

Devicetree Specification

Release v0.4

devicetree.org

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We would also like to acknowledge the contribution of the PowerPC and ARM Linux communities that developed and implemented the flattened devicetree concept.

Table 1: Revision History

Revision	Date	Description
0.1	2016-MAY-24	Initial prerelease version. Imported ePAPR text into reStructured Text format and removed Power ISA specific elements.
0.2	2017-DEC-20	<ul style="list-style-type: none">• Added more recommended generic node names• Added interrupts-extended• Additional phy times• Filled out detail in source language chapter• Editorial changes• Added changebar version to release documents
0.3	2020-FEB-13	<ul style="list-style-type: none">• Added more recommended generic node names• Document generic nexus binding• codespell support and spelling fixes

INTRODUCTION

1.1 Purpose and Scope

To initialize and boot a computer system, various software components interact. Firmware might perform low-level initialization of the system hardware before passing control to software such as an operating system, bootloader, or hypervisor. Bootloaders and hypervisors can, in turn, load and transfer control to operating systems. Standard, consistent interfaces and conventions facilitate the interactions between these software components. In this document the term *boot program* is used to generically refer to a software component that initializes the system state and executes another software component referred to as a *client program*. Examples of a boot program include: firmware, bootloaders, and hypervisors. Examples of a client program include: bootloaders, hypervisors, operating systems, and special purpose programs. A piece of software may be both a client program and a boot program (e.g. a hypervisor).

This specification, the Devicetree Specification (DTSpec), provides a complete boot program to client program interface definition, combined with minimum system requirements that facilitate the development of a wide variety of systems.

This specification is targeted towards the requirements of embedded systems. An embedded system typically consists of system hardware, an operating system, and application software that are custom designed to perform a fixed, specific set of tasks. This is unlike general purpose computers, which are designed to be customized by a user with a variety of software and I/O devices. Other characteristics of embedded systems may include:

- a fixed set of I/O devices, possibly highly customized for the application
- a system board optimized for size and cost
- limited user interface
- resource constraints like limited memory and limited nonvolatile storage
- real-time constraints
- use of a wide variety of operating systems, including Linux, real-time operating systems, and custom or proprietary operating systems

Organization of this Document

- [Chapter 1](#) introduces the architecture being specified by DTSpec.
- [Chapter 2](#) introduces the devicetree concept and describes its logical structure and standard properties.
- [Chapter 3](#) specifies the definition of a base set of device nodes required by DTSpec-compliant devicetrees.
- [Chapter 4](#) describes device bindings for certain classes of devices and specific device types.
- [Chapter 5](#) specifies the DTB encoding of devicetrees.
- [Chapter 6](#) specifies the DTS source language.

Conventions Used in this Document

The word *shall* is used to indicate mandatory requirements strictly to be followed in order to conform to the standard and from which no deviation is permitted (*shall* equals *is required to*).

The word *should* is used to indicate that among several possibilities one is recommended as particularly suitable, without mentioning or excluding others; or that a certain course of action is preferred but not necessarily required; or that (in the negative form) a certain course of action is deprecated but not prohibited (*should* equals *is recommended that*).

The word *may* is used to indicate a course of action permissible within the limits of the standard (*may* equals *is permitted*).

Examples of devicetree constructs are frequently shown in *Devicetree Syntax* form. See [Section 6](#) for an overview of this syntax.

1.2 Relationship to IEEE™ 1275 and ePAPR

DTSpec is loosely related to the IEEE 1275 Open Firmware standard—*IEEE Standard for Boot (Initialization Configuration) Firmware: Core Requirements and Practices* [[IEEE1275](#)].

The original IEEE 1275 specification and its derivatives such as CHRP [[CHRP](#)] and PAPR [[PAPR](#)] address problems of general purpose computers, such as how a single version of an operating system can work on several different computers within the same family and the problem of loading an operating system from user-installed I/O devices.

Because of the nature of embedded systems, some of these problems faced by open, general purpose computers do not apply. Notable features of the IEEE 1275 specification that are omitted from the DTSpec include:

- Plug-in device drivers
- FCode
- The programmable Open Firmware user interface based on Forth
- FCode debugging
- Operating system debugging

What is retained from IEEE 1275 are concepts from the devicetree architecture by which a boot program can describe and communicate system hardware information to a client program, thus eliminating the need for the client program to have hard-coded descriptions of system hardware.

This specification partially supersedes the ePAPR [[ePAPR](#)] specification. ePAPR documents how devicetree is used by the Power ISA, and covers both general concepts, as well as Power ISA specific bindings. The text of this document was derived from ePAPR, but either removes architecture specific bindings, or moves them into an appendix.

1.3 32-bit and 64-bit Support

The DTSpec supports CPUs with both 32-bit and 64-bit addressing capabilities. Where applicable, sections of the DTSpec describe any requirements or considerations for 32-bit and 64-bit addressing.

1.4 Definition of Terms

AMP

Asymmetric Multiprocessing. Computer available CPUs are partitioned into groups, each running a distinct operating system image. The CPUs may or may not be identical.

boot CPU

The first CPU which a boot program directs to a client program's entry point.

Book III-E

Embedded Environment. Section of the Power ISA defining supervisor instructions and related facilities used in embedded Power processor implementations.

boot program

Used to generically refer to a software component that initializes the system state and executes another software

component referred to as a client program. Examples of a boot program include: firmware, bootloaders, and hypervisors.

client program

Program that typically contains application or operating system software. Examples of a client program include: bootloaders, hypervisors, operating systems, and special purpose programs.

cell

A unit of information consisting of 32 bits.

DMA

Direct memory access

DTB

Devicetree blob. Compact binary representation of the devicetree.

DTC

Devicetree compiler. An open source tool used to create DTB files from DTS files.

DTS

Devicetree syntax. A textual representation of a devicetree consumed by the DTC. See Appendix A Devicetree Source Format (version 1).

effective address

Memory address as computed by processor storage access or branch instruction.

physical address

Address used by the processor to access external device, typically a memory controller.

Power ISA

Power Instruction Set Architecture.

interrupt specifier

A property value that describes an interrupt. Typically information that specifies an interrupt number and sensitivity and triggering mechanism is included.

secondary CPU

CPUs other than the boot CPU that belong to the client program are considered *secondary CPUs*.

SMP

Symmetric multiprocessing. A computer architecture where two or more identical CPUs can share memory and IO and operate under a single operating system.

SoC

System on a chip. A single computer chip integrating one or more CPU core as well as number of other peripherals.

unit address

The part of a node name specifying the node's address in the address space of the parent node.

quiescent CPU

A quiescent CPU is in a state where it cannot interfere with the normal operation of other CPUs, nor can its state be affected by the normal operation of other running CPUs, except by an explicit method for enabling or re-enabling the quiescent CPU.

THE DEVICETREE

2.1 Overview

DTSpec specifies a construct called a *devicetree* to describe system hardware. A boot program loads a devicetree into a client program's memory and passes a pointer to the devicetree to the client.

This chapter describes the logical structure of the devicetree and specifies a base set of properties for use in describing device nodes. [Chapter 3](#) specifies certain device nodes required by a DTSpec-compliant devicetree. [Chapter 4](#) describes the DTSpec-defined device bindings – the requirements for representing certain device types or classes of devices. [Chapter 5](#) describes the in-memory encoding of the devicetree.

A devicetree is a tree data structure with nodes that describe the devices in a system. Each node has property/value pairs that describe the characteristics of the device being represented. Each node has exactly one parent except for the root node, which has no parent.

A device in this context may be an actual hardware device, such as a UART. It may be part of a hardware device, such as the random-number generator in a TPM. It may also be a device provided through virtualisation, such as a protocol providing access to an I2C device attached to a remote CPU. A device may include functions implemented by firmware running in higher privilege levels or remote processors. There is no requirement that nodes in a device tree be a physical hardware device, but generally they have some correlation to physical hardware devices. Nodes should not be designed for OS- or project- specific purposes. They should describe something which can be implemented by any OS or project.

A devicetree is often used to describe devices which cannot necessarily be dynamically detected by a client program. For example, the architecture of PCI enables a client to probe and detect attached devices and thus devicetree nodes describing PCI devices might not be required. However, a device node is often used to describe a PCI host bridge device in the system. This node is required if the bridge cannot be detected by probing, but is otherwise optional. Also, a bootloader may do PCI probing and produce a device tree containing the results of its scan, for passing to the Operating System.

Example

[Fig. 2.1](#) shows an example representation of a simple devicetree that is nearly complete enough to boot a simple operating system, with the platform type, CPU, memory and a single UART described. Device nodes are shown with properties and values inside each node.

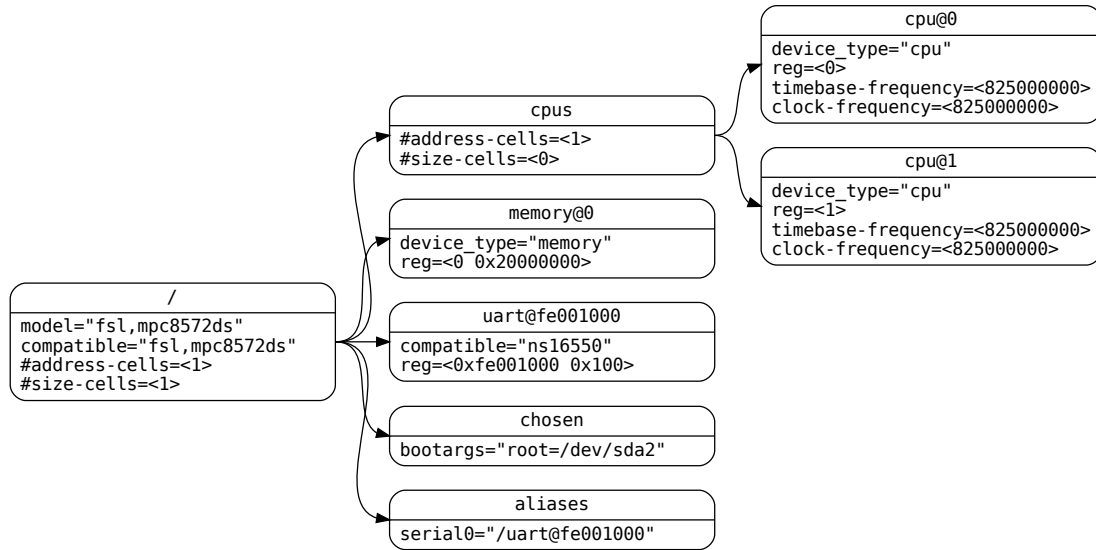


Fig. 2.1: Devicetree Example

2.2 Devicetree Structure and Conventions

2.2.1 Node Names

Node Name Requirements

Each node in the devicetree is named according to the following convention:

`node-name@unit-address`

The *node-name* component specifies the name of the node. It shall be 1 to 31 characters in length and consist solely of characters from the set of characters in Table 2.1.

Table 2.1: Valid characters for node names

Character	Description
0-9	digit
a-z	lowercase letter
A-Z	uppercase letter
,	comma
.	period
_	underscore
+	plus sign
-	dash

The *node-name* shall start with a lower or uppercase character and should describe the general class of device.

The *unit-address* component of the name is specific to the bus type on which the node sits. It consists of one or more ASCII characters from the set of characters in Table 2.1. **The unit-address must match the first address specified in the *reg* property of the node.** If the node has no *reg* property, the *@unit-address* must be omitted and the *node-name* alone differentiates the

node from other nodes at the same level in the tree. The binding for a particular bus may specify additional, more specific requirements for the format of *reg* and the *unit-address*.

In the case of *node-name* without an *@unit-address* the *node-name* shall be unique from any property names at the same level in the tree.

The root node does not have a node-name or unit-address. It is identified by a forward slash (/).

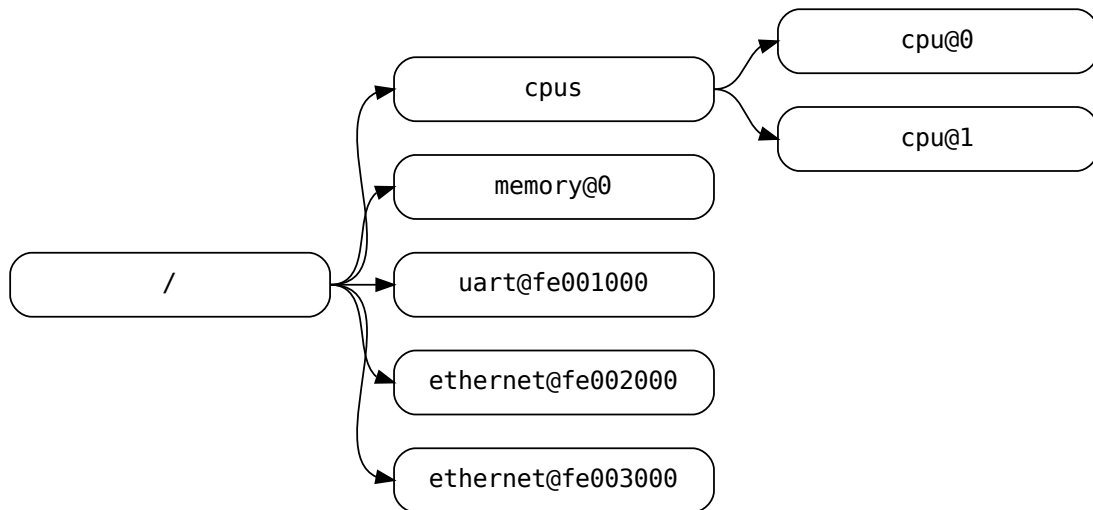


Fig. 2.2: Examples of Node Names

In Fig. 2.2:

- The nodes with the name `cpu` are distinguished by their unit-address values of 0 and 1.
- The nodes with the name `ethernet` are distinguished by their unit-address values of `fe002000` and `fe003000`.

