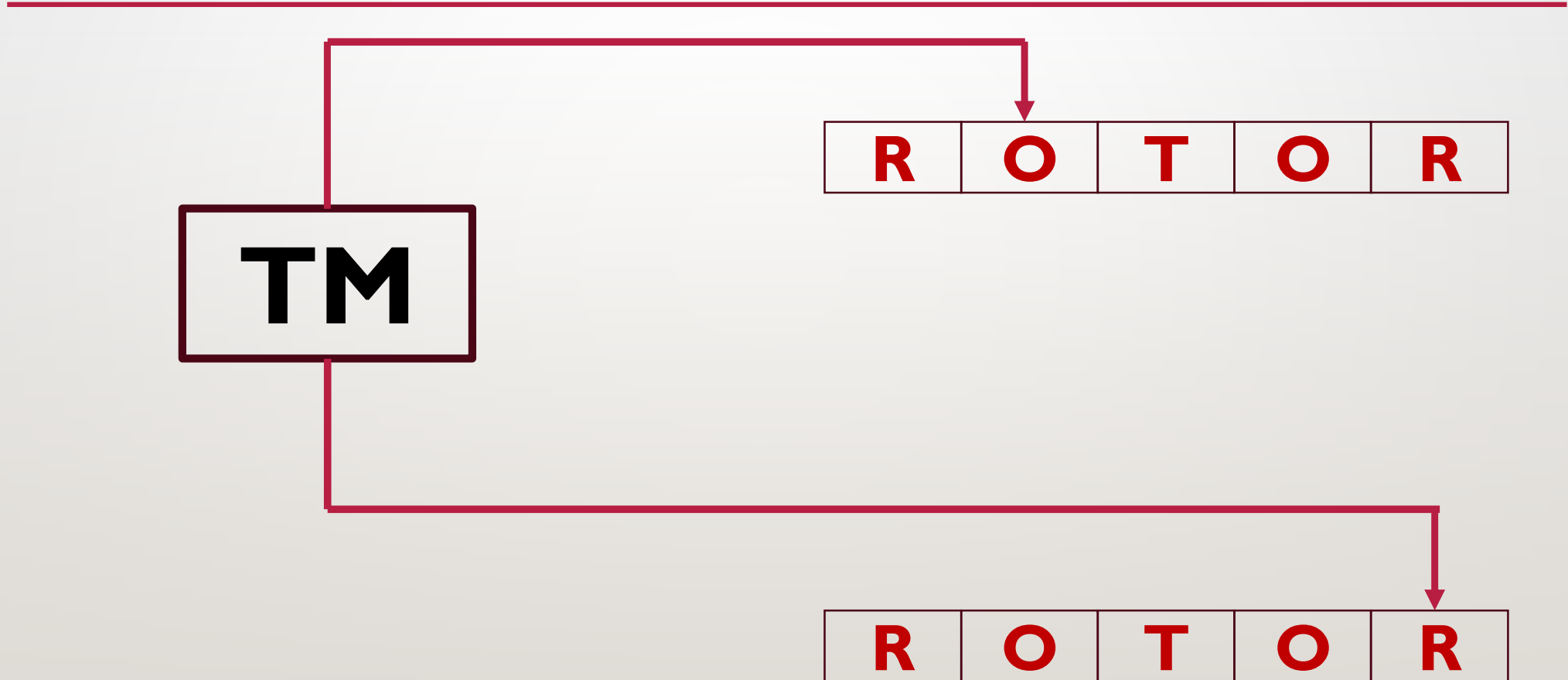
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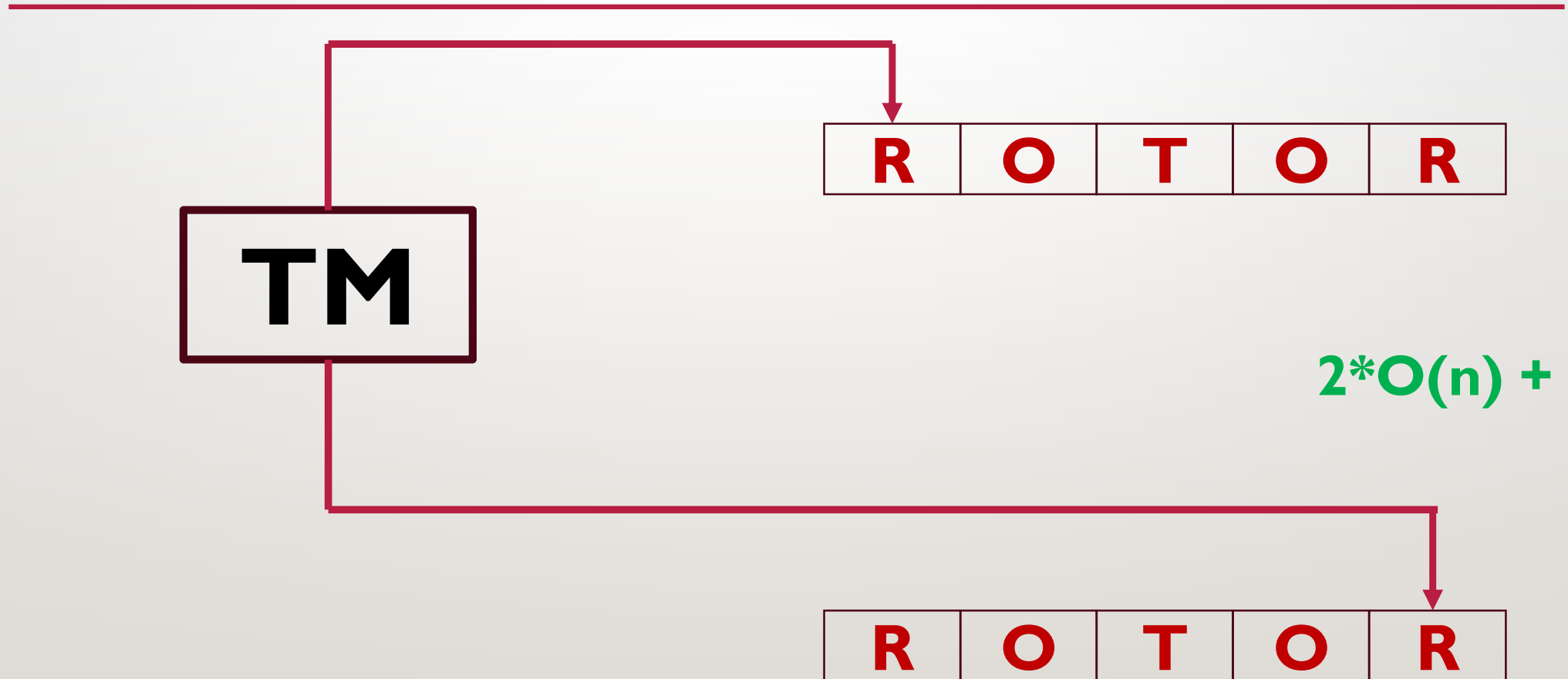
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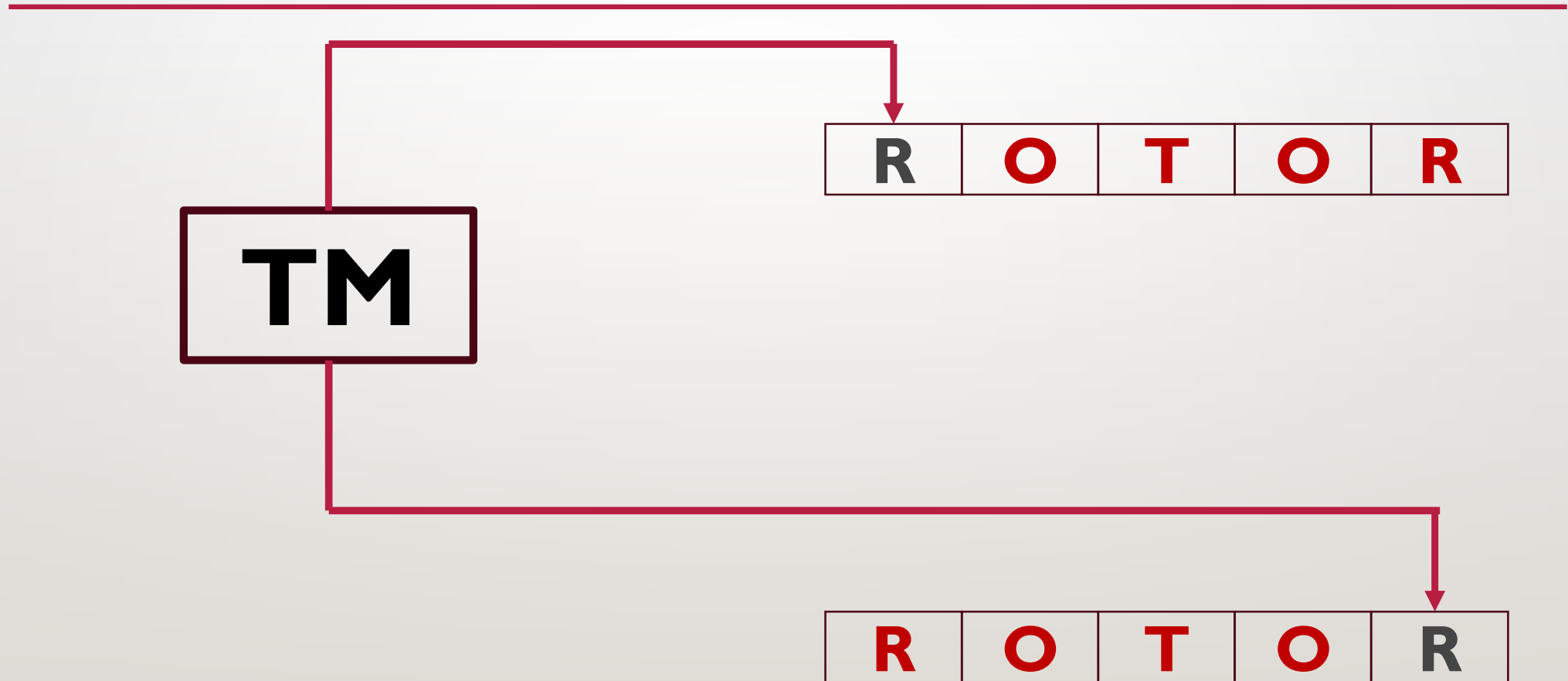
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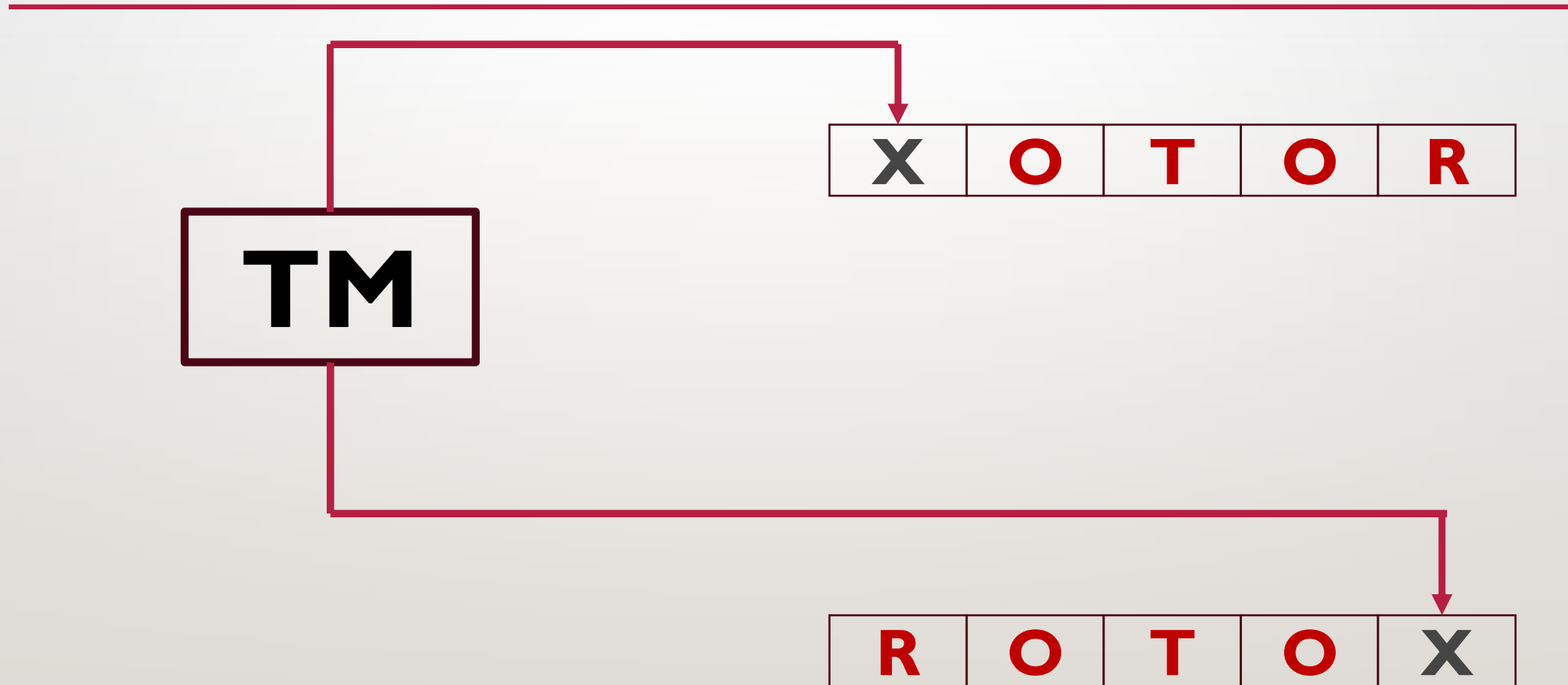
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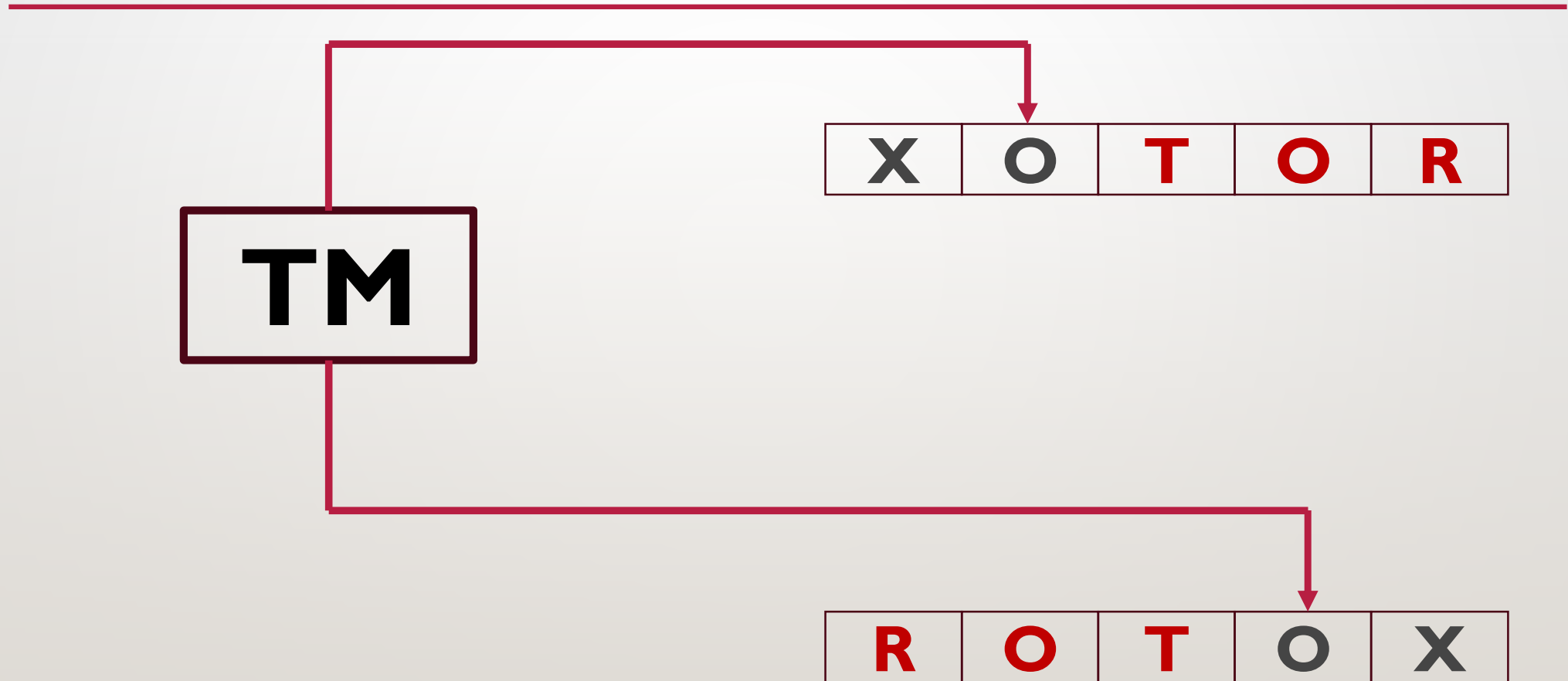
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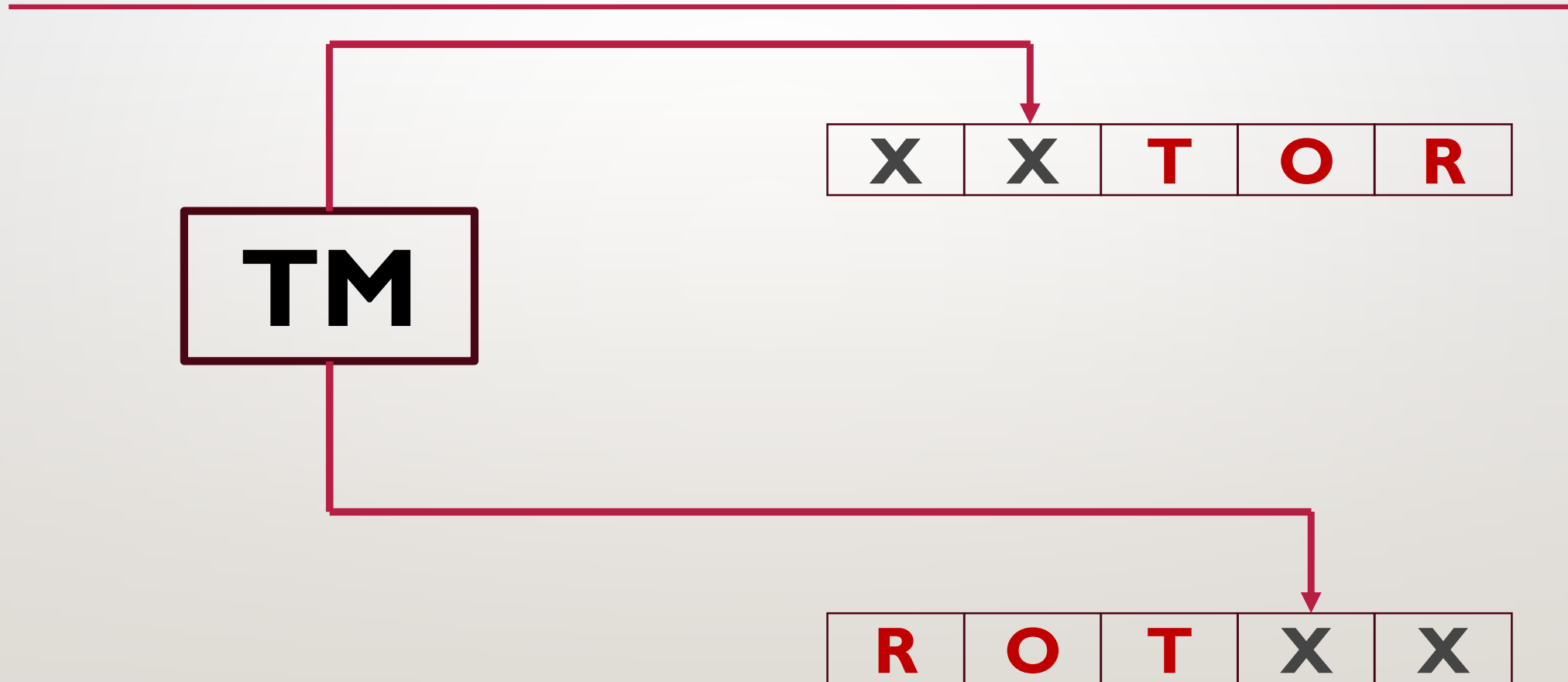
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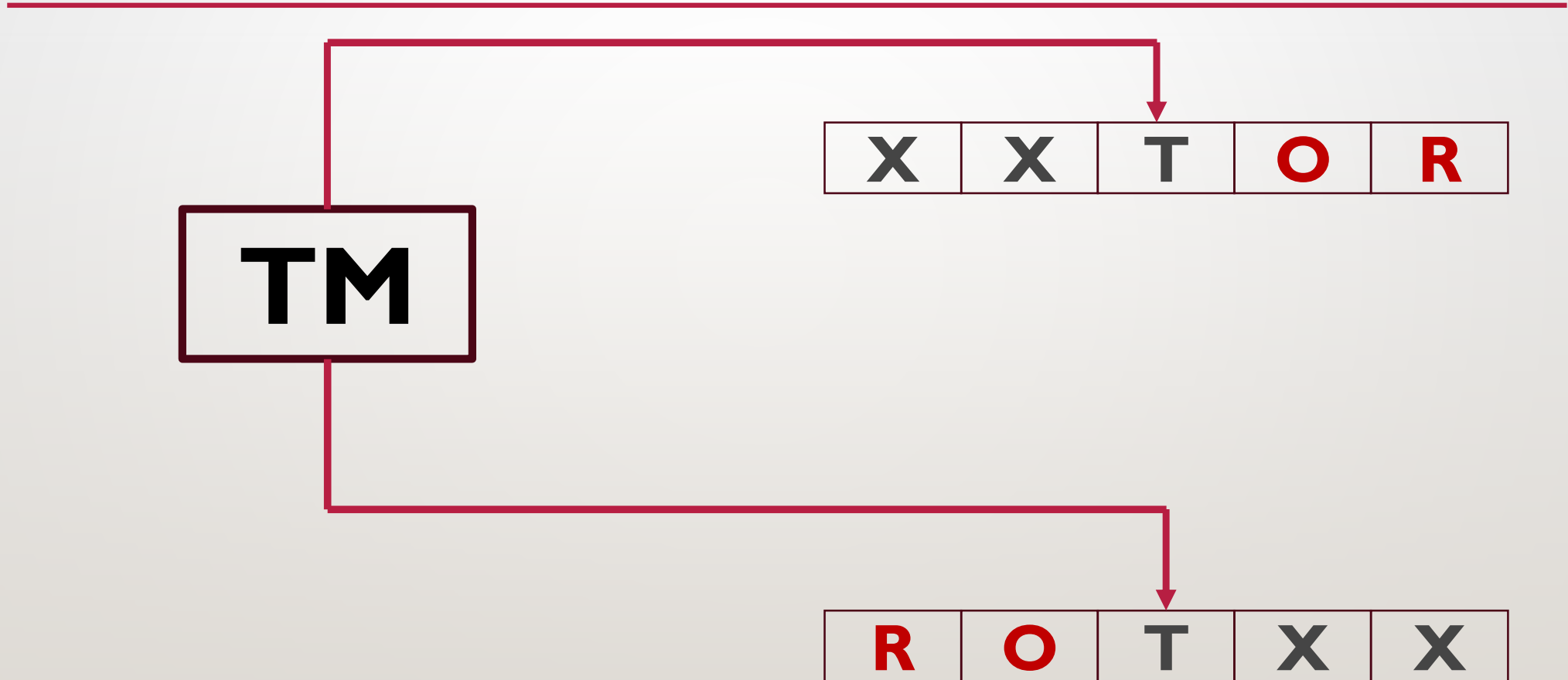
