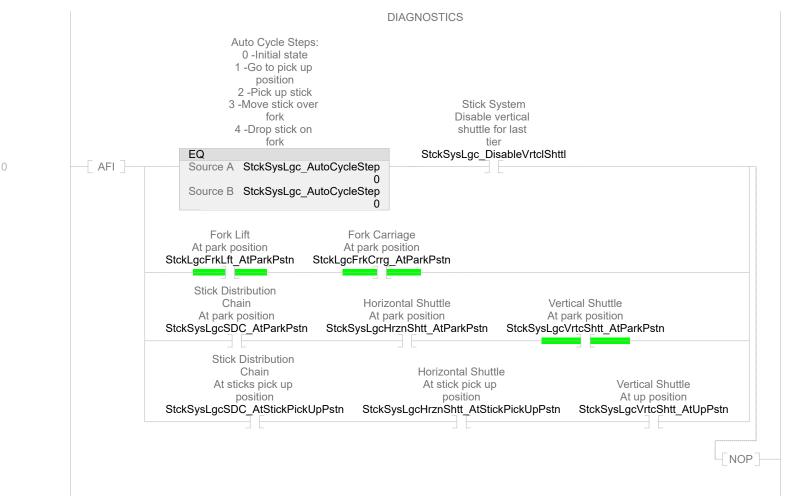
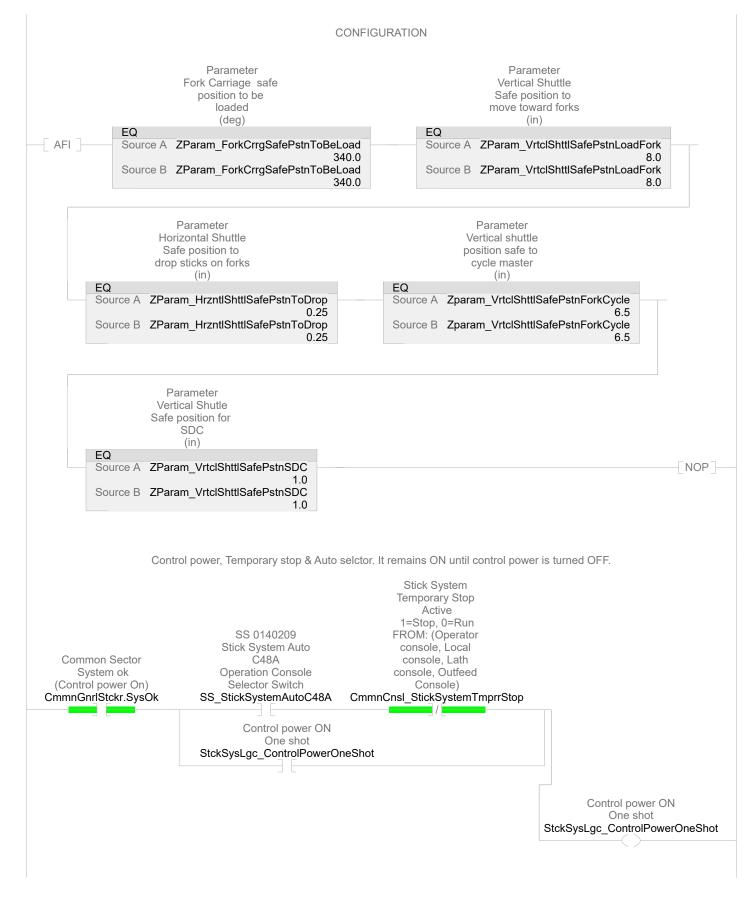
RSGMolalla SMMocoStckr:MainTask:ServoStickSystemLogic Total number of rungs in routine: 27

