# Test & Validation for QD Option Software

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### The VersaLab

#### What it is:

a small cryogen -free cryocooler-based Vibrating Sample Magnetometer (VSM)

#### What it does:

Temp range: 50K to 400K

Magnetic range: -3 to 3 Tesla

#### Who uses it:

Universities, Industries, Laboratories, and other programs exploring what certain samples do at various temperatures and/or magnetic fields.



# Option Software Testing on VersaLab

- VSM Errors
  - activation alarms passed
  - VSM temperature control fails passed
  - Final Test: Magnet passed
  - Scan Temperature with No Overshoot passed
- VSM Oven Errors
  - No Overshoot (crash & overshooting) passed
  - Fast Temperature Rate causes Crash passed

## Software Testing

#### Objectives:

- Ensure that the customer will not run into any difficulties performing any of the predicted tasks
- Ensure that the results given are accurate and meaningful

#### Approaches:

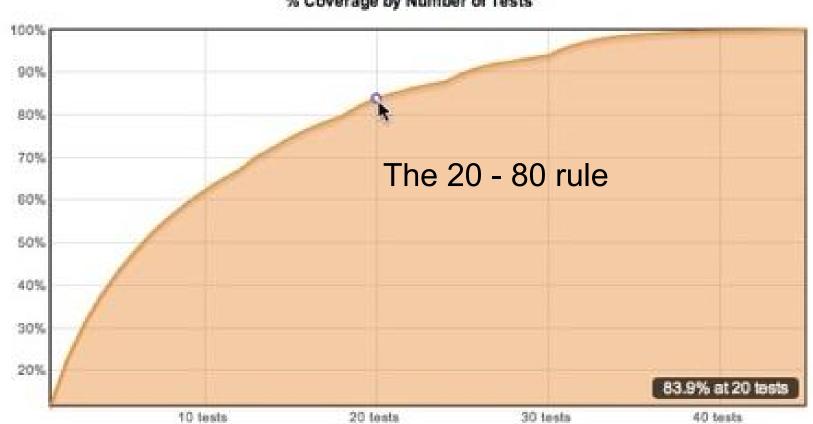
- Ad Hoc or Formal
- Graphical User Interface (GUI), MultiVu, Option Interface, or CAN Interface

## The Test Process



## Test Coverage





## Test Coverage

- Glass Box- exercise all possible pathways (complete structure known)
- Black Box- exercise for functionality; "Can it do what it needs to?"
- Path Testing: coverage criteria
  - Line coverage: execution of every line once; weakest
  - Branch coverage: go down every path (true and false); complete coverage (but not complete testing); **50**%
  - Condition coverage: each possibility (true, false 1, false 2, false 3); the
     best

## Defect Tracking

- Progress Tracking: new, in-progress, finished
- Statistics: accurate glimpse at state of product, allocating time & resources
- Setting Milestones
- Accountability: ownership of tickets and progress

### Three Parts To Every Good Bug Report

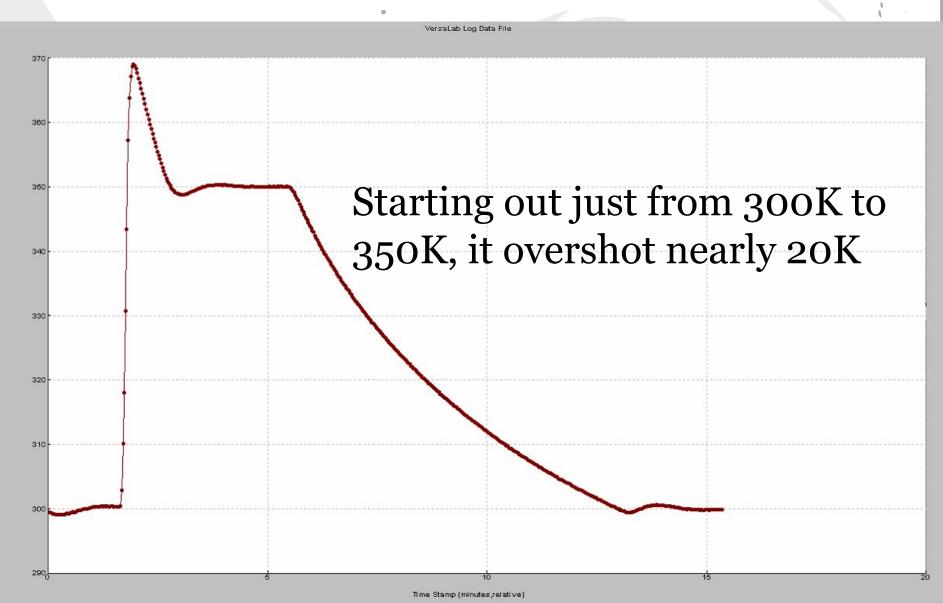
And the Lord spake, saying, "First shalt thou take out the Holy Pin. Then, shalt thou count to three, no more, no less. Three shall be the number thou shalt count, and the number of the counting shalt be three. Four shalt thou not count, nor either count thou two, excepting that thou then proceed to three. Five is right out. Once the number three, being the third number, be reached, then lobbest thou thy Holy Hand Grenade of Antioch towards thou foe."