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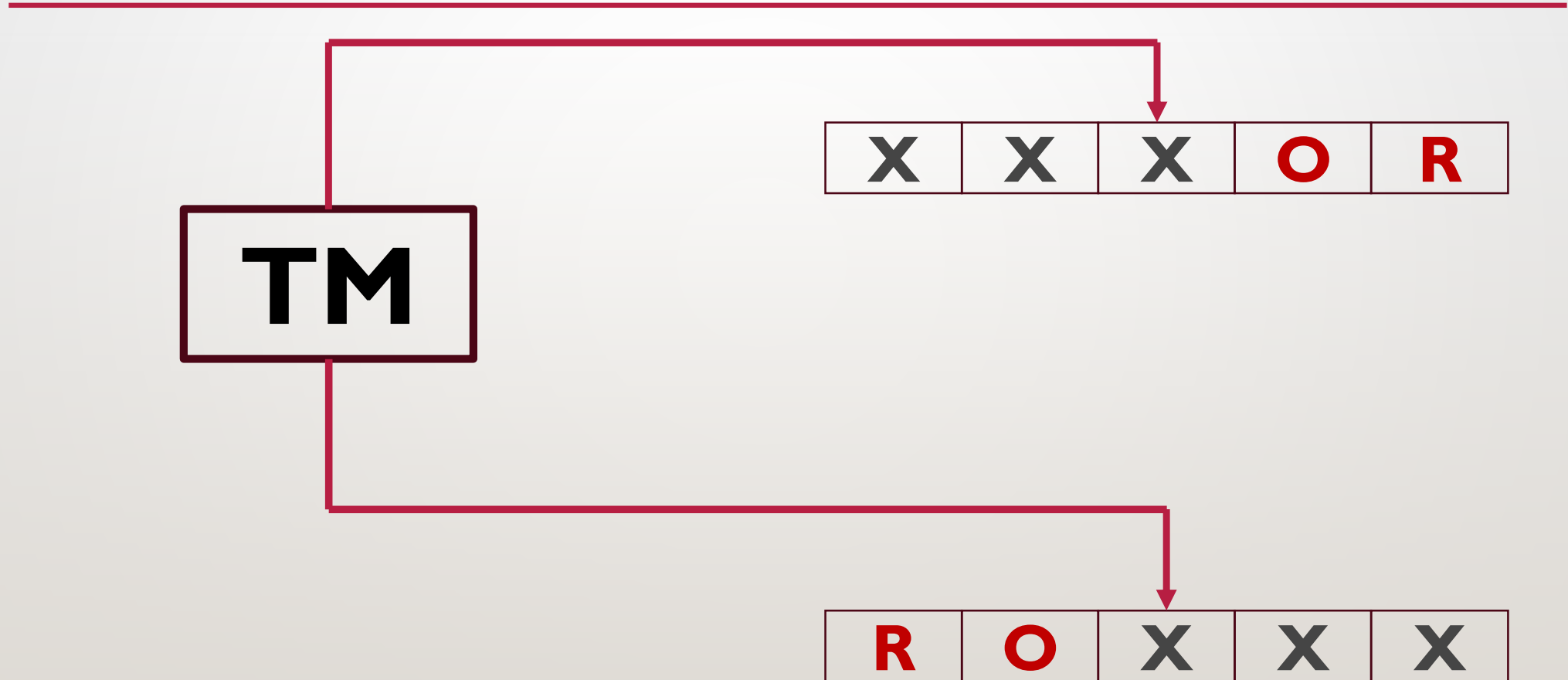
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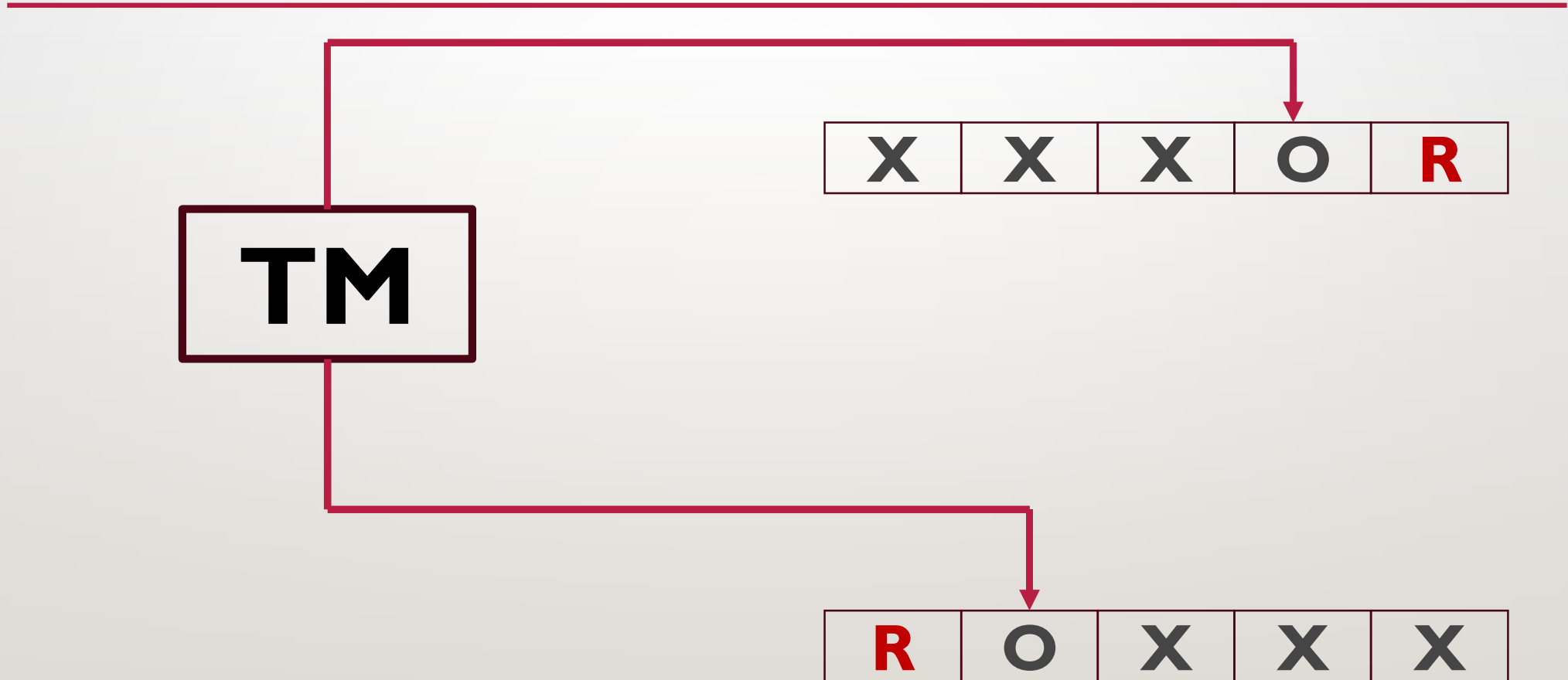
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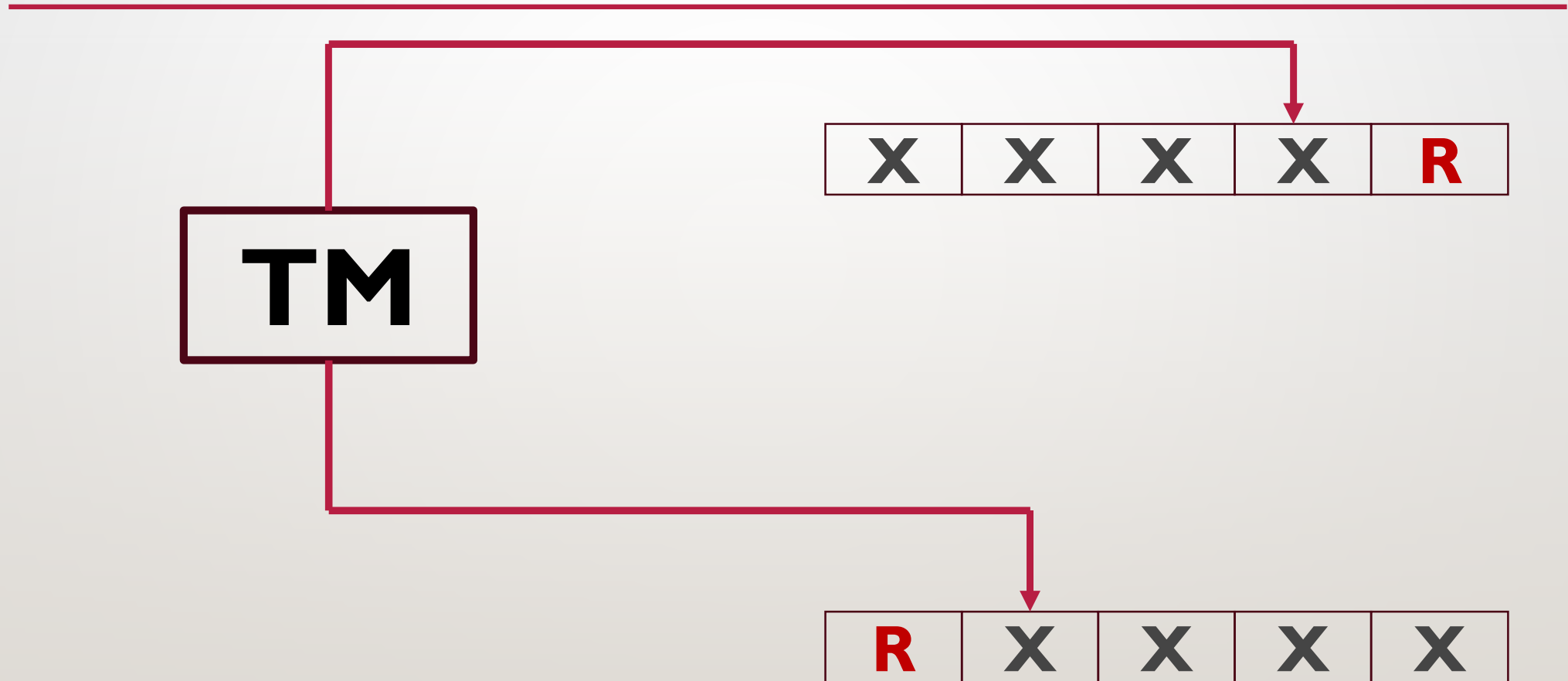
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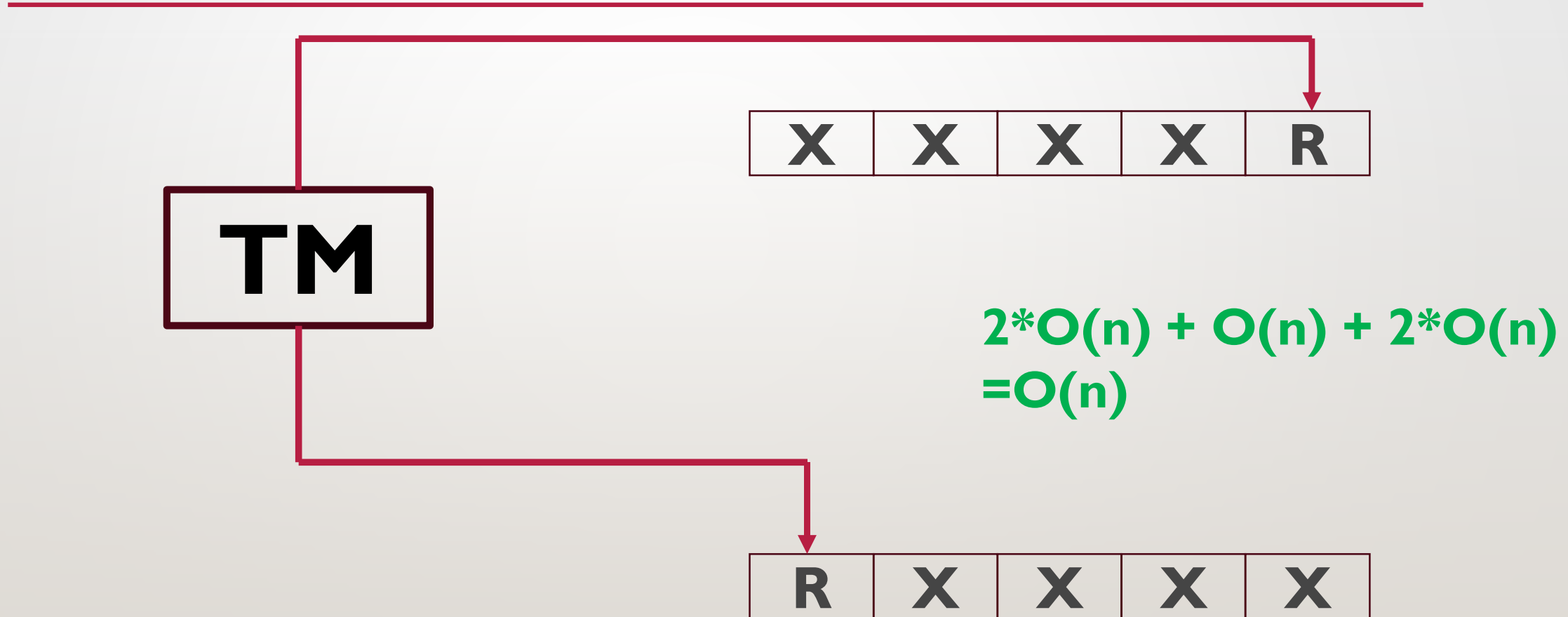
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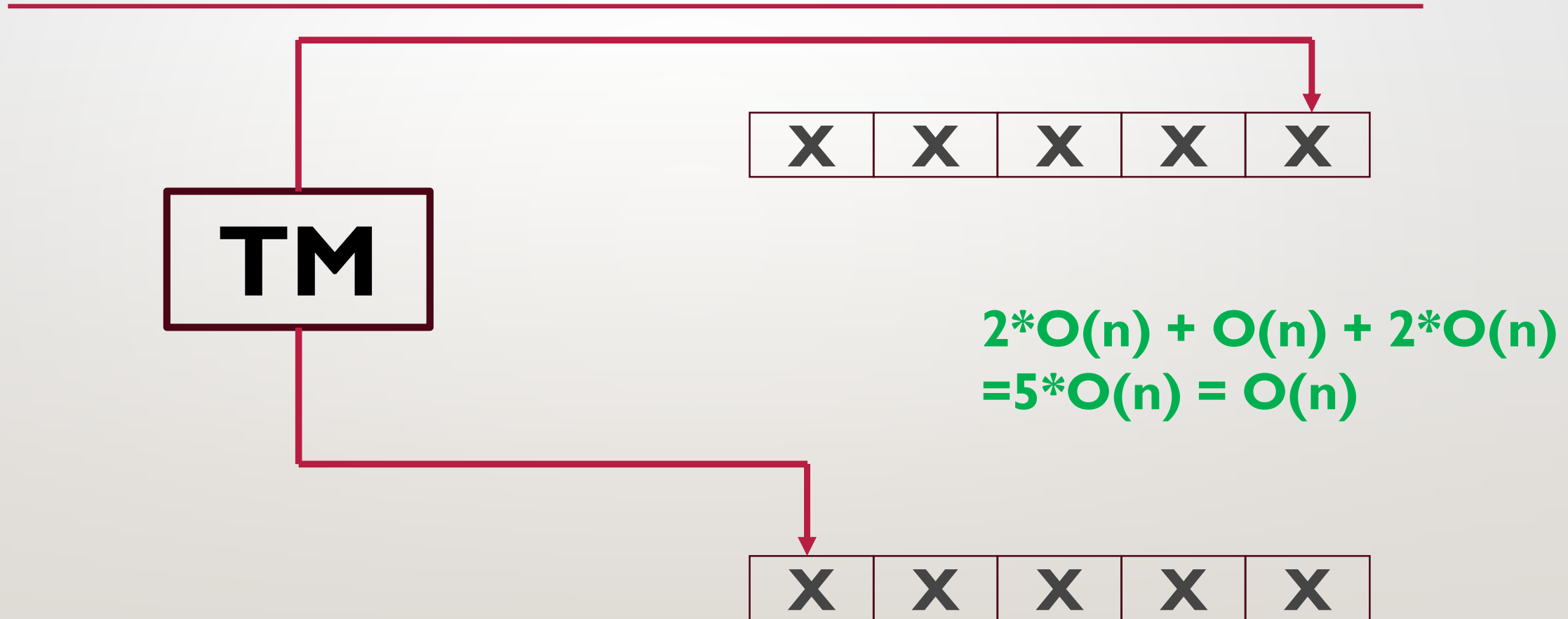
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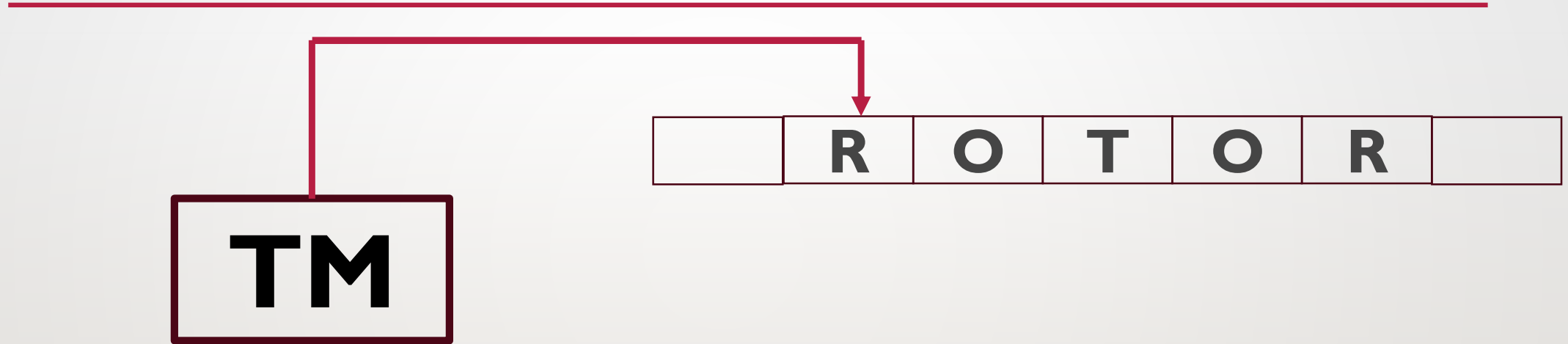
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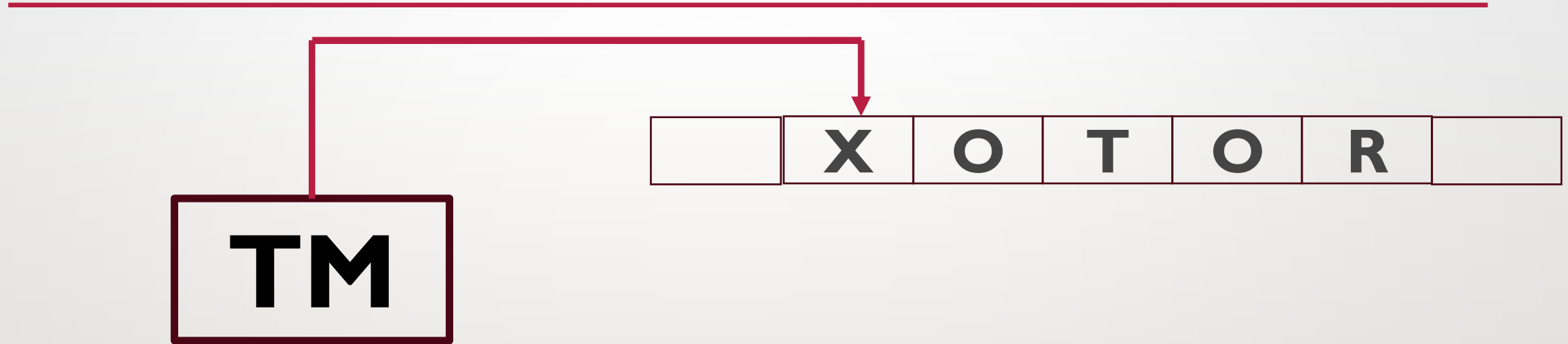
