# User manual for R functions used in Post-Shock Persistence Testing

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This document describes the functions that are used in the post-shock persistence testing.

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## 1 scm function

scm(X, Tstar) is a core function in post-shock prediction methodology that is used to compute the synthetic weights  $W^*$  in Lin and Eck (2021). It computes the weights to minimize the Euclidean distance between the convex combination of the covariates in the donor pool and the covariates of the time series of interest. The optimization is based on nonlinear

optimization using the solnp in the R package Rsolnp (Ghalanos, Theussl, & Ghalanos, 2012).

Suppose the donor pool size is n. scm(X, Tstar) takes X and Tstar as inputs and outputs a vector of weights  $\mathbf{W}^*$  and other convergence details related to solnp, where

- X is a list of covariates with length n+1, where the first element of the list should be the covariates of the time series of interest and the remaining elements of the list are the covariates of the donors. The covariates should be in the class of matrix with size  $T_i \times p$  for i = 1, ..., n+1.
- Tstar is a vector of shock-effect time points when the shock occurs at  $T_i^* + 1$  for i = 1, ..., n + 1. The size of Tstar should be n + 1.
- The default for scale is scale = FALSE. If scale = TRUE, the function collects  $Q = \{\mathbf{x}_{i,T_i^*+1}: i=1,\ldots,n+1\}$  and scale and center within Q, i.e., center by the sample mean of  $\{x_{i,j,T_i^*+1}: i=1,\ldots,n+1\}$ , where j index stands for the jth variable.

#### Examples:

```
p <- 2; n <- 10;
T \leftarrow round(rgamma(n = n + 1, shape = 15, scale = 10)) # Time Length
Tstar <- c() # Shock Time Points
for (t in T) {
  Tstar \leftarrow c(Tstar, sample((p + 3 + 1):(t - 1), size = 1))
}
phi <- round(runif(n + 1, 0, 1), 3) # autoregressive parameters
# construction of design matrix
X < - C()
for (i in 1: (n + 1)) {
  Ti <- T[i]
  Tstari <- Tstar[i]</pre>
  X[[i]] \leftarrow matrix(rgamma(n = p * (Ti + 1), shape = 1, scale = 1),
                    ncol = p, byrow = T)
}
scm(X, Tstar)
```

# 2 sel function

sel (yhat,y) function is a function that computes the squared error loss between  $\hat{y}$  and y, where

- yhat is either a vector or a scalar
- y is either a vector or a scalar

yhat and y must have equal length. The output of sel (yhat, y) is the squared error loss. It may be a vector or scalar.

Examples:

```
sel(rnorm(10), rep(0,10))
```

### 3 taSPA.mhfc function

taspa.mhfc (ell, d, B, bw) is a core function that implements the hypothesis test of Quaedvlieg (2021) that compares two forecasts in terms of average superior predictive ability (aSPA) for multiple horizons. See the theoretical and algorithmic details of the hypotheses in Quaedvlieg (2021). Let H be the maximum horizon number for the forecasts and T be the sample size. The test statistic is

$$t_{aSPA,ij} = \frac{\sqrt{T}\bar{d}_{ij}}{\hat{\zeta}_{ii}},$$

where  $d_{ij,t}$  ( $H \times 1$ ) is the loss differential between forecasts i and j at time t,  $\bar{d}_{ij}$  is the average across  $t = 1, \ldots, T$ ,  $\bar{d}_{ij} = w'\bar{d}_{ij}$ ,  $\xi_{ij} = \sqrt{w'\Omega_{ij}w}$  is estimated by HAC estimator,  $\Omega_{ij}$  is the asymptotic variance of  $\bar{d}_{ij}$ .  $w = \mathbf{1}_H/H$  is taken as default. The computation of HAC estimator requires specification of a bandwidth parameter bw. Provided with a loss differential matrix d, this test uses moving-block bootstrap to approximate the distribution of the test statistic. Note that

- ell is the block length of the moving block bootstrap. Theory of Quaedvlieg (2021) requires ell =  $o(T^{1/2})$ .
- d is the loss differential matrix of size  $T \times H$ . It must be of matrix class. The element in tth row and hth column should be the loss differential between two h-step forecasts for tth observation.
- B is the bootstrap sample size.
- bw is the bandwidth of computation for HAC estimator. HAC estimation is based on HAC from Schlittgen (2021) using quadratic spectral kernel.