2.2.2 Generic Names Recommendation

The name of a node should be somewhat generic, reflecting the function of the device and not its precise programming model. If appropriate, the name should be one of the following choices:

- | | | |
|------------------------|--------------------|------------------------|
| • adc | • clock-controller | • ethernet |
| • accelerometer | • co2-sensor | • ethernet-phy |
| • air-pollution-sensor | • compact-flash | • fdcc |
| • atm | • cpu | • flash |
| • audio-codec | • cpus | • gnss |
| • audio-controller | • crypto | • gpio |
| • backlight | • disk | • gpu |
| • bluetooth | • display | • gyrometer |
| • bus | • dma-controller | • hdmi |
| • cache-controller | • dsi | • hwlock |
| • camera | • dsp | • i2c |
| • can | • eeprom | • i2c-mux |
| • charger | • efuse | • ide |
| • clock | • endpoint | • interrupt-controller |

- iommu
- isa
- keyboard
- key
- keys
- lcd-controller
- led
- leds
- led-controller
- light-sensor
- lora
- magnetometer
- mailbox
- mdio
- memory
- memory-controller
- mmc
- mmc-slot
- mouse
- nand-controller
- nvram
- oscillator
- parallel
- pc-card
- pci
- pcie
- phy
- pinctrl
- pmic
- pmu
- port
- ports
- power-monitor
- pwm
- regulator
- reset-controller
- rng
- rtc
- sata
- scsi
- serial
- sound
- spi
- spmi
- sram-controller
- ssi-controller
- syscon
- temperature-sensor
- timer
- touchscreen
- tpm
- usb
- usb-hub
- usb-phy
- vibrator
- video-codec
- vme
- watchdog
- wifi

2.2.3 Path Names

A node in the devicetree can be uniquely identified by specifying the full path from the root node, through all descendant nodes, to the desired node.

The convention for specifying a device path is:

/node-name-1/node-name-2/node-name-N

For example, in [Fig. 2.2](#), the device path to cpu #1 would be:

/cpus/cpu@1

The path to the root node is `/`.

A unit address may be omitted if the full path to the node is unambiguous.

If a client program encounters an ambiguous path, its behavior is undefined.

2.2.4 Properties

Each node in the devicetree has properties that describe the characteristics of the node. Properties consist of a name and a value.

Property Names

Property names are strings of 1 to 31 characters from the characters show in [Table 2.2](#)

Table 2.2: Valid characters for property names

Character	Description
0-9	digit
a-z	lowercase letter
A-Z	uppercase letter
,	comma
.	period
_	underscore
+	plus sign
?	question mark
#	hash
-	dash

Nonstandard property names should specify a unique string prefix, such as a stock ticker symbol, identifying the name of the company or organization that defined the property. Examples:

```
fsl,channel-fifo-len
ibm,ppc-interrupt-server#s
linux,network-index
```

Property Values

A property value is an array of zero or more bytes that contain information associated with the property.

Properties might have an empty value if conveying true-false information. In this case, the presence or absence of the property is sufficiently descriptive.

Table 2.3 describes the set of basic value types defined by the DTSpec.

Table 2.3: Property values

Value	Description								
<empty>	Value is empty. Used for conveying true-false information, when the presence or absence of the property itself is sufficiently descriptive.								
<u32>	<p>A 32-bit integer in big-endian format. Example: the 32-bit value 0x11223344 would be represented in memory as:</p> <table> <tr> <td>address</td><td>11</td></tr> <tr> <td>address+1</td><td>22</td></tr> <tr> <td>address+2</td><td>33</td></tr> <tr> <td>address+3</td><td>44</td></tr> </table>	address	11	address+1	22	address+2	33	address+3	44
address	11								
address+1	22								
address+2	33								
address+3	44								

continues on next page

Table 2.3 – continued from previous page

Value	Description
<u64>	<p>Represents a 64-bit integer in big-endian format. Consists of two <u32> values where the first value contains the most significant bits of the integer and the second value contains the least significant bits.</p> <p>Example: the 64-bit value 0x1122334455667788 would be represented as two cells as: <0x11223344 0x55667788>.</p> <p>The value would be represented in memory as:</p> <pre> address 11 address+1 22 address+2 33 address+3 44 address+4 55 address+5 66 address+6 77 address+7 88 </pre>
<string>	<p>Strings are printable and null-terminated. Example: the string “hello” would be represented in memory as:</p> <pre> address 68 'h' address+1 65 'e' address+2 6C 'l' address+3 6C 'l' address+4 6F 'o' address+5 00 '\0' </pre>
<prop-encoded-array>	Format is specific to the property. See the property definition.
<phandle>	<p>A <u32> value. A <i>phandle</i> value is a way to reference another node in the devicetree. Any node that can be referenced defines a phandle property with a unique <u32> value. That number is used for the value of properties with a phandle value type.</p>
<stringlist>	<p>A list of <string> values concatenated together.</p> <p>Example: The string list “hello,” “world” would be represented in memory as:</p> <pre> address 68 'h' address+1 65 'e' address+2 6C 'l' address+3 6C 'l' address+4 6F 'o' address+5 00 '\0' address+6 77 'w' address+7 6f 'o' address+8 72 'r' address+9 6C 'l' address+10 64 'd' address+11 00 '\0' </pre>

2.3 Standard Properties

DTSpec specifies a set of standard properties for device nodes. These properties are described in detail in this section. Device nodes defined by DTSpec (see [Chapter 3](#)) may specify additional requirements or constraints regarding the use of the standard properties. [Chapter 4](#) describes the representation of specific devices and may also specify additional requirements.

Note: All examples of devicetree nodes in this document use the DTS (Devicetree Source) format for specifying nodes and properties.

2.3.1 compatible

Property name: `compatible`

Value type: `<stringlist>`

Description:

The *compatible* property value consists of one or more strings that define the specific programming model for the device. This list of strings should be used by a client program for device driver selection. The property value consists of a concatenated list of null terminated strings, from most specific to most general. They allow a device to express its compatibility with a family of similar devices, potentially allowing a single device driver to match against several devices.

The recommended format is "`manufacturer,model`", where `manufacturer` is a string describing the name of the manufacturer (such as a stock ticker symbol), and `model` specifies the model number.

The compatible string should consist only of lowercase letters, digits and dashes, and should start with a letter. A single comma is typically only used following a vendor prefix. Underscores should not be used.

Example:

```
compatible = "fsl,mpc8641", "ns16550";
```

In this example, an operating system would first try to locate a device driver that supported `fsl,mpc8641`. If a driver was not found, it would then try to locate a driver that supported the more general `ns16550` device type.

2.3.2 model

Property name: `model`

Value type: `<string>`

Description:

The model property value is a `<string>` that specifies the manufacturer's model number of the device.

The recommended format is: "`manufacturer,model`", where `manufacturer` is a string describing the name of the manufacturer (such as a stock ticker symbol), and `model` specifies the model number.

Example:

```
model = "fsl,MPC8349EMITX";
```

2.3.3 phandle

Property name: `phandle`

Value type: `<u32>`

Description:

The *phandle* property specifies a numerical identifier for a node that is unique within the devicetree. The *phandle* property value is used by other nodes that need to refer to the node associated with the property.

Example:

See the following devicetree excerpt:

```
pic@100000000 {
    phandle = <1>;
    interrupt-controller;
    reg = <0x100000000 0x100>;
};
```

A *phandle* value of 1 is defined. Another device node could reference the `pic` node with a *phandle* value of 1:

```
another-device-node {
    interrupt-parent = <1>;
};
```

Note: Older versions of devicetrees may be encountered that contain a deprecated form of this property called `linux,phandle`. For compatibility, a client program might want to support `linux,phandle` if a `phandle` property is not present. The meaning and use of the two properties is identical.

Note: Most devicetrees in DTS (see Appendix A) will not contain explicit *phandle* properties. The DTC tool automatically inserts the *phandle* properties when the DTS is compiled into the binary DTB format.

2.3.4 status

Property name: `status`

Value type: `<string>`

Description:

The *status* property indicates the operational status of a device. The lack of a *status* property should be treated as if the property existed with the value of "okay". Valid values are listed and defined in [Table 2.4](#).

Table 2.4: Values for status property

Value	Description
"okay"	Indicates the device is operational.
"disabled"	Indicates that the device is not presently operational, but it might become operational in the future (for example, something is not plugged in, or switched off). Refer to the device binding for details on what disabled means for a given device.
"reserved"	Indicates that the device is operational, but should not be used. Typically this is used for devices that are controlled by another software component, such as platform firmware.
"fail"	Indicates that the device is not operational. A serious error was detected in the device, and it is unlikely to become operational without repair.
"fail-sss"	Indicates that the device is not operational. A serious error was detected in the device and it is unlikely to become operational without repair. The <i>sss</i> portion of the value is specific to the device and indicates the error condition detected.

2.3.5 #address-cells and #size-cells

Property name: #address-cells, #size-cells

Value type: <u32>

Description:

The #address-cells and #size-cells properties may be used in any device node that has children in the devicetree hierarchy and describes how child device nodes should be addressed. The #address-cells property defines the number of <u32> cells used to encode the address field in a child node's *reg* property. The #size-cells property defines the number of <u32> cells used to encode the size field in a child node's *reg* property.

The #address-cells and #size-cells properties are not inherited from ancestors in the devicetree. They shall be explicitly defined.

A DTSPEC-compliant boot program shall supply #address-cells and #size-cells on all nodes that have children.

If missing, a client program should assume a default value of 2 for #address-cells, and a value of 1 for #size-cells.

Example:

See the following devicetree excerpt:

```
soc {
    #address-cells = <1>;
    #size-cells = <1>;

    serial@4600 {
        compatible = "ns16550";
        reg = <0x4600 0x100>;
        clock-frequency = <0>;
        interrupts = <0xA 0x8>;
        interrupt-parent = <&ipic>;
    };
};
```

In this example, the #address-cells and #size-cells properties of the soc node are both set to 1. This setting specifies that one cell is required to represent an address and one cell is required to represent the size of nodes that are children of this node.

The serial device *reg* property necessarily follows this specification set in the parent (soc) node—the address is represented by a single cell (0x4600), and the size is represented by a single cell (0x100).

2.3.6 reg

Property name: `reg`

Property value: `<prop-encoded-array>` encoded as an arbitrary number of (*address*, *length*) pairs.

Description:

The *reg* property describes the address of the device's resources within the address space defined by its parent bus. Most commonly this means the offsets and lengths of memory-mapped IO register blocks, but may have a different meaning on some bus types. **Addresses in the address space defined by the root node are CPU real addresses.**

The value is a `<prop-encoded-array>`, composed of an arbitrary number of pairs of address and length, `<address length>`. The number of `<u32>` cells required to specify the address and length are bus-specific and are specified by the `#address-cells` and `#size-cells` properties in the parent of the device node. If the parent node specifies a value of 0 for `#size-cells`, the length field in the value of *reg* shall be omitted.

Example:

Suppose a device within a system-on-a-chip had two blocks of registers, a 32-byte block at offset 0x3000 in the SOC and a 256-byte block at offset 0xFE00. The *reg* property would be encoded as follows (assuming `#address-cells` and `#size-cells` values of 1):

```
reg = <0x3000 0x20 0xFE00 0x100>;
```

2.3.7 virtual-reg

Property name: `virtual-reg`

Value type: `<u32>`

Description:

The *virtual-reg* property specifies an effective address that maps to the first physical address specified in the *reg* property of the device node. This property enables boot programs to provide client programs with virtual-to-physical mappings that have been set up.

2.3.8 ranges

Property name: `ranges`

Value type: `<empty>` or `<prop-encoded-array>` encoded as an arbitrary number of (*child-bus-address*, *parent-bus-address*, *length*) triplets.

Description:

The *ranges* property provides a means of defining a mapping or translation between the address space of the bus (the child address space) and the address space of the bus node's parent (the parent address space).

The format of the value of the *ranges* property is an arbitrary number of triplets of (*child-bus-address*, *parent-bus-address*, *length*)

- The *child-bus-address* is a physical address within the child bus' address space. The number of cells to represent the address is bus dependent and can be determined from the `#address-cells` of this node (the node in which the *ranges* property appears).
- The *parent-bus-address* is a physical address within the parent bus' address space. The number of cells to represent the parent address is bus dependent and can be determined from the `#address-cells` property of the node that defines the parent's address space.
- The *length* specifies the size of the range in the child's address space. The number of cells to represent the size can be determined from the `#size-cells` of this node (the node in which the *ranges* property appears).

