

Digital Communication 23EC2208A

Digital Carrier Modulation

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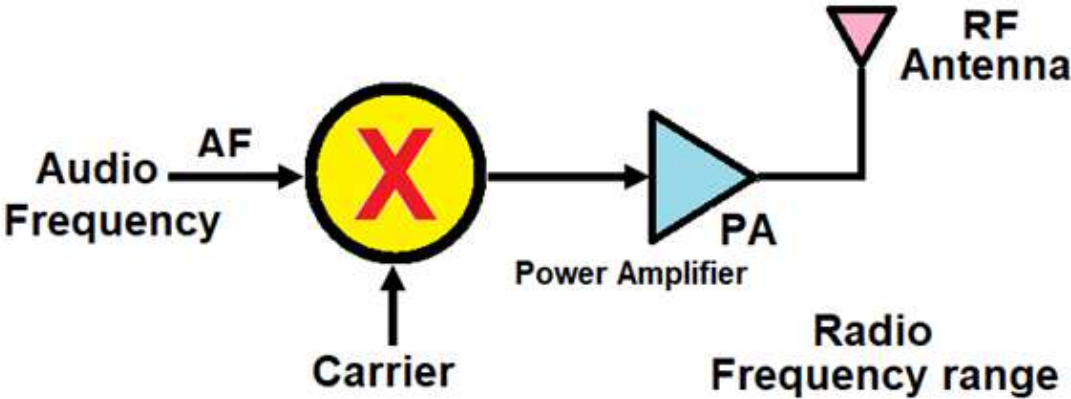
Digital Pass Band Communication



