

# **Design and Analysis of Algorithms**

**Session -33** 











## **BASIC CONCEPTS**

The computing times of algorithms fall into two groups.

- **Group1** Consists of problems whose solutions are bounded by the polynomial of small degree. Example Binary search O(logn), sorting O(nlogn), matrix multiplication O(n<sup>2.81</sup>)
- **Group2** Contains problems whose best known algorithms are non polynomial.

Example –Traveling salesperson problem  $0(n^22^n)$ , knapsack problem  $0(2^{n/2})$  etc.











There are two classes of non polynomial time problems

- 1. NP-Complete: Have the property that it can be solved in polynomial time if all other NP-Complete problems can be solved in polynomial time.
- 2. NP-Hard- If it can be solved in polynomial time then all NP-Complete can be solved in polynomial time.
- "All NP-Complete problems are NP-Hard but not all NP Hard problems are not NP-Complete"









# **Deterministic and Non-Deterministic Algorithms**

Algorithms with the property that the result of every operation is uniquely defined are termed deterministic.

- Such algorithms agree with the way programs are executed on a computer.
- When the outcome is not uniquely defined but is limited to a specific set of possibilities, we call it non deterministic algorithm

To specify such algorithms in SPARKS, we introduce three statements

- i) choice(S): arbitrarily chooses one of the elements of the set S.
- ii) failure : Signals an unsuccessful completion.
- iii) Success: Signals a successful completion.











# **EXAMPLE OF A DETERMINISTIC ALGORITHM**

```
Algorithm Lsearch (A, n, x) {
  for i:= I to n do {
         if(a[i]=x) then
                  return i;
  return 0;
```











# **EXAMPLE OF A NON DETERMINISTIC ALGORITHM**

```
Algorithm Search(A, n, x) {
  j:= choice(I,n);
  if(a[j]=x) then {
         return j;
         success();
  return 0;
  failure();
```











## **DEFINITIONS**

## Decision problem

Any problem whose answer is yes or no

## Decision algorithm

An algorithm for a decision problem is termed as a decision algorithm

## Optimization problem

Any problem that involves the identification of an optimal (either minimum or maximum) values of a given cost function is known as an optimization problem.

## Optimization algorithm

An optimization algorithm is used to solve an optimization problem.











**P** is the set of all decision problems solvable by a deterministic algorithm in polynomial time.

#### **Sample Problems in P:**

Fractional Knapsack, MST, Sorting.

> NP is the set of all decision problems solvable by a nondeterministic algorithm in polynomial time.

## **Sample Problems in NP:**

Fractional Knapsack, MST, Sorting and Hamiltonian Cycle (Traveling Salesman), Graph Coloring











## **SATISFIABILITY**

• Let x1,x2,x3...,xn denotes Boolean variables.

• Let  $X_i$  denotes the negation of  $X_i$ .

• A literal is either a variable or its negation.

• A formula in the prepositional calculus is an expression that can be constructed using literals and the operators  $\Lambda(AND)$  and V(OR).











- A formula is in Conjunctive Normal Form (CNF) iff it is represented as  $\Lambda C_i$ , where the  $C_i$  are clauses each represented as  $vl_{ij}$ .
- It is in Disjunctive Normal Form (DNF) iff it is represented as  $vC_i$  and each clause is represented as  $\lambda l_{ii}$
- The satisfiability problem is to determine if a formula is true for some assignment of truth values to the variables
- CNF-Satisability is the satisfiability problem for CNF formulas











## **ALGORITHM FOR SATISFIABILITY**

```
Algorithm EVAL(E, n)
for i := 1 to n do
   xi := choice(true, false);
if E(x1,...,xn)
       then success();
       failure();
else
```









#### Reducibility

Let  $L_1$  and  $L_2$  be problems.  $L_1$  reduces to  $L_2$  ( $L_1 \alpha L_2$ ) if and only if there is a deterministic polynomial time algorithm to solve  $L_1$  that solves  $L_2$  in polynomial time.

ightharpoonup If L<sub>1</sub>  $\alpha$  L<sub>2</sub> and L<sub>2</sub>  $\alpha$  L<sub>3</sub> then L<sub>1</sub>  $\alpha$  L<sub>3</sub>.

#### **COOK's Theorem**

Satisfiability is in P if and only if P = NP.

**NP-Hard** 

A problem L is NP-hard if any only if satisfiability reduces to L.