If the property is defined with an `<empty>` value, it specifies that the parent and child address space is identical, and no address translation is required.

If the property is not present in a bus node, it is assumed that no mapping exists between children of the node and the parent address space.

Address Translation Example:

```
soc {
    compatible = "simple-bus";
    #address-cells = <1>;
    #size-cells = <1>;
    ranges = <0x0 0xe0000000 0x00100000>;

    serial@4600 {
        device_type = "serial";
        compatible = "ns16550";
        reg = <0x4600 0x100>;
        clock-frequency = <0>;
        interrupts = <0xA 0x8>;
        interrupt-parent = <&ipic>;
    };
};
```

The soc node specifies a *ranges* property of

```
<0x0 0xe0000000 0x00100000>;
```

This property value specifies that for a 1024 KB range of address space, a child node addressed at physical 0x0 maps to a parent address of physical 0xe0000000. With this mapping, the `serial` device node can be addressed by a load or store at address 0xe0004600, an offset of 0x4600 (specified in *reg*) plus the 0xe0000000 mapping specified in *ranges*.

2.3.9 dma-ranges

Property name: `dma-ranges`

Value type: `<empty>` or `<prop-encoded-array>` encoded as an arbitrary number of (*child-bus-address*, *parent-bus-address*, *length*) triplets.

Description:

The *dma-ranges* property is used to describe the direct memory access (DMA) structure of a memory-mapped bus whose devicetree parent can be accessed from DMA operations originating from the bus. It provides a means of defining a mapping or translation between the physical address space of the bus and the physical address space of the parent of the bus.

The format of the value of the *dma-ranges* property is an arbitrary number of triplets of (*child-bus-address*, *parent-bus-address*, *length*). Each triplet specified describes a contiguous DMA address range.

- The *child-bus-address* is a physical address within the child bus' address space. The number of cells to represent the address depends on the bus and can be determined from the *#address-cells* of this node (the node in which the *dma-ranges* property appears).
- The *parent-bus-address* is a physical address within the parent bus' address space. The number of cells to represent the parent address is bus dependent and can be determined from the *#address-cells* property of the node that defines the parent's address space.
- The *length* specifies the size of the range in the child's address space. The number of cells to represent the size can be determined from the *#size-cells* of this node (the node in which the *dma-ranges* property appears).

2.3.10 dma-coherent

Property name: `dma-coherent`

Value type: `<empty>`

Description:

For architectures which are by default non-coherent for I/O, the *dma-coherent* property is used to indicate a device is capable of coherent DMA operations. Some architectures have coherent DMA by default and this property is not applicable.

2.3.11 dma-noncoherent

Property name: `dma-noncoherent`

Value type: `<empty>`

Description:

For architectures which are by default coherent for I/O, the *dma-noncoherent* property is used to indicate a device is not capable of coherent DMA operations. Some architectures have non-coherent DMA by default and this property is not applicable.

2.3.12 name (deprecated)

Property name: `name`

Value type: `<string>`

Description:

The *name* property is a string specifying the name of the node. This property is deprecated, and its use is not recommended. However, it might be used in older non-DTSpec-compliant devicetrees. Operating system should determine a node's name based on the *node-name* component of the node name (see [Section 2.2.1](#)).

2.3.13 device_type (deprecated)

Property name: `device_type`

Value type: `<string>`

Description:

The *device_type* property was used in IEEE 1275 to describe the device's FCode programming model. Because DTSpec does not have FCode, new use of the property is deprecated, and it should be included only on `cpu` and `memory` nodes for compatibility with IEEE 1275-derived devicetrees.

2.4 Interrupts and Interrupt Mapping

DTSpec adopts the interrupt tree model of representing interrupts specified in *Open Firmware Recommended Practice: Interrupt Mapping, Version 0.9* [b7]. Within the devicetree a logical interrupt tree exists that represents the hierarchy and routing of interrupts in the platform hardware. While generically referred to as an interrupt tree it is more technically a directed acyclic graph.

The physical wiring of an interrupt source to an interrupt controller is represented in the devicetree with the *interrupt-parent* property. Nodes that represent interrupt-generating devices contain an *interrupt-parent* property which has a *phandle* value that points to the device to which the device's interrupts are routed, typically an interrupt controller. If an interrupt-generating device does not have an *interrupt-parent* property, its interrupt parent is assumed to be its devicetree parent.

Each interrupt generating device contains an *interrupts* property with a value describing one or more interrupt sources for that device. Each source is represented with information called an *interrupt specifier*. The format and meaning of an

interrupt specifier is interrupt domain specific, i.e., it is dependent on properties on the node at the root of its interrupt domain. The `#interrupt-cells` property is used by the root of an interrupt domain to define the number of <u32> values needed to encode an interrupt specifier. For example, for an Open PIC interrupt controller, an interrupt-specifier takes two 32-bit values and consists of an interrupt number and level/sense information for the interrupt.

An interrupt domain is the context in which an interrupt specifier is interpreted. The root of the domain is either (1) an interrupt controller or (2) an interrupt nexus.

1. An *interrupt controller* is a physical device and will need a driver to handle interrupts routed through it. It may also cascade into another interrupt domain. An interrupt controller is specified by the presence of an *interrupt-controller* property on that node in the devicetree.
2. An *interrupt nexus* defines a translation between one interrupt domain and another. The translation is based on both domain-specific and bus-specific information. This translation between domains is performed with the *interrupt-map* property. For example, a PCI controller device node could be an interrupt nexus that defines a translation from the PCI interrupt namespace (INTA, INTB, etc.) to an interrupt controller with Interrupt Request (IRQ) numbers.

The root of the interrupt tree is determined when traversal of the interrupt tree reaches an interrupt controller node without an *interrupts* property and thus no explicit interrupt parent.

See Fig. 2.3 for an example of a graphical representation of a devicetree with interrupt parent relationships shown. It shows both the natural structure of the devicetree as well as where each node sits in the logical interrupt tree.

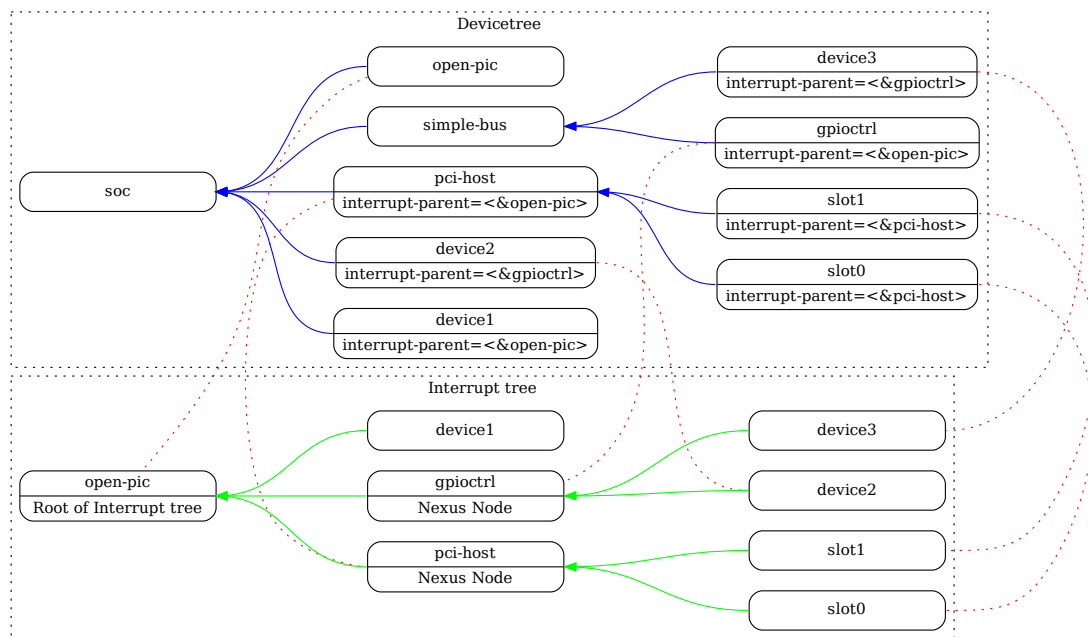


Fig. 2.3: Example of the interrupt tree

In the example shown in Fig. 2.3:

- The `open-pic` interrupt controller is the root of the interrupt tree.
- The interrupt tree root has three children—devices that route their interrupts directly to the `open-pic`
 - `device1`
 - PCI host controller

- GPIO Controller
- Three interrupt domains exist; one rooted at the `open-pic` node, one at the `PCI host bridge` node, and one at the `GPIO Controller` node.
- There are two nexus nodes; one at the `PCI host bridge` and one at the `GPIO controller`.

2.4.1 Properties for Interrupt Generating Devices

interrupts

Property: `interrupts`

Value type: `<prop-encoded-array>` encoded as arbitrary number of interrupt specifiers

Description:

The *interrupts* property of a device node defines the interrupt or interrupts that are generated by the device. The value of the *interrupts* property consists of an arbitrary number of interrupt specifiers. The format of an interrupt specifier is defined by the binding of the interrupt domain root.

interrupts is overridden by the *interrupts-extended* property and normally only one or the other should be used.

Example:

A common definition of an interrupt specifier in an open PIC-compatible interrupt domain consists of two cells; an interrupt number and level/sense information. See the following example, which defines a single interrupt specifier, with an interrupt number of `0xA` and level/sense encoding of `8`.

```
interrupts = <0xA 8>;
```

interrupt-parent

Property: `interrupt-parent`

Value type: `<phandle>`

Description:

Because the hierarchy of the nodes in the interrupt tree might not match the devicetree, the *interrupt-parent* property is available to make the definition of an interrupt parent explicit. The value is the phandle to the interrupt parent. If this property is missing from a device, its interrupt parent is assumed to be its devicetree parent.

interrupts-extended

Property: `interrupts-extended`

Value type: `<phandle>` `<prop-encoded-array>`

Description:

The *interrupts-extended* property lists the interrupt(s) generated by a device. *interrupts-extended* should be used instead of *interrupts* when a device is connected to multiple interrupt controllers as it encodes a parent phandle with each interrupt specifier.

Example:

This example shows how a device with two interrupt outputs connected to two separate interrupt controllers would describe the connection using an *interrupts-extended* property. `pic` is an interrupt controller with an *#interrupt-cells* specifier of `2`, while `gic` is an interrupt controller with an *#interrupt-cells* specifier of `1`.

```
interrupts-extended = <&pic 0xA 8>, <&gic 0xda>;
```

The *interrupts* and *interrupts-extended* properties are mutually exclusive. A device node should use one or the other, but not both. Using both is only permissible when required for compatibility with software that does not understand *interrupts-extended*. If both *interrupts-extended* and *interrupts* are present then *interrupts-extended* takes precedence.

2.4.2 Properties for Interrupt Controllers

#interrupt-cells

Property: `#interrupt-cells`

Value type: `<u32>`

Description:

The *#interrupt-cells* property defines the number of cells required to encode an interrupt specifier for an interrupt domain.

interrupt-controller

Property: `interrupt-controller`

Value type: `<empty>`

Description:

The presence of an *interrupt-controller* property defines a node as an interrupt controller node.

2.4.3 Interrupt Nexus Properties

An interrupt nexus node shall have an *#interrupt-cells* property.

interrupt-map

Property: `interrupt-map`

Value type: `<prop-encoded-array>` encoded as an arbitrary number of interrupt mapping entries.

Description:

An *interrupt-map* is a property on a nexus node that bridges one interrupt domain with a set of parent interrupt domains and specifies how interrupt specifiers in the child domain are mapped to their respective parent domains.

The interrupt map is a table where each row is a mapping entry consisting of five components: *child unit address*, *child interrupt specifier*, *interrupt-parent*, *parent unit address*, *parent interrupt specifier*.

child unit address

The unit address of the child node being mapped. The number of 32-bit cells required to specify this is described by the *#address-cells* property of the bus node on which the child is located.

child interrupt specifier

The interrupt specifier of the child node being mapped. The number of 32-bit cells required to specify this component is described by the *#interrupt-cells* property of this node—the nexus node containing the *interrupt-map* property.

interrupt-parent

A single `<phandle>` value that points to the interrupt parent to which the child domain is being mapped.

parent unit address

The unit address in the domain of the interrupt parent. The number of 32-bit cells required to specify this address is described by the *#address-cells* property of the node pointed to by the *interrupt-parent* field.

parent interrupt specifier

The interrupt specifier in the parent domain. The number of 32-bit cells required to specify this component is described by the *#interrupt-cells* property of the node pointed to by the *interrupt-parent* field.

Lookups are performed on the interrupt mapping table by matching a unit-address/interrupt specifier pair against the child components in the *interrupt-map*. Because some fields in the unit interrupt specifier may not be relevant, a mask is applied before the lookup is done. This mask is defined in the *interrupt-map-mask* property (see [Section 2.4.3](#)).

Note: Both the child node and the interrupt parent node are required to have *#address-cells* and *#interrupt-cells* properties defined. If a unit address component is not required, *#address-cells* shall be explicitly defined to be zero.

interrupt-map-mask

Property: *interrupt-map-mask*

Value type: <prop-encoded-array> encoded as a bit mask

Description:

An *interrupt-map-mask* property is specified for a nexus node in the interrupt tree. This property specifies a mask that is ANDed with the incoming unit interrupt specifier being looked up in the table specified in the *interrupt-map* property.