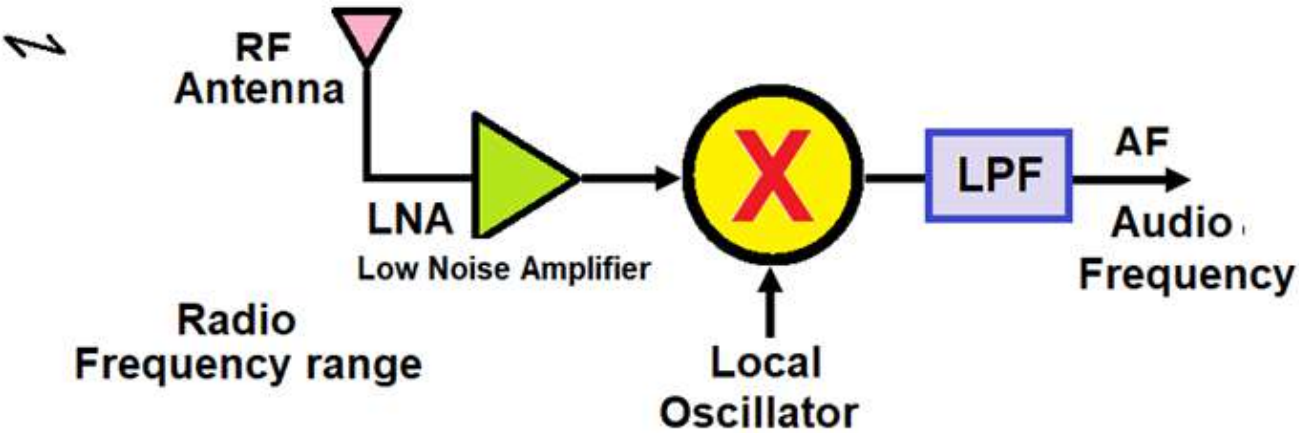
Base Band Transmission



Pass Band Transmission



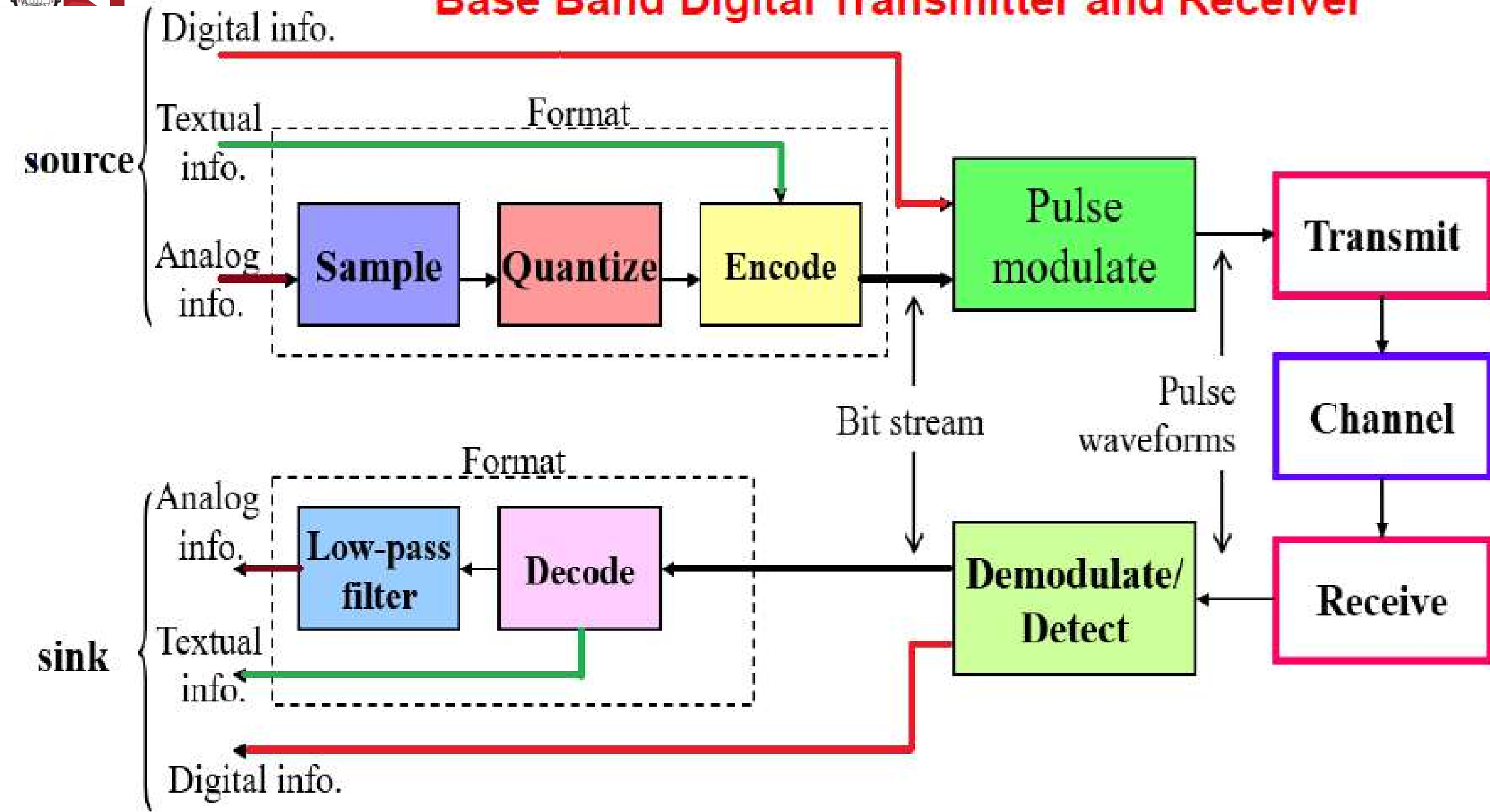
(a) Transmitter



(b) Receiver



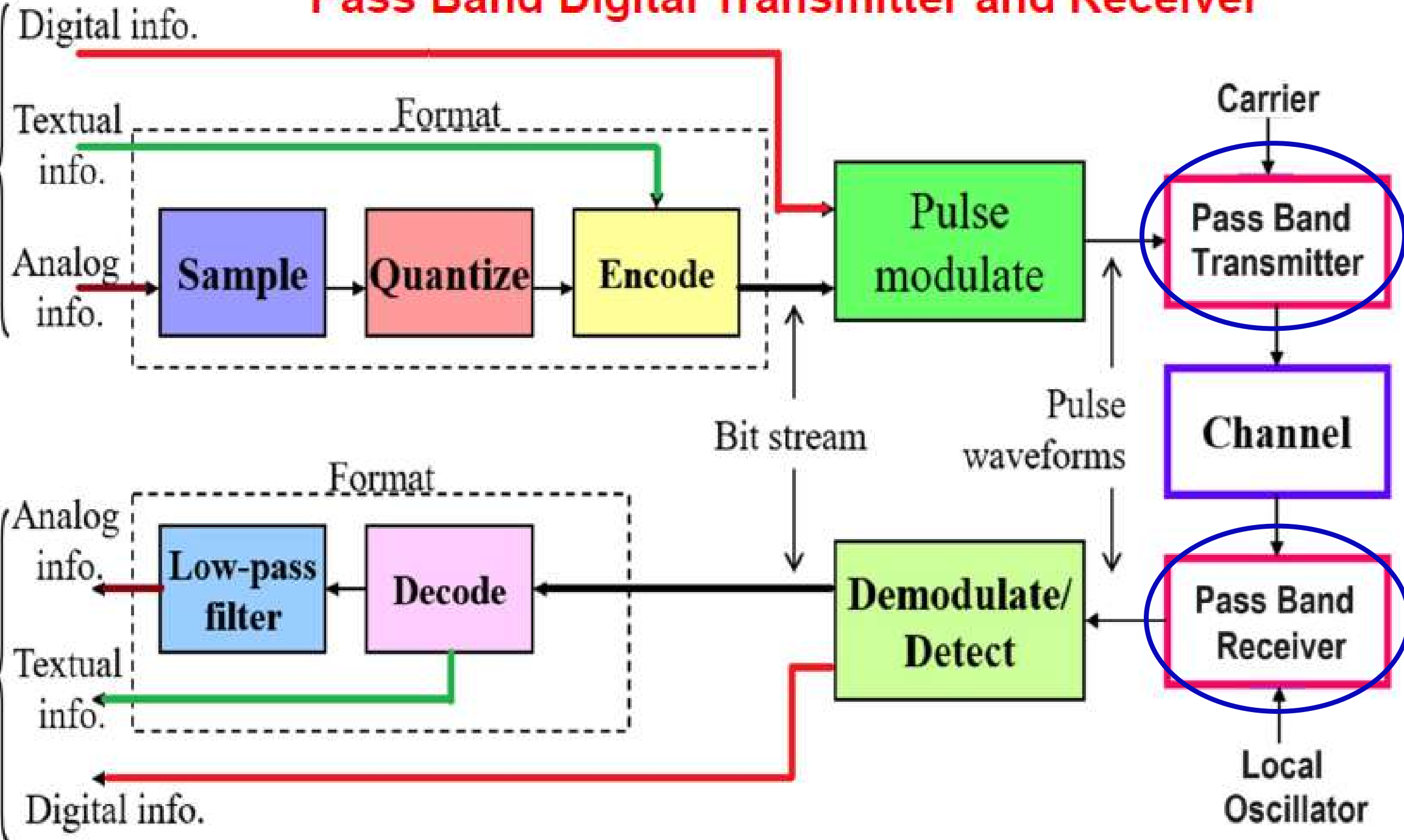
Base Band Digital Transmitter and Receiver





