

# Appendix.03 Probability Theory

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## Definition.A.3.1 Probability

### 1. Subjective(Empirical) Definition :

Our measure of how much we believe something to be true.

### 2. Relative Frequency Definition :

Repeating the physical process an extremely large number of times(trials) and then to look at the fraction of times that the outcome of interest occurs.

### 3. Mathematical(Classical) Definition :

The ratio of a number of interested outcomes to the of number of all possible outcomes, presuming they all equally likely.

## Axiom.A.3.1 Nonnegativity

$$P(A) \geq 0 \quad \forall \text{ event } A$$

## Axiom.A.3.2 Additivity

$$P\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} P(A_n) \quad \text{if } A_i \cap A_j = \emptyset, \forall i \neq j$$

## Axiom.A.3.3 Normalization

$$P(\Omega) = 1$$

## Definition.A.3.2 Conditional Probability of A given B

$$\Rightarrow P(A \cap B) = P(A|B)P(B)$$

**Theorem.A.3.1 Total Probability Theorem**

$$\text{then } P(B) = P(A_1 \cap B) + \cdots + P(A_n \cap B) = P(B|A_1)P(A_1) + \cdots + P(B|A_n)P(A_n) = P(B) = \sum_i P(B|A_i)P(A_i)$$

**Proof)**

Trivial ■

**Theorem.A.3.2 Bayes Rule**

$$\text{then } P(A_i|B) = \frac{P(B|A_i)P(A_i)}{P(B)} = \frac{P(B|A_i)P(A_i)}{\sum_{j=1}^n P(B|A_j)P(A_j)} \quad \text{for } P(B) > 0$$

**Proof)**

$$\begin{aligned} P(A_i \cap B) &= P(A_i|B)P(B) & \cdots (1) \\ &= P(B|A_i)P(A_i) & \cdots (2) \end{aligned}$$

$$\begin{aligned} P(A_i|B) &= \frac{P(B|A_i)P(A_i)}{P(B)} & (\because \text{by (1), (2)}) \\ &= \frac{P(B|A_i)P(A_i)}{\sum_{j=1}^n P(B|A_j)P(A_j)} & (\because \text{Theorem.A.3.1}) \quad \blacksquare \end{aligned}$$

We can express the posterior probability in terms of the prior probability and likelihood.

**Definition.A.3.3 Independence**

$A$  and  $B$  are independence, if and only if,

$$\begin{aligned} P(A \cap B) &= P(A)P(B) \\ \Rightarrow \quad P(A|B) &= P(A) \quad \text{for } P(B) > 0 \\ P(B|A) &= P(B) \quad \text{for } P(A) > 0 \end{aligned}$$

**Theorem.A.3.3 Independence and disjoint**

Independent  $\nleftrightarrow$  Disjoint

**Proof.**

i)  $A, A^c$  : disjoint, but dependent.

ii)

$$\begin{aligned} P(A \cup B) &= P(A) + P(B) - P(A \cap B) \\ &= P(A) + P(B) \quad (\because P(A \cap B) = 0) \quad \blacksquare \end{aligned}$$

**Definition.A.3.4 Discrete random variables**

If the random variable  $X \in S$

$$s.t. \quad S = \{x_1, x_2, \dots\} \quad S \text{ is a countable set,}$$

then  $X$  is called discrete random variable.

**Definition.A.3.5 Probability mass functions(PMFs)**

In a discrete random variable  $X$ ,

$$P_X(x) = P(\{X = x\})$$

is called probability mass function of random variable  $X$ .

It has

$$\sum_x P_X(x) = 1, \quad P(X \in S) = \sum_{x \in S} P_X(x) = 1$$

**Definition.A.3.6 Expectation**

Suppose  $X$  is a discrete random variable.