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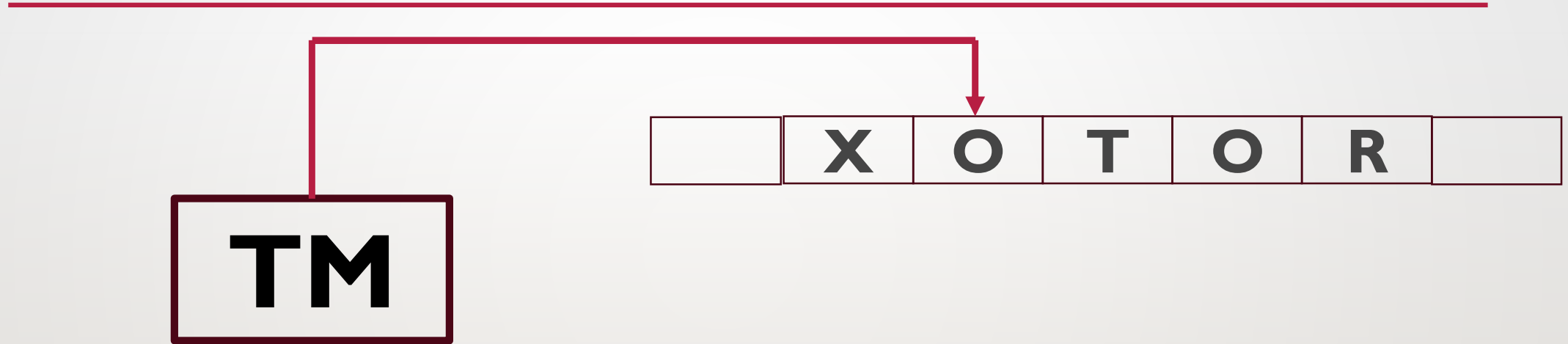
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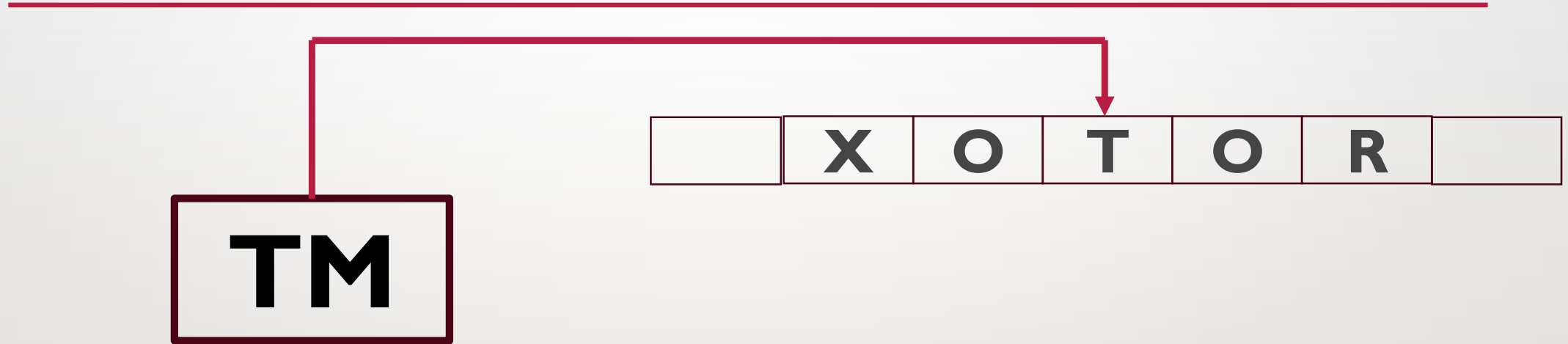
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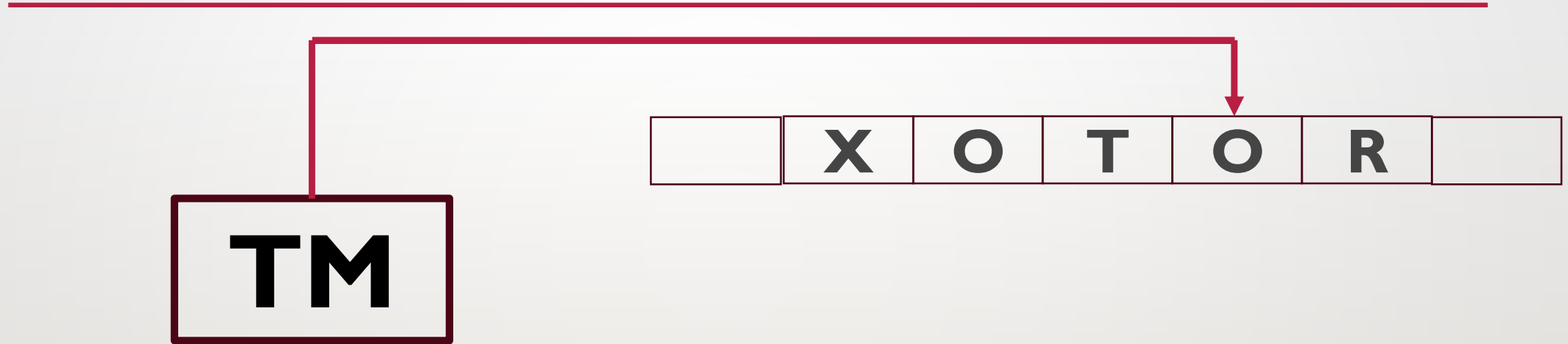
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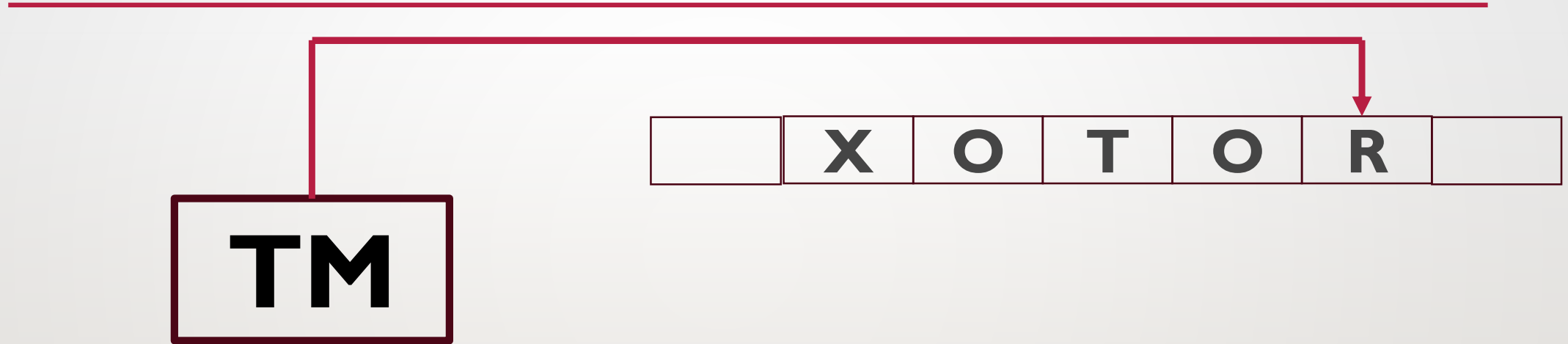
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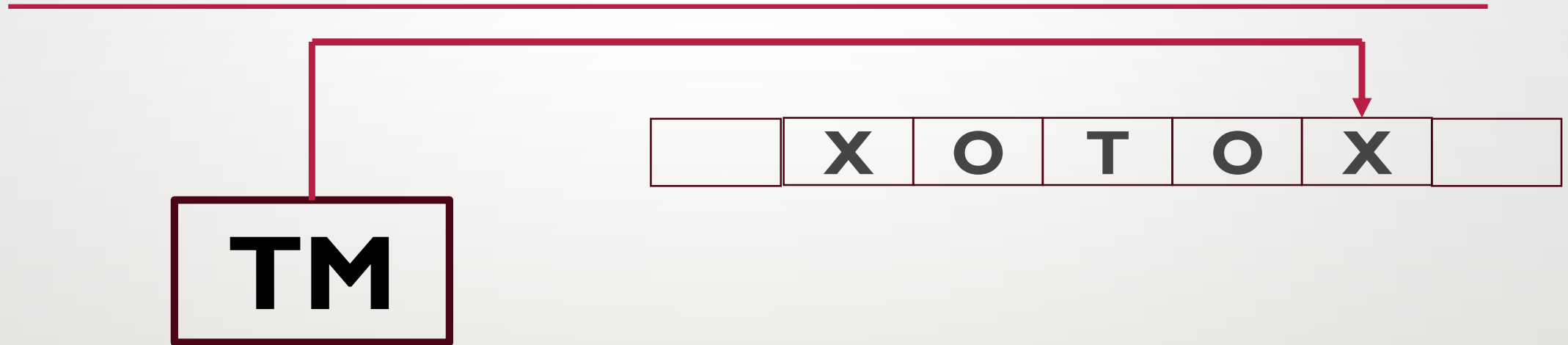
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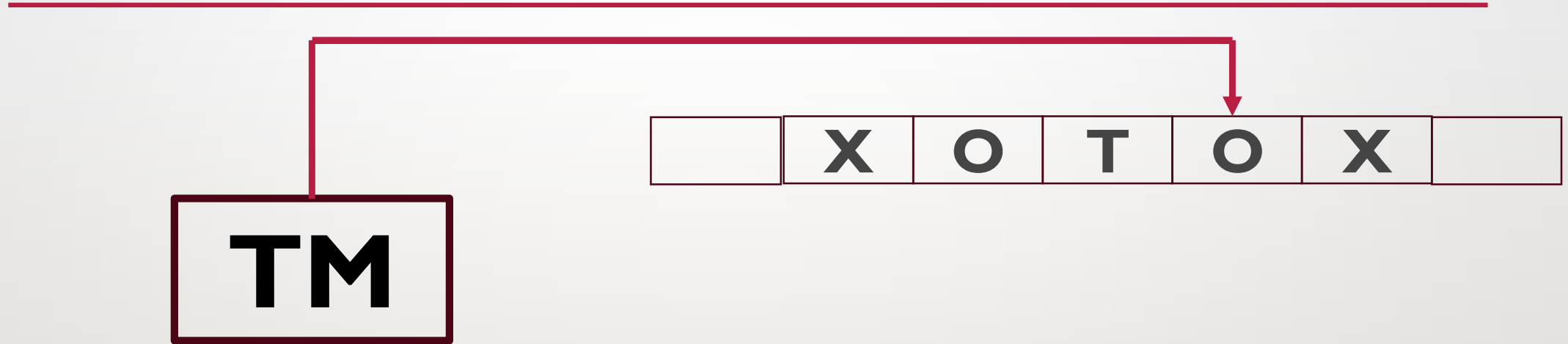
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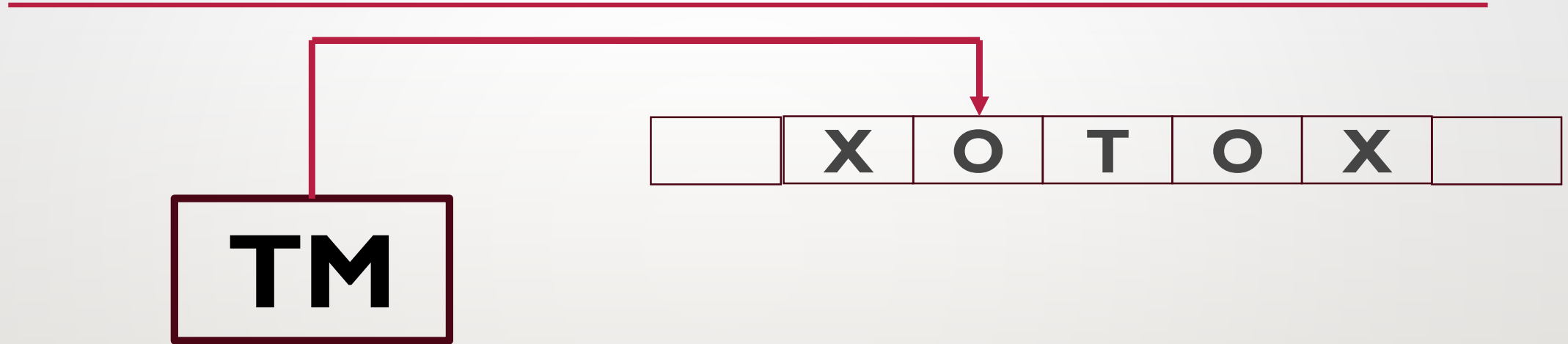