Pass Band Digital Transmitter and Receiver

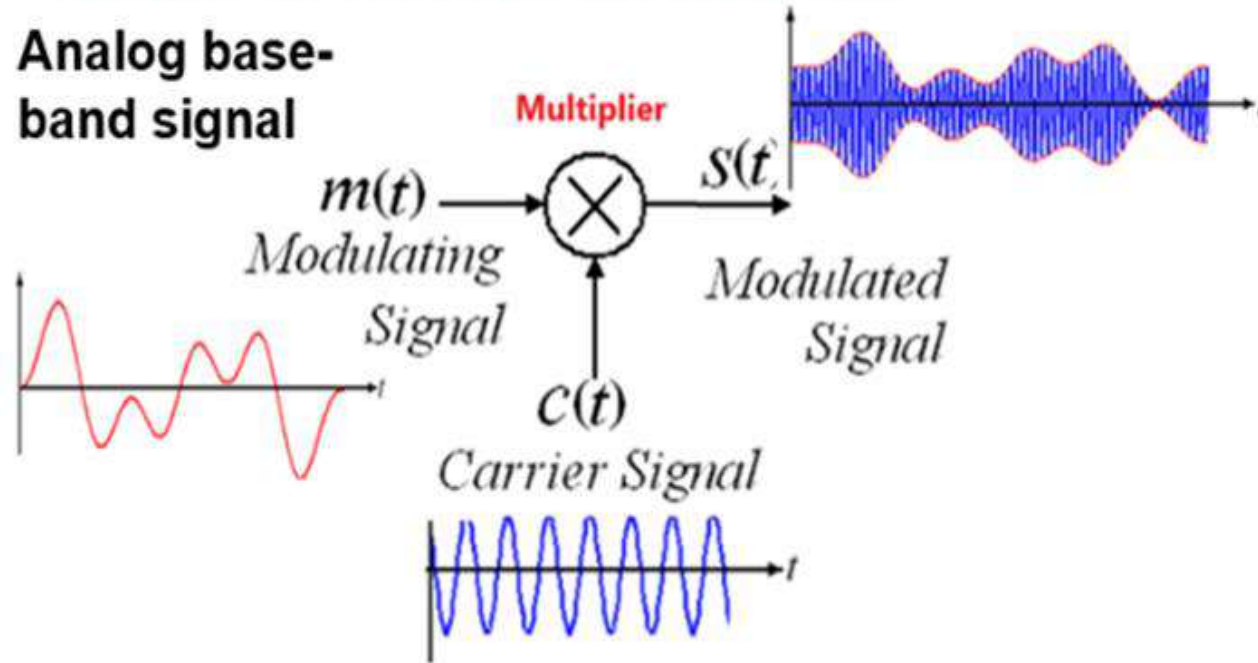
source



Pass-Band Communication

Analog Communication

Analog base-band signal

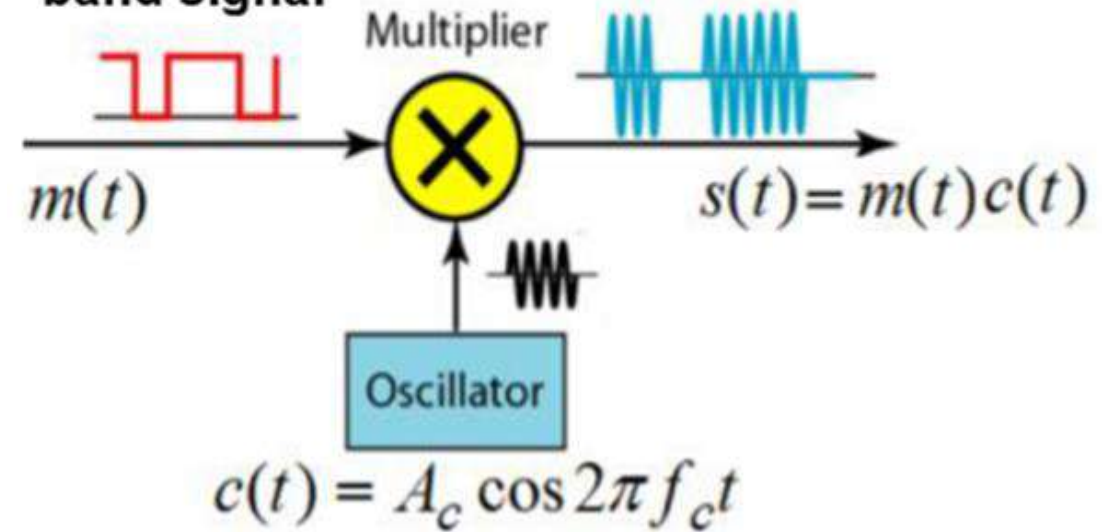


Modulating Signal **Analog**

Carrier Signal **Analog**

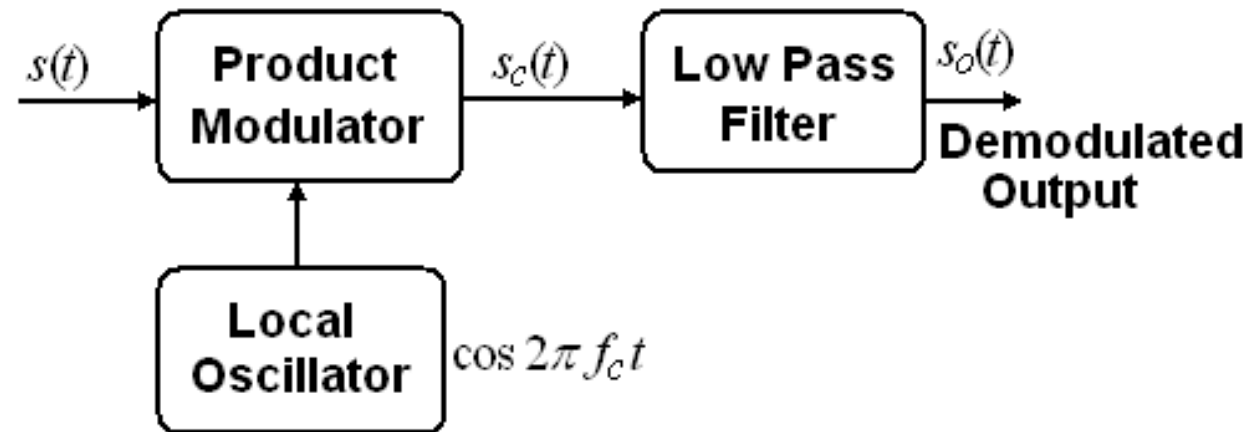
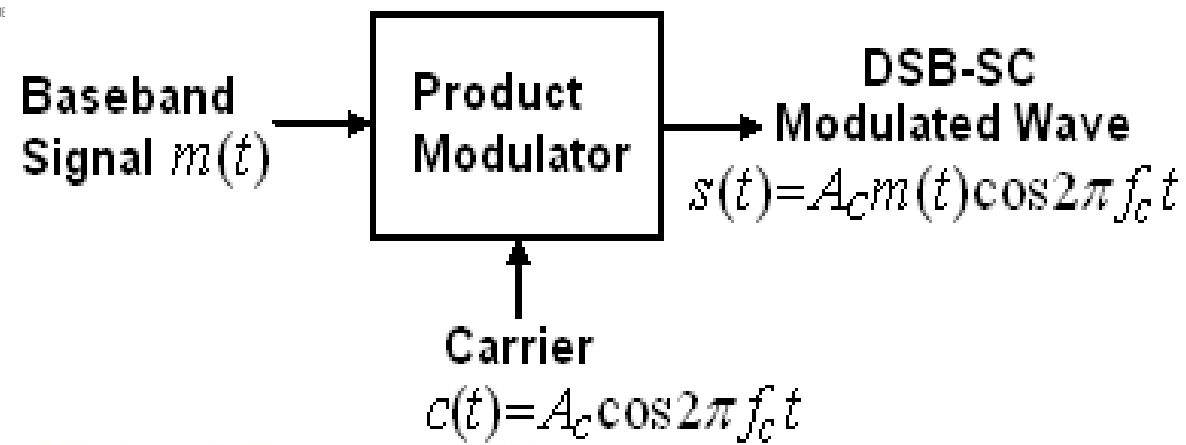
Digital Communication

Digital base-band signal



Digital

Analog



DSB-SC signal is $s(t) = A_c m(t) \cos 2\pi f_c t$

Then the product modulator output $s_c(t)$ is given by

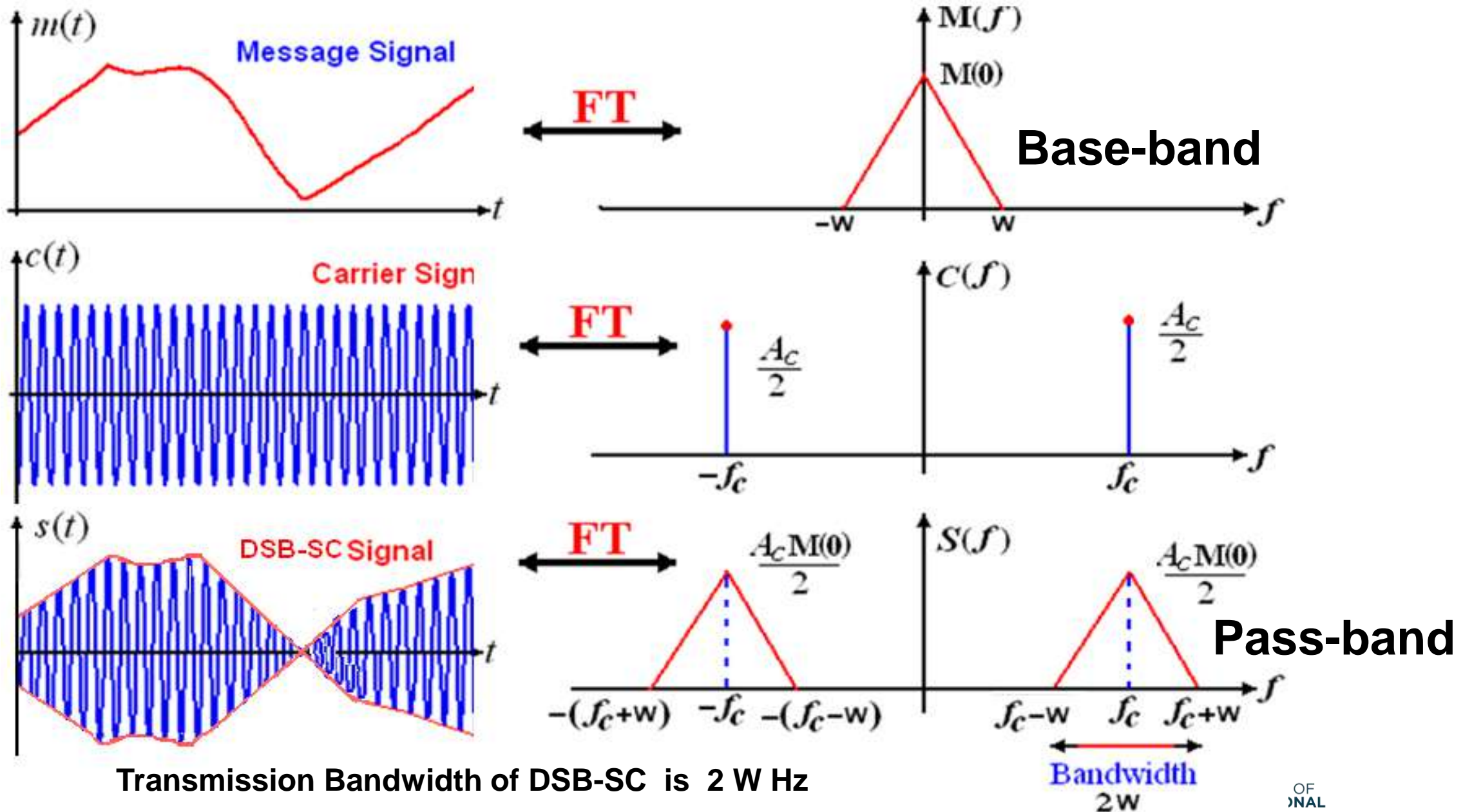
$$s_c(t) = s(t) \cos 2\pi f_c t = [A_c m(t) \cos 2\pi f_c t] \cos 2\pi f_c t$$

