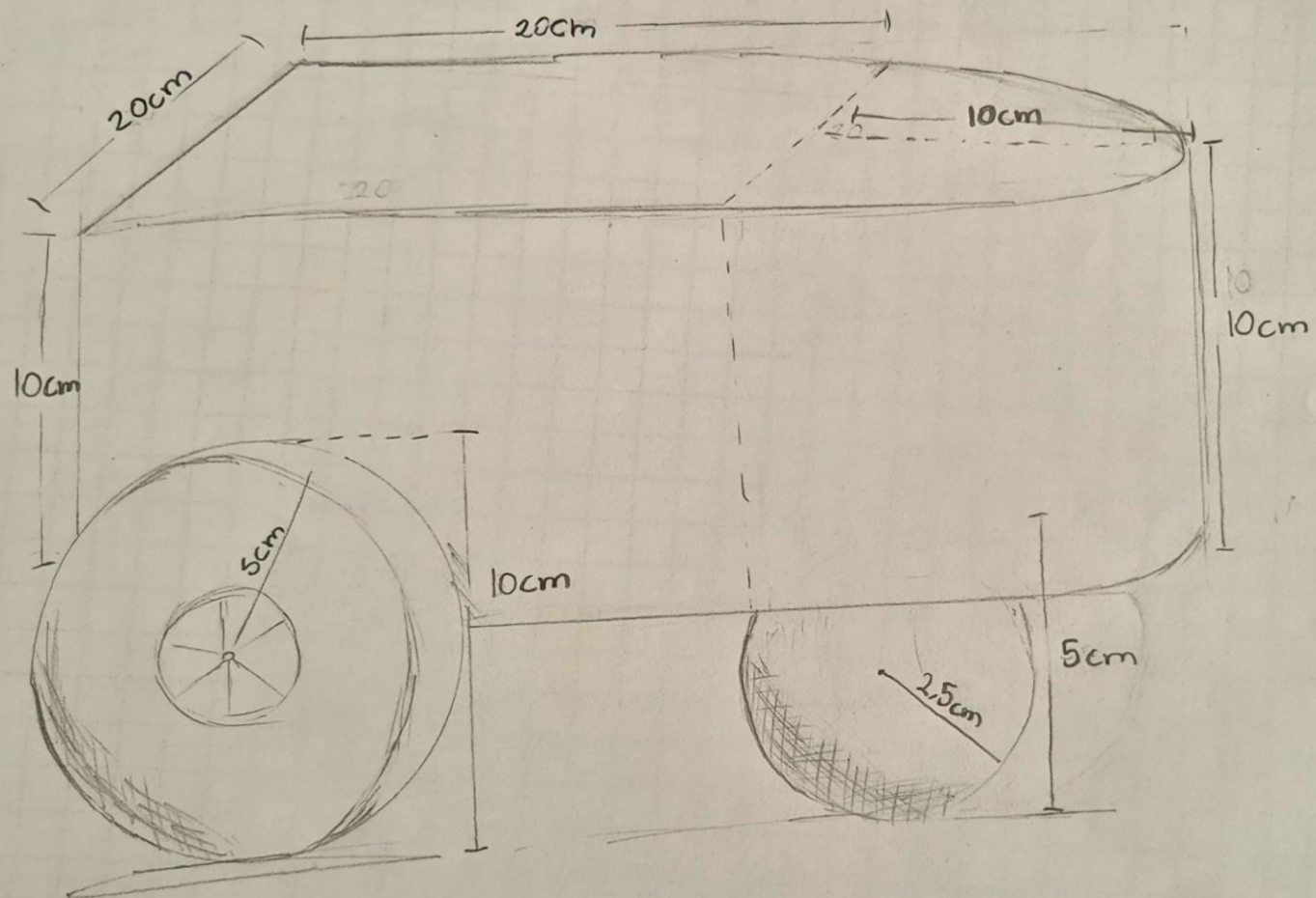
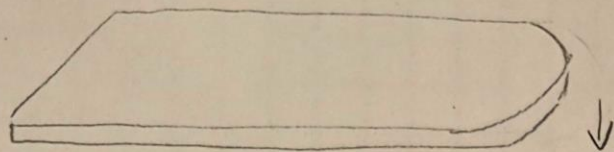
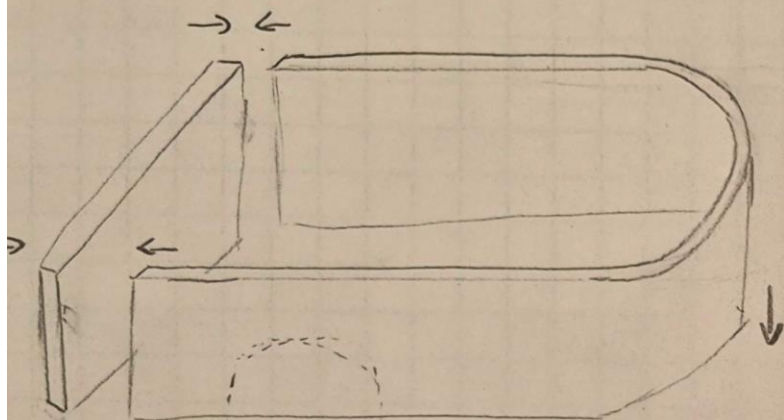