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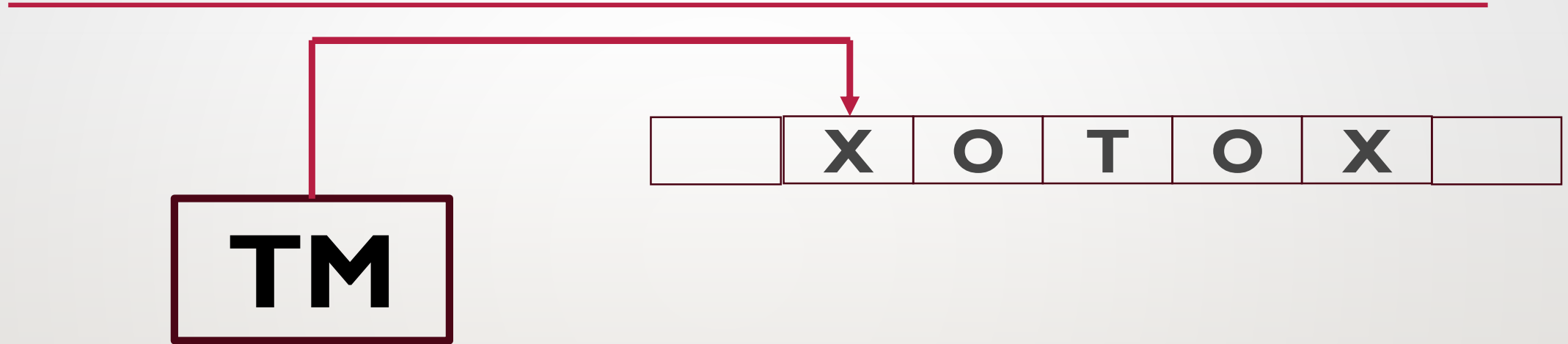
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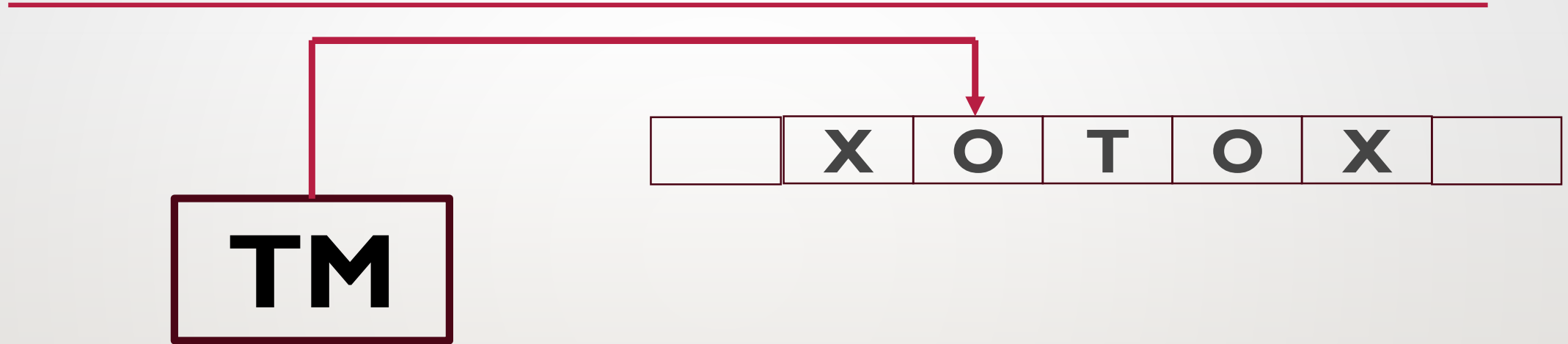
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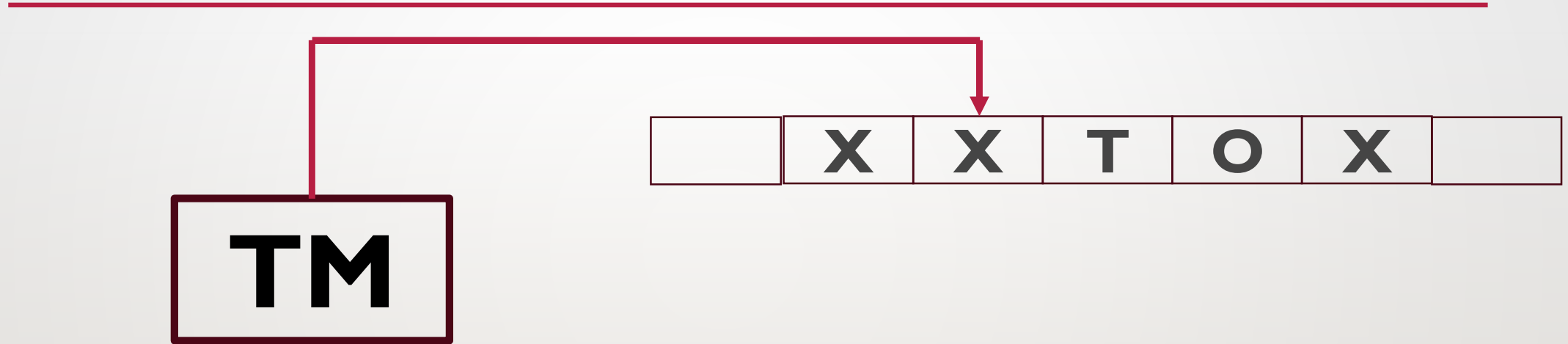
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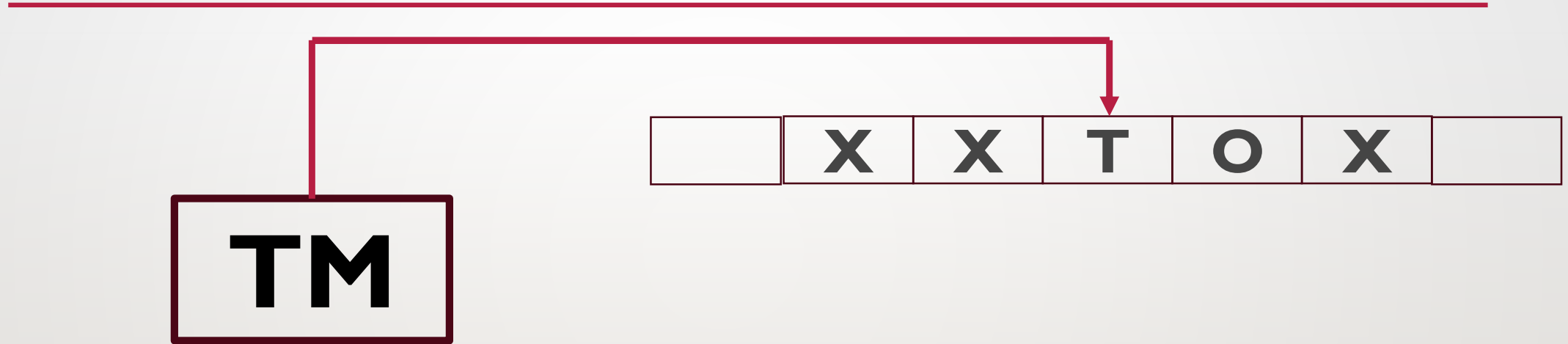
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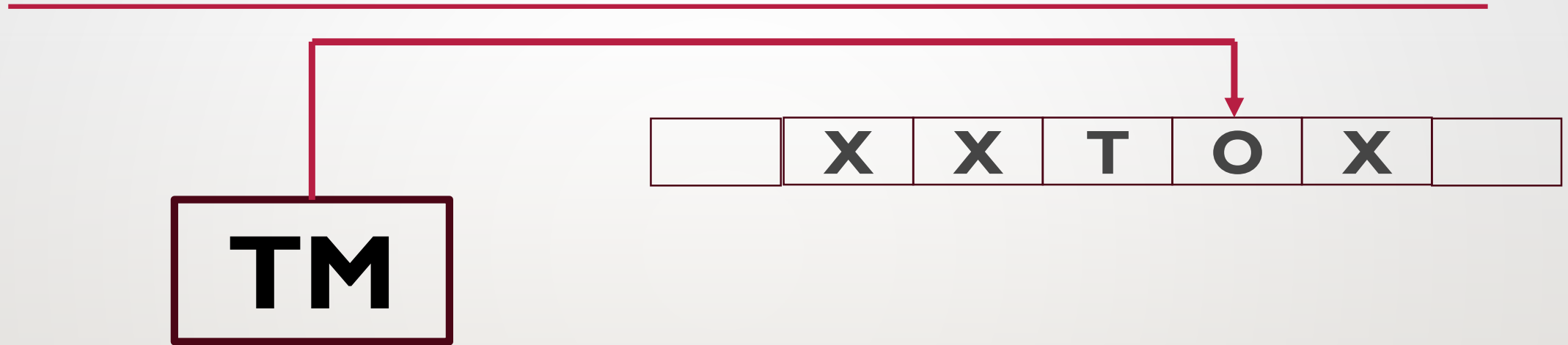
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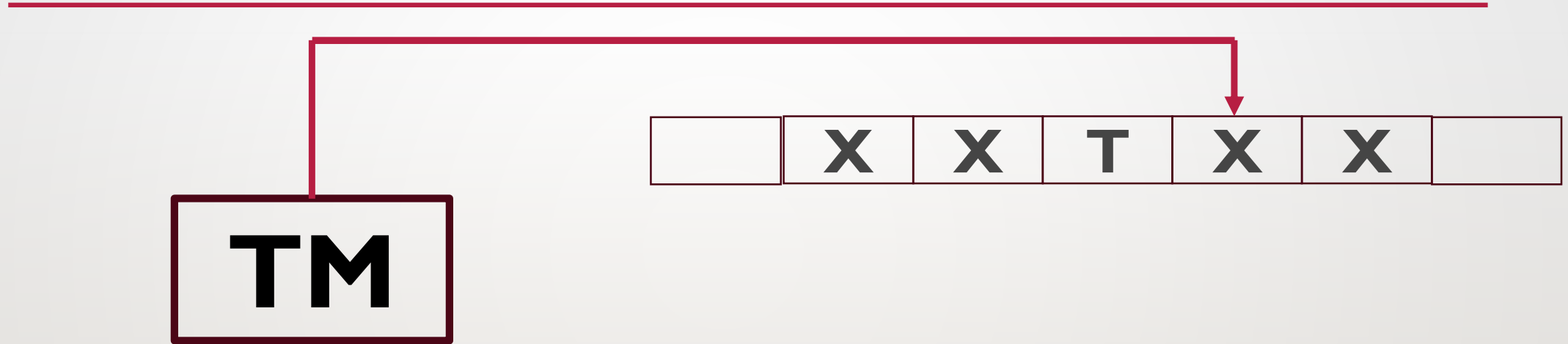
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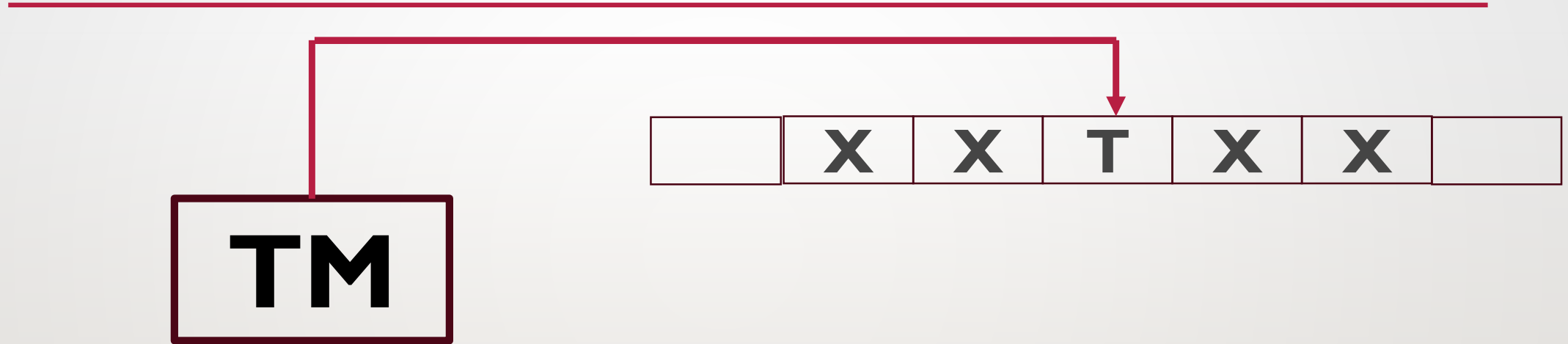