-- Monty Python and the Holy Grail

#### Every good bug report needs exactly three things.

- 1. Steps to reproduce
- 2. What you expected to see
- 3. What you saw instead

## The No Overshoot Problem



#### PID Calculations

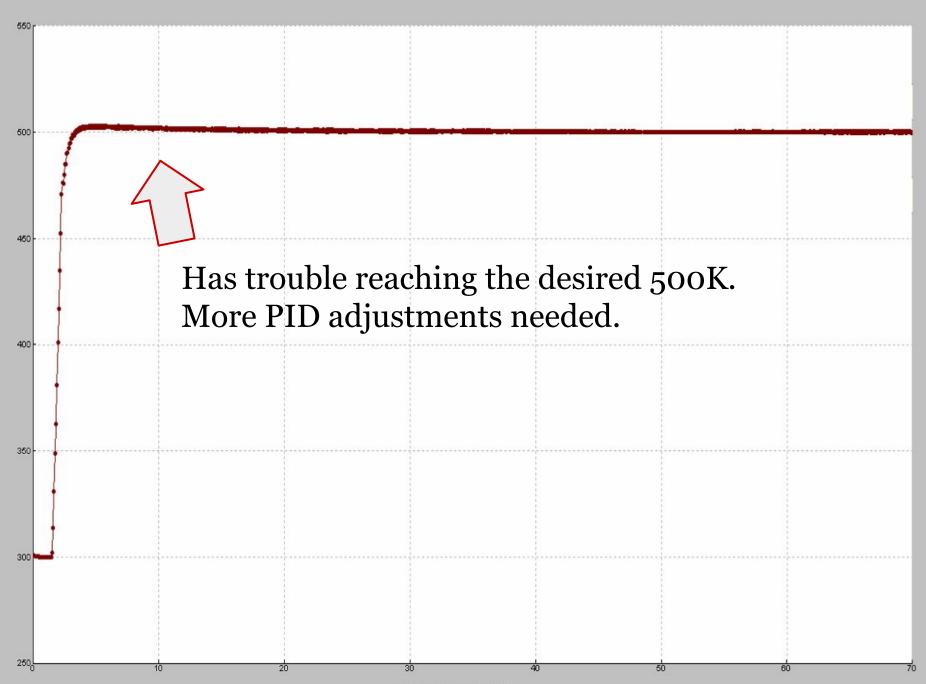
Proportional - Integral - Differential Controller (PID)

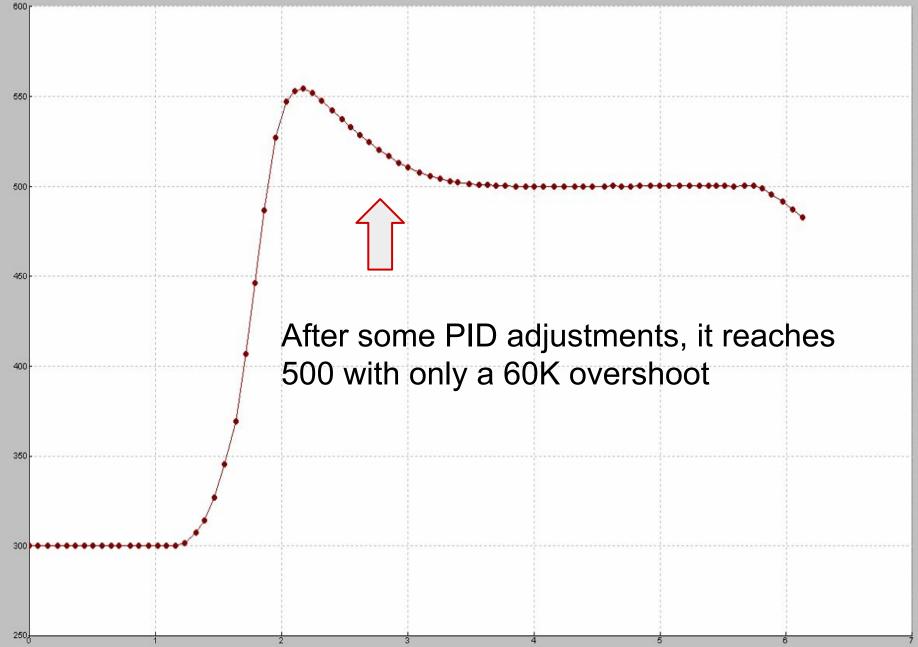
**Proportional Gain-** proportional to current error value, adjusts stability.  $P_{\text{out}} = K_p e(t)$ 