The output of taSPA.mhfc(ell,d,B,bw) is the *p*-value of the test, which is a scalar. Importantly, taSPA.mhfc(ell,d,B,bw) tests a *one-sided* hypothesis. Thus it is necessary to check whether the way about how the loss differential d is computed matches the hypothesis that is tested. See more details of the hypothesis that is tested in Quaedvlieg (2021).

Examples:

```
y <- arima.sim(list(2,0,0), n = 100)
```

```
T < -50; H < -10; K < -40
m1.L.i <- matrix(NA, nrow = T, ncol = H)
m2.L.i \leftarrow matrix(NA, nrow = T, ncol = H)
for (h in 1:H) {
  for (t in 1:T) {
    y.t \leftarrow y[(t + H - h + 1):(t + K + H - h)]
    m1 < - arima(y.t, order = c(1, 0, 0))
    m2 < - arima(y.t, order = c(2, 0, 0))
    y.t.hat.1 <- predict(m1, h)$pred[h]</pre>
    y.t.hat.2 <- predict(m1, h) $pred[h]</pre>
    m1.L.i[t, h] <- sel(y = y[t + K + H], yhat = y.t.hat.1)
    m2.L.i[t, h] \leftarrow sel(y = y[t + K + H], yhat = y.t.hat.2)
  }
}
d <- m2.L.i - m1.L.i
taSPA.mhfc(ell = 2, d = d, B = 200, bw = 4)
```

## 4 vote function

vote (ps, sig) is a function that yields the significance voting from a vector of p-values given a significance level. To be specific, if over 50% of the tests, each of which corresponds to a p-value in the donor pool, are significant according to the given significance level, the output of vote (ps, sig) would be 1. It is 0 otherwise. Note that

- ps is a vector of *p*-values with values in [0,1].
- sig is the significance level. It is 0.05 in default. It should be a scalar.

```
Examples:
vote(runif(10), .05)
```

# 5 ols.est.alphahat function

ols.est.alphahat (Tstar, Y, X) is the core function in Lin and Eck (2021) that is used to compute the weighted adjusted shock effect estimate  $\hat{\alpha}_{wadj}$  that aggregates information in the donor pool. Suppose the donor pool size is n. Given the shock time points, it performs n OLS regressions across the donor pool to estimate the shock effect of each donor.

The regression is based on the AR(1) model with covariates as specified in Section 2.1 of Lin and Eck (2021). The function internally uses scm function to compute the weights  $W^*$  and weight the donors' shock effects to compute  $\hat{\alpha}_{wadj}$ . It also computes the  $\hat{\alpha}_{IVW}$  estimate and  $\hat{\alpha}_{adj}$  estimate. See more details of these two estimates in Lin and Eck (2021). Note that

- X is a list of covariates with length n + 1, where the first element of the list should be the covariates of the time series of interest and the remaining elements of the list are the covariates of the donors. The covariates should be in the class of matrix with size  $T_i \times p$  for i = 1, ..., n + 1.
- Tstar is a vector of shock-effect time points when the shock occurs at  $T_i^* + 2$  for i = 1, ..., n + 1. The size of Tstar should be n + 1.
- Y is a list of responses with length n + 1, where the first element of the list should be the response of the time series of interest and the remaining elements of the list are the responses of the donors. It should be a vector. Note that to compute the lag, the effective sample size used is  $T_i 1$ , where  $T_i$  is the time series length of ith time series.