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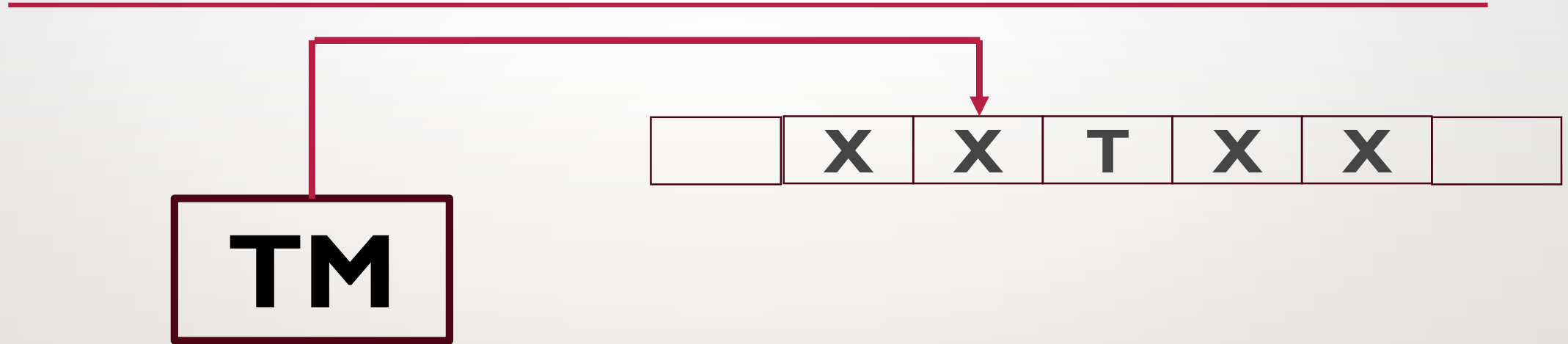
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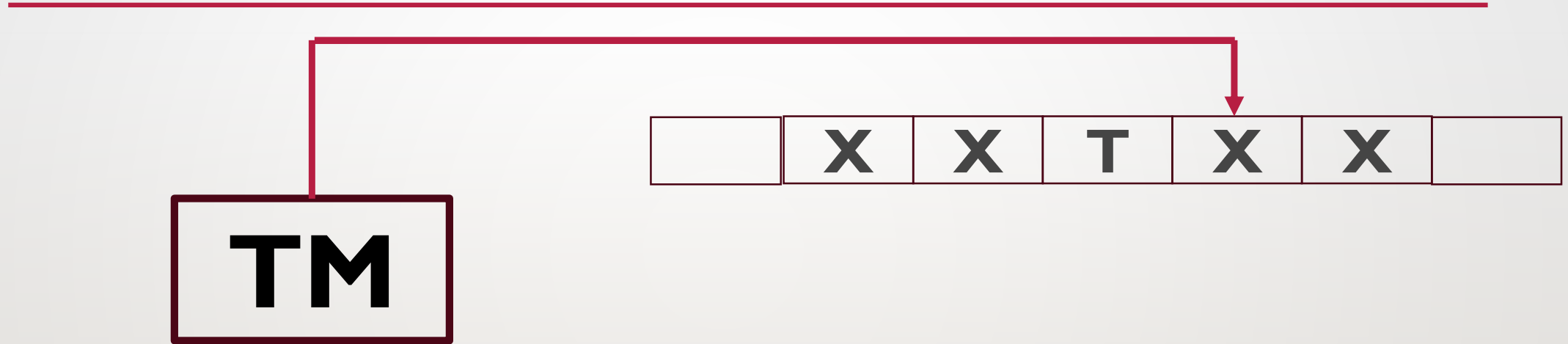
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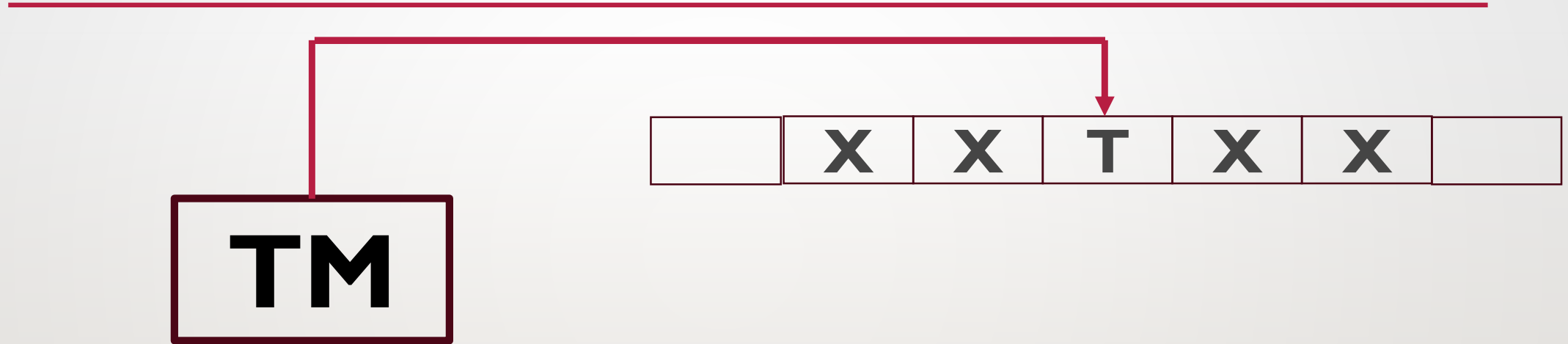
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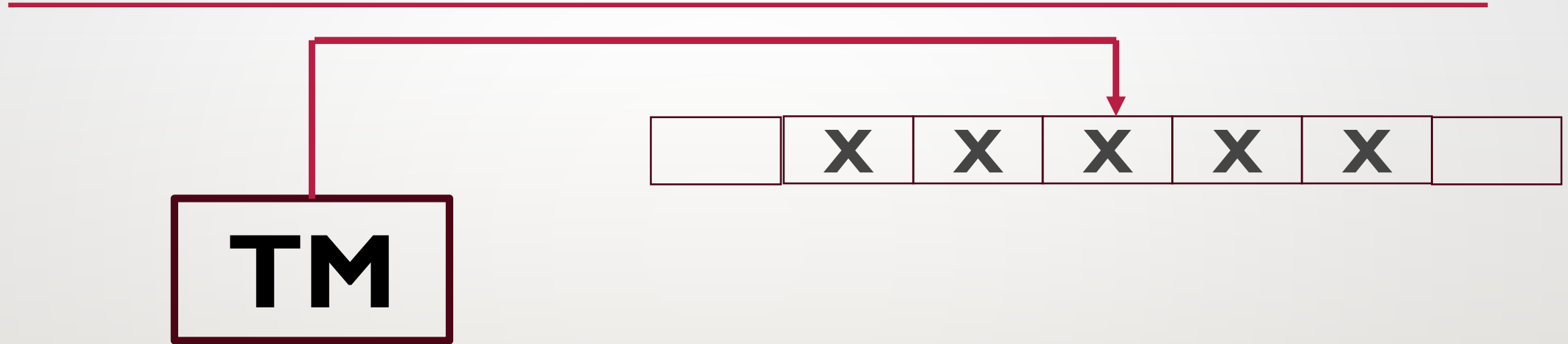
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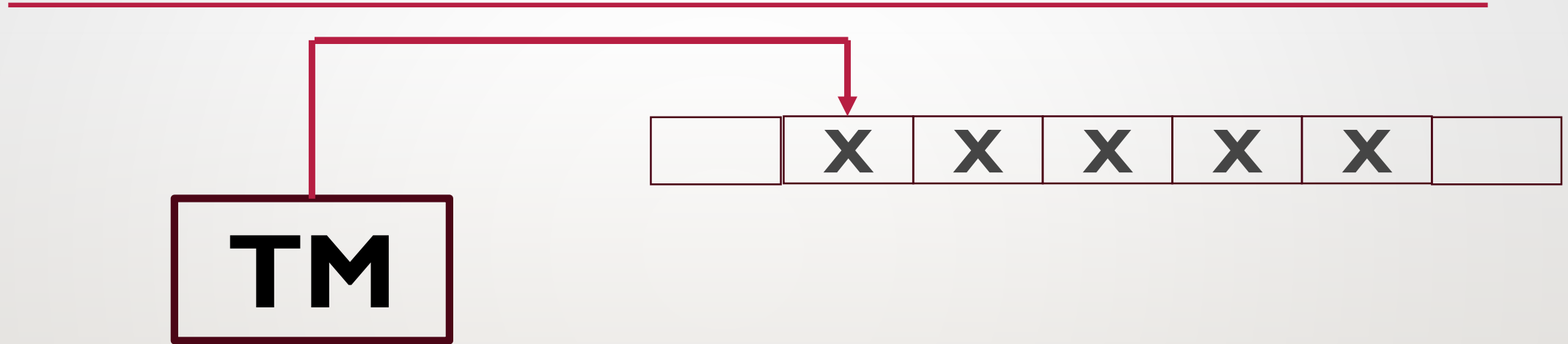
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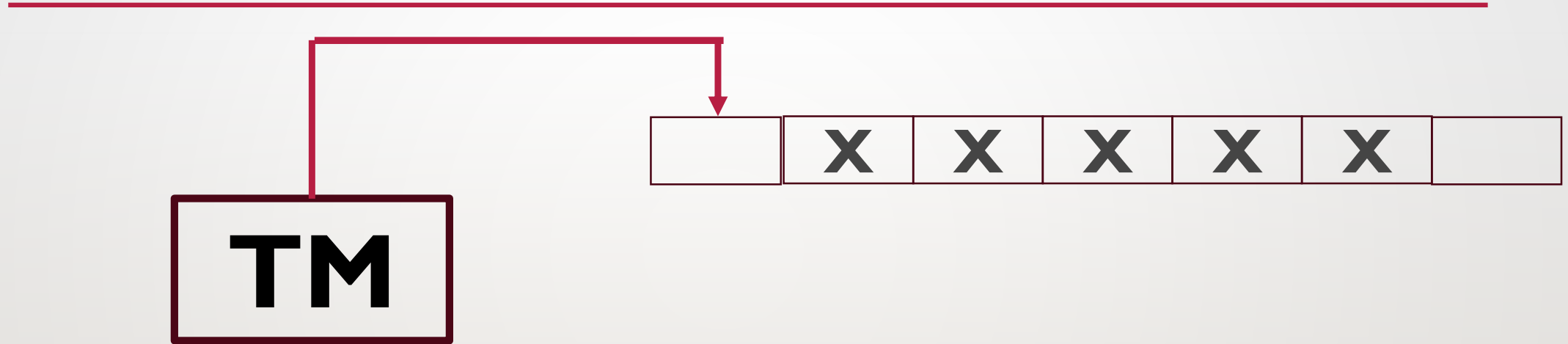
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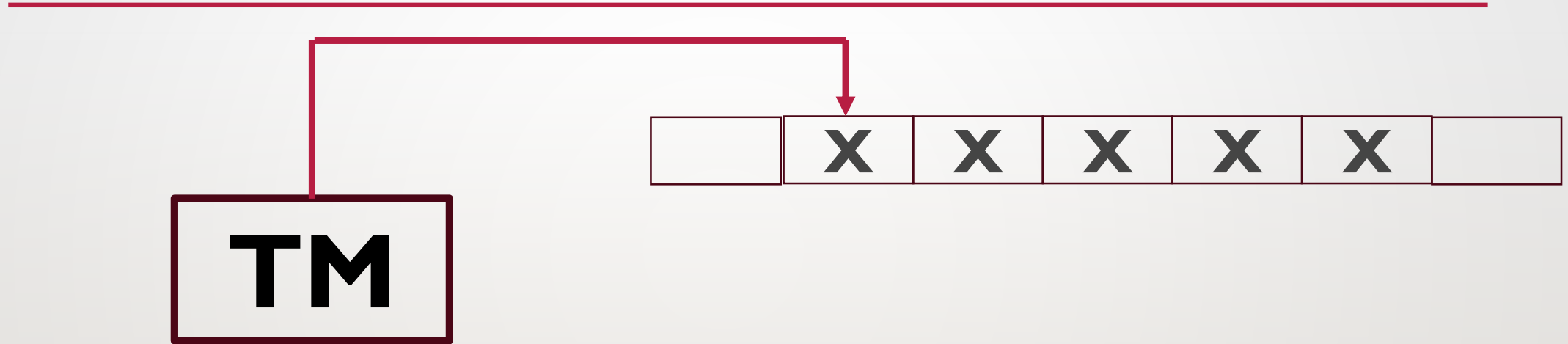