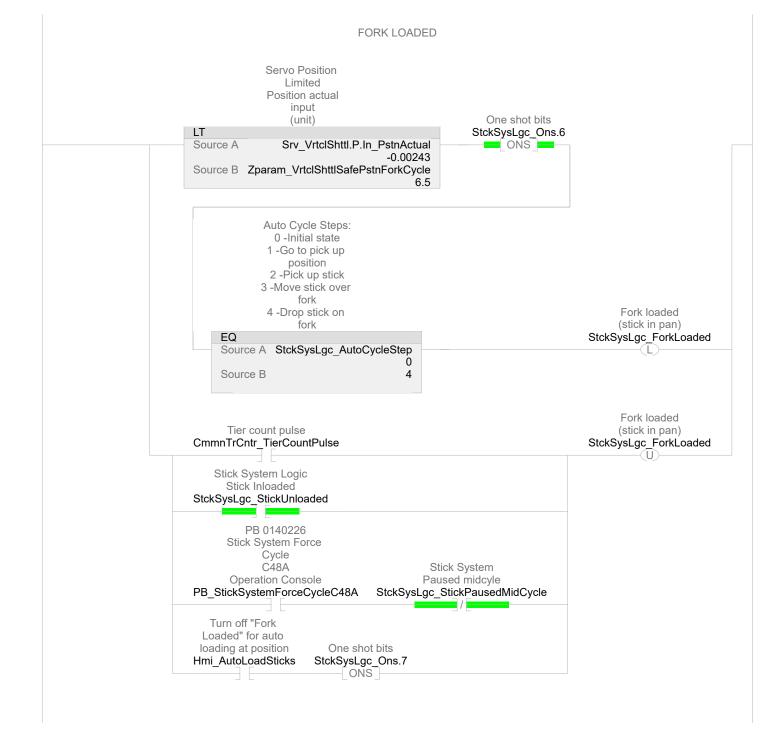


...9 Molalla, OR\Program PLC\RSG_MolallaSmStacker_20250831C.ACD

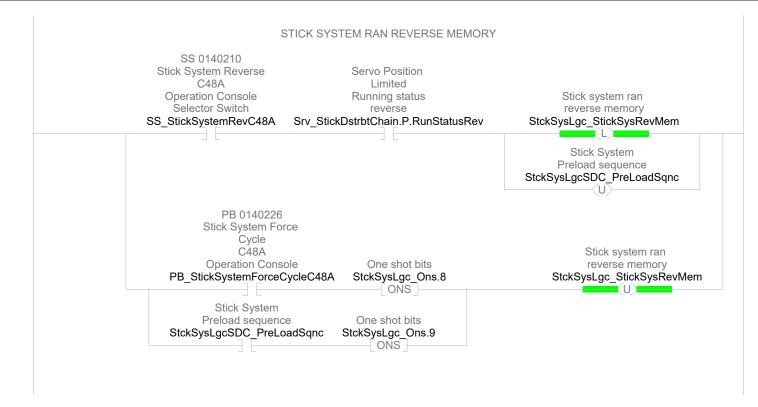


ALL SERVO OF STICK SYSTEM GO TO START POSITION Control power ON One shot One shot bits StckSysLgc_Ons.0 StckSysLgc ControlPowerOneShot ONS SS 0140209 Stick System Auto C48A Operation Console Stick system ran Selector Switch One shot bits reverse memory SS_StickSystemAutoC48A StckSysLgc_Ons.1 StckSysLgc_StickSysRevMem ONS FROM HMI Stick System go to park position One shot bits HMI_StickSysGoToParkPstn StckSysLgc_Ons.2 ONS TOGGLE Stick system go to park position One shot bits Tggl_StickSysGoToParkPstn StckSysLgc_Ons.3 ONS Stick System Temporary Stop Active 1=Stop, 0=Run FROM: (Operator console, Local console, Lath console, Outfeed Stick System Servos Console) Go to park position StckSysLgc_AllServoGoToParkPstn CmmnCnsl_StickSystemTmprrStop Stick System Servos Go to park position memory StckSysLgc_AllServoGoToParkPstnMem Stick Distribution Stick System Servos Chain Go to park position At park position memory StckSysLgcSDC_AtParkPstn StckSysLgc_AllServoGoToParkPstnMem (U)

