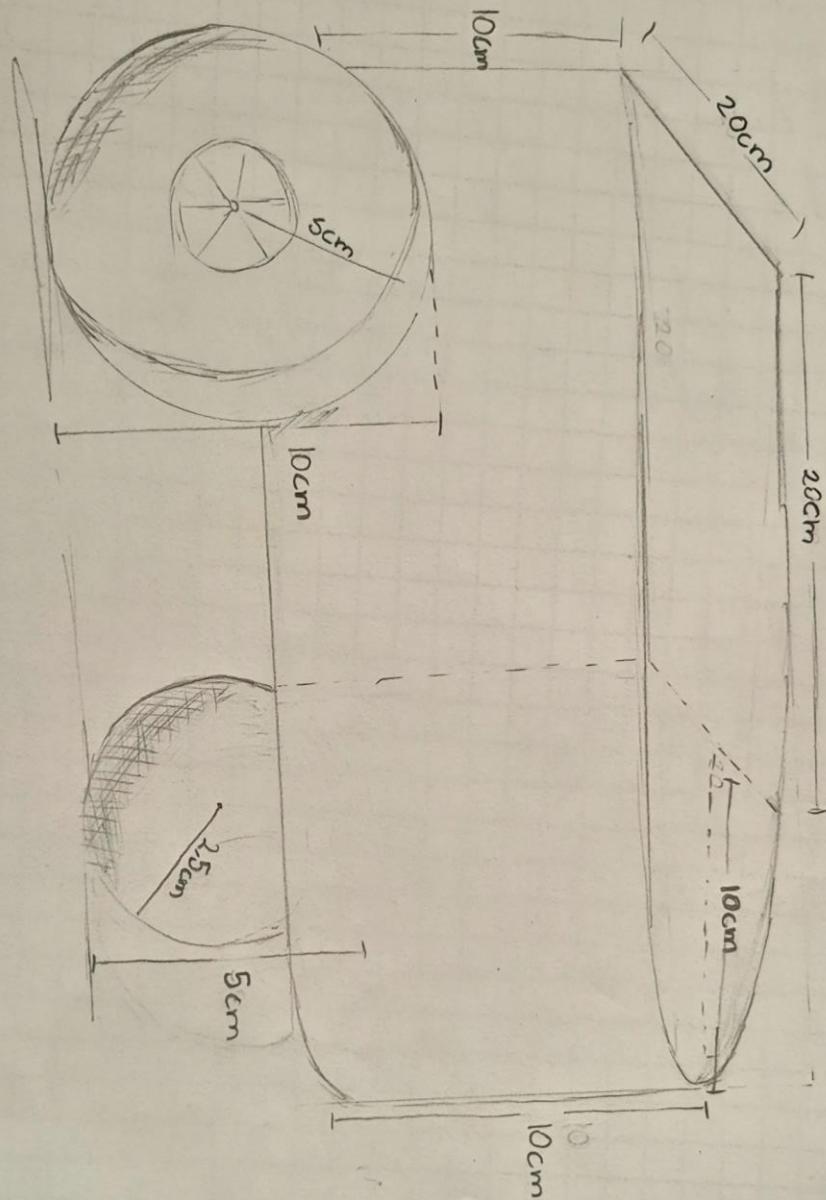
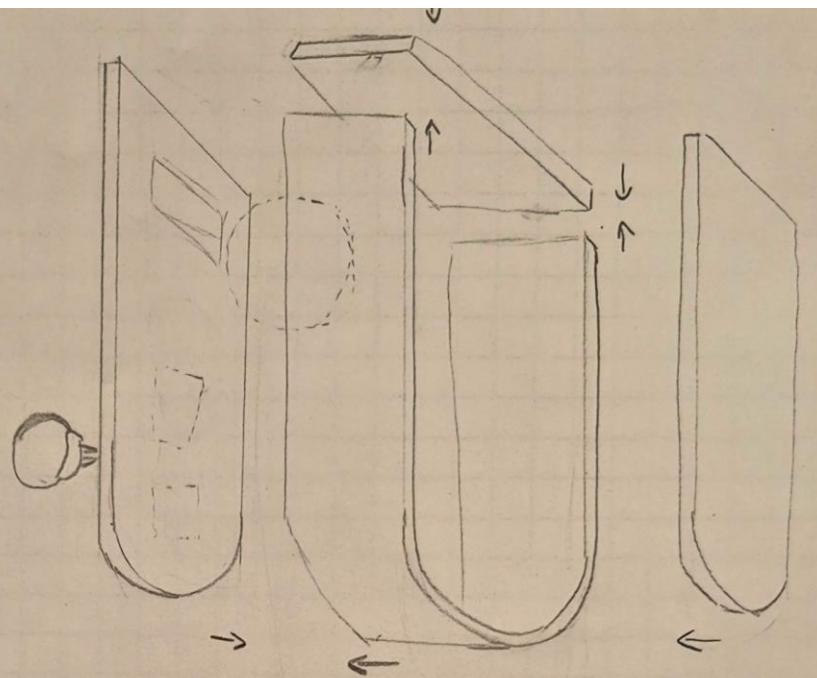