Diseño General

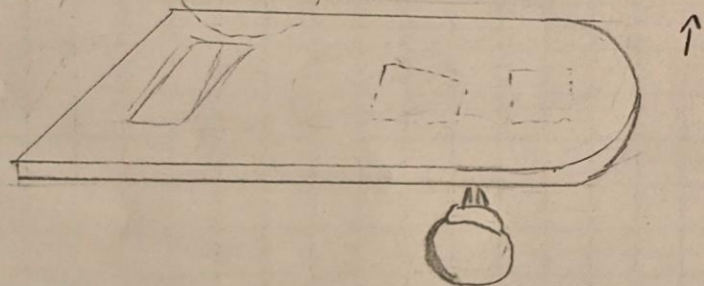




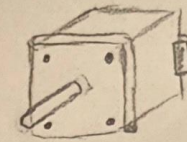
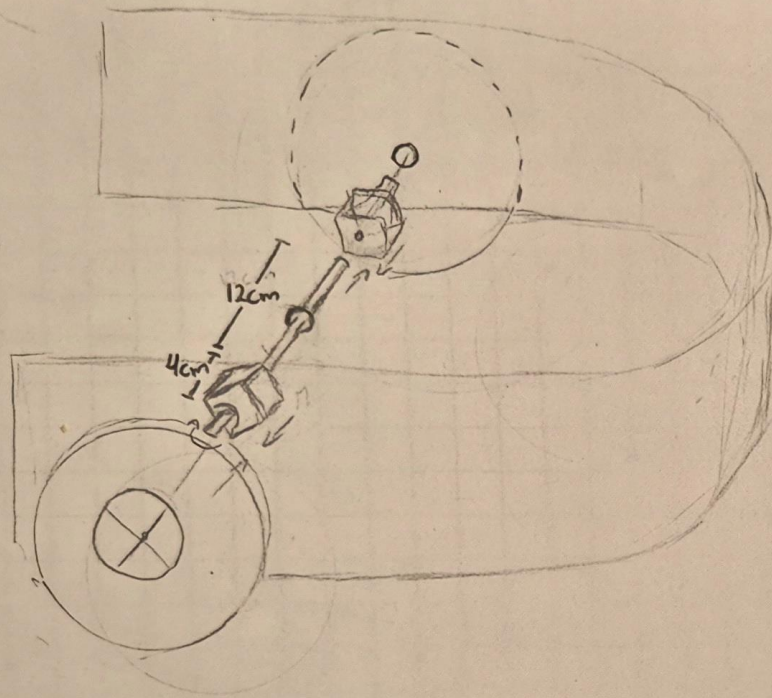
Top