#interrupt-cells

Property: *#interrupt-cells*

Value type: <u32>

Description:

The *#interrupt-cells* property defines the number of cells required to encode an interrupt specifier for an interrupt domain.

2.4.4 Interrupt Mapping Example

The following shows the representation of a fragment of a devicetree with a PCI bus controller and a sample interrupt map for describing the interrupt routing for two PCI slots (IDSEL 0x11,0x12). The INTA, INTB, INTC, and INTD pins for slots 1 and 2 are wired to the Open PIC interrupt controller.

```
soc {
    compatible = "simple-bus";
    #address-cells = <1>;
    #size-cells = <1>;

    open-pic {
        clock-frequency = <0>;
        interrupt-controller;
        #address-cells = <0>;
        #interrupt-cells = <2>;
    };

    pci {
        #interrupt-cells = <1>;
        #size-cells = <2>;
```

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```

#address-cells = <3>;
interrupt-map-mask = <0xf800 0 0 7>;
interrupt-map = <
    /* IDSEL 0x11 - PCI slot 1 */
    0x8800 0 0 1 &open-pic 2 1 /* INTA */
    0x8800 0 0 2 &open-pic 3 1 /* INTB */
    0x8800 0 0 3 &open-pic 4 1 /* INTC */
    0x8800 0 0 4 &open-pic 1 1 /* INTD */
    /* IDSEL 0x12 - PCI slot 2 */
    0x9000 0 0 1 &open-pic 3 1 /* INTA */
    0x9000 0 0 2 &open-pic 4 1 /* INTB */
    0x9000 0 0 3 &open-pic 1 1 /* INTC */
    0x9000 0 0 4 &open-pic 2 1 /* INTD */
>;
};
};

```

One Open PIC interrupt controller is represented and is identified as an interrupt controller with an *interrupt-controller* property.

Each row in the interrupt-map table consists of five parts: a child unit address and interrupt specifier, which is mapped to an *interrupt-parent* node with a specified parent unit address and interrupt specifier.

- For example, the first row of the interrupt-map table specifies the mapping for INTA of slot 1. The components of that row are shown here

child unit address: 0x8800 0 0

child interrupt specifier: 1

interrupt parent: &open-pic

parent unit address: (empty because #address-cells = <0> in the open-pic node)

parent interrupt specifier: 2 1

- The child unit address is <0x8800 0 0>. This value is encoded with three 32-bit cells, which is determined by the value of the #address-cells property (value of 3) of the PCI controller. The three cells represent the PCI address as described by the binding for the PCI bus.
 - The encoding includes the bus number (0x0 << 16), device number (0x11 << 11), and function number (0x0 << 8).
- The child interrupt specifier is <1>, which specifies INTA as described by the PCI binding. This takes one 32-bit cell as specified by the #interrupt-cells property (value of 1) of the PCI controller, which is the child interrupt domain.
- The interrupt parent is specified by a phandle which points to the interrupt parent of the slot, the Open PIC interrupt controller.
- The parent has no unit address because the parent interrupt domain (the open-pic node) has an #address-cells value of <0>.
- The parent interrupt specifier is <2 1>. The number of cells to represent the interrupt specifier (two cells) is determined by the #interrupt-cells property on the interrupt parent, the open-pic node.
 - The value <2 1> is a value specified by the device binding for the Open PIC interrupt controller (see [Section 4.5](#)). The value <2> specifies the physical interrupt source number on the interrupt controller to which INTA is wired. The value <1> specifies the level/sense encoding.

In this example, the interrupt-map-mask property has a value of <0xf800 0 0 7>. This mask is applied to a child unit interrupt specifier before performing a lookup in the *interrupt-map* table.

To perform a lookup of the open-pic interrupt source number for INTB for IDSEL 0x12 (slot 2), function 0x3, the following steps would be performed:

- The child unit address and interrupt specifier form the value `<0x9300 0 0 2>`.
 - The encoding of the address includes the bus number (0x0 << 16), device number (0x12 << 11), and function number (0x3 << 8).
 - The interrupt specifier is 2, which is the encoding for INTB as per the PCI binding.
- The interrupt-map-mask value `<0xf800 0 0 7>` is applied, giving a result of `<0x9000 0 0 2>`.
- That result is looked up in the *interrupt-map* table, which maps to the parent interrupt specifier `<4 1>`.

2.5 Nexus Nodes and Specifier Mapping

2.5.1 Nexus Node Properties

A nexus node shall have a `#<specifier>-cells` property, where `<specifier>` is some specifier space such as 'gpio', 'clock', 'reset', etc.

`<specifier>-map`

Property: `<specifier>-map`

Value type: `<prop-encoded-array>` encoded as an arbitrary number of specifier mapping entries.

Description:

A *<specifier>-map* is a property in a nexus node that bridges one specifier domain with a set of parent specifier domains and describes how specifiers in the child domain are mapped to their respective parent domains.

The map is a table where each row is a mapping entry consisting of three components: *child specifier*, *specifier parent*, and *parent specifier*.

child specifier

The specifier of the child node being mapped. The number of 32-bit cells required to specify this component is described by the `#<specifier>-cells` property of this node—the nexus node containing the `<specifier>-map` property.

specifier parent

A single `<phandle>` value that points to the specifier parent to which the child domain is being mapped.

parent specifier

The specifier in the parent domain. The number of 32-bit cells required to specify this component is described by the `#<specifier>-cells` property of the specifier parent node.

Lookups are performed on the mapping table by matching a specifier against the child specifier in the map. Because some fields in the specifier may not be relevant or need to be modified, a mask is applied before the lookup is done. This mask is defined in the `<specifier>-map-mask` property (see [Section 2.5.1](#)).

Similarly, when the specifier is mapped, some fields in the unit specifier may need to be kept unmodified and passed through from the child node to the parent node. In this case, a `<specifier>-map-pass-thru` property (see [Section 2.5.1](#)) may be specified to apply a mask to the child specifier and copy any bits that match to the parent unit specifier.

<specifier>-map-mask

Property: <specifier>-map-mask

Value type: <prop-encoded-array> encoded as a bit mask

Description:

A <specifier>-map-mask property may be specified for a nexus node. This property specifies a mask that is ANDed with the child unit specifier being looked up in the table specified in the <specifier>-map property. If this property is not specified, the mask is assumed to be a mask with all bits set.

<specifier>-map-pass-thru

Property: <specifier>-map-pass-thru

Value type: <prop-encoded-array> encoded as a bit mask

Description:

A <specifier>-map-pass-thru property may be specified for a nexus node. This property specifies a mask that is applied to the child unit specifier being looked up in the table specified in the <specifier>-map property. Any matching bits in the child unit specifier are copied over to the parent specifier. If this property is not specified, the mask is assumed to be a mask with no bits set.

#<specifier>-cells

Property: #<specifier>-cells

Value type: <u32>

Description:

The #<specifier>-cells property defines the number of cells required to encode a specifier for a domain.

2.5.2 Specifier Mapping Example

The following shows the representation of a fragment of a devicetree with two GPIO controllers and a sample specifier map for describing the GPIO routing of a few gpios on both of the controllers through a connector on a board to a device. The expansion device node is on one side of the connector node and the SoC with the two GPIO controllers is on the other side of the connector.

```
soc {
    soc_gpio1: gpio-controller1 {
        #gpio-cells = <2>;
    };

    soc_gpio2: gpio-controller2 {
        #gpio-cells = <2>;
    };
};

connector: connector {
    #gpio-cells = <2>;
    gpio-map = <0 0 &soc_gpio1 1 0>,
               <1 0 &soc_gpio2 4 0>,
               <2 0 &soc_gpio1 3 0>,
               <3 0 &soc_gpio2 2 0>;
    gpio-map-mask = <0xf 0x0>;
    gpio-map-pass-thru = <0x0 0x1>;
};
```

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```
};

expansion_device {
    reset-gpios = <&connector 2 GPIO_ACTIVE_LOW>;
};
```

Each row in the *gpio-map* table consists of three parts: a child unit specifier, which is mapped to a *gpio-controller* node with a parent specifier.

- For example, the first row of the specifier-map table specifies the mapping for GPIO 0 of the connector. The components of that row are shown here

child specifier: 0 0

specifier parent: &soc_gpio1

parent specifier: 1 0

- The child specifier is <0 0>, which specifies GPIO 0 in the connector with a *flags* field of 0. This takes two 32-bit cells as specified by the *#gpio-cells* property of the connector node, which is the child specifier domain.
- The specifier parent is specified by a phandle which points to the specifier parent of the connector, the first GPIO controller in the SoC.
- The parent specifier is <1 0>. The number of cells to represent the gpio specifier (two cells) is determined by the *#gpio-cells* property on the specifier parent, the *soc_gpio1* node.
 - * The value <1 0> is a value specified by the device binding for the GPIO controller. The value <1> specifies the GPIO pin number on the GPIO controller to which GPIO 0 on the connector is wired. The value <0> specifies the flags (active low, active high, etc.).

In this example, the *gpio-map-mask* property has a value of <0xf 0>. This mask is applied to a child unit specifier before performing a lookup in the *gpio-map* table. Similarly, the *gpio-map-pass-thru* property has a value of <0x0 0x1>. This mask is applied to a child unit specifier when mapping it to the parent unit specifier. Any bits set in this mask are cleared out of the parent unit specifier and copied over from the child unit specifier to the parent unit specifier.

To perform a lookup of the connector's specifier source number for GPIO 2 from the expansion device's *reset-gpios* property, the following steps would be performed:

- The child specifier forms the value <2 GPIO_ACTIVE_LOW>.
 - The specifier is encoding GPIO 2 with active low flags per the GPIO binding.
- The *gpio-map-mask* value <0xf 0x0> is ANDed with the child specifier, giving a result of <0x2 0>.
- The result is looked up in the *gpio-map* table, which maps to the parent specifier <3 0> and &soc_gpio1 phandle.
- The *gpio-map-pass-thru* value <0x0 0x1> is inverted and ANDed with the parent specifier found in the *gpio-map* table, resulting in <3 0>. The child specifier is ANDed with the *gpio-map-pass-thru* mask, forming <0 GPIO_ACTIVE_LOW> which is then ORed with the cleared parent specifier <3 0> resulting in <3 GPIO_ACTIVE_LOW>.
- The specifier <3 GPIO_ACTIVE_LOW> is appended to the mapped phandle &soc_gpio1 resulting in <&soc_gpio1 3 GPIO_ACTIVE_LOW>.

DEVICE NODE REQUIREMENTS

3.1 Base Device Node Types

The sections that follow specify the requirements for the base set of device nodes required in a DTSpec-compliant device-tree.

All devicetrees shall have a root node and the following nodes shall be present at the root of all devicetrees:

- One /cpus node
- At least one /memory node

3.2 Root node

The devicetree has a single root node of which all other device nodes are descendants. The full path to the root node is /.

Table 3.1: Root Node Properties

Property Name	Usage	Value Type	Definition
#address-cells	R	<u32>	Specifies the number of <u32> cells to represent the address in the reg property in children of root.
#size-cells	R	<u32>	Specifies the number of <u32> cells to represent the size in the reg property in children of root.
model	R	<string>	Specifies a string that uniquely identifies the model of the system board. The recommended format is “manufacturer,model-number”.
compatible	R	<stringlist>	Specifies a list of platform architectures with which this platform is compatible. This property can be used by operating systems in selecting platform specific code. The recommended form of the property value is: "manufacturer,model" For example: compatible = "fsl,mpc8572ds"
serial-number	O	<string>	Specifies a string representing the device's serial number.
chassis-type	OR	<string>	Specifies a string that identifies the form-factor of the system. The property value can be one of: <ul style="list-style-type: none"> • "desktop" • "laptop" • "convertible" • "server" • "tablet" • "handset" • "watch" • "embedded"
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties (Section 2.3) are allowed but are optional.

3.3 /aliases node

A devicetree may have an aliases node (/aliases) that defines one or more alias properties. The alias node shall be at the root of the devicetree and have the node name /aliases.

Each property of the /aliases node defines an alias. The property name specifies the alias name. The property value specifies the full path to a node in the devicetree. For example, the property serial0 = "/simple-bus@fe000000/serial@11c500" defines the alias serial0.

Alias names shall be a lowercase text strings of 1 to 31 characters from the following set of characters.

Table 3.2: Valid characters for alias names

Character	Description
0-9	digit
a-z	lowercase letter
-	dash

An alias value is a device path and is encoded as a string. The value represents the full path to a node, but the path does not need to refer to a leaf node.

A client program may use an alias property name to refer to a full device path as all or part of its string value. A client program, when considering a string as a device path, shall detect and use the alias.

Example

```
aliases {
    serial0 = "/simple-bus@fe000000/serial@11c500";
    ethernet0 = "/simple-bus@fe000000/ethernet@31c000";
};
```

Given the alias `serial0`, a client program can look at the `/aliases` node and determine the alias refers to the device path `/simple-bus@fe000000/serial@11c500`.