$$= A_c m(t) \cos^2 2\pi f_c t = A_c m(t) \frac{1}{2} [1 + \cos 4\pi f_c t]$$

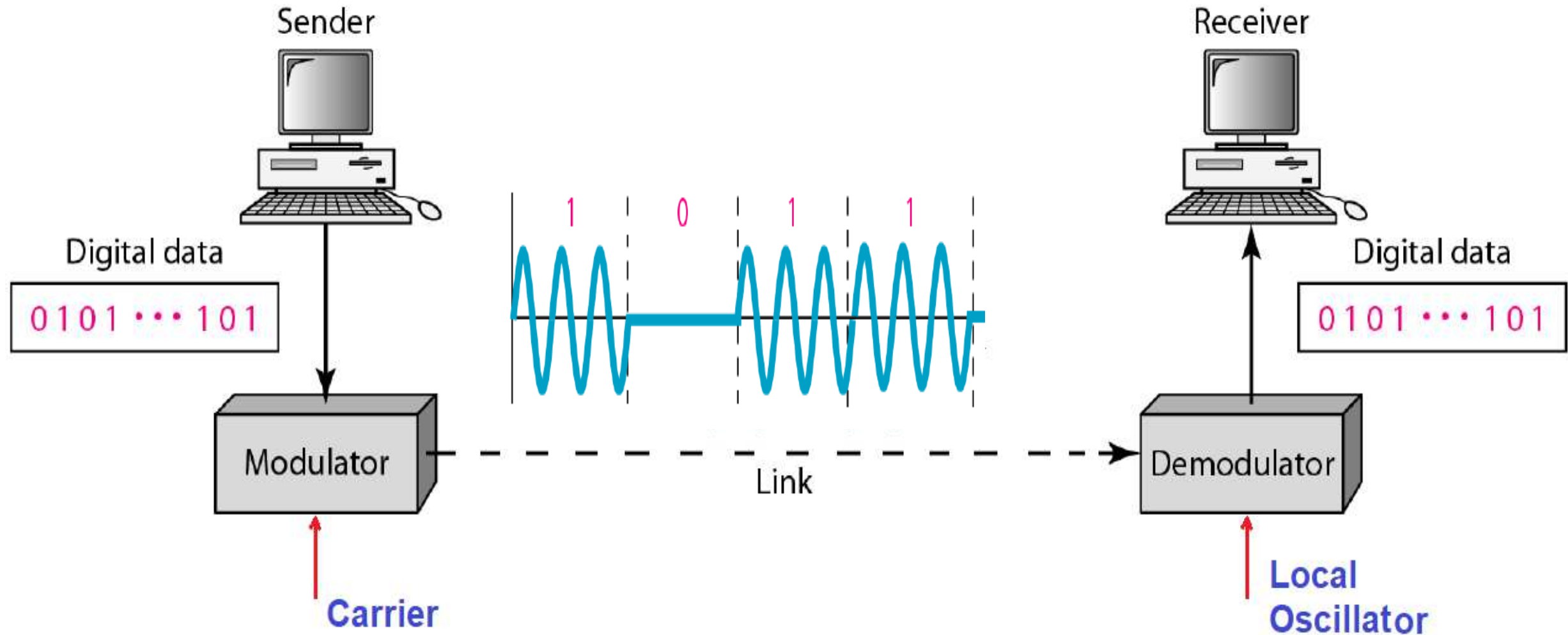
$$= \frac{1}{2} A_c m(t) + \frac{1}{2} A_c m(t) \cos 4\pi f_c t$$

$$s_o(t) = \frac{1}{2} A_c m(t)$$

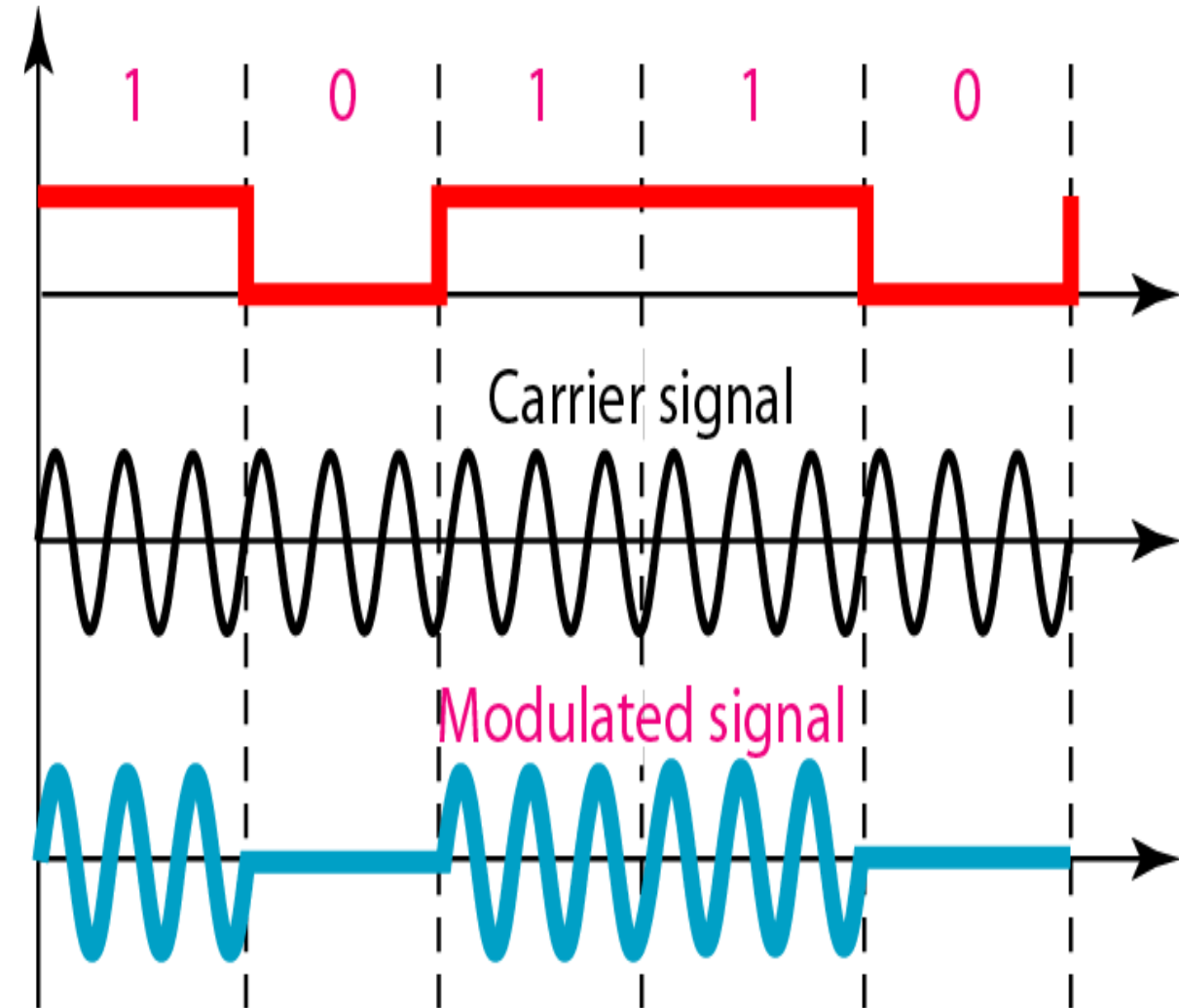
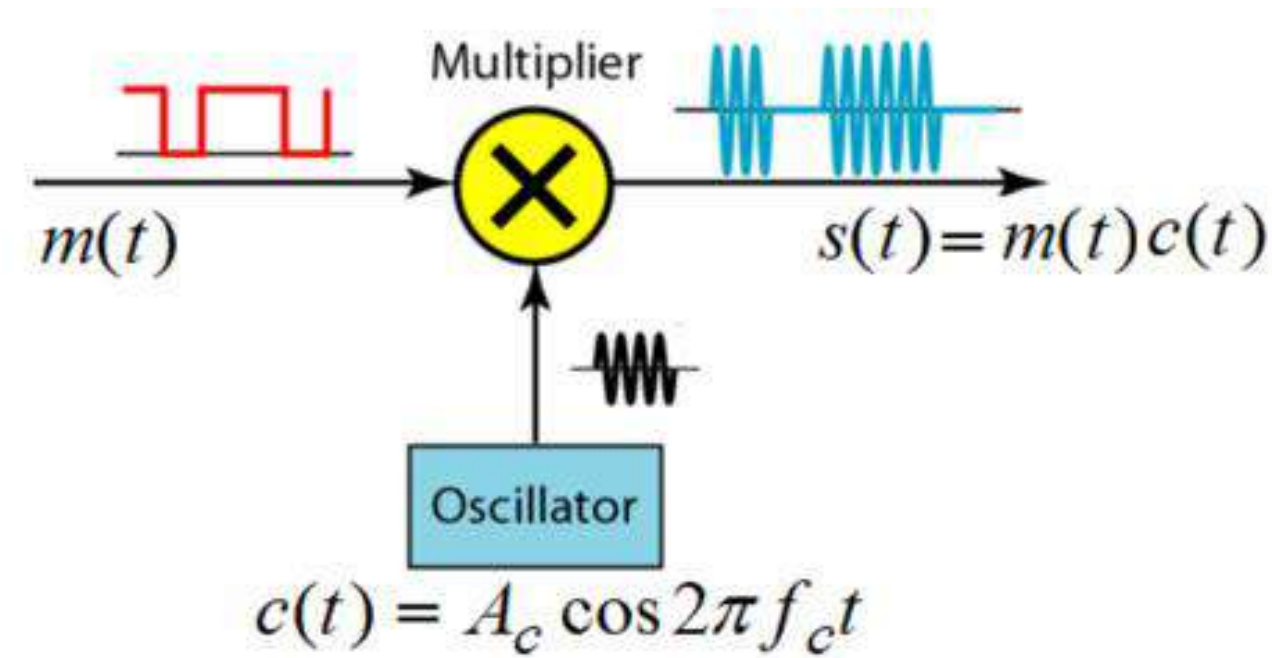
Baseband AM(DSB-SC) Spectrum