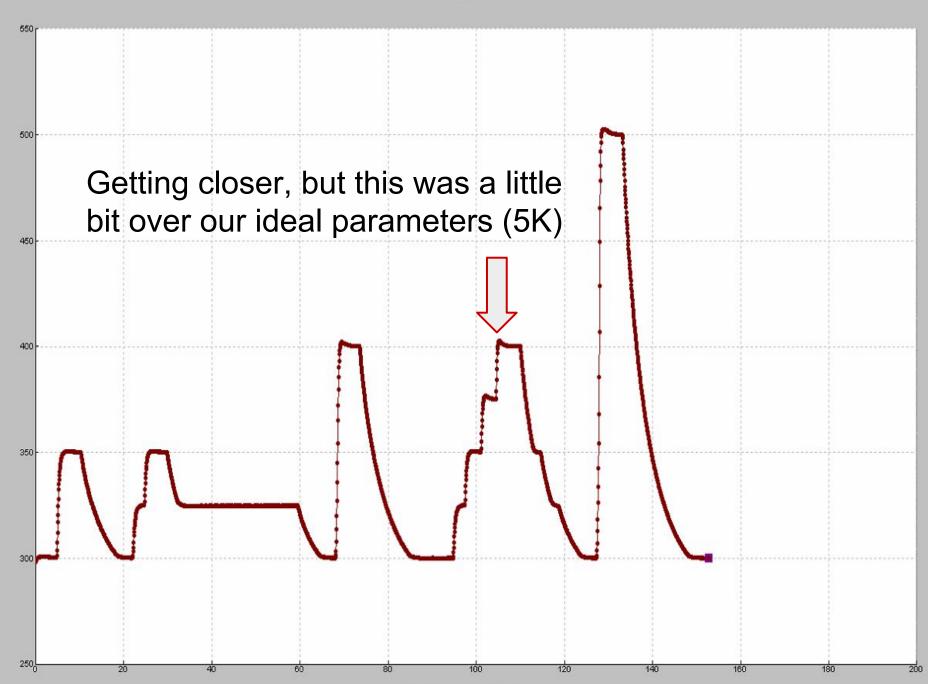
**Integral Gain-** proportional to current error magnitude and duration, reaches the set point.  $I_{\text{out}} = K_i \int_0^t e(\tau) d\tau$ 

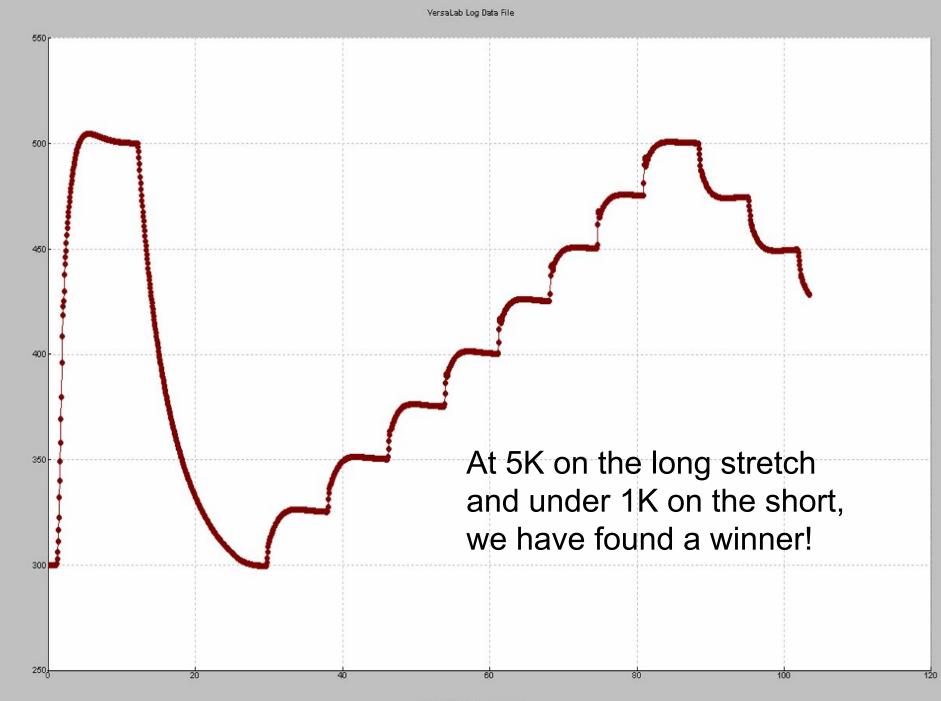
Differential Gain- proportional to error's slope.

$$D_{\rm out} = K_d \frac{d}{dt} e(t)$$









# Thank you all for coming!

And a special thanks to Petar, Tofik, and Mark W. for their work, patience, and support this summer.

# A Bizarre Assortment of (2) Unreproducible Occurrences