Expectation of  $X$  is

$$E[X] = \sum_x x p_X(x).$$

**Theorem.A.3.4 Expected value rule**

$$E[g(X)] = \sum_x g(x) p_X(x)$$

**Proof.**

Let  $Y = g(X)$

$$\begin{aligned} E[g(X)] &= E[Y] \\ &= \sum_y y P_Y(y) \\ &= \sum_y \sum_{\{x : g(x) = y\}} y p_X(x) \\ &= \sum_y \sum_{\{x : g(x) = y\}} g(x) p_X(x) \\ &= \sum_x g(x) p_X(x) \quad \blacksquare \end{aligned}$$

**Definition.A.3.7 Variance, standard deviation and  $n$ th moment**

Suppose  $X$  is a discrete random variable.

Variance of  $X$  is

$$\text{Var}(X) = \mathbb{E}[(X - \mathbb{E}[X])^2].$$

Standard deviation of  $X$  is

$$\sigma_X = \sqrt{\text{Var}(X)}.$$

$n$ th moment of  $X$  is

$$\mathbb{E}[X^n] = \sum_x x^n p_X(x).$$

**Theorem.A.3.5 Variance rule**

$$\text{Var}(X) = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

**Proof.**

Trivial.

**Theorem.A.3.6 Properties of mean and variance**

Let  $Y = aX + b$

$$\begin{aligned}\mathbb{E}[Y] &= \sum_x (ax + b)p_X(x) \\ &= a\sum_x xp_X(x) + b\sum_x p_X(x) \\ &= a\mathbb{E}[X] + b\end{aligned}$$

$$\begin{aligned}\text{Var}[Y] &= \sum_x (ax + b - \mathbb{E}[aX + b])^2 p_X(x) \\ &= \sum_x (ax + b - a\mathbb{E}[X] - b)^2 p_X(x) \\ &= a^2 \sum_x (x - \mathbb{E}[X])^2 p_X(x) \\ &= a^2 \text{Var}(X) \quad \text{which is called shift-invariance.} \quad \blacksquare\end{aligned}$$

**Definition.A.3.8 Joint PMFs of multiple random variables**

Suppose  $X$  and  $Y$  are discrete random variables.

$$P_{X,Y}(x, y) = P(X = x, Y = y)$$

**Theorem.A.3.7 Marginal PMF of multiple random variables**

Suppose  $X$  and  $Y$  are discrete random variables.

$$p_X(x) = \sum_y p_{X,Y}(x, y), \quad p_Y(y) = \sum_x p_{X,Y}(x, y)$$

**Proof.**

$$p_X(x) = P(\{X = x \cap Y = y_1\} \cup \{X = x \cap Y = y_2\} \cup \dots \{X = x \cap Y = y_k\})$$

$$p_Y(y) = P(\{X = x_1 \cap Y = y\} \cup \{X = x_2 \cap Y = y\} \cup \dots \{X = x_j \cap Y = y\})$$

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**Definition.A.3.9 Conditional PMF given an event and random variable**

With given event  $A$ ,

$$p_{X|A}(x) = P(X = x|A) = \frac{P(\{X = x\} \cap A)}{P(A)}.$$

With given a random variable  $Y$ ,

$$p_{X|Y}(x|y) = P(X = x|Y = y) = \frac{P(X = x, Y = y)}{P(Y = y)} = \frac{p_{X,Y}(x, y)}{p_Y(y)}$$

- Normalization :

$$\sum_x p_{X|Y}(x|y) = \frac{1}{p_Y(y)} \sum_x p_{X,Y}(x, y) = \frac{p_Y(y)}{p_Y(y)} = 1$$

- Joint PMF :

$$p_{X,Y}(x, y) = p_{X|Y}(x|y)p_Y(y) = p_{Y|X}(y|x)p_X(x)$$

$$p_{X,Y,Z}(x, y, z) = p_X(x)p_{Y|X}(y|x)p_{Z|X,Y}(z|x, y)$$

- Marginal PMF

$$p_X(x) = \sum_y p_{X|Y}(x|y)p_Y(y)$$

$$p_Y(y) = \sum_x p_{Y|X}(y|x)p_X(x)$$