#### This function outputs

- alphahat is a vector of *n* length and contains the OLS shock effect estimates for the donors.
- est is a vector of three shock effect estimates,  $\hat{\alpha}_{adj}$ ,  $\hat{\alpha}_{wadj}$ , and  $\hat{\alpha}_{IVW}$ .
- Tstar is the same as the one in the input.
- X is the same as the one in the input.
- Y is the same as the one in the input.
- lmod is a list of n lm objects that were fitted by OLS for each donor. The ordering is the same as how the donor is ordered in X, Y, and Tstar.
- res is a list of *n* residual objects corresponding to each element of lmod.
- Wstar is the synthetic weights, as defined in the output of scm.
- se is a vector of length *n* and each element is the OLS standard error for the OLS shock effect estimate for each donor.

#### Examples:

```
n <- 10; p <- 2
Ts <- ceiling(rgamma(n + 1, scale = 10, shape = 10)) # Time Length
Tstar <- c() # Shock Time Points
for (t in Ts) {
   Tstar <- c(Tstar, sample((p + 3 + 1):(t - 1), size = 1))
}
phi <- round(runif(n + 1, 0, 1), 3) # autoregressive parameters</pre>
```

```
X < - C()
alpha <- c()
# construction of design matrix and shock effects
gamma <- c()
for (i in 1: (n + 1)) {
  Ti <- Ts[i]
  Tstari <- Tstar[i]</pre>
  X[[i]] \leftarrow matrix(rgamma(n = p * (Ti + 1),
                            shape = 1, scale = 1), ncol = p, byrow = TRUE)
  gamma[[i]] \leftarrow matrix(rnorm(p, mean = 1, sd = 1), nrow = 1)
  epsilontildei <- rnorm(n = 1, sd = 1)
  alpha <- c(alpha, 1 + gamma[[i]] %*% X[[i]][Tstari + 1, ] +
                epsilontildei)
}
# generation of yit
Y < - C()
for (i in 1: (n + 1)) {
  yi0 <- rnorm(1)
  Tstari <- Tstar[i]</pre>
  alphai <- alpha[i]</pre>
  phii <- phi[i]</pre>
  xi <- X[[i]]
  yi <- yi0
  thetai <- matrix(rnorm(p), nrow = 1)</pre>
  etai <- rnorm(1)
  for (t in 2: (Ts[i] + 1)) {
    epsilonit \leftarrow rnorm(n = 1, sd = 1)
    yi <- c(yi, etai + alphai * ifelse(t >= Tstari + 2,
                                           yes = 1, no = 0) +
               phii * yi[t - 1] + thetai %*% xi[t, ] + epsilonit)
  }
  Y[[i]] <- yi
ols.est.alphahat(Tstar,Y,X)
```

# 6 ps.indic.W.permanent

ps.indic.W.permanent (Tstar, Y, X, K, H, Ts, ell, B, bw, sig.levl) is a core function that produces the synthetic weights from scm, a sequence of *p*-values and corresponding rejection/acceptance decisions for each donor in the donor pool based on a give significance level and the test function taSPA.mhfc. The assumed model for this function

$$y_{i,t} = \eta_i + \phi_i y_{i,t-1} + x_{i,t} \theta + \alpha_i I(t > T_i^* + 1) + \varepsilon_{i,t},$$
  

$$\alpha_i = \mu_\alpha + x_{i,T_i^* + 1} + \varepsilon_{\alpha,i},$$

where  $T_i^* + 1$  is the time point when the shock occurs for i = 2, ..., n + 1,  $x_{i,t}$  is the covariate, and  $\eta_i$  is the intercept. Note that only  $\theta$ ,  $\eta_i$ , and  $\alpha_i$  are estimable. The above model is called permanent model due to the presence of a persistent shock term. For each donor, this function computes the adjusted forecast and unadjusted forecast, construct the corresponding loss differential matrix, and perform the forecast comparison test. Suppose the donor pool size is n. It is important to note that the ordering of the donors should be with respect to the timing when those time series occur, from the earliest to the latest.