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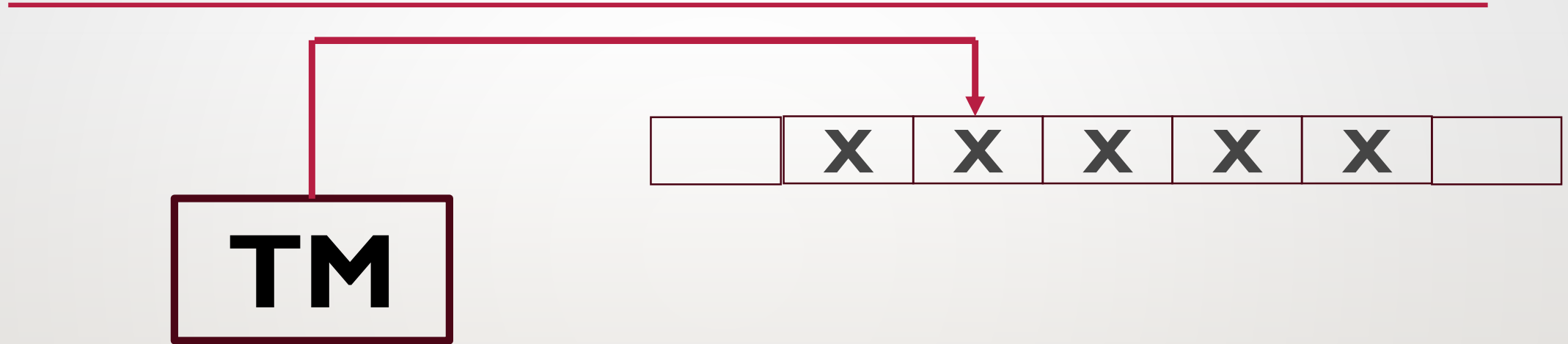
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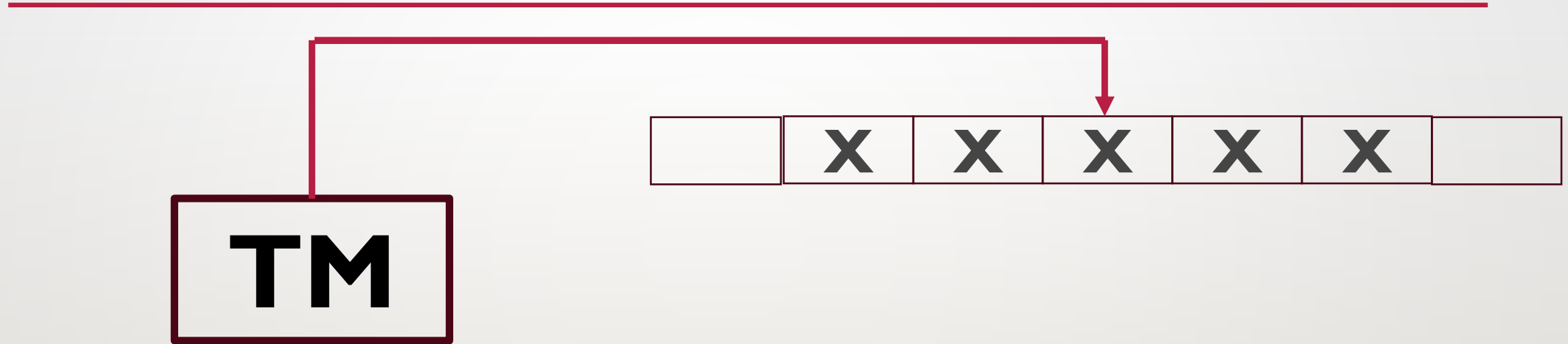
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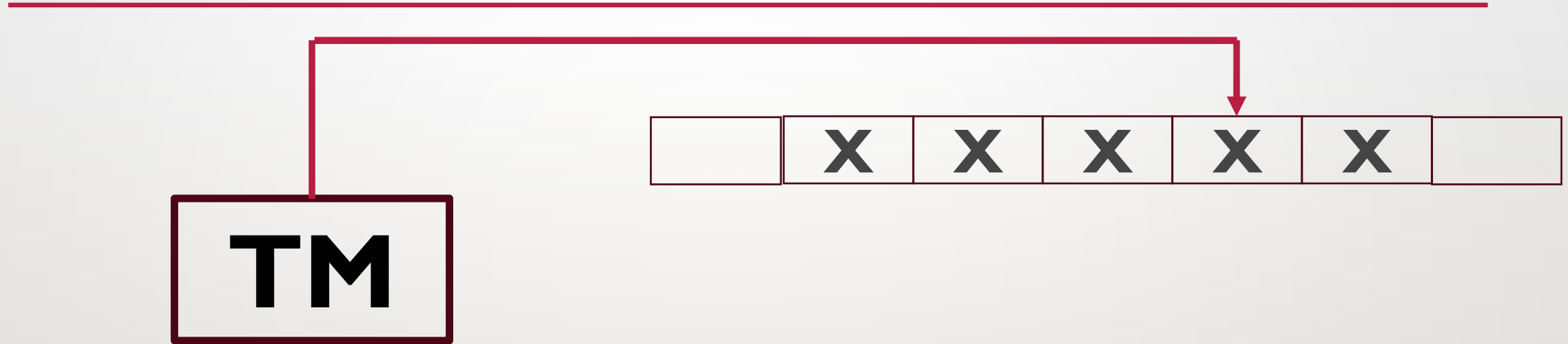
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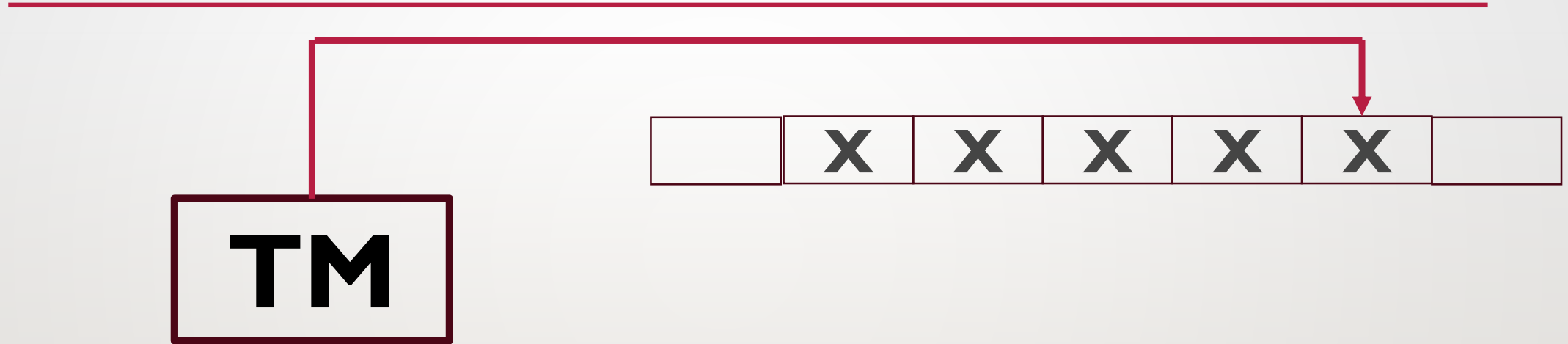
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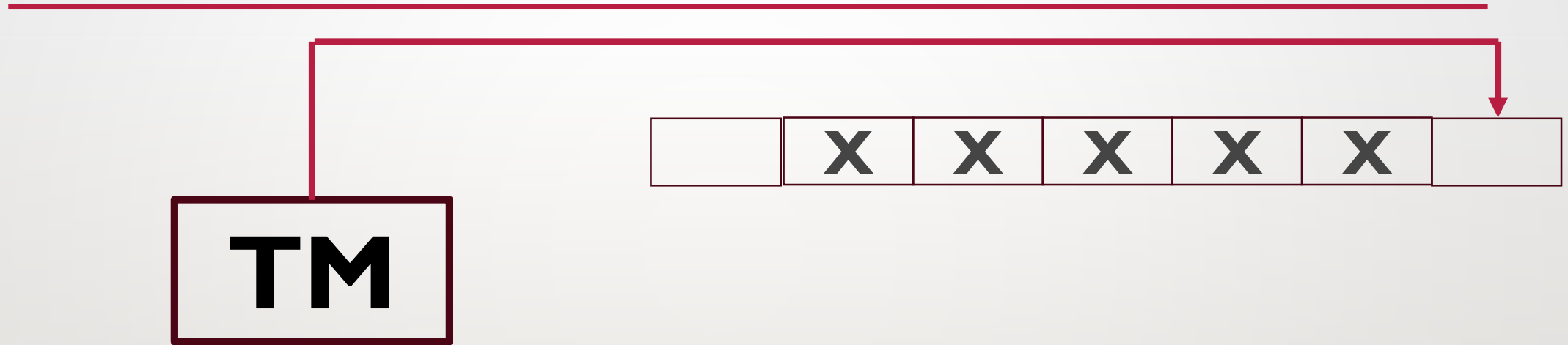
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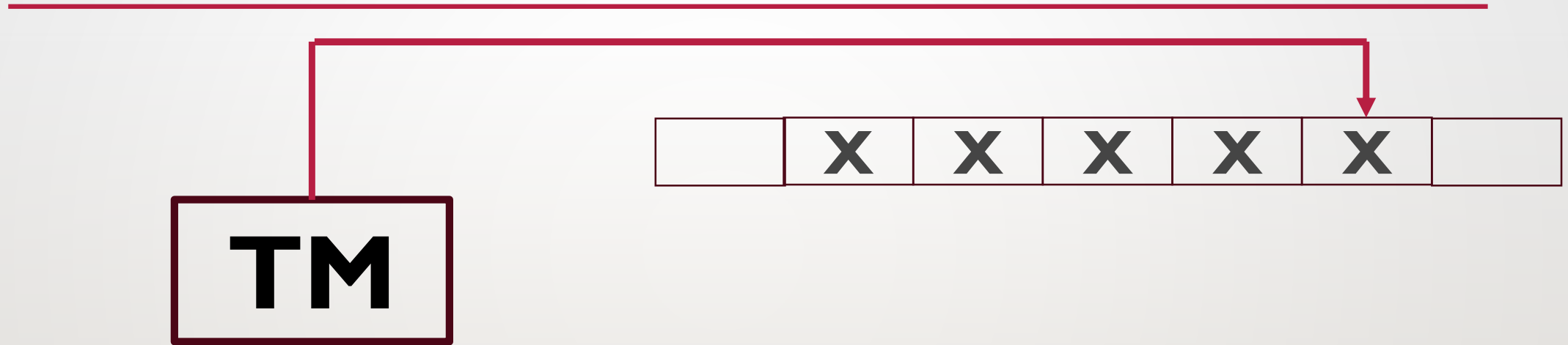
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$O(n^2)$