Diseño General

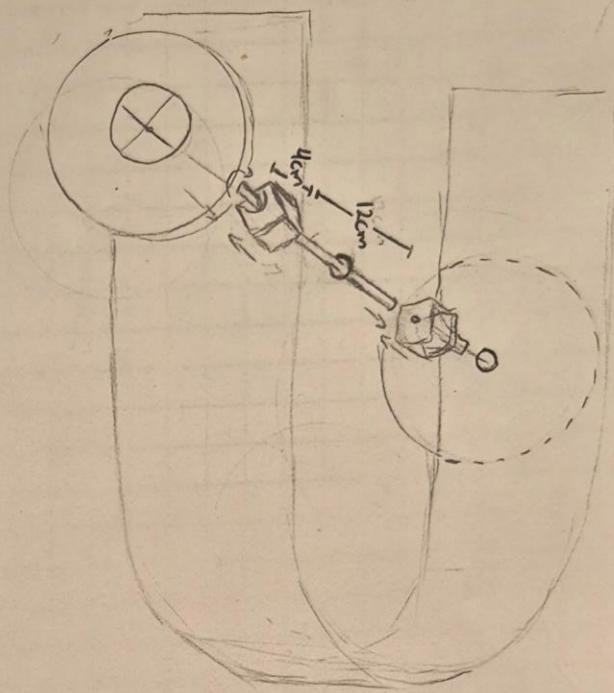




TOP

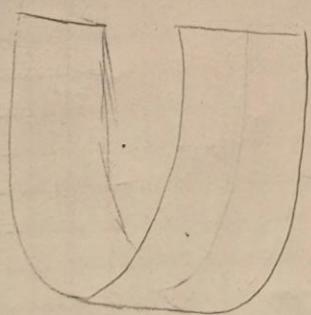
Wheel Chassis

Base Inferior

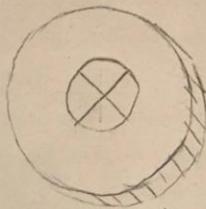


- Conectar : Rueda → Chasis ↴
↳ Motor → Soporte

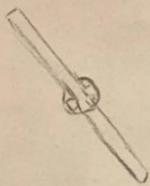
• Ambos lados



Chassis



Rueda



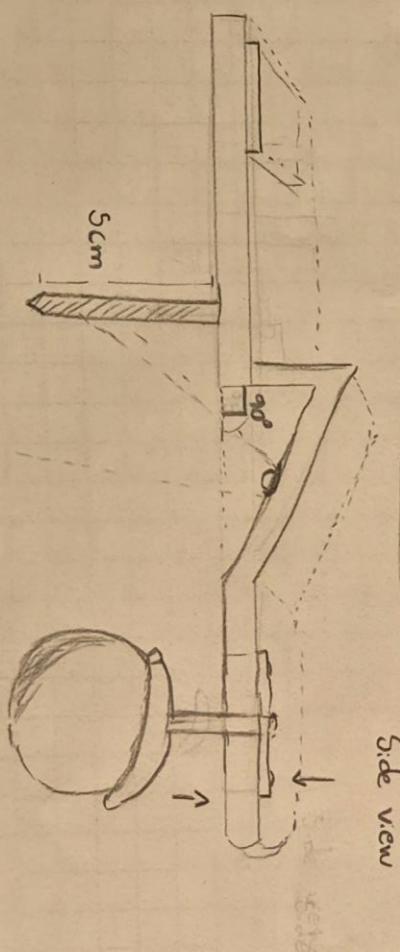
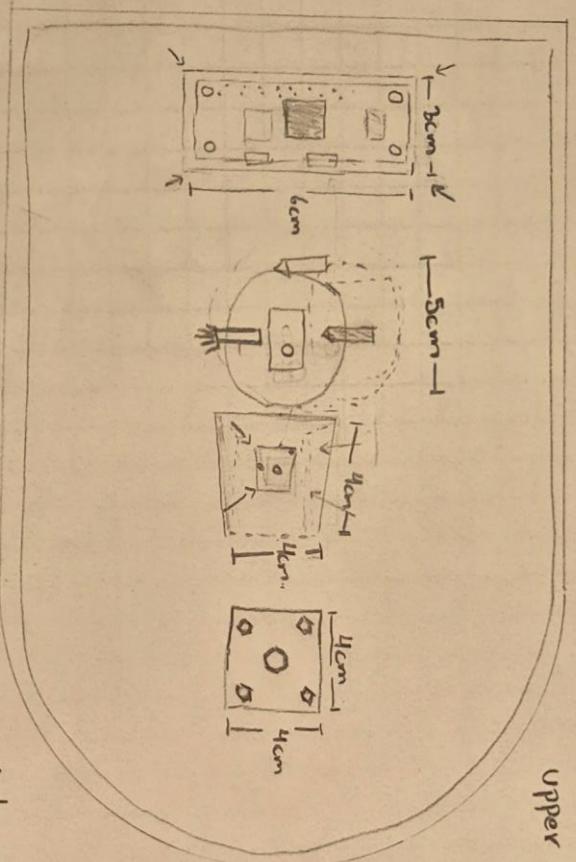
Soporte



Motor
Nema 17

Base (Inferior)

upper view



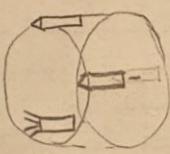
side view



Raspberry
Pi camera

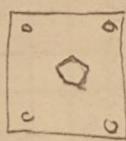


Sonar
sensor



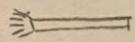
LoRa

Caster
wheel



Mecanismo escritura y borrado

Lapiz borrador



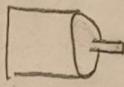
soporte lápiz - micro servo



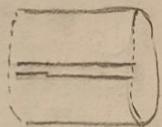
Lapiz negro/rojo



motor hima 17



soporte cilindrico



Micro servo