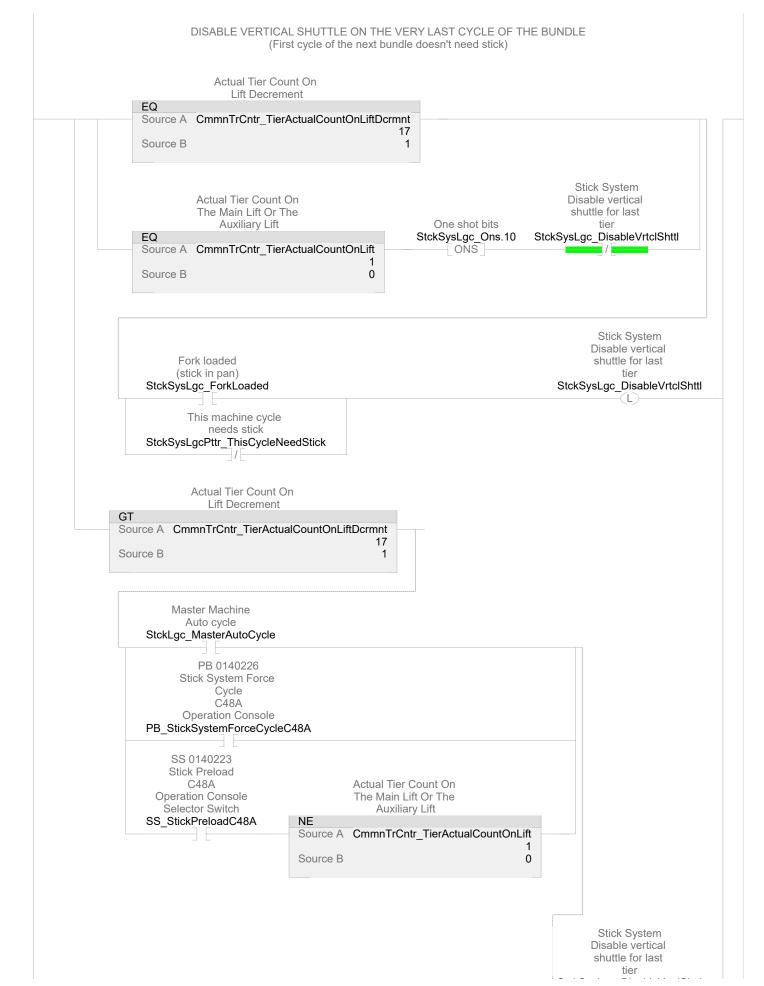
ALL SERVO OF STICK SYSTEM RESYNC Go to recover position accordingly to the Auto Cycle Grafcet Stick System Temporary Stop Active 1=Stop, 0=Run FROM: (Operator SS 0140209 Stick System Auto console, Local Stick System Servos C48A console, Lath Operation Console Go to recovery console, Outfeed Selector Switch Console) One shot bits position SS_StickSystemAutoC48A CmmnCnsl StickSystemTmprrStop StckSysLgc_AllServoResync StckSysLgc_Ons.4 ONS Stick System Temporary Stop Active 1=Stop, 0=Run FROM: (Operator console, Local **TOGGLE** console, Lath All stacker servo console, Outfeed Resync with master One shot bits Console) Tggl StckrAllServoResync StckSysLgc Ons.5 CmmnCnsl StickSystemTmprrStop ONS ALL SERVO OF STICK SYSTEM, MOTION SERVO ON STATUS Servo Position Servo Position Stick Feeder Limited Limited Motion servo ON Motion servo ON Motion servo ON status status status Srv_StickFeeder.P.MotionServoOnStatus Srv_StickDstrbtChain.P.MotionServoOnStatus Srv_VrtclShttl.P.MotionServoOnStatus Servo Position



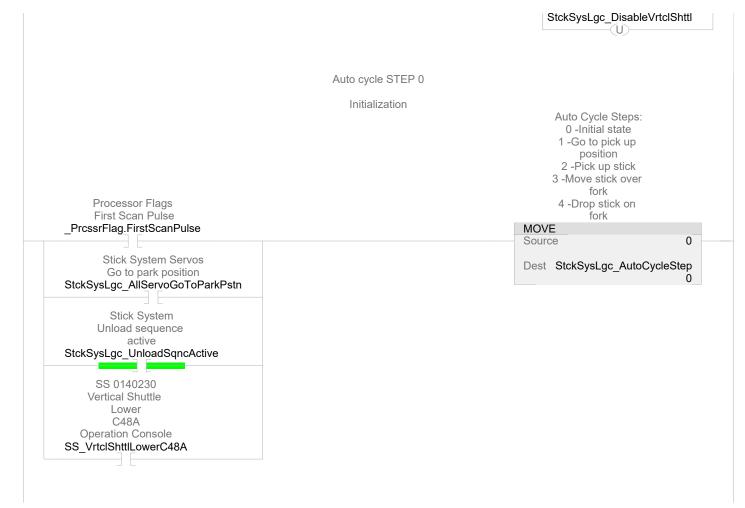
...9 Molalla, OR\Program PLC\RSG MolallaSmStacker 20250831C.ACD



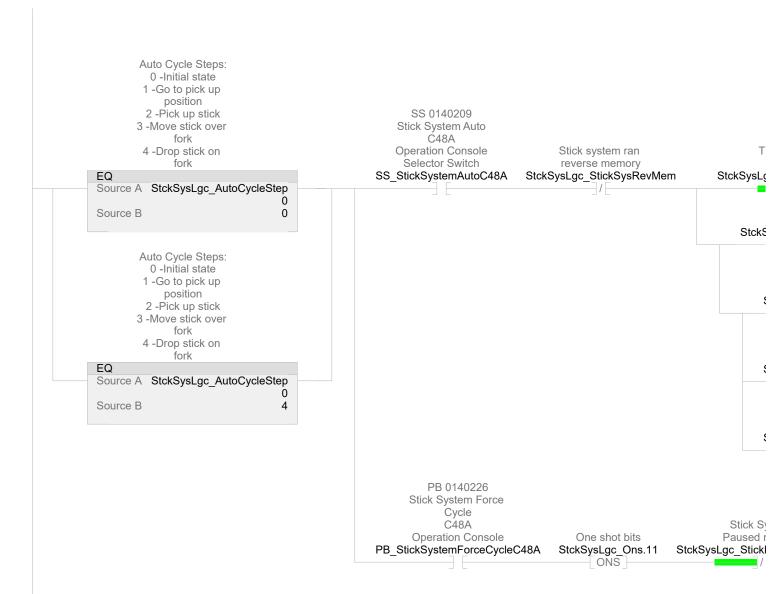
Total number of rungs in routine: 27 ..9 Molalla, OR\Program PLC\RSG MolallaSmStacker 20250831C.ACD

