

today

Due: Component 1, 2, 3 of Midterm project

CHANGE THE WORLD

Push Pop

Lab to work on midterm project

Student Presentations

Reading: Ch 4-6 on p.60, optional Ch 14

Monday, Feb 8

Due: Component 4 from Midterm project

Lab for component 5

Functions

Student Presentations

a quick review from last class

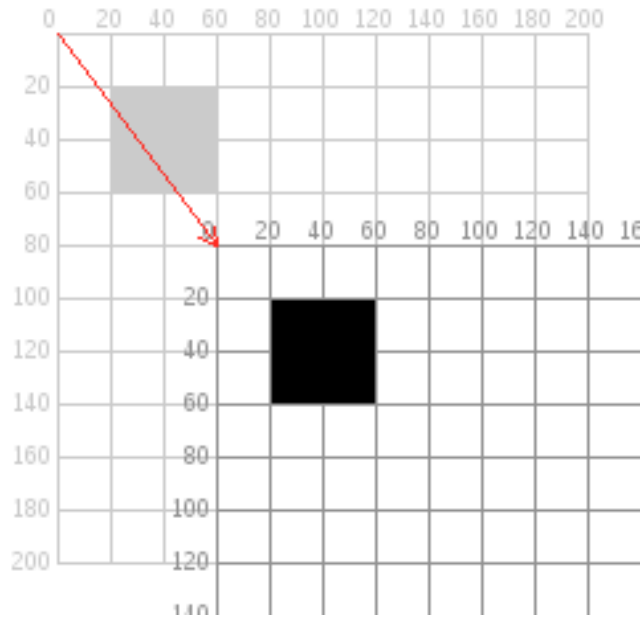
Transform

translate

rotate

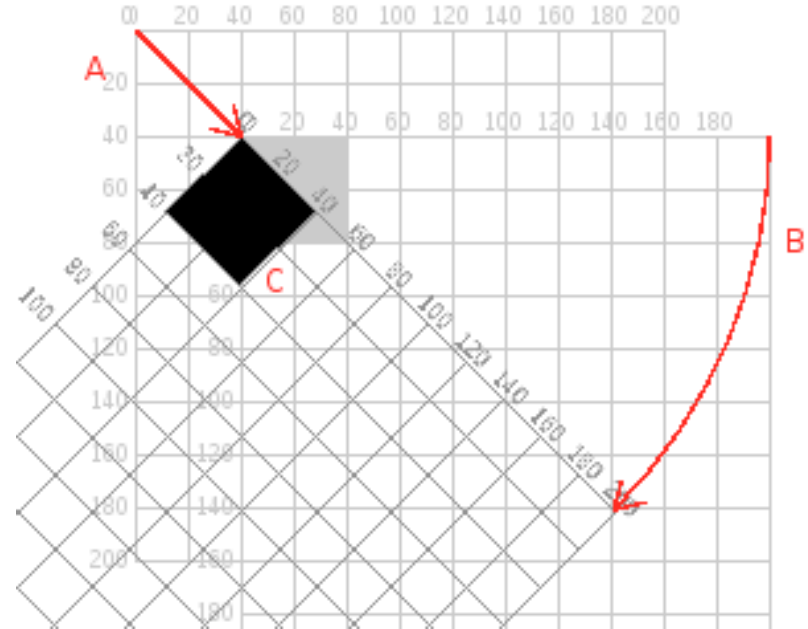
scale

translate



```
translate(60,80);  
rect(20,20,40,40);
```

translate then rotate



```
translate(40,40);  
rotate(radians(45));  
rect(0,0,40,40);
```

Where is the center of rotation?

sketch_14_1_basic_translate_rotate_scale.pde

```
void setup() {  
  size(500, 500);  
  background(0);  
  stroke(250);  
  fill(255);  
}  
  
void draw() {  
  
  translate(100, 100); //move the origin from (0,0) to (10,10)  
  //translate (mouseX,mouseY);  
  rotate (PI/4); //rotate the rectangle 45 degrees clockwise  
  //float rad = radians(45);  
  //rotate(rad);  
  scale (1.5); //scale up 1.5 times  
  
  rect(0, 0, 100, 50);  
}
```

The order of operation matters!

**What happens when you draw
another shape after the coordinates
have been**

translated
rotated
scaled

?

The new transformed coordinates sticks with ya!

Houston, we have a problem!

This makes my math WAY too complex!

Solution:

Push/Pop matrix!

