1. Description

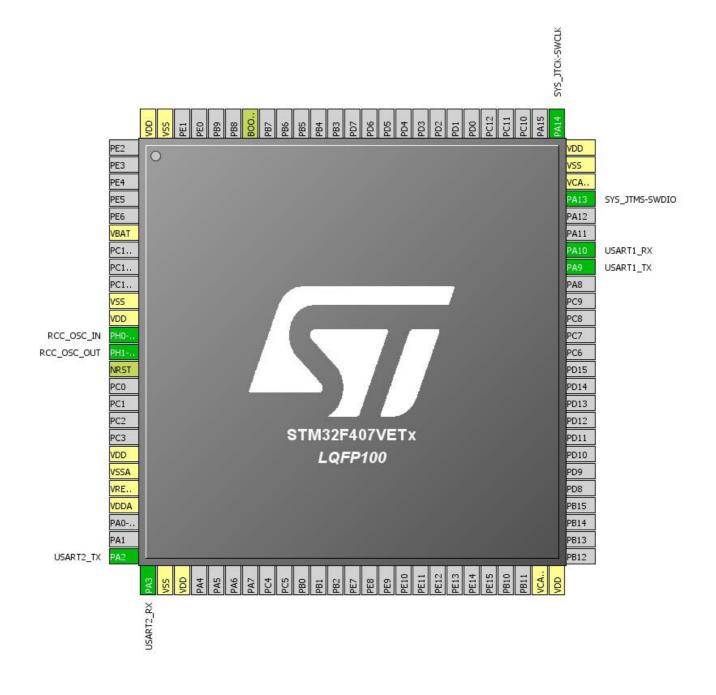
1.1. Project

Project Name	GPS_decoding
Board Name	GPS_decoding
Generated with:	STM32CubeMX 4.22.1
Date	10/31/2017

1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F407/417
MCU name	STM32F407VETx
MCU Package	LQFP100
MCU Pin number	100

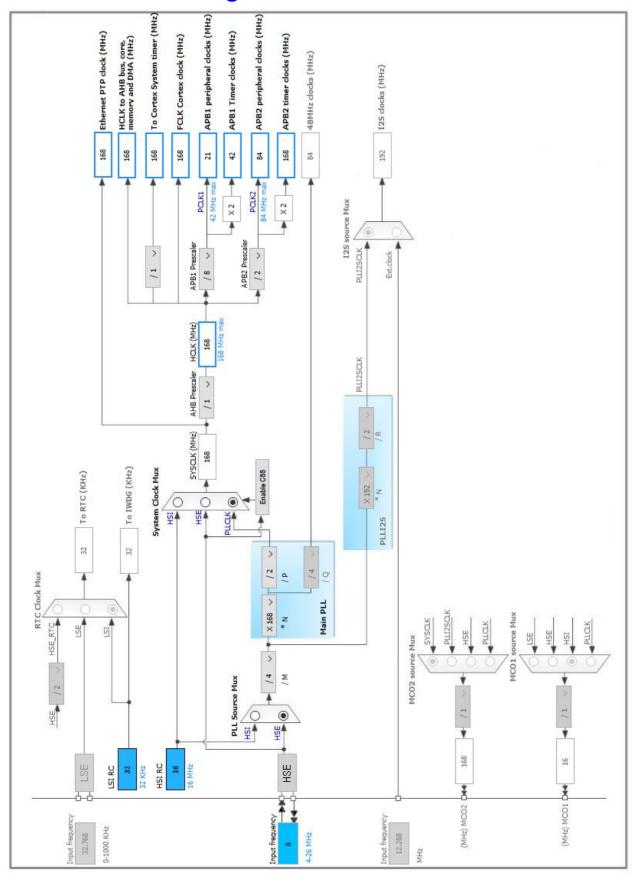
2. Pinout Configuration



3. Pins Configuration

Pin Number LQFP100	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
6	VBAT	Power		
10	VSS	Power		
11	VDD	Power		
12	PH0-OSC_IN	I/O	RCC_OSC_IN	
13	PH1-OSC_OUT	I/O	RCC_OSC_OUT	
14	NRST	Reset		
19	VDD	Power		
20	VSSA	Power		
21	VREF+	Power		
22	VDDA	Power		
25	PA2	I/O	USART2_TX	
26	PA3	I/O	USART2_RX	
27	VSS	Power		
28	VDD	Power		
49	VCAP_1	Power		
50	VDD	Power		
68	PA9	I/O	USART1_TX	
69	PA10	I/O	USART1_RX	
72	PA13	I/O	SYS_JTMS-SWDIO	
73	VCAP_2	Power		
74	VSS	Power		
75	VDD	Power		
76	PA14	I/O	SYS_JTCK-SWCLK	
94	воото	Boot		
99	VSS	Power		
100	VDD	Power		

4. Clock Tree Configuration



5. IPs and Middleware Configuration

5.1. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator

5.1.1. Parameter Settings:

System Parameters:

VDD voltage (V) 3.3
Instruction Cache Enabled
Prefetch Buffer Enabled
Data Cache Enabled

Flash Latency(WS) 5 WS (6 CPU cycle)

RCC Parameters:

HSI Calibration Value 16
HSE Startup Timout Value (ms) 100
LSE Startup Timout Value (ms) 5000

Power Parameters:

Power Regulator Voltage Scale Power Regulator Voltage Scale 1

5.2. SYS

Debug: Serial Wire

Timebase Source: SysTick

5.3. USART1

Mode: Asynchronous

5.3.1. Parameter Settings:

Basic Parameters:

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples

5.4. **USART2**

Mode: Asynchronous

5.4.1. Parameter Settings:

Basic Parameters:

Baud Rate 921600 *

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples

^{*} User modified value

6. System Configuration

6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
RCC	PH0- OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1- OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
SYS	PA13	SYS_JTMS- SWDIO	n/a	n/a	n/a	
	PA14	SYS_JTCK- SWCLK	n/a	n/a	n/a	
USART1	PA9	USART1_TX	Alternate Function Push Pull	Pull-up	Very High *	
	PA10	USART1_RX	Alternate Function Push Pull	Pull-up	Very High	
USART2	PA2	USART2_TX	Alternate Function Push Pull	Pull-up	Very High	
	PA3	USART2_RX	Alternate Function Push Pull	Pull-up	Very High	

6.2. DMA configuration

nothing configured in DMA service

6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true 0 0		0
USART1 global interrupt	true	0	0
USART2 global interrupt	true 0 0		0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
FPU global interrupt	unused		

^{*} User modified value

7. Power Consumption Calculator report

7.1. Microcontroller Selection

Series	STM32F4
Line	STM32F407/417
мси	STM32F407VETx
Datasheet	022152_Rev8

7.2. Parameter Selection

Temperature	25
Vdd	3.3

8. Software Project

8.1. Project Settings

Name	Value
Project Name	GPS_decoding
Project Folder	D:\sang-min\Club\Drone\source\GPS_decoding
Toolchain / IDE	EWARM
Firmware Package Name and Version	STM32Cube FW_F4 V1.16.0

8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy all used libraries into the project folder
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	No
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	No
consumption)	