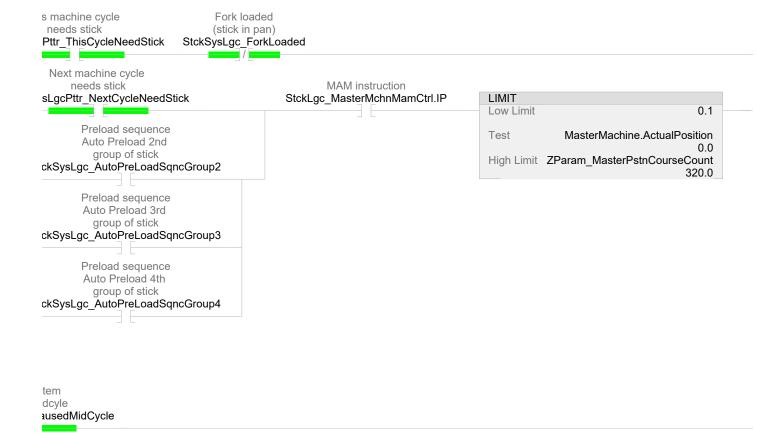


...9 Molalla, OR\Program PLC\RSG_MolallaSmStacker_20250831C.ACD



Total number of rungs in routine: 279 Molalla, OR\Program PLC\RSG_MolallaSmStacker_20250831C.ACD





...9 Molalla, OR\Program PLC\RSG_MolallaSmStacker_20250831C.ACD

Auto Cycle STEP 1

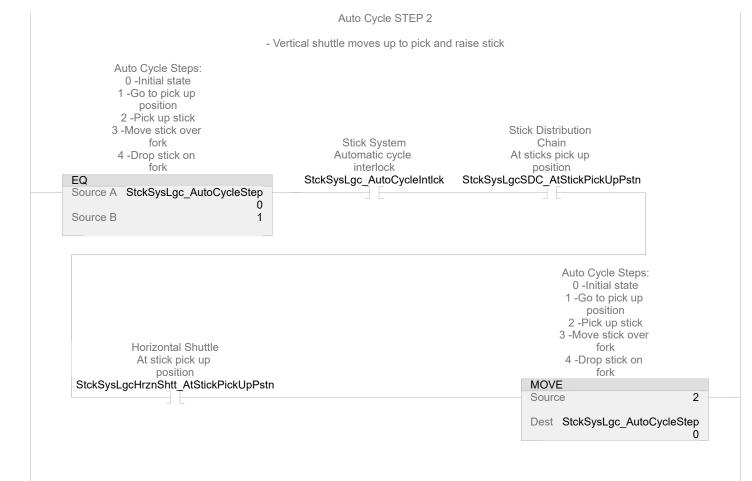
- Stick distribution chain moves to stick pick up position - Horizontal shuttle moves to stick pick up position





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...9 Molalla, OR\Program PLC\RSG_MolallaSmStacker_20250831C.ACD