**NP-complete** 

A problem L is NP-complete if and only if L is NP-hard and L  $\in$  NP.





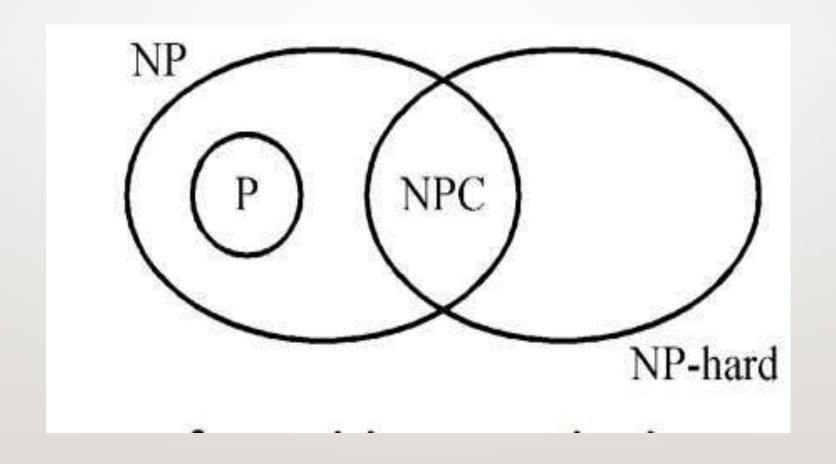






# RELATIONSHIP BETWEEN P, NP, HARD AND NP-COMPLETE

# NP-













## **COOK'S THEOREM**

- Theorem states that satisfiability is in P if and only if P = NP.
- To prove this, we show how to obtain from any polynomial time nondeterministic decision algorithm A and input I a formula Q(A, I) such that Q is satisfiable if A has a successful termination with input I.
- If the length of I is n and the time complexity of A is p(n) for some polynomial p(), then the length of Q is  $O(p^3(n) \log n) = O(p^4(n))$ .









- The time needed to construct Q is also  $O(p^3(n)\log n)$ .
- A deterministic algorithm Z to determine the outcome of A on any input I can be easily obtained.
- Algorithm Z simply computes Q and then uses a deterministic algorithm for the satisfiability problem to determine whether Q is satisfiable.
- If O(q(m)) is the time needed to determine whether a formula of length m is satisfiable, then the complexity of Z is  $O(p^3(n) \log n) + q(p^3(n) \log n)$ .





- If satisfiability is in P, then q(m) is a polynomial function of m and the complexity
  of Z becomes O(r(n)) for some polynomial r(). Hence, if satisfiability is in P, then
  for every nondeterministic algorithm A in NP we can obtain a deterministic Z in
  P.
- So, the above construction shows that if satisfiability is in P, then P = NP.











## **Difference Between NP-Hard and NP-Complete**

NP-Hard	NP-Complete
NP-Hard problems(say X) can be solved if and	NP-Complete problems can be solved by a non-
only if there is a NP-Complete problem(say Y)	deterministic Algorithm/Turing Machine in
that can be reducible into X in polynomial time.	polynomial time.
To solve this problem, it do not have to be in NP	To solve this problem, it must be both NP and
	NP-hard problems.
Do not have to be a Decision problem.	It is exclusively a Decision problem.
<b>Example</b> : Halting problem, Vertex cover	<b>Example</b> : Determine whether a graph has a
problem, etc.	Hamiltonian cycle, Determine whether a
	Boolean formula is satisfiable or not, Circuit-
	satisfiability problem, etc.











**Example :** Halting problem is NP-hard decision problem, but it is not NP-complete. **Halting problem is NP-hard** 

To show that Halting problem is NP-hard, we show that

satisfiability  $\alpha$  halting problem.

For this let us construct an algorithm A whose input is a prepositional formula X.

- Suppose X has n variables.
- Algorithm A tries out all 2<sup>n</sup> possible truth assignments and verifies if X is satisfiable.

Halting problem is un-decidable.

- Hence there exists no algorithm to solve this problem.
- So, it is not in NP. Therefore, it is not NP-complete.











#### **Questions:**

- 1. With suitable example, explain nondeterministic algorithm.
- 2. Explain terminology used in Satisfiability Problem.
- 3. Explain Cook's theorem.
- 4. Differentiate NP-Hard with NP-Completeness.









# **THANK YOU**