3.4 /memory node

A memory device node is required for all devicetrees and describes the physical memory layout for the system. If a system has multiple ranges of memory, multiple memory nodes can be created, or the ranges can be specified in the *reg* property of a single memory node.

The *unit-name* component of the node name (see [Section 2.2.1](#)) shall be `memory`.

The client program may access memory not covered by any memory reservations (see [Section 5.3](#)) using any storage attributes it chooses. However, before changing the storage attributes used to access a real page, the client program is responsible for performing actions required by the architecture and implementation, possibly including flushing the real page from the caches. The boot program is responsible for ensuring that, without taking any action associated with a change in storage attributes, the client program can safely access all memory (including memory covered by memory reservations) as `WIMG = 0b001x`. That is:

- not Write Through Required
- not Caching Inhibited
- Memory Coherence
- Required either not Guarded or Guarded

If the VLE storage attribute is supported, with `VLE=0`.

Table 3.3: /memory Node Properties

Property Name	Usage	Value Type	Definition
device_type	R	<string>	Value shall be “memory”
reg	R	<prop-encoded-array>	Consists of an arbitrary number of address and size pairs that specify the physical address and size of the memory ranges.
initial-mapped-area	O	<prop-encoded-array>	Specifies the address and size of the Initial Mapped Area Is a prop-encoded-array consisting of a triplet of (effective address, physical address, size). The effective and physical address shall each be 64-bit (<u64> value), and the size shall be 32-bits (<u32> value).
hotpluggable	O	<empty>	Specifies an explicit hint to the operating system that this memory may potentially be removed later.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties (Section 2.3) are allowed but are optional.

3.4.1 /memory node and UEFI

When booting via [UEFI], the system memory map is obtained via the GetMemoryMap() UEFI boot time service as defined in [UEFI] § 7.2, and if present, the OS must ignore any /memory nodes.

3.4.2 /memory Examples

Given a 64-bit Power system with the following physical memory layout:

- RAM: starting address 0x0, length 0x80000000 (2 GB)
- RAM: starting address 0x100000000, length 0x100000000 (4 GB)

Memory nodes could be defined as follows, assuming #address-cells = <2> and #size-cells = <2>.

Example #1

```
memory@0 {
    device_type = "memory";
    reg = <0x000000000 0x000000000 0x000000000 0x800000000
          0x000000001 0x000000000 0x000000001 0x000000000>;
};
```

Example #2

```
memory@0 {
    device_type = "memory";
    reg = <0x000000000 0x000000000 0x000000000 0x800000000>;
};
memory@100000000 {
    device_type = "memory";
    reg = <0x000000001 0x000000000 0x000000001 0x000000000>;
};
```


The `reg` property is used to define the address and size of the two memory ranges. The 2 GB I/O region is skipped. Note that the `#address-cells` and `#size-cells` properties of the root node specify a value of 2, which means that two 32-bit cells are required to define the address and length for the `reg` property of the memory node.

3.5 /reserved-memory Node

Reserved memory is specified as a node under the `/reserved-memory` node. The operating system shall exclude reserved memory from normal usage. One can create child nodes describing particular reserved (excluded from normal use) memory regions. Such memory regions are usually designed for the special usage by various device drivers.

Parameters for each memory region can be encoded into the device tree with the following nodes:

3.5.1 /reserved-memory parent node

Table 3.4: /reserved-memory Parent Node Properties

Property Name	Usage	Value Type	Definition
<code>#address-cells</code>	R	<u32>	Specifies the number of <u32> cells to represent the address in the <code>reg</code> property in children of root.
<code>#size-cells</code>	R	<u32>	Specifies the number of <u32> cells to represent the size in the <code>reg</code> property in children of root.
<code>ranges</code>	R	<prop encoded array>	This property represents the mapping between parent address to child address spaces (see Section 2.3.8, ranges).
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

`#address-cells` and `#size-cells` should use the same values as for the root node, and `ranges` should be empty so that address translation logic works correctly.

3.5.2 /reserved-memory/ child nodes

Each child of the reserved-memory node specifies one or more regions of reserved memory. Each child node may either use a `reg` property to specify a specific range of reserved memory, or a `size` property with optional constraints to request a dynamically allocated block of memory.

Following the generic-names recommended practice, node names should reflect the purpose of the node (ie. “*framebuffer*” or “*dma-pool*”). Unit address (@<address>) should be appended to the name if the node is a static allocation.

A reserved memory node requires either a `reg` property for static allocations, or a `size` property for dynamics allocations. Dynamic allocations may use `alignment` and `alloc-ranges` properties to constrain where the memory is allocated from. If both `reg` and `size` are present, then the region is treated as a static allocation with the `reg` property taking precedence and `size` is ignored.

Table 3.5: /reserved-memory/ Child Node Properties

Property Name	Usage	Value Type	Definition
reg	O	<prop-encoded-array>	Consists of an arbitrary number of address and size pairs that specify the physical address and size of the memory ranges.
size	O	<prop-encoded-array>	Size in bytes of memory to reserve for dynamically allocated regions. Size of this property is based on parent node's #size-cells property.
alignment	O	<prop-encoded-array>	Address boundary for alignment of allocation. Size of this property is based on parent node's #size-cells property.
alloc-ranges	O	<prop-encoded-array>	Specifies regions of memory that are acceptable to allocate from. Format is (address, length pairs) tuples in same format as for reg properties.
compatible	O	<stringlist>	May contain the following strings: <ul style="list-style-type: none"> • shared-dma-pool: This indicates a region of memory meant to be used as a shared pool of DMA buffers for a set of devices. It can be used by an operating system to instantiate the necessary pool management subsystem if necessary. • vendor specific string in the form <vendor>,[<device>-]<usage>
no-map	O	<empty>	If present, indicates the operating system must not create a virtual mapping of the region as part of its standard mapping of system memory, nor permit speculative access to it under any circumstances other than under the control of the device driver using the region.
reusable	O	<empty>	The operating system can use the memory in this region with the limitation that the device driver(s) owning the region need to be able to reclaim it back. Typically that means that the operating system can use that region to store volatile or cached data that can be otherwise regenerated or migrated elsewhere.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties (Section 2.3) are allowed but are optional.

The no-map and reusable properties are mutually exclusive and both must not be used together in the same node.

Linux implementation notes:

- If a `linux,cma-default` property is present, then Linux will use the region for the default pool of the contiguous memory allocator.
- If a `linux,dma-default` property is present, then Linux will use the region for the default pool of the consistent DMA allocator.

3.5.3 Device node references to reserved memory

Regions in the `/reserved-memory` node may be referenced by other device nodes by adding a `memory-region` property to the device node.

Table 3.6: Properties for referencing reserved-memory regions

Property Name	Usage	Value Type	Definition
<code>memory-region</code>	O	<code><prop-encoded-array></code>	phandle, specifier pairs to children of <code>/reserved-memory</code>
<code>memory-region-names</code>	O	<code><stringlist>></code>	A list of names, one for each corresponding entry in the <code>memory-region</code> property
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

3.5.4 /reserved-memory and UEFI

When booting via [UEFI], static `/reserved-memory` regions must also be listed in the system memory map obtained via the `GetMemoryMap()` UEFI boot time service as defined in [UEFI] § 7.2. The reserved memory regions need to be included in the UEFI memory map to protect against allocations by UEFI applications.

Reserved regions with the `no-map` property must be listed in the memory map with type `EfiReservedMemoryType`. All other reserved regions must be listed with type `EfiBootServicesData`.

Dynamic reserved memory regions must not be listed in the [UEFI] memory map because they are allocated by the OS after exiting firmware boot services.

3.5.5 /reserved-memory Example

This example defines 3 contiguous regions are defined for Linux kernel: one default of all device drivers (named `linux`, `cma` and 64MiB in size), one dedicated to the framebuffer device (named `framebuffer@78000000`, 8MiB), and one for multimedia processing (named `multimedia@77000000`, 64MiB).

```
/ {
    #address-cells = <1>;
    #size-cells = <1>;

    memory {
        reg = <0x40000000 0x40000000>;
    };

    reserved-memory {
        #address-cells = <1>;
        #size-cells = <1>;
        ranges;

        /* global autoconfigured region for contiguous allocations */
        linux,cma {
            compatible = "shared-dma-pool";
            reusable;
            size = <0x40000000>;
            alignment = <0x2000>;
            linux,cma-default;
        };

        display_reserved: framebuffer@78000000 {
```

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```

    reg = <0x78000000 0x800000>;
};

multimedia_reserved: multimedia@77000000 {
    compatible = "acme,multimedia-memory";
    reg = <0x77000000 0x4000000>;
};

/* ... */

fb0: video@12300000 {
    memory-region = <&display_reserved>;
    /* ... */
};

scaler: scaler@12500000 {
    memory-region = <&multimedia_reserved>;
    /* ... */
};

codec: codec@12600000 {
    memory-region = <&multimedia_reserved>;
    /* ... */
};
};

```

3.6 /chosen Node

The /chosen node does not represent a real device in the system but describes parameters chosen or specified by the system firmware at run time. It shall be a child of the root node.

Table 3.7: /chosen Node Properties

Property Name	Usage	Value Type	Definition
bootargs	O	<string>	A string that specifies the boot arguments for the client program. The value could potentially be a null string if no boot arguments are required.
stdout-path	O	<string>	A string that specifies the full path to the node representing the device to be used for boot console output. If the character “:” is present in the value it terminates the path. The value may be an alias. If the stdin-path property is not specified, stdout-path should be assumed to define the input device.
stdin-path	O	<string>	A string that specifies the full path to the node representing the device to be used for boot console input. If the character “:” is present in the value it terminates the path. The value may be an alias.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties ([Section 2.3](#)) are allowed but are optional.

Example