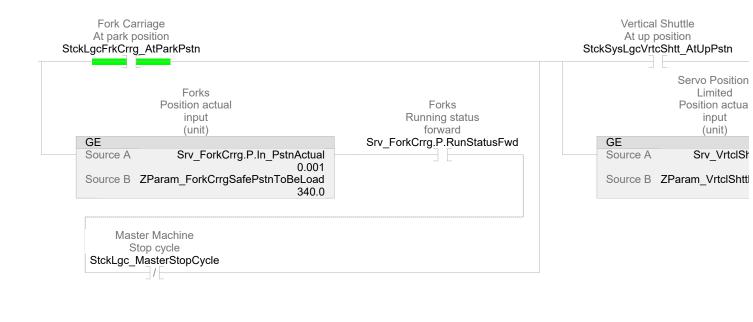


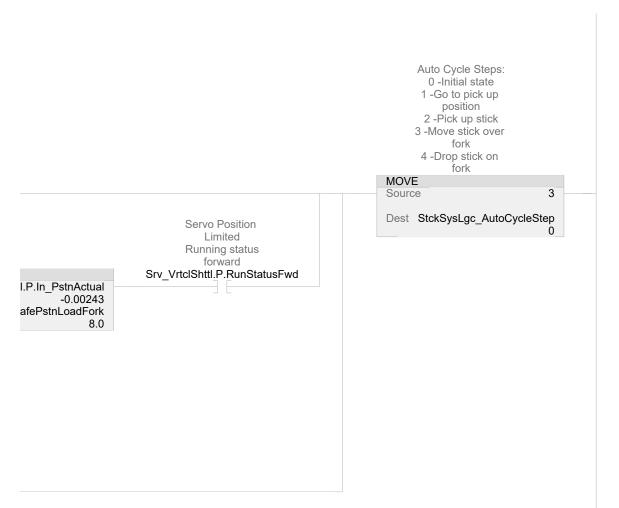
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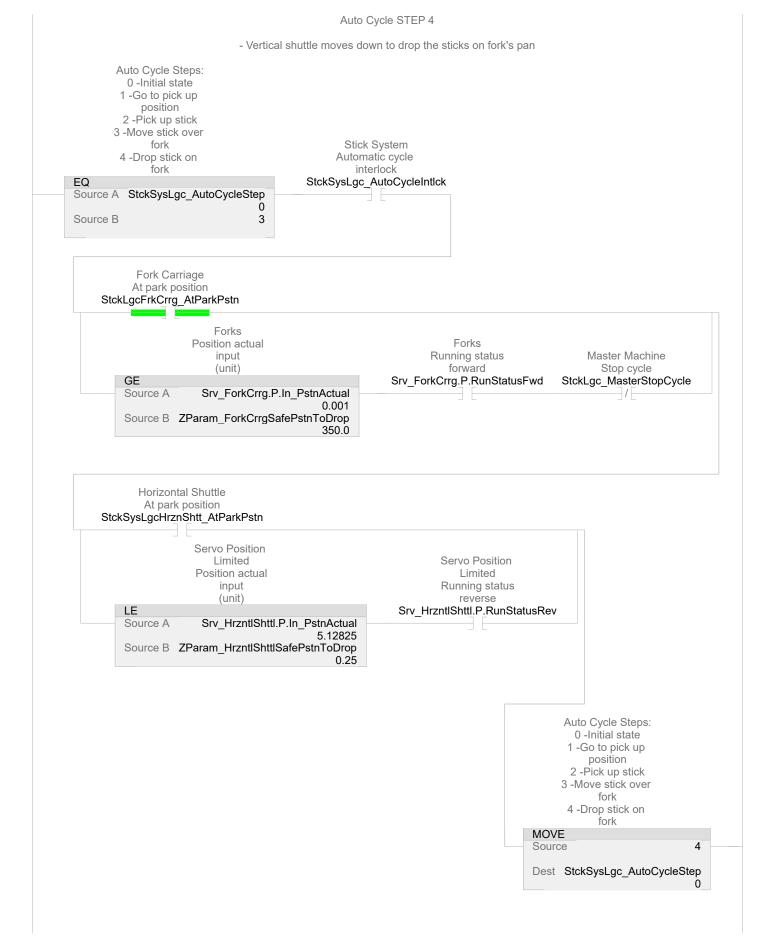


