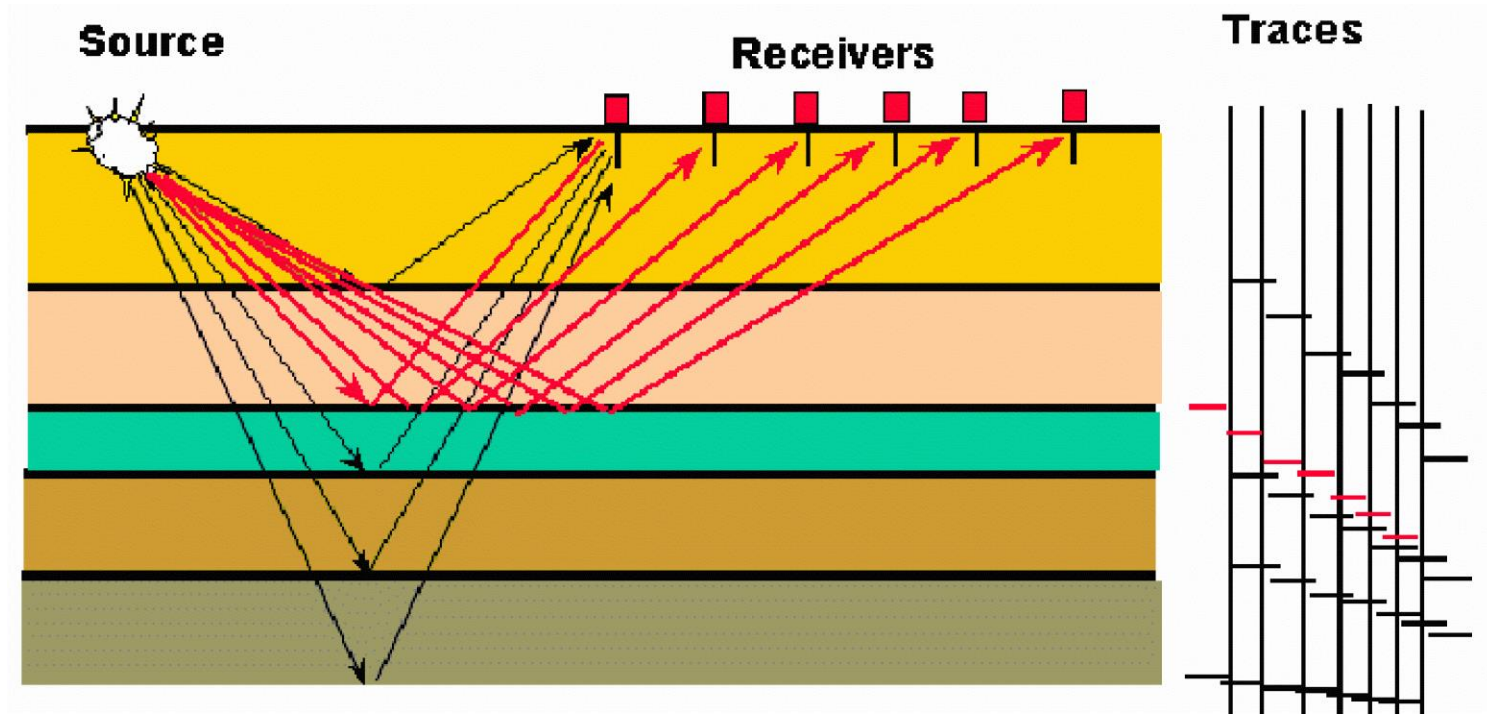


# 10. Reflection seismic

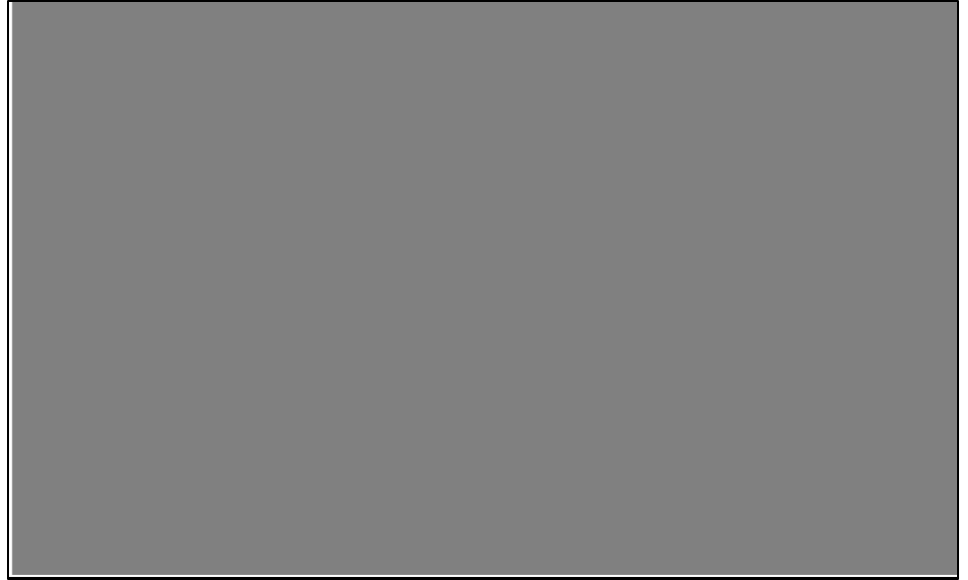
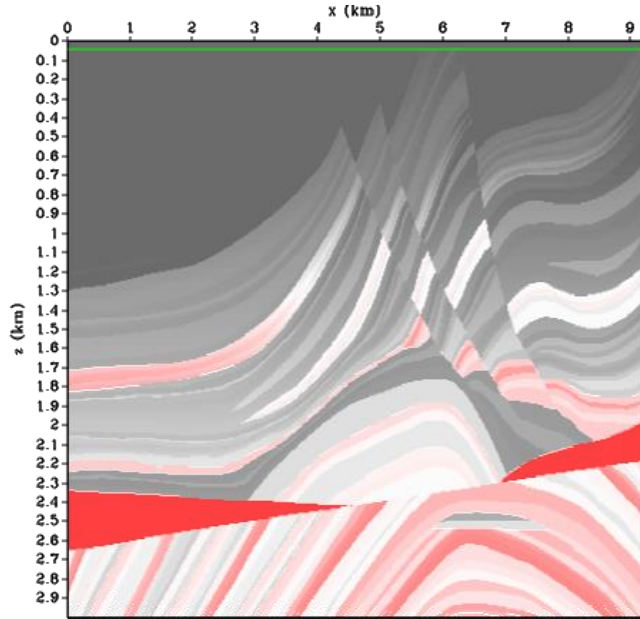
**M. Ravasi**