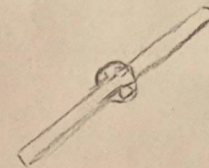
Wheel Chassis



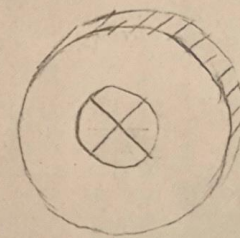
Base Inferior



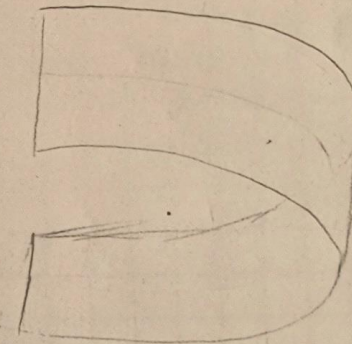
Motor
Nema 17



Soporte



Rueda



Chasis

• Conectar : Rueda → Chasis

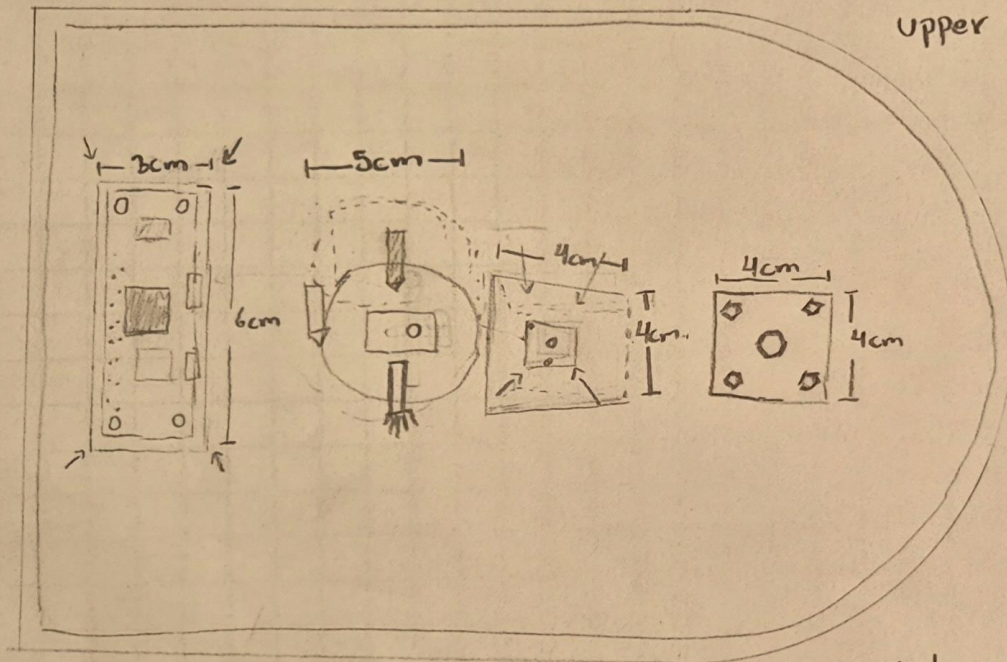
↳ Motor → Soporte

• Ambos lados

• Ambos lados

Base (Inferior)

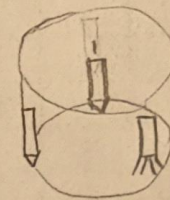
upper view



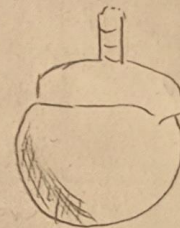
Raspberry
Pi zero 2w



Raspberry
Pi camera

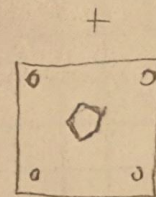
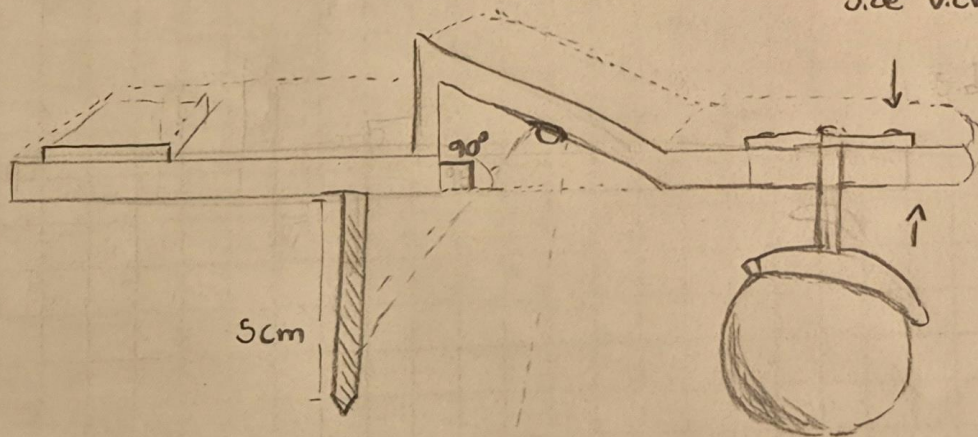


Soporte
Logico

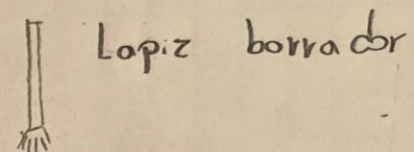
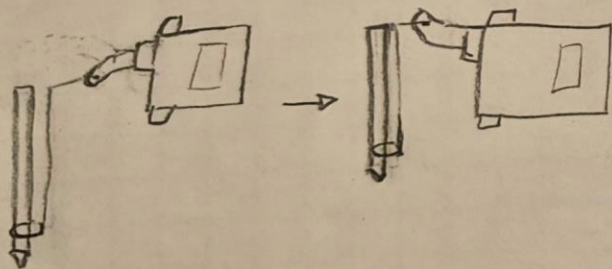
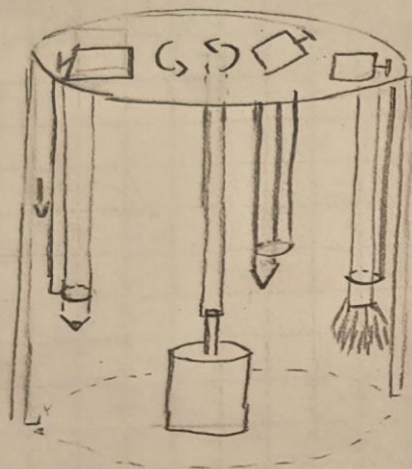


Caster
wheel

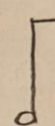
side view



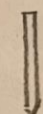
Mecanismo escritura y borrado



Lapiz borrador



soporte lapiz - micro servo



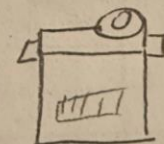
Lapiz negro/rojo



motor nema 17



soporte cilindrico



Micro servo