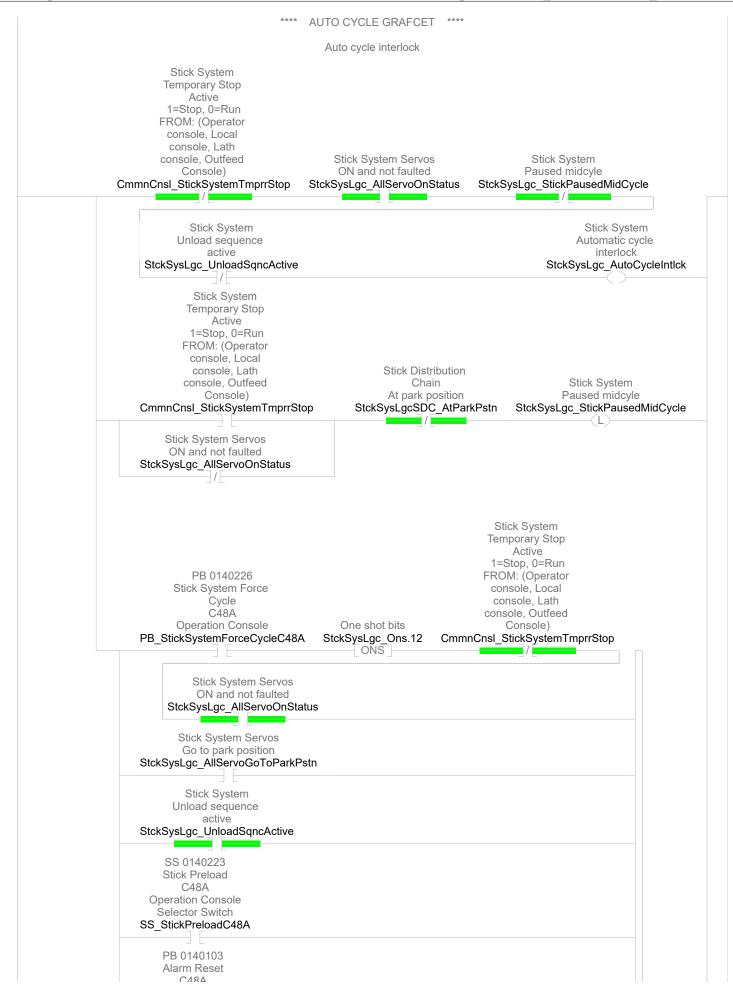
Auto Cycle STEP 3

- Horizontal shuttle moves toward the fork to bring stick over the pan - Stick distribution chain moves to park position position, so the shuttle doesn't touch sticks on the chain



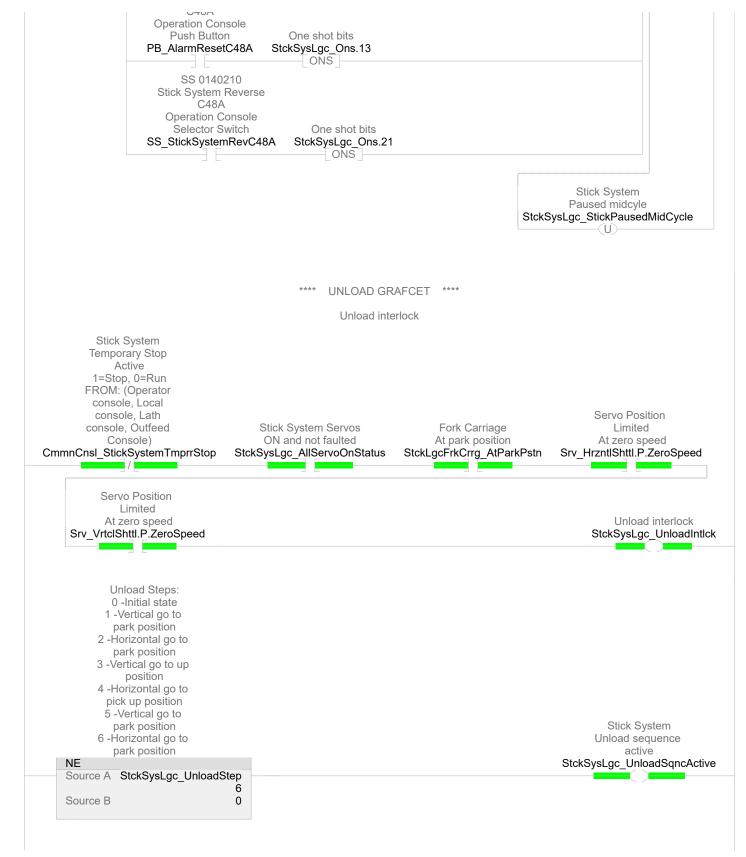






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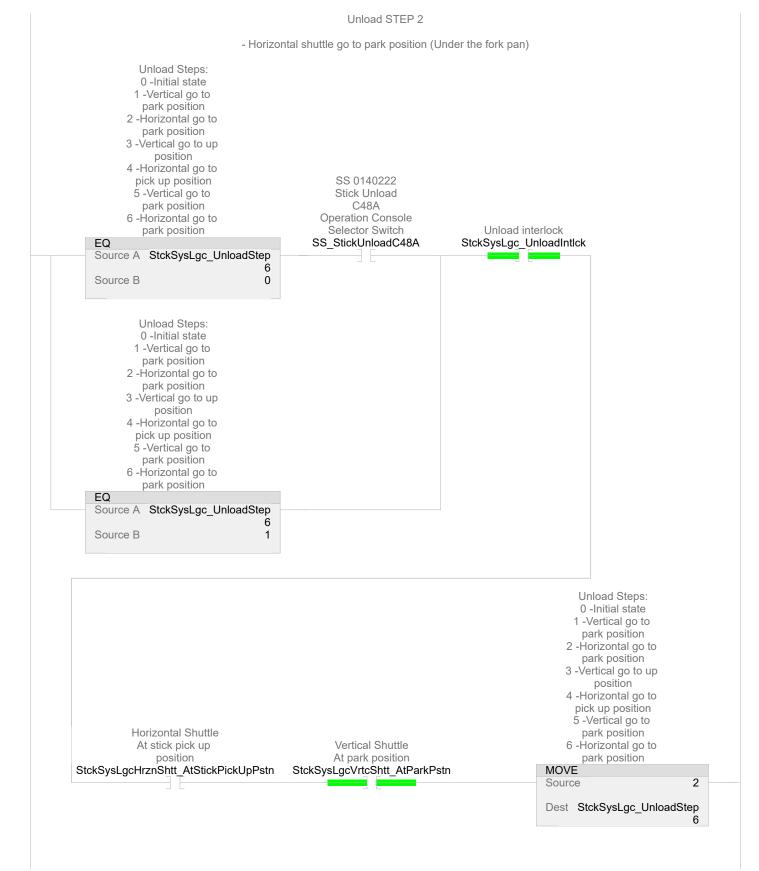
9/5/2025 1:40:28 PM Total number of rungs in routine: 27 ...9 Molalla, OR\Program PLC\RSG MolallaSmStacker 20250831C.ACD