CLASS OF LANGUAGES

- Let $t: \mathbb{N} \rightarrow \mathbb{R}^+$ be a function. Define the *time complexity class*, $TIME(t(n))$, to be the collection of all languages that are decided by an $O(t(n))$ time Turing Machine.

CHALLENGES FACED

- Classifying problems by time complexity is challenging when grouping those requiring quadratic (n^2) or cubic (n^3) time into one set.
- This challenge stems from the dependency of classification on the underlying execution architecture.
- A classification system is needed to accommodate such problems within a polynomial time complexity class, regardless of execution architecture.

-
- P is the class of languages **decidable in polynomial time** on a deterministic single-tape Turing Machine

$$P = \bigcup_{k=1}^{\infty} TIME(n^k)$$

P is class of problems realistically solvable on a computer.

Properties

- **Robust** i.e. independent of exact model of computation.
- **Efficient** i.e. It constitutes all efficient algorithms

-
- ***To show an algorithm belongs to P , we need to:***
 - **Provide polynomial upper bound on number of stages**
 - **Examine each stage to ensure it can run in polynomial time**

Examples

Path problem

- Is there a path from s to t in a given graph G ?
- $\text{PATH} = \{ \langle G, s, t \rangle \mid G \text{ is directed graph with directed path from } s \text{ to } t \}$

Example: *Path problem*

- **Brute force approach**
- If **G** has **m** nodes, path cannot be more than **m**
- Upper bound on possible paths m^m
- Try each “path” one by one for legality and for linking s-to-t

Example: *Path problem*

- **Breadth first search**
- **Place mark on node s**
- **Repeat until no new nodes marked**
 - **Scan all edges; If edge (a, b) found from marked node a to unmarked b, mark b**
- **If t is marked, accept; Otherwise, reject**

Breadth First Search Time Complexity

- Measure complexity based on number of nodes n
- Place mark on node $s \leftarrow n$ steps (find node s in list of m nodes)
- Repeat until no new nodes marked $\leftarrow n$ steps (if mark **1** new node/ loop)
- For each edge (a, b) with 'a' already marked, mark 'b' also $\leftarrow O(n^3)$

(n^2 max total edges, for each edge, search for 'a' to see if marked (n steps), then mark b in list if needed (n steps))

- In total: $n^2 \times (n + n) = 2n^3$
- If t marked, accept; else, reject $\leftarrow n$ steps (find node t in list of n nodes)
- In total: $f(n) = n + n \times 2n^3 + n = 2n^4 + 2n = O(n^4)$ It's **POLYNOMIAL!**

Example: RELPRIME

- Two numbers are relatively prime if **1** is the largest number that evenly divides them both
- **10** and **21** are relatively prime
- **10** and **22** are not relatively prime
- Solution: search all divisors from 2 until $\min(x, y) / 2$
- $\min(x, y) / 2$ numbers tried, **$\min(x, y) / 2$ steps**
- size of input n = length of binary encoding = $\log_2(\max(x, y))$
- **2^n steps – exponential complexity!**

RELPRIME: Faster Solution

Euclidean algorithm

- **E = On input $\langle x, y \rangle$**
- **Repeat until $y = 0$**
 - **Assign $x = x \bmod y$**
 - **Exchange x and y**
- **Output x**
- **R = On input $\langle x, y \rangle$, Run E on $\langle x, y \rangle$**
- **If result is 1, accept: Otherwise, reject**

RELPRIME: Simulating the Euclidean algorithm

x=10 y=21 Perform $x \% y$

x=10 y = 21 x=y and y = (x **MOD y)**

x=21 y=10 Perform $x \% y$

x=10 y=1 x=y, and y=(x **MOD y)**

x=0 y=1

y=1 when x=0, so original numbers relatively prime

RELPRIME: Euclidean Algorithm – complexity

$x = x \bmod y \leftarrow$ new x always less than y

- If old x is twice y or more, new x will be cut at least in half**
- If old x between y and $2y$, new x will be cut at least in half**
 - new $x = x - y$**

Number of loops: $2 \cdot \log_2(\max(x, y))$

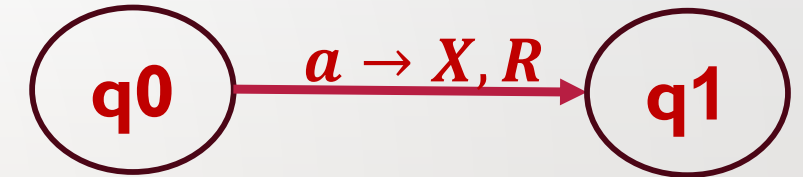
Length of input (in binary): $\log_2(x) + \log_2(y) = O(\log_2(\max(x, y)))$

Number of loops: $O(n)$

TURING MACHINE

A Decider for the language $L = \{a^n b^n c^n : n > 0\}$

Input Tape



q0aabbcc



Configuration → xq1abbcc

TURING MACHINE

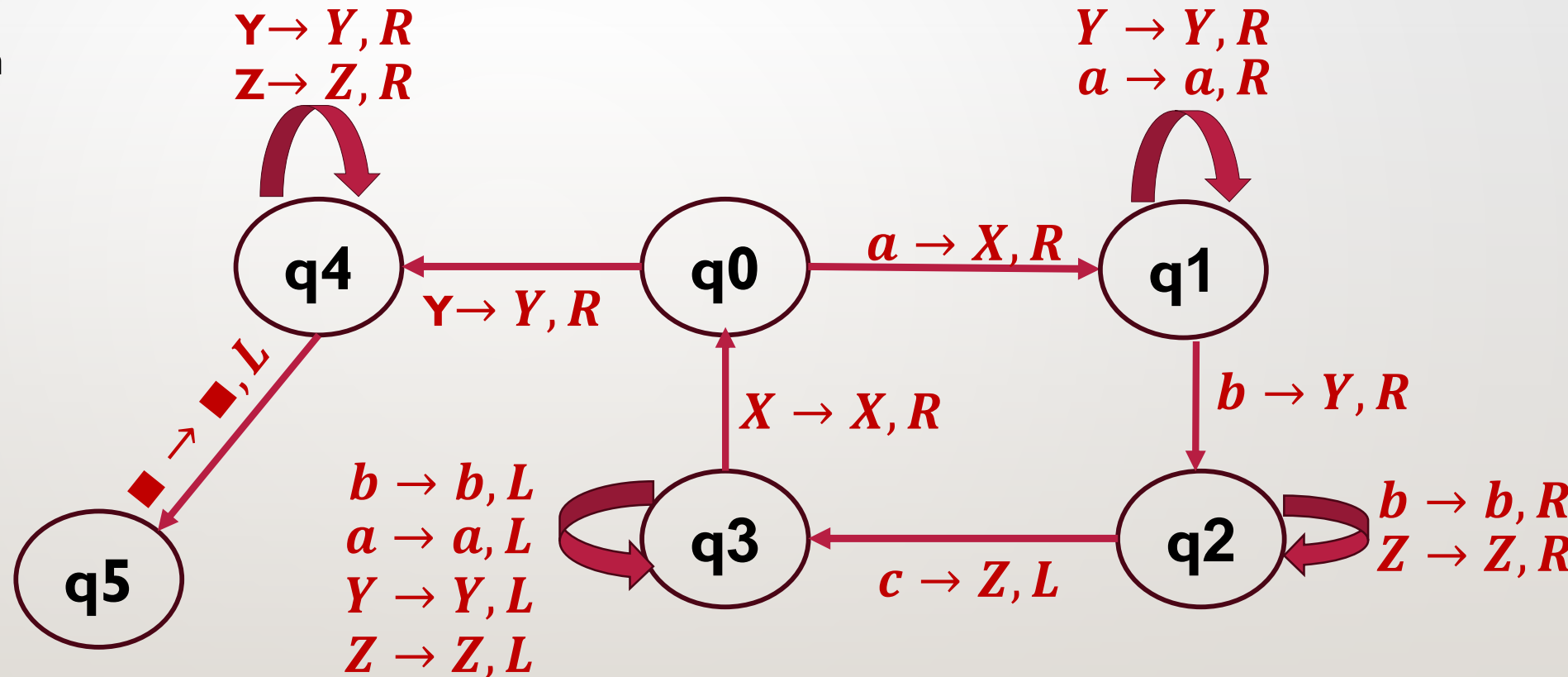
A Decider for the language $L = \{a^n b^n c^n : n > 0\}$