```
chosen {
    bootargs = "root=/dev/nfs rw nfsroot=192.168.1.1 console=ttyS0,115200";
};
```

Older versions of devicetrees may be encountered that contain a deprecated form of the *stdout-path* property called *linux,stdout-path*. For compatibility, a client program might want to support *linux,stdout-path* if a *stdout-path* property is not present. The meaning and use of the two properties is identical.

3.7 /cpus Node Properties

A /cpus node is required for all devicetrees. It does not represent a real device in the system, but acts as a container for child cpu nodes which represent the systems CPUs.

Table 3.8: /cpus Node Properties

Property Name	Usage	Value Type	Definition
#address-cells	R	<u32>	The value specifies how many cells each element of the <code>reg</code> property array takes in children of this node.
#size-cells	R	<u32>	Value shall be 0. Specifies that no size is required in the <code>reg</code> property in children of this node.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties ([Section 2.3](#)) are allowed but are optional.

The /cpus node may contain properties that are common across cpu nodes. See [Section 3.8](#) for details.

For an example, see [Section 3.8.4](#).

3.8 /cpus/cpu* Node Properties

A cpu node represents a hardware execution block that is sufficiently independent that it is capable of running an operating system without interfering with other CPUs possibly running other operating systems.

Hardware threads that share an MMU would generally be represented under one cpu node. If other more complex CPU topographies are designed, the binding for the CPU must describe the topography (e.g. threads that don't share an MMU).

CPUs and threads are numbered through a unified number-space that should match as closely as possible the interrupt controller's numbering of CPUs/threads.

Properties that have identical values across cpu nodes may be placed in the /cpus node instead. A client program must first examine a specific cpu node, but if an expected property is not found then it should look at the parent /cpus node. This results in a less verbose representation of properties which are identical across all CPUs.

The node name for every CPU node should be `cpu`.

3.8.1 General Properties of /cpus/cpu* nodes

The following table describes the general properties of `cpu` nodes. Some of the properties described in [Table 3.9](#) are select standard properties with specific applicable detail.

Table 3.9: /cpus/cpu* Node General Properties

Property Name	Usage	Value Type	Definition
<code>device_type</code>	R	<string>	Value shall be "cpu".
<code>reg</code>	R	array	<p>The value of <code>reg</code> is a <prop-encoded-array> that defines a unique CPU/thread id for the CPU/threads represented by the CPU node.</p> <p>If a CPU supports more than one thread (i.e. multiple streams of execution) the <code>reg</code> property is an array with 1 element per thread. The <code>#address-cells</code> on the /cpus node specifies how many cells each element of the array takes. Software can determine the number of threads by dividing the size of <code>reg</code> by the parent node's <code>#address-cells</code>.</p> <p>If a CPU/thread can be the target of an external interrupt the <code>reg</code> property value must be a unique CPU/thread id that is addressable by the interrupt controller.</p> <p>If a CPU/thread cannot be the target of an external interrupt, then <code>reg</code> must be unique and out of bounds of the range addressed by the interrupt controller</p> <p>If a CPU/thread's PIR (pending interrupt register) is modifiable, a client program should modify PIR to match the <code>reg</code> property value. If PIR cannot be modified and the PIR value is distinct from the interrupt controller number space, the CPUs binding may define a binding-specific representation of PIR values if desired.</p>
<code>clock-frequency</code>	O	array	<p>Specifies the clock speed of the CPU in Hertz, if that is constant. The value is a <prop-encoded-array> in one of two forms:</p> <ul style="list-style-type: none"> A 32-bit integer consisting of one <u32> specifying the frequency. A 64-bit integer represented as a <u64> specifying the frequency.
<code>timebase-frequency</code>	O	array	<p>Specifies the current frequency at which the timebase and decremter registers are updated (in Hertz). The value is a <prop-encoded-array> in one of two forms:</p> <ul style="list-style-type: none"> A 32-bit integer consisting of one <u32> specifying the frequency. A 64-bit integer represented as a <u64>.

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Table 3.9 – continued from previous page

Property Name	Us- age	Value Type	Definition
status	SD	<string>	<p>A standard property describing the state of a CPU. This property shall be present for nodes representing CPUs in a symmetric multiprocessing (SMP) configuration. For a CPU node the meaning of the "okay", "disabled" and "fail" values are as follows:</p> <p>"okay" : The CPU is running.</p> <p>"disabled" : The CPU is in a quiescent state.</p> <p>"fail" : The CPU is not operational or does not exist.</p> <p>A quiescent CPU is in a state where it cannot interfere with the normal operation of other CPUs, nor can its state be affected by the normal operation of other running CPUs, except by an explicit method for enabling or re-enabling the quiescent CPU (see the enable-method property).</p> <p>In particular, a running CPU shall be able to issue broadcast TLB invalidates without affecting a quiescent CPU.</p> <p>Examples: A quiescent CPU could be in a spin loop, held in reset, and electrically isolated from the system bus or in another implementation dependent state.</p> <p>A CPU with "fail" status does not affect the system in any way. The status is assigned to nodes for which no corresponding CPU exists.</p>

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Table 3.9 – continued from previous page

Property Name	Usage	Value Type	Definition
enable-method	SD	<stringlist>	<p>Describes the method by which a CPU in a disabled state is enabled. This property is required for CPUs with a status property with a value of "disabled". The value consists of one or more strings that define the method to release this CPU. If a client program recognizes any of the methods, it may use it. The value shall be one of the following:</p> <p>"spin-table" : The CPU is enabled with the spin table method defined in the DTSpec.</p> <p>"[vendor],[method]" : Implementation dependent string that describes the method by which a CPU is released from a "disabled" state. The required format is: "[vendor],[method]", where vendor is a string describing the name of the manufacturer and method is a string describing the vendor specific mechanism.</p> <p>Example: "fsl,MPC8572DS"</p> <hr/> <p>Note: Other methods may be added to later revisions of the DTSpec specification.</p>
cpu-release-addr	SD	<u64>	<p>The cpu-release-addr property is required for cpu nodes that have an enable-method property value of "spin-table". The value specifies the physical address of a spin table entry that releases a secondary CPU from its spin loop.</p>
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties (Section 2.3) are allowed but are optional.

Table 3.10: /cpus/cpu* Node Power ISA Properties

Property Name	Usage	Value Type	Definition
power-isa-version	O	<string>	<p>A string that specifies the numerical portion of the Power ISA version string. For example, for an implementation complying with Power ISA Version 2.06, the value of this property would be "2.06".</p>

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Table 3.10 – continued from previous page

Property Name	Usage	Value Type	Definition
power-isa-*	O	<empty>	If the power-isa-version property exists, then for each category from the Categories section of Book I of the Power ISA version indicated, the existence of a property named power-isa-[CAT], where [CAT] is the abbreviated category name with all uppercase letters converted to lowercase, indicates that the category is supported by the implementation. For example, if the power-isa-version property exists and its value is "2.06" and the power-isa-e.hv property exists, then the implementation supports [Category:Embedded.Hypervisor] as defined in Power ISA Version 2.06.
cache-op-block-size	SD	<u32>	Specifies the block size in bytes upon which cache block instructions operate (e.g., dcbz). Required if different than the L1 cache block size.
reservation-granule-size	SD	<u32>	Specifies the reservation granule size supported by this processor in bytes.
mmu-type	O	<string>	Specifies the CPU's MMU type. Valid values are shown below: <ul style="list-style-type: none"> • "mpc8xx" • "ppc40x" • "ppc440" • "ppc476" • "power-embedded" • "powerpc-classic" • "power-server-stab" • "power-server-slb" • "none"
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties (Section 2.3) are allowed but are optional.

Older versions of devicetree may be encountered that contain a bus-frequency property on CPU nodes. For compatibility, a client-program might want to support bus-frequency. The format of the value is identical to that of clock-frequency. The recommended practice is to represent the frequency of a bus on the bus node using a clock-frequency property.

3.8.2 TLB Properties

The following properties of a cpu node describe the translate look-aside buffer in the processor's MMU.

Table 3.11: /cpu/cpu* Node Power ISA TLB Properties

Property Name	Usage	Value Type	Definition
tlb-split	SD	<empty>	If present specifies that the TLB has a split configuration, with separate TLBs for instructions and data. If absent, specifies that the TLB has a unified configuration. Required for a CPU with a TLB in a split configuration.
tlb-size	SD	<u32>	Specifies the number of entries in the TLB. Required for a CPU with a unified TLB for instruction and data addresses.
tlb-sets	SD	<u32>	Specifies the number of associativity sets in the TLB. Required for a CPU with a unified TLB for instruction and data addresses.
d-tlb-size	SD	<u32>	Specifies the number of entries in the data TLB. Required for a CPU with a split TLB configuration.
d-tlb-sets	SD	<u32>	Specifies the number of associativity sets in the data TLB. Required for a CPU with a split TLB configuration.
i-tlb-size	SD	<u32>	Specifies the number of entries in the instruction TLB. Required for a CPU with a split TLB configuration.
i-tlb-sets	SD	<u32>	Specifies the number of associativity sets in the instruction TLB. Required for a CPU with a split TLB configuration.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties ([Section 2.3](#)) are allowed but are optional.

3.8.3 Internal (L1) Cache Properties

The following properties of a cpu node describe the processor's internal (L1) cache.

Table 3.12: /cpu/cpu* Node Power ISA Cache Properties

Property Name	Usage	Value Type	Definition
cache-unified	SD	<empty>	If present, specifies the cache has a unified organization. If not present, specifies that the cache has a Harvard architecture with separate caches for instructions and data.
cache-size	SD	<u32>	Specifies the size in bytes of a unified cache. Required if the cache is unified (combined instructions and data).
cache-sets	SD	<u32>	Specifies the number of associativity sets in a unified cache. Required if the cache is unified (combined instructions and data)
cache-block-size	SD	<u32>	Specifies the block size in bytes of a unified cache. Required if the processor has a unified cache (combined instructions and data)
cache-line-size	SD	<u32>	Specifies the line size in bytes of a unified cache, if different than the cache block size. Required if the processor has a unified cache (combined instructions and data).
i-cache-size	SD	<u32>	Specifies the size in bytes of the instruction cache. Required if the cpu has a separate cache for instructions.
i-cache-sets	SD	<u32>	Specifies the number of associativity sets in the instruction cache. Required if the cpu has a separate cache for instructions.
i-cache-block-size	SD	<u32>	Specifies the block size in bytes of the instruction cache. Required if the cpu has a separate cache for instructions.
i-cache-line-size	SD	<u32>	Specifies the line size in bytes of the instruction cache, if different than the cache block size. Required if the cpu has a separate cache for instructions.
d-cache-size	SD	<u32>	Specifies the size in bytes of the data cache. Required if the cpu has a separate cache for data.
d-cache-sets	SD	<u32>	Specifies the number of associativity sets in the data cache. Required if the cpu has a separate cache for data.
d-cache-block-size	SD	<u32>	Specifies the block size in bytes of the data cache. Required if the cpu has a separate cache for data.
d-cache-line-size	SD	<u32>	Specifies the line size in bytes of the data cache, if different than the cache block size. Required if the cpu has a separate cache for data.
next-level-cache	SD	<phandle>	If present, indicates that another level of cache exists. The value is the phandle of the next level of cache. The phandle value type is fully described in Section 2.3.3 .
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties ([Section 2.3](#)) are allowed but are optional.

Older versions of devicetrees may be encountered that contain a deprecated form of the next-level-cache property called 12-cache. For compatibility, a client-program may wish to support 12-cache if a next-level-cache property is not present.

The meaning and use of the two properties is identical.

3.8.4 Example

Here is an example of a /cpus node with one child cpu node:

```
cpus {
    #address-cells = <1>;
    #size-cells = <0>;
    cpu@0 {
        device_type = "cpu";
        reg = <0>;
        d-cache-block-size = <32>; // L1 - 32 bytes
        i-cache-block-size = <32>; // L1 - 32 bytes
        d-cache-size = <0x8000>; // L1, 32K
        i-cache-size = <0x8000>; // L1, 32K
        timebase-frequency = <82500000>; // 82.5 MHz
        clock-frequency = <825000000>; // 825 MHz
    };
};
```

3.9 Multi-level and Shared Cache Nodes (/cpus/cpu*/l?-cache)

Processors and systems may implement additional levels of cache hierarchy. For example, second-level (L2) or third-level (L3) caches. These caches can potentially be tightly integrated to the CPU or possibly shared between multiple CPUs.

A device node with a compatible value of "cache" describes these types of caches.

The cache node shall define a phandle property, and all cpu nodes or cache nodes that are associated with or share the cache each shall contain a next-level-cache property that specifies the phandle to the cache node.

A cache node may be represented under a CPU node or any other appropriate location in the devicetree.

Multiple-level and shared caches are represented with the properties in Table 3-9. The L1 cache properties are described in Table 3-8.

Table 3.13: /cpu/cpu*/l?-cache Node Power ISA Multiple-level and Shared Cache Properties

Property Name	Usage	Value Type	Definition
compatible	R	<string>	A standard property. The value shall include the string "cache".
cache-level	R	<u32>	Specifies the level in the cache hierarchy. For example, a level 2 cache has a value of 2.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties (Section 2.3) are allowed but are optional.

3.9.1 Example

See the following example of a devicetree representation of two CPUs, each with their own on-chip L2 and a shared L3.

```
cpus {
    #address-cells = <1>;
    #size-cells = <0>;
    cpu@0 {
        device_type = "cpu";
        reg = <0>;
        cache-unified;
        cache-size = <0x8000>; // L1, 32 KB
        cache-block-size = <32>;
        timebase-frequency = <82500000>; // 82.5 MHz
        next-level-cache = <&L2_0>; // phandle to L2

        L2_0:l2-cache {
            compatible = "cache";
            cache-unified;
            cache-size = <0x40000>; // 256 KB

            cache-sets = <1024>;
            cache-block-size = <32>;
            cache-level = <2>;
            next-level-cache = <&L3>; // phandle to L3

            L3:l3-cache {
                compatible = "cache";
                cache-unified;
                cache-size = <0x40000>; // 256 KB
                cache-sets = <0x400>; // 1024
                cache-block-size = <32>;
                cache-level = <3>;
            };
        };
    };