17

Unload STEP 0 Initialization Processor Flags First Scan Pulse _PrcssrFlag.FirstScanPulse Stick System Servos Go to park position StckSysLgc_AllServoGoToParkPstn Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to park position 6 -Horizontal go to Horizontal Shuttle Vertical Shuttle park position At park position At park position EQ StckSysLgcHrznShtt_AtParkPstn StckSysLgcVrtcShtt_AtParkPstn Source A StckSysLgc_UnloadStep 6 Source B Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to park position 6 -Horizontal go to park position MOVE 0 Source Dest StckSysLgc_UnloadStep RSGMolalla SMMocoStckr:MainTask:ServoStickSystemLogic Total number of rungs in routine: 27

Unload STEP 1 - Vertical shuttle moves to park position (it moves down) Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to SS 0140222 pick up position 5 -Vertical go to Stick Unload C48A park position 6 -Horizontal go to **Operation Console** Selector Switch Unload interlock park position EQ SS_StickUnloadC48A StckSysLgc_UnloadIntlck Source A StckSysLgc_UnloadStep 6 Source B 0 Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to Horizontal Shuttle park position At stick pick up Vertical Shuttle 6 -Horizontal go to position At up position park position MOVE $StckSysLgcHrznShtt_AtStickPickUpPstn$ StckSysLgcVrtcShtt_AtUpPstn Source 1 Dest StckSysLgc_UnloadStep



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Unload STEP 3 - Vertical shuttle moves up to pick stick from fork pan Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position SS 0140222 5 -Vertical go to Stick Unload park position C48A 6 -Horizontal go to **Operation Console** Selector Switch Unload interlock park position EQ SS_StickUnloadC48A StckSysLgc_UnloadIntlck Source A StckSysLgc UnloadStep 6 Source B Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to park position 6 -Horizontal go to park position EQ Source A StckSysLgc_UnloadStep 6 Source B Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to park position Horizontal Shuttle Vertical Shuttle 6 -Horizontal go to At park position At park position park position StckSysLgcHrznShtt_AtParkPstn StckSysLgcVrtcShtt_AtParkPstn MOVE 3 Dest StckSysLgc_UnloadStep

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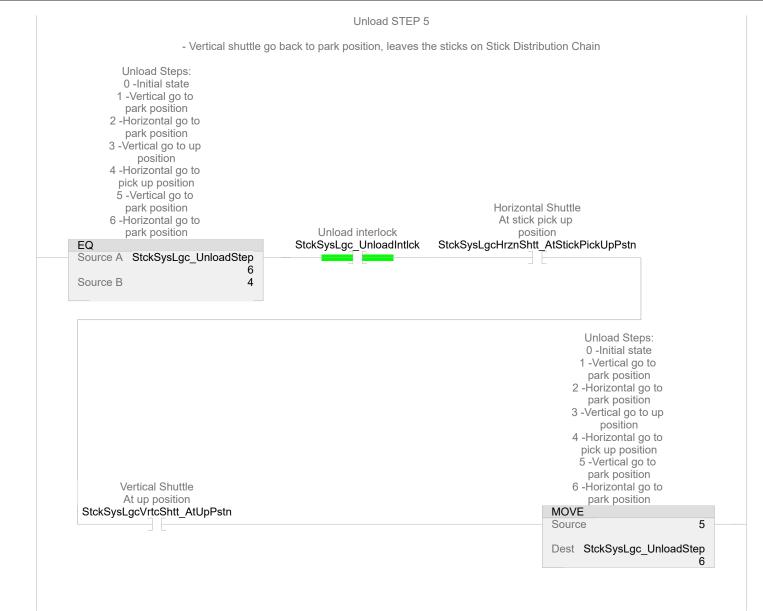
21

Unload STEP 4 - Horizontal shuttle moves away from fork (moves to auto cycle "stick pick up position") Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position SS 0140222 5 -Vertical go to Stick Unload park position C48A 6 -Horizontal go to **Operation Console** Selector Switch Unload interlock park position EQ SS_StickUnloadC48A StckSysLgc_UnloadIntlck Source A StckSysLgc UnloadStep 6 Source B Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to park position 6 -Horizontal go to park position EQ Source A StckSysLgc_UnloadStep 6 Source B Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to park position Horizontal Shuttle Vertical Shuttle 6 -Horizontal go to At park position At up position park position StckSysLgcHrznShtt_AtParkPstn StckSysLgcVrtcShtt_AtUpPstn MOVE 4 Dest StckSysLgc_UnloadStep