Pass-band Digital Communication



Pass-band Digital Transmitter



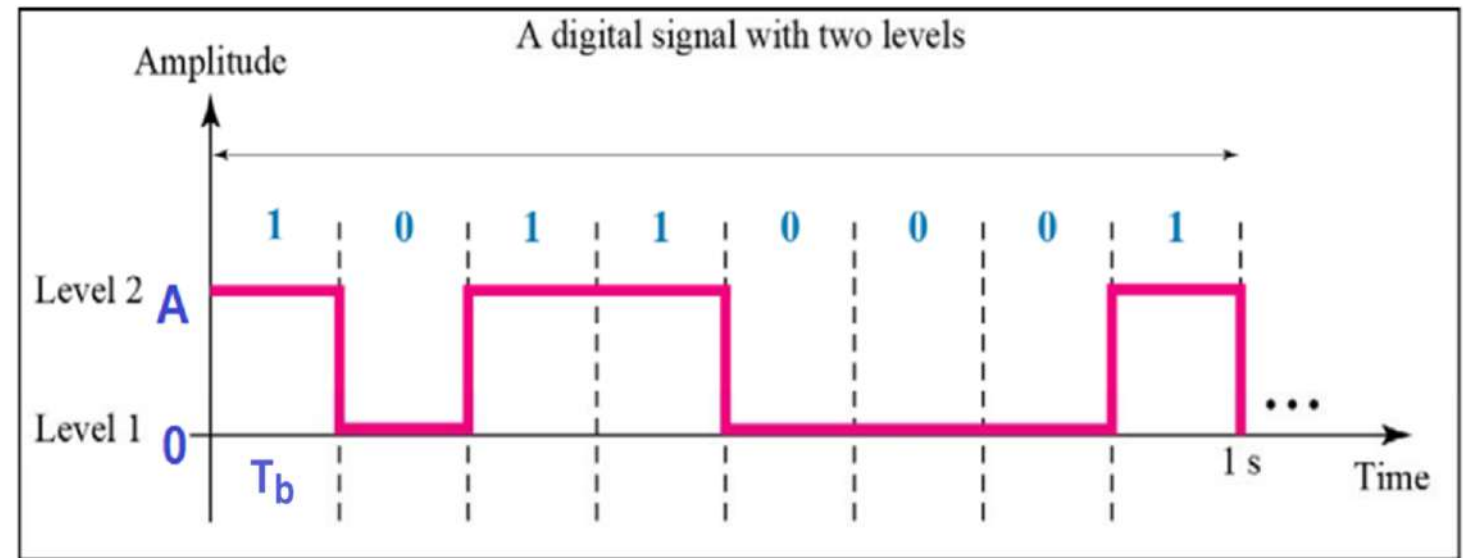
Digital Signals

In addition to being represented by an analog signal, information can also be represented by a digital signal.

- For example, a 1 can be encoded as a positive voltage and a 0 as zero voltage as shown below:
- Bit rate is defined as the number of bits transmitted over a second.

What is the bit rate for this digital signal?

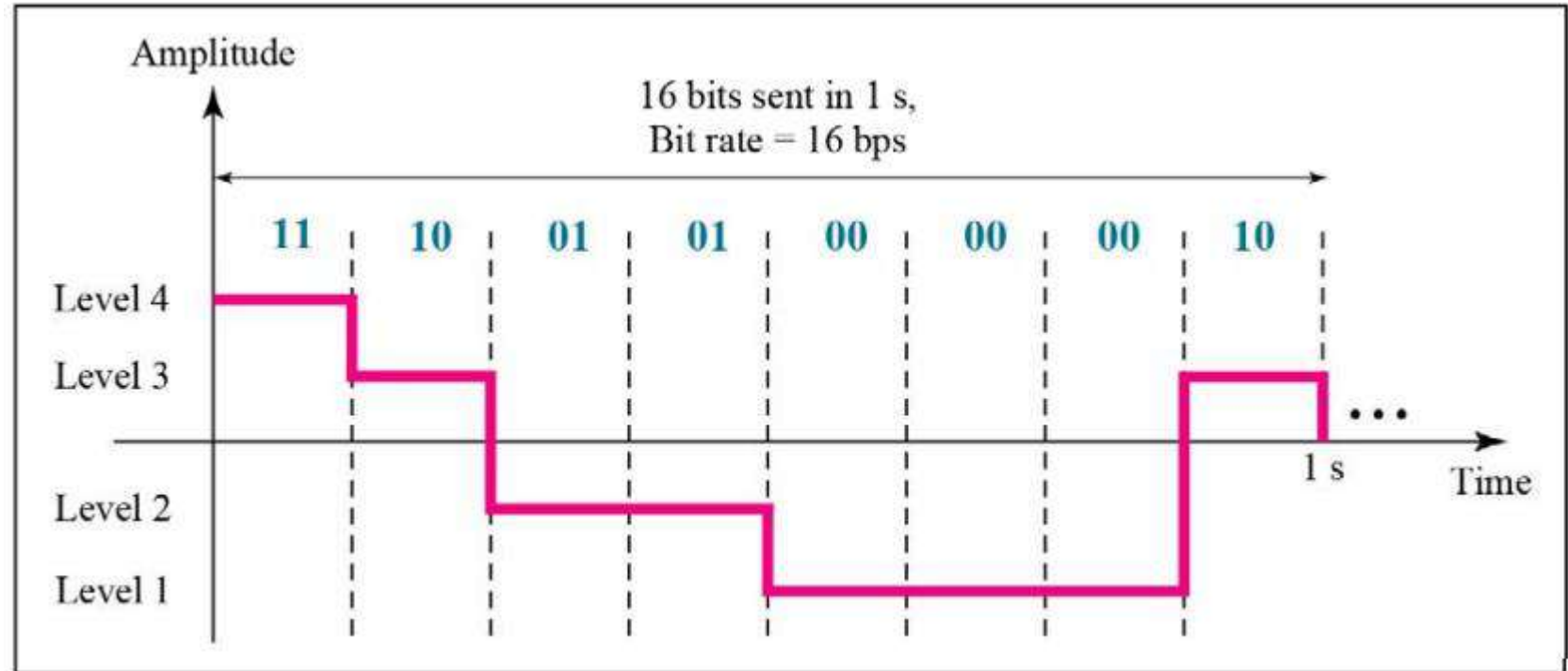
8 bits sent in 1 sec.
Bit rate = 8 bps



- Hence the above digital data bit rate is 8 bits per second or bps.
- What is the bit period / duration ? $\frac{1}{8} = 0.125 \text{ sec}$

Digital Signals

A digital signal can have more than two levels as shown below. In this case, we can send more than 1 bit for each level.

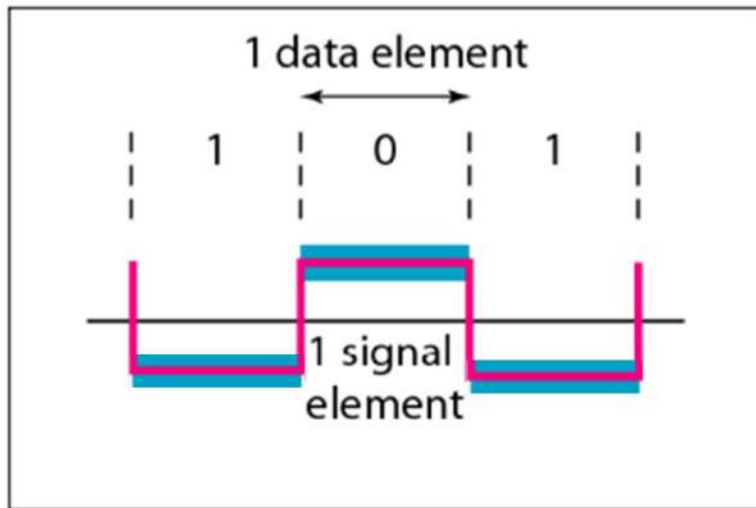


b. A digital signal with four levels

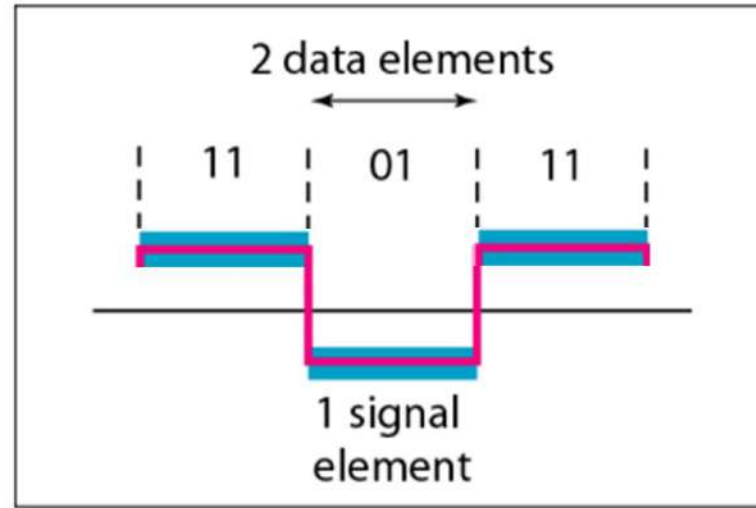
Each pulse is represented by two bits. Hence in this case the bit-rate is $8 \times 2 = 16 \text{ bps}$