**ERSE 210 Seismology**

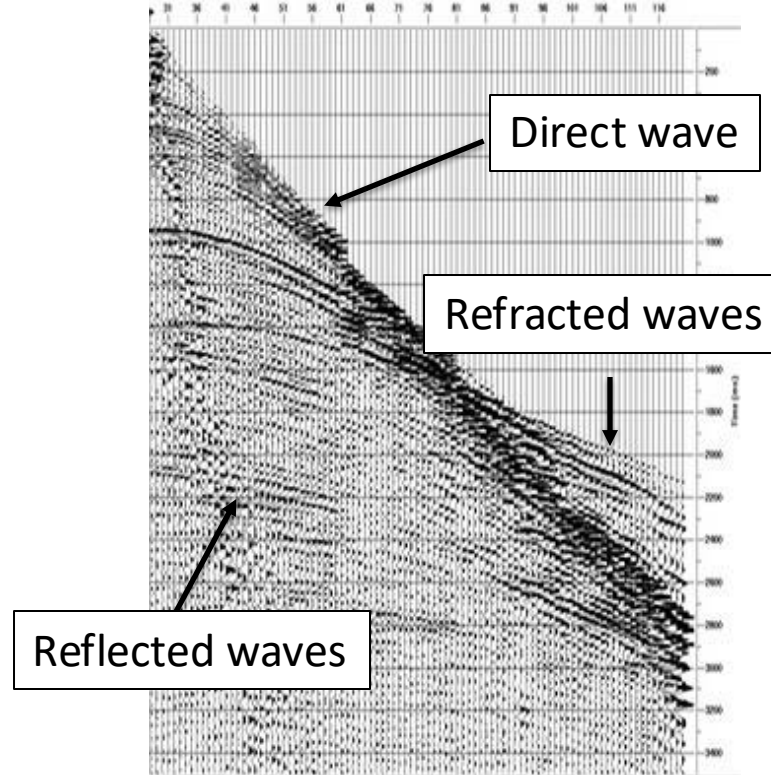
# Seismic acquisition



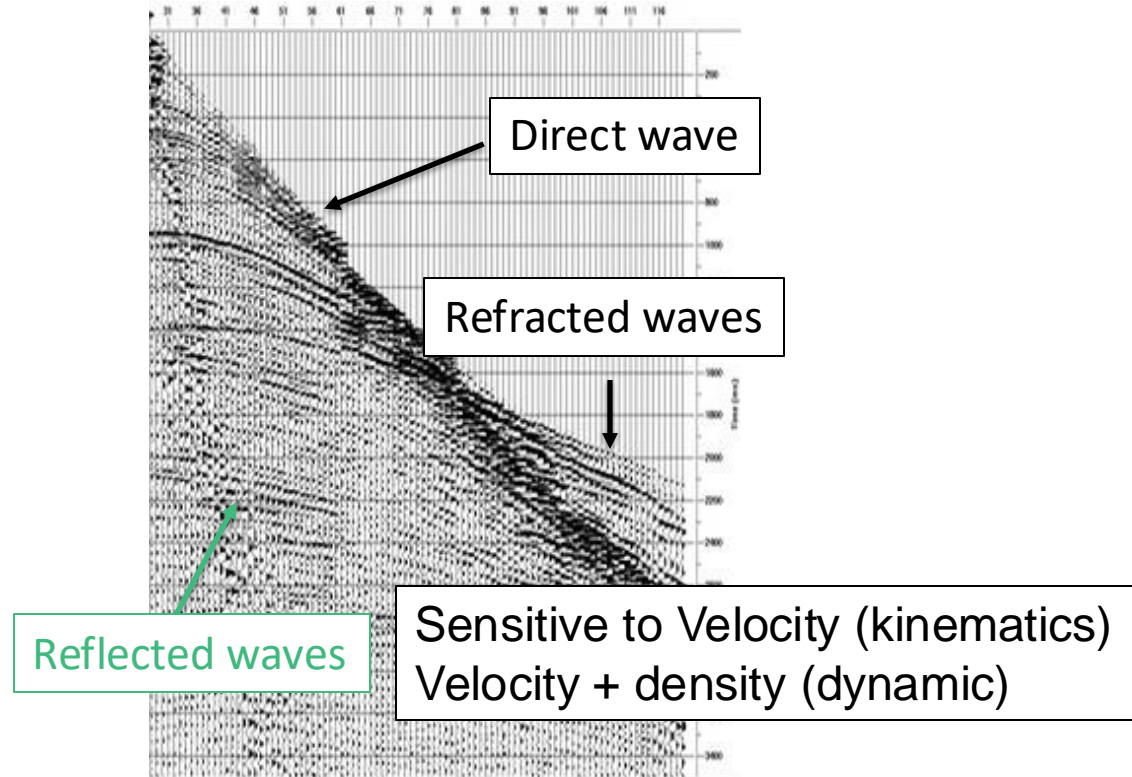
# Seismic propagation movie



# Seismic recordings

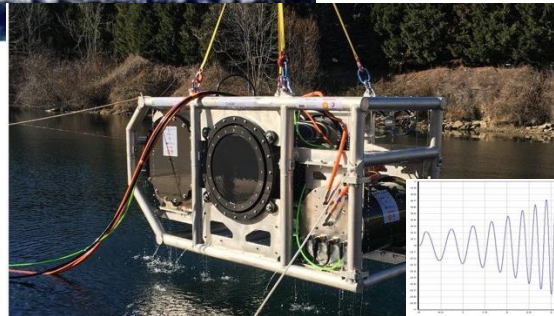


# Seismic recordings



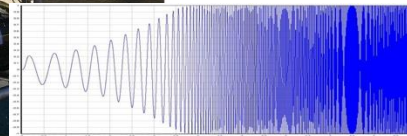
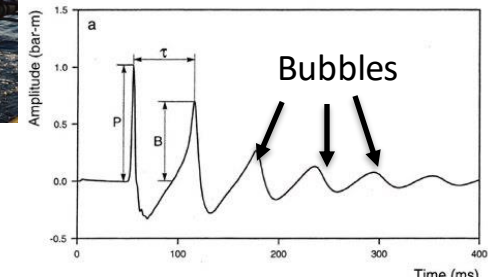