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...9 Molalla, OR\Program PLC\RSG MolallaSmStacker 20250831C.ACD



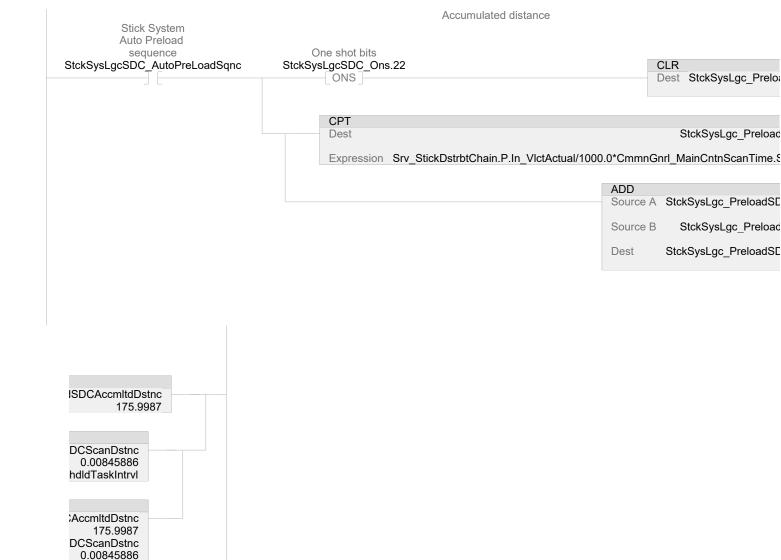
Unload STEP 6 - Horizontal shuttle go back to park position (Under the fork pan) Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to Horizontal Shuttle park position 6 -Horizontal go to At stick pick up Unload interlock park position position $StckSysLgcHrznShtt_AtStickPickUpPstn$ EQ StckSysLgc_UnloadIntlck Source A StckSysLgc UnloadStep 23 6 Source B 5 Unload Steps: 0 -Initial state 1 -Vertical go to park position 2 -Horizontal go to park position 3 -Vertical go to up position 4 -Horizontal go to pick up position 5 -Vertical go to park position Vertical Shuttle 6 -Horizontal go to At park position park position MOVE StckSysLgcVrtcShtt_AtParkPstn Source 6 Dest StckSysLgc_UnloadStep Stick System Logic Stick Inloaded StckSysLgc_StickUnloaded SS 0140209 Stick System Auto C48A Operation Console Stick System Logic Selector Switch One shot bits Stick Inloaded StckSysLgc_StickUnloaded SS_StickSystemAutoC48A StckSysLgc_Ons.14 ONS (U)

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AccmltdDstnc 175.9987

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Total number of rungs in routine: 279 Molalla, OR\Program PLC\RSG_MolallaSmStacker_20250831C.ACD



264.0

Stick System Stick S Auto Preload Stick System Auto Pr Auto Preload Sequence Group 4 Sequence Accumulated Distance sequence Accumulate StckSysLgcSDC_AutoPreLoadSqnc MUL MUL Source A Srv_StickDstrbtChain.P.AxisPrprtPstnUnwind Source A Srv_StickDstrbt0 104.0 Source B Source B Dest StckSysLgc_AutoPreLoadSqncGroup4Dstnc Dest StckSysLgc_Au GT Source A StckSysLgc_PreloadSDCAccmltdDstnc Source B StckSysLgc_AutoPreLoadSqncGroup4Dstnc 0.88 GT Source A StckSysLgc_PreloadSDCAccmltdDstnc 175.9987 Source B StckSysLgc_AutoPreLoadSqncGroup3Dstnc 176.0 GT StckSysLgc PreloadSDCAccmltdDstnc Source A Source B StckSysLgc_AutoPreLoadSqncGroup2Dstnc

...9 Molalla, OR\Program PLC\RSG MolallaSmStacker 20250831C.ACD

Stick System tem Auto Preload oad iroup 3 Sequence Group 2 Distance Accumulated Distance MUL Source A Srv_StickDstrbtChain.P.AxisPrprtPstnUnwind nain.P.AxisPrprtPstnUnwind 104.0 104.0 2 Source B 3 PreLoadSqncGroup3Dstnc Dest StckSysLgc_AutoPreLoadSqncGroup2Dstnc 176.0 Stick System Auto Preload Sequence Group 4 Loaded $StckSysLgc_AutoPreLoadSqncGroup4loaded$ Stick System Auto Preload Sequence Group 3 Loaded StckSysLgc_AutoPreLoadSqncGroup3Loaded Stick System Auto Preload Sequence Group 2 Loaded StckSysLgc_AutoPreLoadSqncGroup2Loaded

(End)