Signal element versus data element

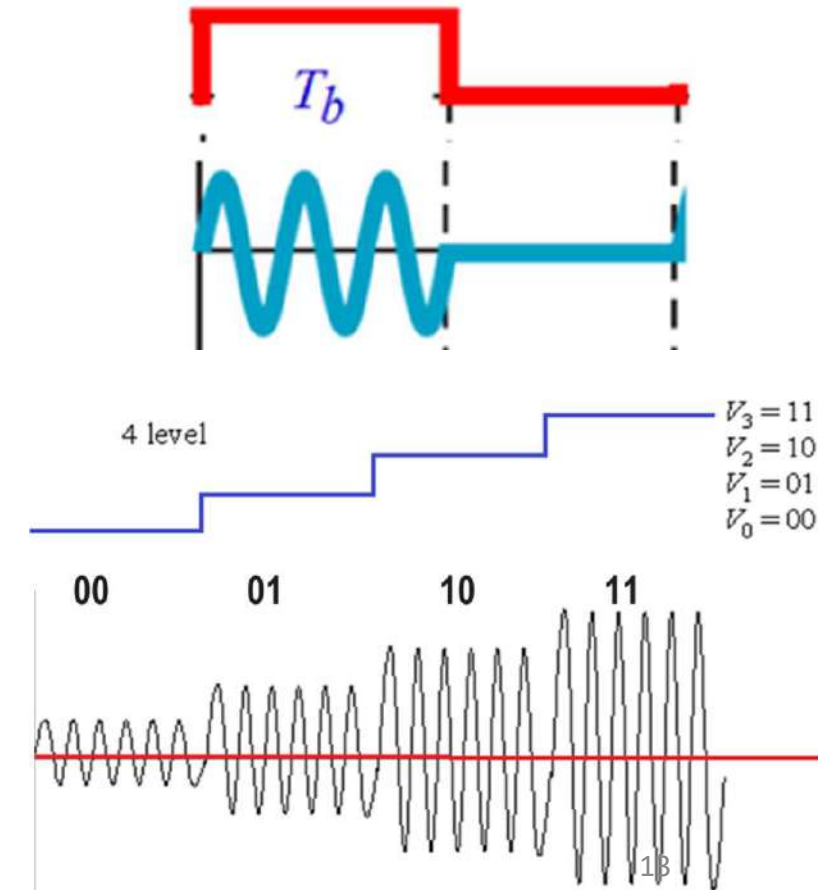
- A data element is the smallest entity that represent a piece of information; this is the bit.
- A signal elements is the shortest unit (timewise) of a digital signal.
- In other words, data elements are what we need to send; signal element are what we can send.



One data element per one signal element



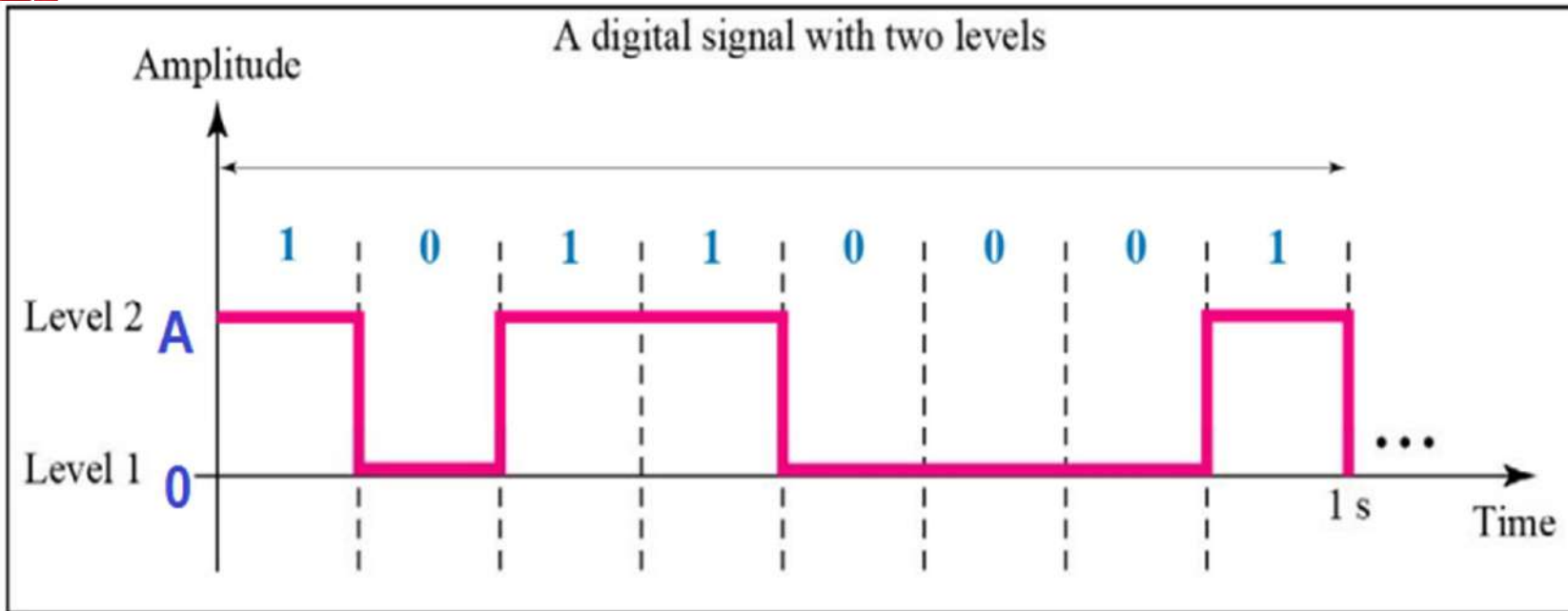
Two data elements per one signal element