#### The input for this function is

- Tstar is a vector of shock-effect time points when the shock occurs at  $T_i^* + 2$  for i = 1, ..., n + 1. The size of Tstar should be n + 1.
- Y is a list of responses with length n + 1, where the first element of the list should be the response of the time series of interest and the remaining elements of the list are the responses of the donors. It should be a vector. Note that to compute the lag, the effective sample size used is  $T_i 1$ , where  $T_i$  is the time series length of ith time series.
- X is a list of covariates with length n + 1, where the first element of the list should be the covariates of the time series of interest and the remaining elements of the list are the covariates of the donors. The covariates should be in the class of matrix with size  $T_i \times p$  for i = 1, ..., n + 1. Note that the sample size of each element in X should be  $T_i + K_i + H$ , where  $K_i$  is the training sample size and  $T_i$  is the length of the donor time series that are wished to be considered as the data used in forecast comparison. H is the maximum horizon.
- K is a vector of training sample sizes that are used to compute h-step forecast for each data point. K has a length of n + 1. If retro = FALSE, K[1] can be NA.
- H is the maximum h that an h-step forecast that is wished to be considered in the multi-horizon forecast comparison testing procedure in Quaedvlieg (2021).
- Ts is a vector of length n + 1, and it specifies the length of the time series (ordered from the time series of interest to donors). Note that for each element of Ts, it should be at least greater than or equal to  $K_i + H + 2$ .
- ell is the block length of the moving block bootstrap. See details in taspa.mhfc.
- B is the bootstrap sample size. See details in taSPA.mhfc.
- bw is the bandwidth of computation for HAC estimator. See details in taSPA.mhfc.
- sig.levl is the significance level for the test. It is 0.05 in default.

- retro is a logical value indicating TRUE or FALSE. If TRUE, the *p*-value for the time series of interest will be computed. If FALSE, only the *p*-values of donors will be computed. This argument is intended for retrospective data analysis where the *p*-value of the time series of interest is needed.
- scale option can allow users to compute weights based on scaled covariates or not. See details in scm.
- sc.x is a list of one vector and a list, where the ordering matters. The first vector should be a vector of indices referring to which time series wish to consider additional covariates that are present in the models but not considered in the weight computation. The second list should be a list of matrices with length equal to the length of the first vector. The matrices are the matrices of covariates, which are present in the models but not considered in the weight computation.

#### The output of this function is

- ps is a sequence of *p*-values from forecast comparison test of Quaedvlieg (2021) for the donors. It is of length *n*.
- W is a vector of synthetic weights and is of length n.
- Is is a sequence of rejection/acceptance decisions from forecast comparison for the donors, where 1 stands for rejection and 0 for acceptance. It is of length *n*.