    cpu@1 {
        device_type = "cpu";
        reg = <1>;
        cache-unified;
        cache-block-size = <32>;
        cache-size = <0x8000>; // L1, 32 KB
        timebase-frequency = <82500000>; // 82.5 MHz
        clock-frequency = <825000000>; // 825 MHz
        next-level-cache = <&L2_1>; // phandle to L2
        L2_1:l2-cache {
            compatible = "cache";
            cache-unified;
            cache-level = <2>;
            cache-size = <0x40000>; // 256 KB
            cache-sets = <0x400>; // 1024
            cache-line-size = <32>; // 32 bytes
            next-level-cache = <&L3>; // phandle to L3
        };
    };
};
```

DEVICE BINDINGS

This chapter contains requirements, known as bindings, for how specific types and classes of devices are represented in the devicetree. The compatible property of a device node describes the specific binding (or bindings) to which the node complies.

Bindings may be defined as extensions of other each. For example a new bus type could be defined as an extension of the simple-bus binding. In this case, the compatible property would contain several strings identifying each binding—from the most specific to the most general (see [Section 2.3.1](#), compatible).

4.1 Binding Guidelines

4.1.1 General Principles

When creating a new devicetree representation for a device, a binding should be created that fully describes the required properties and value of the device. This set of properties shall be sufficiently descriptive to provide device drivers with needed attributes of the device.

Some recommended practices include:

1. Define a compatible string using the conventions described in [Section 2.3.1](#).
2. Use the standard properties (defined in [Section 2.3](#) and [Section 2.4](#)) as applicable for the new device. This usage typically includes the `reg` and `interrupts` properties at a minimum.
3. Use the conventions specified in [Section 4](#) (Device Bindings) if the new device fits into one the DTSpec defined device classes.
4. Use the miscellaneous property conventions specified in [Section 4.1.2](#), if applicable.
5. If new properties are needed by the binding, the recommended format for property names is: "`<company>, <property-name>`", where `<company>` is an OUI or short unique string like a stock ticker that identifies the creator of the binding.

Example: `"ibm,ppc-interrupt-server#s"`

4.1.2 Miscellaneous Properties

This section defines a list of helpful properties that might be applicable to many types of devices and device classes. They are defined here to facilitate standardization of names and usage.

clock-frequency Property

Table 4.1: clock-frequency Property

Property	clock-frequency
Value type	<prop-encoded-array>
Description	Specifies the frequency of a clock in Hz. The value is a <prop-encoded-array> in one of two forms: a 32-bit integer consisting of one <u32> specifying the frequency a 64-bit integer represented as a <u64> specifying the frequency

reg-shift Property

Table 4.2: reg-shift Property

Property	reg-shift
Value type	<u32>
Description	The <code>reg-shift</code> property provides a mechanism to represent devices that are identical in most respects except for the number of bytes between registers. The <code>reg-shift</code> property specifies in bytes how far the discrete device registers are separated from each other. The individual register location is calculated by using following formula: “registers address” << reg-shift. If unspecified, the default value is 0. For example, in a system where 16540 UART registers are located at addresses 0x0, 0x4, 0x8, 0xC, 0x10, 0x14, 0x18, and 0x1C, a <code>reg-shift = <2></code> property would be used to specify register locations.

label Property

Table 4.3: label Property

Property	label
Value type	<string>
Description	The label property defines a human readable string describing a device. The binding for a given device specifies the exact meaning of the property for that device.

4.2 Serial devices

4.2.1 Serial Class Binding

The class of serial devices consists of various types of point to point serial line devices. Examples of serial line devices include the 8250 UART, 16550 UART, HDLC device, and BISYNC device. In most cases hardware compatible with the RS-232 standard fit into the serial device class.

I²C and SPI (Serial Peripheral Interface) devices shall not be represented as serial port devices because they have their own specific representation.

clock-frequency Property

Table 4.4: clock-frequency Property

Property	clock-frequency
Value type	<u32>
Description	Specifies the frequency in Hertz of the baud rate generator's input clock.
Example	clock-frequency = <100000000>;

current-speed Property

Table 4.5: current-speed Property

Property	current-speed
Value type	<u32>
Description	Specifies the current speed of a serial device in bits per second. A boot program should set this property if it has initialized the serial device.
Example	115,200 Baud: current-speed = <115200>;

4.2.2 National Semiconductor 16450/16550 Compatible UART Requirements

Serial devices compatible to the National Semiconductor 16450/16550 UART (Universal Asynchronous Receiver Transmitter) should be represented in the devicetree using following properties.

Table 4.6: ns16550 UART Properties

Property Name	Usage	Value Type	Definition
compatible	R	<string list>	Value shall include "ns16550".
clock-frequency	R	<u32>	Specifies the frequency (in Hz) of the baud rate generator's input clock
current-speed	OR	<u32>	Specifies current serial device speed in bits per second
reg	R	<prop encoded array>	Specifies the physical address of the registers device within the address space of the parent bus
interrupts	OR	<prop encoded array>	Specifies the interrupts generated by this device. The value of the interrupts property consists of one or more interrupt specifiers. The format of an interrupt specifier is defined by the binding document describing the node's interrupt parent.
reg-shift	O	<u32>	Specifies in bytes how far the discrete device registers are separated from each other. The individual register location is calculated by using following formula: "registers address" << reg-shift. If unspecified, the default value is 0.
virtual-reg	SD	<u32> or <u64>	See Section 2.3.7 . Specifies an effective address that maps to the first physical address specified in the reg property. This property is required if this device node is the system's console.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties (Section 2.3) are allowed but are optional.

4.3 Network devices

Network devices are packet oriented communication devices. Devices in this class are assumed to implement the data link layer (layer 2) of the seven-layer OSI model and use Media Access Control (MAC) addresses. Examples of network devices include Ethernet, FDDI, 802.11, and Token-Ring.

4.3.1 Network Class Binding

address-bits Property

Table 4.7: address-bits Property

Property	address-bits
Value type	<u32>
Description	Specifies number of address bits required to address the device described by this node. This property specifies number of bits in MAC address. If unspecified, the default value is 48.
Example	address-bits = <48>;

local-mac-address Property

Table 4.8: local-mac-address Property

Property	local-mac-address
Value type	<prop-encoded-array> encoded as an array of hex numbers
Description	Specifies MAC address that was assigned to the network device described by the node containing this property.
Example	local-mac-address = [00 00 12 34 56 78];

mac-address Property

Table 4.9: mac-address Property

Property	mac-address
Value type	<prop-encoded-array> encoded as an array of hex numbers
Description	Specifies the MAC address that was last used by the boot program. This property should be used in cases where the MAC address assigned to the device by the boot program is different from the local-mac-address property. This property shall be used only if the value differs from local-mac-address property value.
Example	mac-address = [02 03 04 05 06 07];

max-frame-size Property

Table 4.10: max-frame-size Property

Property	max-frame-size
Value type	<u32>
Description	Specifies maximum packet length in bytes that the physical interface can send and receive.
Example	max-frame-size = <1518>;

4.3.2 Ethernet specific considerations

Network devices based on the IEEE 802.3 collections of LAN standards (collectively referred to as Ethernet) may be represented in the devicetree using following properties, in addition to properties specified of the network device class.

The properties listed in this section augment the properties listed in the network device class.

max-speed Property

Table 4.11: max-speed Property

Property	max-speed
Value type	<u32>
Description	Specifies maximum speed (specified in megabits per second) supported the device.
Example	max-speed = <1000>;

phy-connection-type Property

Table 4.12: phy-connection-type Property

Property	phy-connection-type
Value type	<string>
Description	Specifies interface type between the Ethernet device and a physical layer (PHY) device. The value of this property is specific to the implementation. Recommended values are shown in the following table.
Example	phy-connection-type = "mii";

Table 4.13: Defined values for the `phy-connection-type` Property

Connection type	Value
Media Independent Interface	<code>mii</code>
Reduced Media Independent Interface	<code>rmii</code>
Gigabit Media Independent Interface	<code>gmii</code>
Reduced Gigabit Media Independent	<code>rgmii</code>
rgmii with internal delay	<code>rgmii-id</code>
rgmii with internal delay on TX only	<code>rgmii-txid</code>
rgmii with internal delay on RX only	<code>rgmii-rxid</code>
Ten Bit Interface	<code>tbi</code>
Reduced Ten Bit Interface	<code>rtbi</code>
Serial Media Independent Interface	<code>smii</code>
Serial Gigabit Media Independent Interface	<code>sgmii</code>
Reverse Media Independent Interface	<code>rev-mii</code>
10 Gigabits Media Independent Interface	<code>xgmii</code>
Multimedia over Coaxial	<code>moca</code>
Quad Serial Gigabit Media Independent Interface	<code>qsgmii</code>
Turbo Reduced Gigabit Media Independent Interface	<code>trgmii</code>

`phy-handle` Property

Table 4.14: `phy-handle` Property

Property	<code>phy-handle</code>
Value type	<code><phandle></code>
Description	Specifies a reference to a node representing a physical layer (PHY) device connected to this Ethernet device. This property is required in case where the Ethernet device is connected a physical layer device.
Example	<code>phy-handle = <&PHY0>;</code>

4.4 Power ISA Open PIC Interrupt Controllers

This section specifies the requirements for representing Open PIC compatible interrupt controllers. An Open PIC interrupt controller implements the Open PIC architecture (developed jointly by AMD and Cyrix) and specified in The Open Programmable Interrupt Controller (PIC) Register Interface Specification Revision 1.2 [b18].

Interrupt specifiers in an Open PIC interrupt domain are encoded with two cells. The first cell defines the interrupt number. The second cell defines the sense and level information.

Sense and level information shall be encoded as follows in interrupt specifiers:

```

0 = low to high edge sensitive type enabled
1 = active low level sensitive type enabled
2 = active high level sensitive type enabled
3 = high to low edge sensitive type enabled

```

Table 4.15: Open-PIC properties

Property Name	Usage	Value Type	Definition
compatible	R	<string>	Value shall include "open-pic"
reg	R	<prop encoded array>	Specifies the physical address of the registers device within the address space of the parent bus
interrupt-controller	R	<empty>	Specifies that this node is an interrupt controller
#interrupt-cells	R	<u32>	Shall be 2.
#address-cells	R	<u32>	Shall be 0.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

Note: All other standard properties (Section 2.3) are allowed but are optional.

4.5 simple-bus Compatible Value

System-on-a-chip processors may have an internal I/O bus that cannot be probed for devices. The devices on the bus can be accessed directly without additional configuration required. This type of bus is represented as a node with a compatible value of "simple-bus".

Table 4.16: simple-bus Compatible Node Properties

Property Name	Usage	Value Type	Definition
compatible	R	<string>	Value shall include "simple-bus".
ranges	R	<prop encoded array>	This property represents the mapping between parent address to child address spaces (see Section 2.3.8, ranges).
nonposted-mmio	O	<empty>	Specifies that direct children of this bus should use non-posted memory accesses (i.e. a non-posted mapping mode) for MMIO ranges.
Usage legend: R=Required, O=Optional, OR=Optional but Recommended, SD=See Definition			

FLATTENED DEVICETREE (DTB) FORMAT

The Devicetree Blob (DTB) format is a flat binary encoding of devicetree data. It used to exchange devicetree data between software programs. For example, when booting an operating system, firmware will pass a DTB to the OS kernel.

Note: IEEE1275 Open Firmware [IEEE1275] does not define the DTB format. On most Open Firmware compliant platforms the devicetree is extracted by calling firmware methods to walk through the tree structure.

The DTB format encodes the devicetree data within a single, linear, pointerless data structure. It consists of a small header (see [Section 5.2](#)), followed by three variable sized sections: the memory reservation block (see [Section 5.3](#)), the structure block (see [Section 5.4](#)), and the strings block (see [Section 5.5](#)). These should be present in the flattened devicetree in that order. Thus, the devicetree structure as a whole, when loaded into memory at address, will resemble the diagram in [Fig. 5.1](#) (lower addresses are at the top of the diagram).

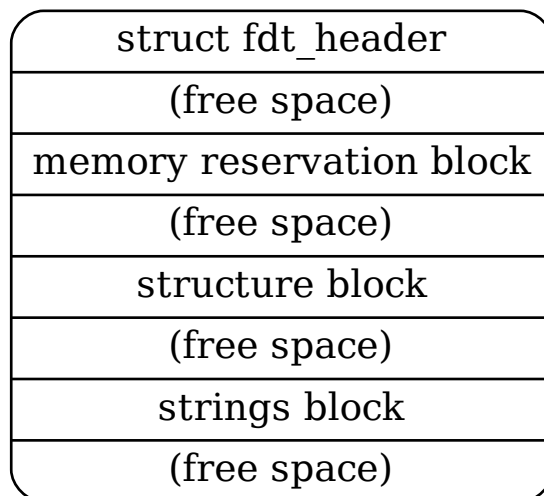


Fig. 5.1: Devicetree .dtb Structure

The (free space) sections may not be present, though in some cases they might be required to satisfy the alignment constraints of the individual blocks (see [Section 5.6](#)).

5.1 Versioning

Several versions of the flattened devicetree structure have been defined since the original definition of the format. Fields in the header give the version, so that the client program can determine if the devicetree is encoded in a compatible format.

This document describes only version 17 of the format. DTSpec compliant boot programs shall provide a devicetree of version 17 or later, and should provide a devicetree of a version that is backwards compatible with version 16. DTSpec compliant client programs shall accept devicetrees of any version backwards compatible with version 17 and may accept other versions as well.

Note: The version is with respect to the binary structure of the device tree, not its content.

5.2 Header

The layout of the header for the devicetree is defined by the following C structure. All the header fields are 32-bit integers, stored in big-endian format.

Flattened Devicetree Header Fields