Bit rate and Baud rate

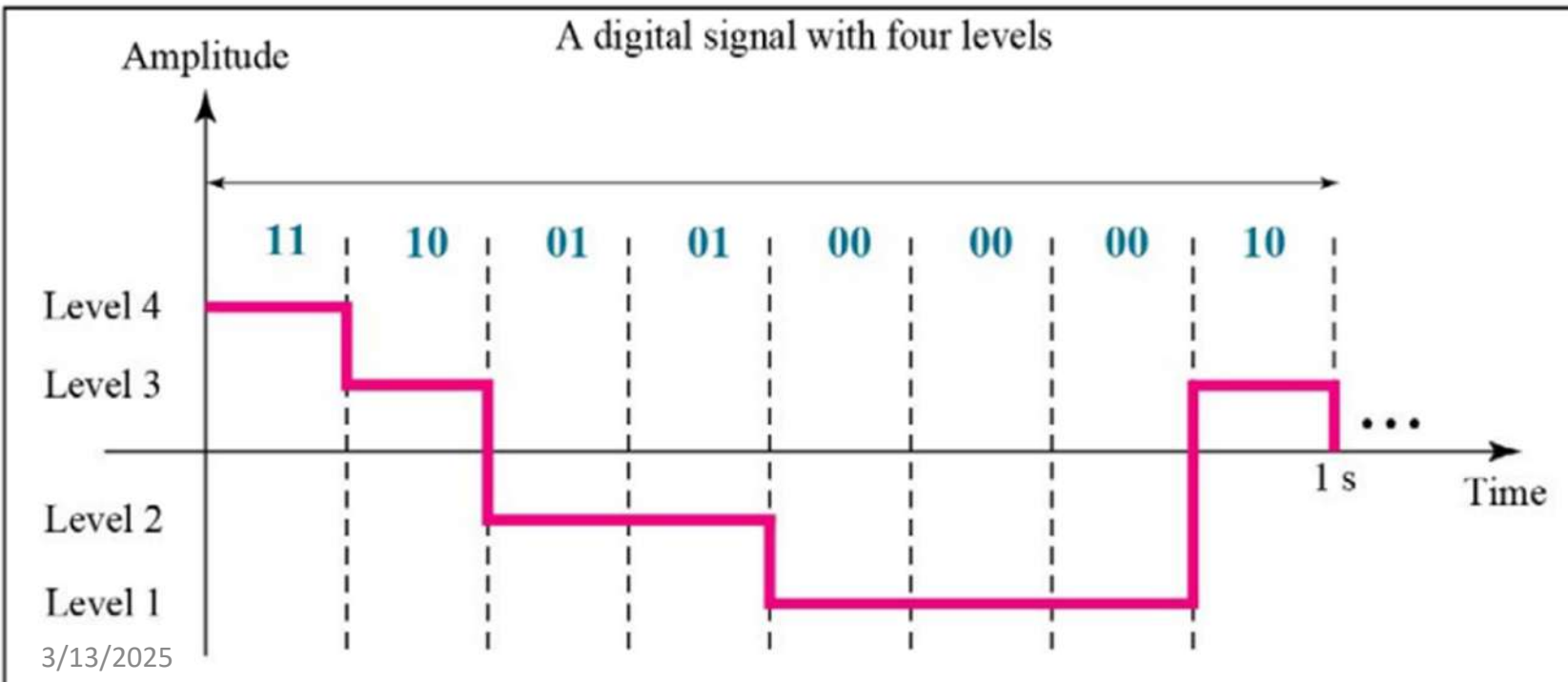
- Bit rate is the number of bits transmitted over a second.
- Baud rate is the number of symbols / signal units transmitted over a second.
- Baud rate is less than or equal to the bit rate.
- Baud rate = Bit rate / no. of bits per signal unit

$$= \frac{f_b}{n}$$



Bit rate: 8 bps

Baud rate: 8 bps



Bit rate: 16 bps

Baud rate: 8 bps

Ex1: An analog signal carries 4 bits per signal element. If 1000 signal elements are sent per second, find the bit rate.

Ans: Baud rate = 1000, No. of elements $N = 4$;

Bit rate = $1000 \times 4 = 4000$ bps.

Ex2: An analog signal has a bit rate of 8000 bps and a baud rate of 1000 baud. How many data elements are carried by each signal element?
How many signal elements do we need?

Data elements = Bit rate / baud rate = 8 bits / baud

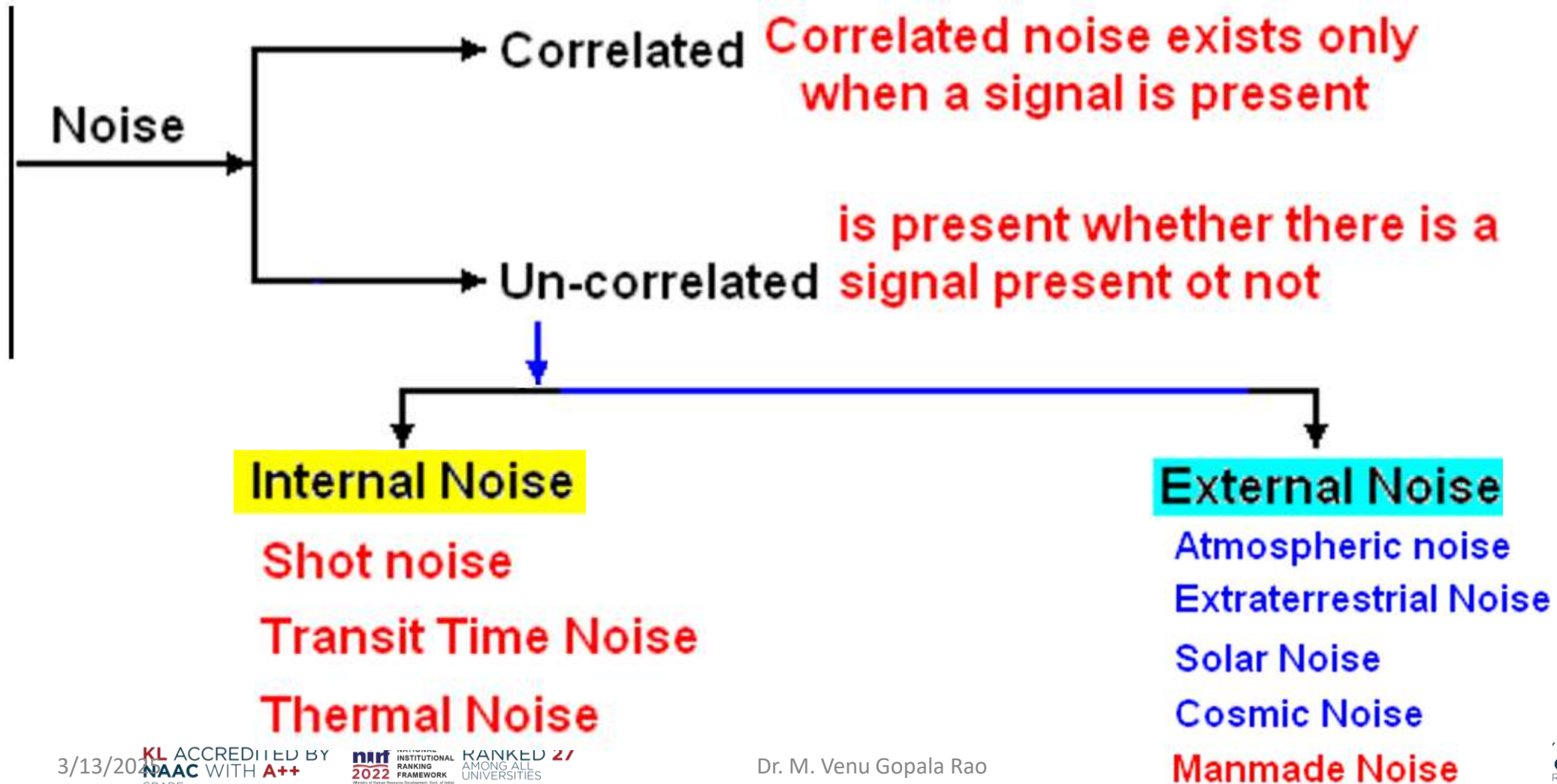
Then the number of signal elements $L = 2^8 = 256$ levels.

Bandwidth

- The actual bandwidth necessary to propagate a given bit rate depends on several factors,
 - ❖ including the type of encoding and modulation used,
 - ❖ the types of filters used, system noise, and
 - ❖ desired error performance.
- The ideal bandwidth is generally used for comparison purposes only.
- The relationship between bandwidth and bit rate also applies to the opposite situation. For a given bandwidth (B), *the highest theoretical bit rate is $2B$.*

Introduction to Noise

Electrical noise is defined as undesirable electrical energy that falls within the passband of the signal.





Gaussian Noise

- Let $\eta(t)$ denote a noisy signal.
- The values of noisy signal are **unpredictable** and only a probability can be associated to them,

$$\Pr\{n_1 < \eta(t) \leq n_2\}$$

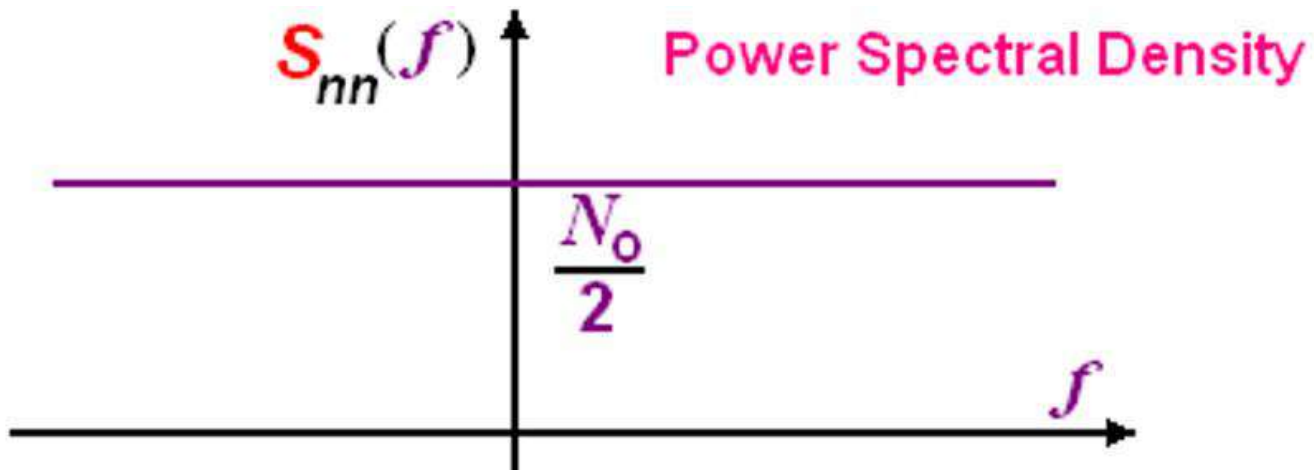
- The most common type of noise found in a communication system is **Gaussian** with PDF