Solution:

Push/Pop matrix to **isolate** transformations!

pushMatrix() and popMatrix()

```
pushMatrix(); //saves current matrix
```

```
popMatrix(); // restores last saved matrix
```

```
draw(); // restores to default matrix
```

multiple translations

```
//Multiple Translations
```

```
void setup() {  
  size (200, 200);  
}
```

```
void draw() {  
  translate (mouseX, mouseY);  
  /*everything below this line of code is stuck to a new  
  coordinate system, which in this case, it is set by the  
  positions of the mouse.*/
```

```
    rect(0, 0, 30, 30);  
    translate (35, 10);  
    rect (0, 0, 15, 15);  
}
```

```
//each time it draws, the coordinates are set to default.
```

multiple translations

isolating transformations

//Multiple Translations

```
void setup() {  
  size (200, 200);  
}  
  
void draw() {  
  translate (mouseX, mouseY);  
  rect(0, 0, 30, 30);  
  
  translate (35, 10);  
  rect (0, 0, 15, 15);  
}
```

//Isolating Transformations

```
void setup() {  
  size (200, 200);  
}  
  
void draw() {  
  pushMatrix(); //isolating the big rectangle  
  translate (mouseX, mouseY);  
  rect(0, 0, 30, 30);  
  popMatrix();  
  
  translate (35, 10);  
  rect (0, 0, 15, 15);  
}
```

if

you want the transformation to propagate -
for each transformation to build on the last.

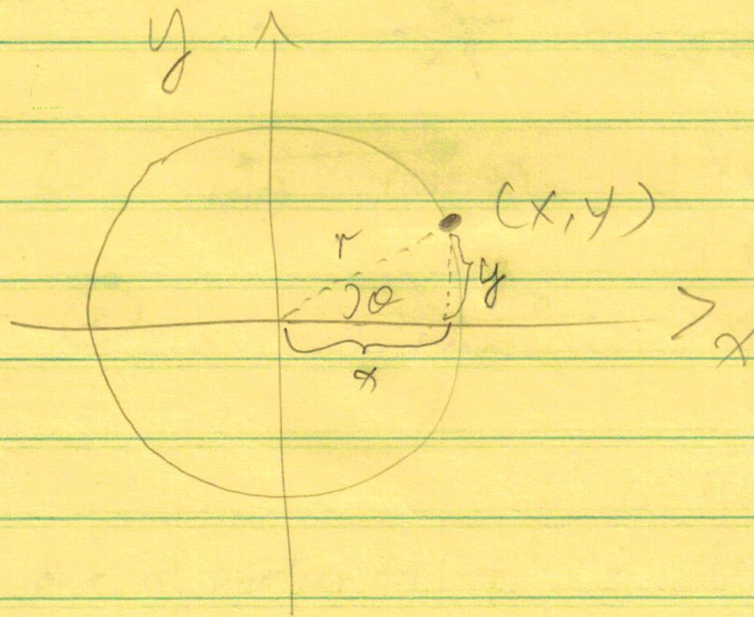
don't use Push/Pop matrix!

a fun example on push pop

sketch_14_17_nested_pushpop.pde

p.292

first: a little math



$$\sin \theta = \frac{y}{r} \Rightarrow y = \sin \theta \cdot r$$
$$\cos \theta = \frac{x}{r} \Rightarrow x = \cos \theta \cdot r$$

point (x, y)

fixed r

changing θ

for. ($\theta=0$, $\theta < 360$, $\theta++$)

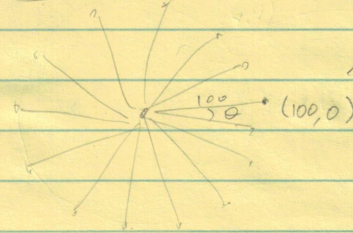
logic for
 sketch_14_17_nested
 _pushpop.pde

page 292 Shiffman Book

i step size
 $3.14 \times 2 \div 0.2$

better use
 degree

? Lines



draw line always at $(100, 0)$
 fixed $r = 100$
 rotating θ (rotating coordinates)
 about $(0, 0)$

Carrier
 (Space ship)

1. push a set of coordinates in
2. rotate θ amount
3. draw a line at $(0, 0, 100, 0)$
4. pop to reset coordinates

idea of a
 for loop.
 stepping i
 20 times!

1. push a set of coordinates in
2. rotate $\theta + i$ amount
- * 3. draw a line at $(0, 0, 100, 0)$
4. draw a small group of lines at $(100, 0)$
5. pop to reset coordinates

for (float i=0; i<Two-PI; i+=0.2)

inner loop.

① $(0,0)$ $(100,0)$

translate $(100, 0)$

② $(100,0)$ $(100,50)$

fixed $r = 50$

rotate θ at $(100, 0)$

idea of another for loop
 stepping j X times

for (float j=0; j<Two-PI; j+=0.5)

1. push
2. translate $(100, 0)$
3. rotate $-(\theta + j)$
4. line $(0, 0, 50, 0)$ (new coordinates)
5. pop

create an illusion for motion, otherwise each draw
 goes on top of each other, and you can see motion.

$\theta += 0.01$ (can't see the tiny amount, will see motion)

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