```
struct fdt_header {
    uint32_t magic;
    uint32_t totalsize;
    uint32_t off_dt_struct;
    uint32_t off_dt_strings;
    uint32_t off_mem_rsvmap;
    uint32_t version;
    uint32_t last_comp_version;
    uint32_t boot_cpuid_phys;
    uint32_t size_dt_strings;
    uint32_t size_dt_struct;
};
```

magic

This field shall contain the value 0xd00dfeed (big-endian).

totalsize

This field shall contain the total size in bytes of the devicetree data structure. This size shall encompass all sections of the structure: the header, the memory reservation block, structure block and strings block, as well as any free space gaps between the blocks or after the final block.

off_dt_struct

This field shall contain the offset in bytes of the structure block (see [Section 5.4](#)) from the beginning of the header.

off_dt_strings

This field shall contain the offset in bytes of the strings block (see [Section 5.5](#)) from the beginning of the header.

off_mem_rsvmap

This field shall contain the offset in bytes of the memory reservation block (see [Section 5.3](#)) from the beginning of the header.

version

This field shall contain the version of the devicetree data structure. The version is 17 if using the structure as defined in this document. An DTSpec boot program may provide the devicetree of a later version, in which case this field shall contain the version number defined in whichever later document gives the details of that version.

last_comp_version

This field shall contain the lowest version of the devicetree data structure with which the version used is backwards compatible. So, for the structure as defined in this document (version 17), this field shall contain 16 because version

17 is backwards compatible with version 16, but not earlier versions. As per [Section 5.1](#), a DTSpec boot program should provide a devicetree in a format which is backwards compatible with version 16, and thus this field shall always contain 16.

boot_cpuid_phys

This field shall contain the physical ID of the system's boot CPU. It shall be identical to the physical ID given in the `reg` property of that CPU node within the devicetree.

size_dt_strings

This field shall contain the length in bytes of the strings block section of the devicetree blob.

size_dt_struct

This field shall contain the length in bytes of the structure block section of the devicetree blob.

5.3 Memory Reservation Block

5.3.1 Purpose

The *memory reservation block* provides the client program with a list of areas in physical memory which are *reserved*; that is, which shall not be used for general memory allocations. It is used to protect vital data structures from being overwritten by the client program. For example, on some systems with an IOMMU, the TCE (translation control entry) tables initialized by a DTSpec boot program would need to be protected in this manner. Likewise, any boot program code or data used during the client program's runtime would need to be reserved (e.g., RTAS on Open Firmware platforms). DTSpec does not require the boot program to provide any such runtime components, but it does not prohibit implementations from doing so as an extension.

More specifically, a client program shall not access memory in a reserved region unless other information provided by the boot program explicitly indicates that it shall do so. The client program may then access the indicated section of the reserved memory in the indicated manner. Methods by which the boot program can indicate to the client program specific uses for reserved memory may appear in this document, in optional extensions to it, or in platform-specific documentation.

The reserved regions supplied by a boot program may, but are not required to, encompass the devicetree blob itself. The client program shall ensure that it does not overwrite this data structure before it is used, whether or not it is in the reserved areas.

Any memory that is declared in a memory node and is accessed by the boot program or caused to be accessed by the boot program after client entry must be reserved. Examples of this type of access include (e.g., speculative memory reads through a non-guarded virtual page).

This requirement is necessary because any memory that is not reserved may be accessed by the client program with arbitrary storage attributes.

Any accesses to reserved memory by or caused by the boot program must be done as not Caching Inhibited and Memory Coherence Required (i.e., `WIMG = 0bx01x`), and additionally for Book III-S implementations as not Write Through Required (i.e., `WIMG = 0b001x`). Further, if the VLE storage attribute is supported, all accesses to reserved memory must be done as `VLE=0`.

This requirement is necessary because the client program is permitted to map memory with storage attributes specified as not Write Through Required, not Caching Inhibited, and Memory Coherence Required (i.e., `WIMG = 0b001x`), and `VLE=0` where supported. The client program may use large virtual pages that contain reserved memory. However, the client program may not modify reserved memory, so the boot program may perform accesses to reserved memory as Write Through Required where conflicting values for this storage attribute are architecturally permissible.

5.3.2 Format

The memory reservation block consists of a list of pairs of 64-bit big-endian integers, each pair being represented by the following C structure.

```
struct fdt_reserve_entry {
    uint64_t address;
    uint64_t size;
};
```

Each pair gives the physical address and size in bytes of a reserved memory region. These given regions shall not overlap each other. The list of reserved blocks shall be terminated with an entry where both address and size are equal to 0. Note that the address and size values are always 64-bit. On 32-bit CPUs the upper 32-bits of the value are ignored.

Each uint64_t in the memory reservation block, and thus the memory reservation block as a whole, shall be located at an 8-byte aligned offset from the beginning of the devicetree blob (see [Section 5.6](#)).

5.3.3 Memory Reservation Block and UEFI

As with the /reserved-memory node ([Section 3.5.4](#)), when booting via [UEFI] entries in the Memory Reservation Block must also be listed in the system memory map obtained via the GetMemoryMap() to protect against allocations by UEFI applications. The memory reservation block entries should be listed with type EfiReservedMemoryType.

5.4 Structure Block

The structure block describes the structure and contents of the devicetree itself. It is composed of a sequence of tokens with data, as described below. These are organized into a linear tree structure, as described below.

Each token in the structure block, and thus the structure block itself, shall be located at a 4-byte aligned offset from the beginning of the devicetree blob (see [Section 5.6](#)).

5.4.1 Lexical structure

The structure block is composed of a sequence of pieces, each beginning with a token, that is, a big-endian 32-bit integer. Some tokens are followed by extra data, the format of which is determined by the token value. All tokens shall be aligned on a 32-bit boundary, which may require padding bytes (with a value of 0x0) to be inserted after the previous token's data.

The five token types are as follows:

FDT_BEGIN_NODE (0x00000001)

The FDT_BEGIN_NODE token marks the beginning of a node's representation. It shall be followed by the node's unit name as extra data. The name is stored as a null-terminated string, and shall include the unit address (see [Section 2.2.1](#)), if any. The node name is followed by zeroed padding bytes, if necessary for alignment, and then the next token, which may be any token except FDT_END.

FDT_END_NODE (0x00000002)

The FDT_END_NODE token marks the end of a node's representation. This token has no extra data; so it is followed immediately by the next token, which may be any token except FDT_PROP.

FDT_PROP (0x00000003)

The FDT_PROP token marks the beginning of the representation of one property in the devicetree. It shall be followed by extra data describing the property. This data consists first of the property's length and name represented as the following C structure:

```
struct {
    uint32_t len;
    uint32_t nameoff;
}
```


Both the fields in this structure are 32-bit big-endian integers.

- `len` gives the length of the property's value in bytes (which may be zero, indicating an empty property, see [Section 2.2.4](#)).
- `nameoff` gives an offset into the strings block (see [Section 5.5](#)) at which the property's name is stored as a null-terminated string.

After this structure, the property's value is given as a byte string of length `len`. This value is followed by zeroed padding bytes (if necessary) to align to the next 32-bit boundary and then the next token, which may be any token except `FDT_END`.

FDT_NOP (0x00000004)

The `FDT_NOP` token will be ignored by any program parsing the device tree. This token has no extra data; so it is followed immediately by the next token, which can be any valid token. A property or node definition in the tree can be overwritten with `FDT_NOP` tokens to remove it from the tree without needing to move other sections of the tree's representation in the devicetree blob.

FDT_END (0x00000009)

The `FDT_END` token marks the end of the structure block. There shall be only one `FDT_END` token, and it shall be the last token in the structure block. It has no extra data; so the byte immediately after the `FDT_END` token has offset from the beginning of the structure block equal to the value of the `size_dt_struct` field in the device tree blob header.

5.4.2 Tree structure

The devicetree structure is represented as a linear tree: the representation of each node begins with an `FDT_BEGIN_NODE` token and ends with an `FDT_END_NODE` token. The node's properties and subnodes (if any) are represented before the `FDT_END_NODE`, so that the `FDT_BEGIN_NODE` and `FDT_END_NODE` tokens for those subnodes are nested within those of the parent.

The structure block as a whole consists of the root node's representation (which contains the representations for all other nodes), followed by an `FDT_END` token to mark the end of the structure block as a whole.

More precisely, each node's representation consists of the following components:

- (optionally) any number of `FDT_NOP` tokens
- `FDT_BEGIN_NODE` token
 - The node's name as a null-terminated string
 - [zeroed padding bytes to align to a 4-byte boundary]
- For each property of the node:
 - (optionally) any number of `FDT_NOP` tokens
 - `FDT_PROP` token
 - * property information as given in [Section 5.4.1](#)
 - * [zeroed padding bytes to align to a 4-byte boundary]
- Representations of all child nodes in this format
- (optionally) any number of `FDT_NOP` tokens
- `FDT_END_NODE` token

Note that this process requires that all property definitions for a particular node precede any subnode definitions for that node. Although the structure would not be ambiguous if properties and subnodes were intermingled, the code needed to process a flat tree is simplified by this requirement.

5.5 Strings Block

The strings block contains strings representing all the property names used in the tree. These null terminated strings are simply concatenated together in this section, and referred to from the structure block by an offset into the strings block.

The strings block has no alignment constraints and may appear at any offset from the beginning of the devicetree blob.

5.6 Alignment

The devicetree blob shall be located at an 8-byte-aligned address. To maintain backwards compatibility for 32-bit machines, 4-byte alignment is supported by some software, but this is not DTSpec-compliant.

For the data in the memory reservation and structure blocks to be used without unaligned memory accesses, they shall lie at suitably aligned memory addresses. Specifically, the memory reservation block shall be aligned to an 8-byte boundary and the structure block to a 4-byte boundary.

Furthermore, the devicetree blob as a whole can be relocated without destroying the alignment of the subblocks.

As described in the previous sections, the structure and strings blocks shall have aligned offsets from the beginning of the devicetree blob. To ensure the in-memory alignment of the blocks, it is sufficient to ensure that the devicetree as a whole is loaded at an address aligned to the largest alignment of any of the subblocks, that is, to an 8-byte boundary. A DTSpec compliant boot program shall load the devicetree blob at such an aligned address before passing it to the client program. If an DTSpec client program relocates the devicetree blob in memory, it should only do so to another 8-byte aligned address.

DEVICETREE SOURCE (DTS) FORMAT (VERSION 1)

The Devicetree Source (DTS) format is a textual representation of a devicetree in a form that can be processed by `dtc` into a binary devicetree in the form expected by the kernel. The following description is not a formal syntax definition of DTS, but describes the basic constructs used to represent devicetrees.

The name of DTS files should end with “.dts”.

6.1 Compiler directives

Other source files can be included from a DTS file. The name of include files should end with “.dtsi”. Included files can in turn include additional files.

```
/include/ "FILE"
```

6.2 Labels

The source format allows labels to be attached to any node or property value in the devicetree. Phandle and path references can be automatically generated by referencing a label instead of explicitly specifying a phandle value or the full path to a node. Labels are only used in the devicetree source format and are not encoded into the DTB binary.

A label shall be between 1 to 31 characters in length, be composed only of the characters in the set [Table 6.1](#), and must not start with a number.

Labels are created by appending a colon (‘:’) to the label name. References are created by prefixing the label name with an ampersand (‘&’).

Table 6.1: Valid characters for DTS labels

Character	Description
0-9	digit
a-z	lowercase letter
A-Z	uppercase letter
_	underscore

6.3 Node and property definitions

Devicetree nodes are defined with a node name and unit address with braces marking the start and end of the node definition. They may be preceded by a label.

```
[label:] node-name[@unit-address] {
    [properties definitions]
    [child nodes]
};
```

Nodes may contain property definitions and/or child node definitions. If both are present, properties shall come before child nodes.

Previously defined nodes may be deleted.

```
/delete-node/ node-name;
/delete-node/ &label;
```

Property definitions are name value pairs in the form:

```
[label:] property-name = value;
```

except for properties with empty (zero length) value which have the form:

```
[label:] property-name;
```

Previously defined properties may be deleted.

```
/delete-property/ property-name;
```

Property values may be defined as an array of 32-bit integer cells, as null-terminated strings, as bytestrings or a combination of these.

- Arrays of cells are represented by angle brackets surrounding a space separated list of C-style integers. Example:

```
interrupts = <17 0xc>;
```

- values may be represented as arithmetic, bitwise, or logical expressions within parenthesis.

Arithmetic operators

```
+    add
-    subtract
*    multiply
/    divide
%    modulo
```

Bitwise operators

```
&    and
|    or
^    exclusive or
~    not
<<  left shift
>>  right shift
```

Logical operators

```
&&  and
```

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```
||    or
!     not
```

Relational operators

```
<    less than
>    greater than
<=   less than or equal
>=   greater than or equal
==    equal
!=    not equal
```

Ternary operators

```
?:    (condition ? value_if_true : value_if_false)
```

- A 64-bit value is represented with two 32-bit cells. Example:

```
clock-frequency = <0x00000001 0x00000000>;
```

- A null-terminated string value is represented using double quotes (the property value is considered to include the terminating NULL character). Example:

```
compatible = "simple-bus";
```

- A bytestring is enclosed in square brackets [] with each byte represented by two hexadecimal digits. Spaces between each byte are optional. Example:

```
local-mac-address = [00 00 12 34 56 78];
```

or equivalently:

```
local-mac-address = [000012345678];
```

- Values may have several comma-separated components, which are concatenated together. Example:

```
compatible = "ns16550", "ns8250";
example = <0xf00f0000 19>, "a strange property format";
```

- In a cell array a reference to another node will be expanded to that node's phandle. References may be & followed by a node's label. Example:

```
interrupt-parent = < &mpic >;
```

or they may be & followed by a node's full path in braces. Example:

```
interrupt-parent = < &{/soc/interrupt-controller@400000} >;
```

- Outside a cell array, a reference to another node will be expanded to that node's full path. Example:

```
ethernet0 = &EMAC0;
```

- Labels may also appear before or after any component of a property value, or between cells of a cell array, or between bytes of a bytestring. Examples:

```
reg = reglabel: <0 sizelabel: 0x10000000>;
prop = [ab cd ef byte4: 00 ff fe];
str = start: "string value" end: ;
```

6.4 File layout

Version 1 DTS files have the overall layout:

```
/dts-v1/;
[memory reservations]
/ {
    [property definitions]
    [child nodes]
};
```

`/dts-v1/;` shall be present to identify the file as a version 1 DTS (dts files without this tag will be treated by dtc as being in the obsolete version 0, which uses a different format for integers in addition to other small but incompatible changes).

Memory reservations (see [Section 5.3](#)) are represented by lines in the form:

```
/memreserve/ <address> <length>;
```

Where `<address>` and `<length>` are 64-bit C-style integers, e.g.,

```
/* Reserve memory region 0x100000000..0x10003fff */
/memreserve/ 0x100000000 0x4000;
```

The `/ { ... };` section defines the root node of the devicetree, and all the device tree data is contained within it.

C style (`/* ... */`) and C++ style (`//`) comments are supported.

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