$$P_{\eta(t)}(n) = \frac{1}{\sqrt{2\pi\sigma_{\eta}^2}} e^{-\frac{1}{2}\left(\frac{n-\mu_{\eta}}{\sigma_{\eta}}\right)^2}$$

where $\mu_{\eta} = E\{\eta(t)\}$: Mean value , and

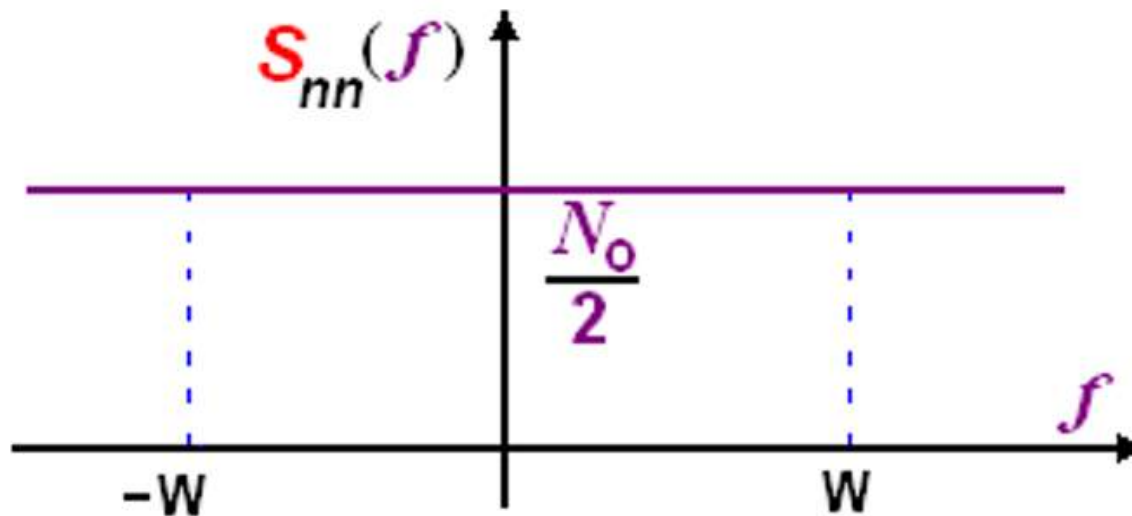
$$\sigma_{\eta}^2 = E\left\{\left(\eta(t) - \mu_{\eta}\right)^2\right\} : \text{Variance}$$

Additive White Noise



Average Power of Additive White Noise

$$P_n = \int_{-W}^W S_{nn}(f) df$$
$$= \frac{N_0}{2} 2W = N_0 W$$



Noise is assumed to be uncorrelated with the signal

1. Signal to Noise Power Ratio

Where P_S Signal Power

P_n Noise Power

The SNR is often expressed as a logarithmic function with the decibel unit

$$\frac{S}{N} = \frac{P_S}{P_n}$$

$$\frac{\tilde{S}}{N}(\text{dB}) = 10 \log_{10} \frac{P_S}{P_n}$$

$$SNR(\text{dB}) = 20 \log_{10} \frac{V_S}{V_n} = 20 \log_{10} \frac{I_S}{I_n}$$

2. Figure of Merit

$$\text{Figure of Merit} = \frac{\text{Output SNR}}{\text{Input SNR}}$$

$$\text{Noise Figure} = \frac{\text{Input SNR}}{\text{Output SNR}}$$

Performance Measures

- *Two key performance measures of a modulation scheme are power efficiency and bandwidth efficiency*
- ***Power efficiency** is a measure of how favorably the tradeoff between fidelity and signal power is made, and is expressed as the ratio of the signal energy per bit (E_b) to the noise PSD (N_0) required to achieve a given probability of error (say 10^{-5}):*

$$\eta_p = \frac{E_b}{N_0}$$

Small η_p is preferred

➤ **Bandwidth efficiency** describes the ability of a modulation scheme to accommodate data within a limited bandwidth, In general, it is defined as the ratio of the data bit rate R to the required RF bandwidth B :

$$\eta_B = \frac{R}{B} (\text{bps/Hz}) \quad \text{Large } \eta_B \text{ is preferred}$$

Error Function

□ Error function $\text{erf}(u) = \frac{2}{\sqrt{\pi}} \int_0^u \exp(-z^2) dz$

□ Complementary error function $\text{erfc}(u) = \frac{2}{\sqrt{\pi}} \int_u^\infty \exp(-z^2) dz$

□ Q-function $Q(u) = \frac{1}{\sqrt{2\pi}} \int_u^\infty \exp\left(-\frac{z^2}{2}\right) dz$

$$\begin{cases} \text{erf}(-u) = -\text{erf}(u) \\ \text{erfc}(u) = 1 - \text{erf}(u) \\ Q(u) = \frac{1}{2} \text{erfc}\left(\frac{u}{\sqrt{2}}\right) \end{cases}$$

Error Function

- Bounds for error function

$$\text{erfc}(x) = \frac{1}{x\sqrt{\pi}} e^{-x^2} \left(1 - \frac{1}{2x^2} + \frac{1 \cdot 3}{2^2 x^4} - \frac{1 \cdot 3 \cdot 5}{2^3 x^6} + \dots \right)$$

$$\text{For } x > 0, \frac{1}{x\sqrt{\pi}} e^{-x^2} \left(1 - \frac{1}{2x^2} \right) < \text{erfc}(x) < \frac{1}{x\sqrt{\pi}} e^{-x^2}$$

(The bound is good when x is large.)

Error rate due to noise

- The optimal BER formula is important in communications:

$$BER_{\text{opt}} = \frac{1}{2} \text{erfc} \left(\sqrt{\frac{E_g}{N_0}} \right) = Q \left(\sqrt{\frac{2E_g}{N_0}} \right)$$

- The best decision is $y \stackrel{+1}{\geq} 0$.

Orthogonal Properties of Sine and Cosine Terms

$$(i) \int_0^T \sin n\omega_0 t \, dt = \int_0^T \cos n\omega_0 t \, dt = \int_0^{2\pi} \sin nx \, dx = \int_0^{2\pi} \cos nx \, dx = 0$$

for all integral values of 'n'

$$(ii) \int_0^T \sin m\omega_0 t \cos n\omega_0 t \, dt = \int_0^T \cos n\omega_0 t \cos m\omega_0 t \, dt = 0, \quad m \neq n$$

$$(iii) \int_0^T \sin^2 n\omega_0 t \, dt = \int_0^T \cos^2 n\omega_0 t \, dt = \frac{T}{2}, \quad \text{and}$$

$$(iv) \int_0^{2\pi} \sin^2 nx \, dx = \int_0^{2\pi} \cos^2 nx \, dx = \pi \quad m = n$$

➤ Any element of set S , $S = \{s_1(t), s_2(t), \dots, s_M(t)\}$, can be represented as a point in a vector space whose coordinates are basis signals $\phi_j(t)$, $j=1, 2, \dots, N$, such that

$$\int_{-\infty}^{\infty} \phi_i(t) \phi_j(t) dt = 0, i \neq j; (\rightarrow \text{orthogonal})$$

$$E = \int_{-\infty}^{\infty} [\phi_i(t)]^2 dt = 1; (\rightarrow \text{normalization})$$

$s_i(t)$ can be represented as a linear combination of the basis signals.

$$s_i(t) = \sum_{j=1}^N s_{ij} \phi_j(t), \quad i = 1, 2, \dots, M$$

End