#### Examples:

```
n < -10; p < -2
K \leftarrow ceiling(rgamma(n + 1, scale = 5, shape = 10)) # training sample size
Ts < ceiling(rgamma(n + 1, scale = 10, shape = 10)) # Time Length
Tstar <- c()
for (i in 1: (n + 1)) {
  Tstar \leftarrow c(Tstar, max(Ts[i] + 1, ceiling(0.5 * (Ts[i] + K[i] + H))))
phi <- round(runif(n + 1, 0, 1), 3) # autoregressive parameters
X < - C()
alpha <- c()
# construction of design matrix and shock effects
gamma <- c()
for (i in 1: (n + 1)) {
  Ti <- Ts[i]
  Tstari <- Tstar[i]</pre>
  Ki <- K[i]</pre>
  X[[i]] \leftarrow matrix(rgamma(n = p * (Ti + Ki + H + 1),
                            shape = 1, scale = 1), ncol = p, byrow = TRUE)
  gamma[[i]] \leftarrow matrix(rnorm(p, mean = 1, sd = 1), nrow = 1)
  epsilontildei \leftarrow rnorm(n = 1, sd = 1)
```

```
alpha <- c(alpha, 1 + gamma[[i]] %*% X[[i]][Tstari + 1, ] +
                epsilontildei)
}
# generation of yit
Y < - C()
for (i in 1:(n + 1)) {
  yi0 <- rnorm(1)
  Tstari <- Tstar[i]</pre>
  alphai <- alpha[i]</pre>
  phii <- phi[i]</pre>
  xi <- X[[i]]
  yi <- yi0
  thetai <- matrix(rnorm(p), nrow = 1)</pre>
  etai <- rnorm(1)
  for (t in 2:(K[i] + Ts[i] + H + 1)) {
    epsilonit \leftarrow rnorm(n = 1, sd = 1)
    yi <- c(yi, etai + alphai * ifelse(t >= Tstari + 2,
                                          yes = 1, no = 0) +
               phii * yi[t - 1] + thetai %*% xi[t, ] + epsilonit)
  Y[[i]] <- yi
est <- ps.indic.W.permanent(Tstar = Tstar, Y = Y, X = X, K = K,
                              H = 10, Ts = Ts, ell = 4, B = 200, bw = 4)
```

# 7 ps.indic.W.dynamic

ps.indic.W.dynamic(Tstar,Y,X,K,H,Ts,q1,q2,ell,B,bw,sig.levl) performs the similar functionality as ps.indic.W.permanent but with a different model as

$$y_{i,t} = \left(\eta_i + \sum_{j=1}^{q_1} \phi_{i,j} y_{i,t-j} + \sum_{j=0}^{q_2-1} x_{i,t-j} \theta_{i,j+1}\right) (1 - D_{i,t}) + f(\mathcal{F}_{i,t} \alpha_i) D_{i,t} + \varepsilon_{i,t}$$

$$f(\mathcal{F}_{i,t}, \alpha_i) = \alpha_i + \sum_{j=1}^{q_1} \tilde{\phi}_{i,j} y_{i,t-j} + \sum_{j=0}^{q_2-1} x_{i,t-j} \tilde{\theta}_{i,j+1}$$

$$\alpha_i = \mu_{\alpha} + x_{i,T_i^*+1} + \varepsilon_{\alpha,i}$$

where  $D_{i,t} = I(t > T_i^* + 1)$ . Note that only  $\eta_i$ ,  $\alpha_i - \eta_i$ ,  $\phi_{i,j}$ ,  $\theta_{i,j+1}$ ,  $\tilde{\phi}_{i,j} - \phi_{i,j}$ ,  $\tilde{\theta}_{i,j+1} - \theta_{i,j+1}$  are estimable. The role of the shock in this model is that the dynamics of  $y_{i,t}$  change after the shock. Note that to prepare the lagged response and covariates, the effective sample size is

 $T_i - \max\{q_1, q_2 - 1\}$ . Note that for each element of Ts, it should be at least greater than or equal to  $K_i + H + \max\{q_1, q_2 - 1\} + 1$ .

Additional functionality of ps.indic.W.dynamic compared to ps.indic.W.permanent is the specification of nolag.i.x, which allows users to add extra covariates that are not wished to be lagged in the model of  $y_{i,t}$ . nolag.i.x should be a list object of length two with the first element being a vector of indices referencing to the donor. The second element should be a list object with elements being the added covariates (of matrix or vector type) that are not wished to be lagged.

Examples are similar to those for ps.indic.W.permanent.

## References

Ghalanos, A., Theussl, S., & Ghalanos, M. A. (2012). Package âĂŸrsolnpâĂŹ.

Lin, J., & Eck, D. J. (2021). Minimizing post-shock forecasting error through aggregation of outside information. *International Journal of Forecasting*.

Quaedvlieg, R. (2021). Multi-horizon forecast comparison. *Journal of Business & Economic Statistics*, 39(1), 40–53.

Schlittgen, R. (2021). R package 'tsapp'.