A partial Computing Path

q0 aabbcc

xq1 abbcc

xaq1 bbcc

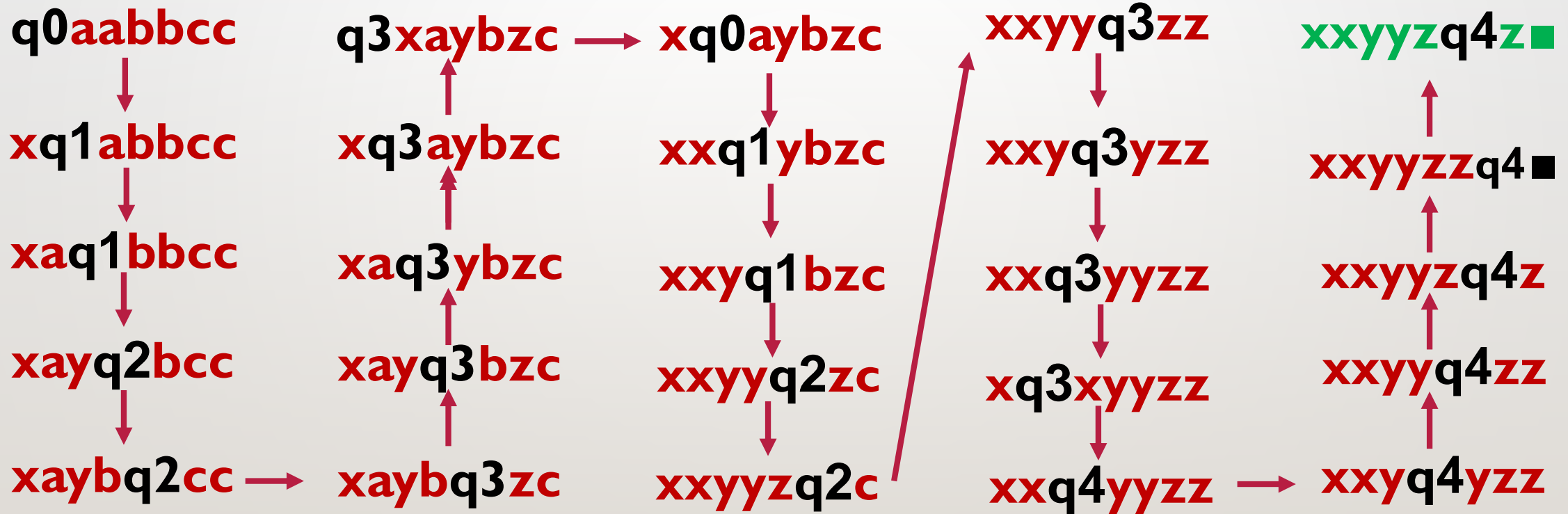


TURING MACHINE

A Decider for the language $L = \{a^n b^n c^n : n > 0\}$

Start configuration

Accept configuration

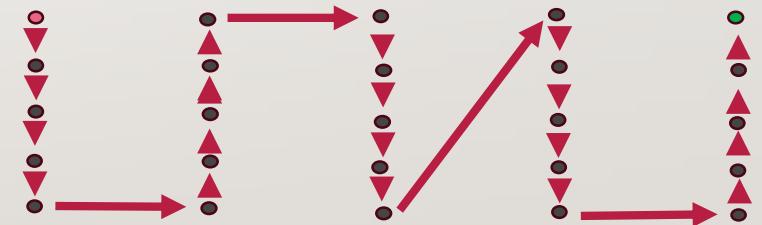




There is a Single Computing Path

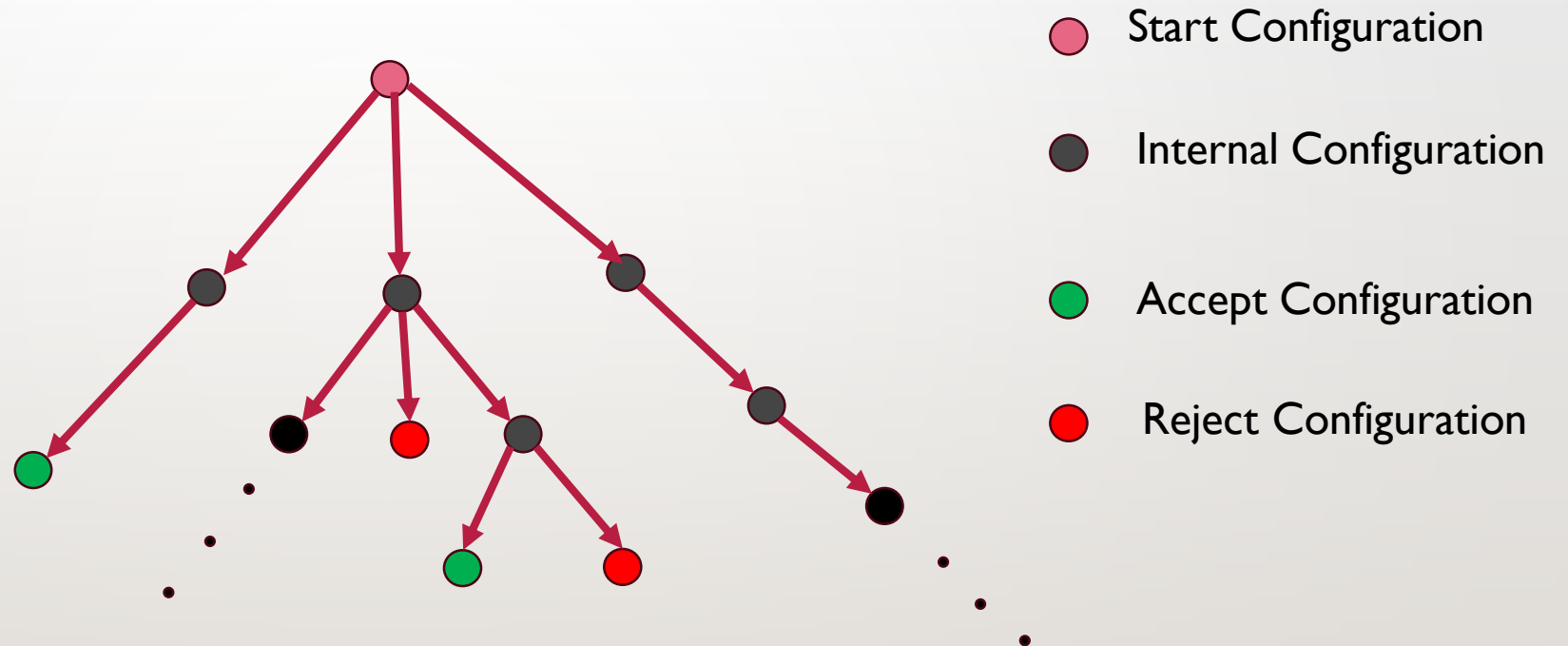
TM halts on every input with either q_{accept} or q_{reject} Configuration.

The TM we discussed is a **DETERMINISTIC** Turing Machine.



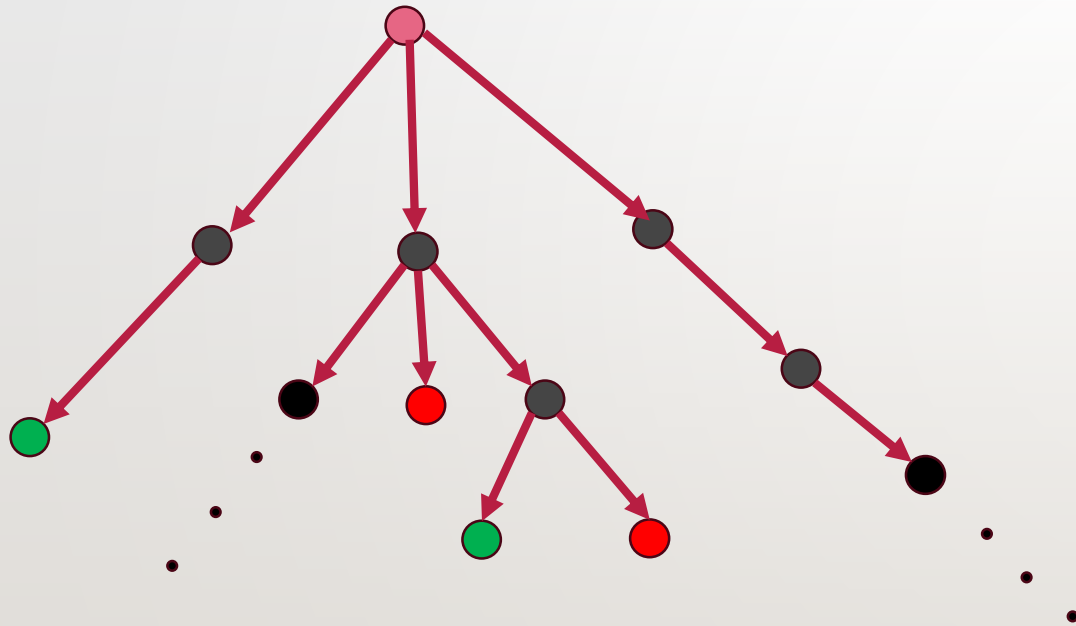
TURING MACHINE

A Non-Deterministic TM



TURING MACHINE

A Non-Deterministic TM



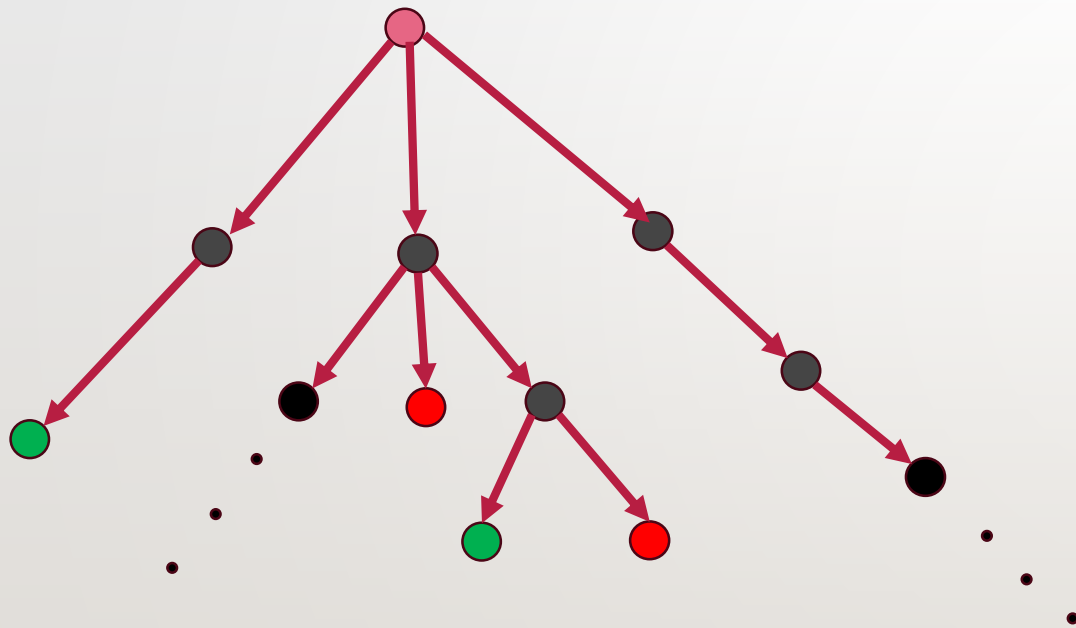
Multiple Computational Paths

Each path may lead to either q_{accept} or q_{reject} Configuration

Many of the computing paths may not be terminating

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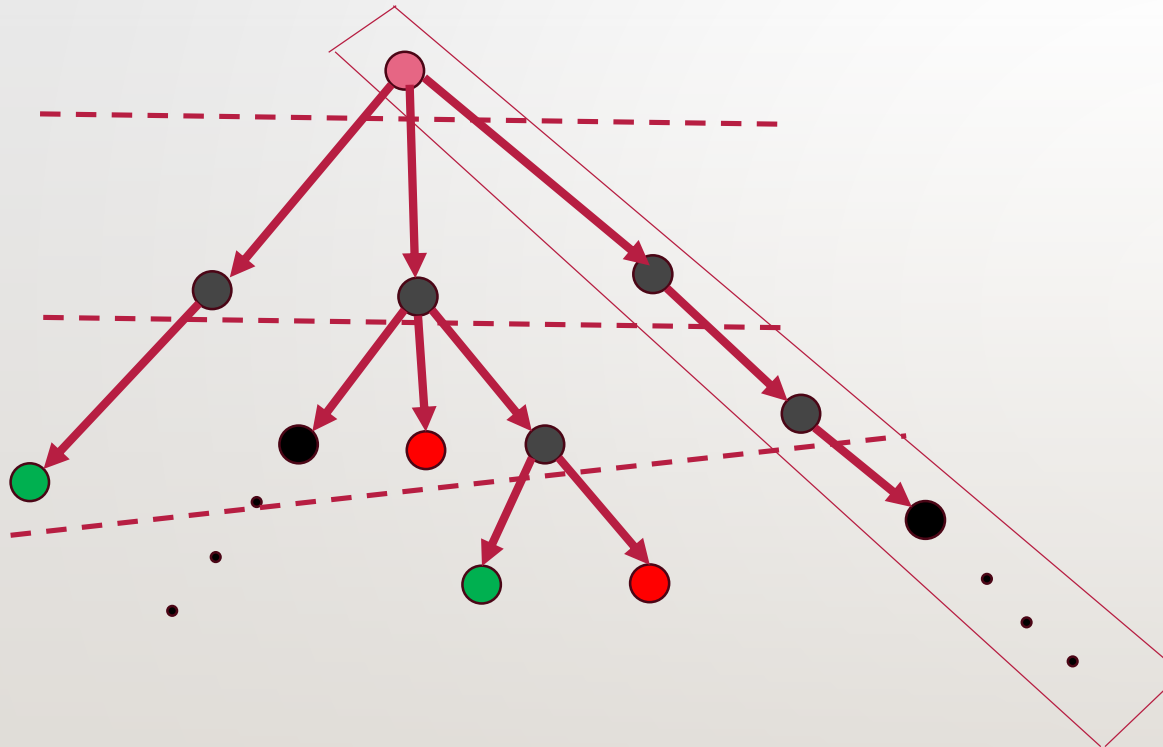
A Non-Deterministic TM



A string is accepted by a NDTM if any of the computing path reaches a q_{accept} configuration

we move from a uniquely determined sequence of computation steps to several possible sequences.

A Non-Deterministic TM



An NDTM has a magical parallelism

We can traverse the tree structure either using BFS or DFS method.

A Non-Deterministic TM

Given a language $L \subseteq \Sigma^*$, we determine the time $t(x)$ needed by a non-deterministic machine to process input $x \in \Sigma^*$ in the following way.

1. If $x \in L$ then $t(x)$ is defined as the length of the shortest path in the computation tree accepting x .
2. If $x \notin L$, the value of $t(x)$ is defined as the length of the shortest path in the computation tree.

TURING MACHINE

A Non-Deterministic TM

Time $t(n)$ needed by T for processing input $x \in \Sigma^*$ with the length $|x| = n \in N$ is defined as the maximum of all finite $t(x)$ for $x \in \Sigma^*$ with $|x| = n$.

Non-Deterministic Polynomial Time

$$NTIME(t(n)) = \{L: L \text{ is decided by a NDTM in } O(t(n))\}$$

$$NP = \bigcup_{k=1}^{\infty} NTIME(n^k)$$

It is also known as given and verify model

Example: SUBSET-SUM

SUBSET – SUM =

$\{ \langle s, t \rangle : s = \{x_1, x_2, \dots, x_n\} \exists t \subseteq \{1, 2, 3, \dots, k\} \text{ such that } \sum_{i \in t} x_i = t \}$

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