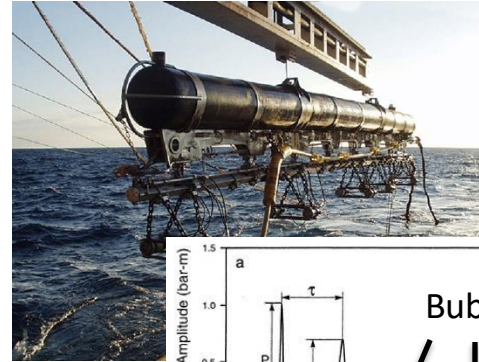
# Seismic sources - marine

**Dynamite**



**Marine Vibroseis**

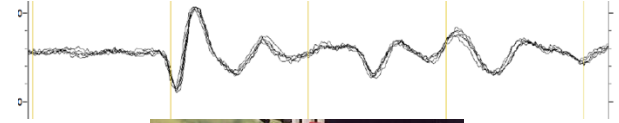
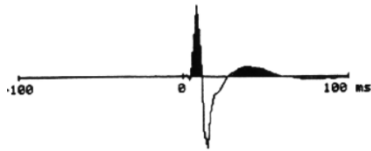
**Airgun**



**Sweep  
(chirp)**

# Seismic sources - land

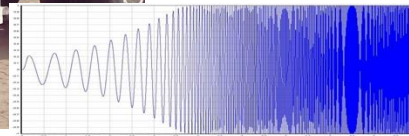
## Dynamite



## Weightdrop



## Vibroseis



Sweep  
(chirp)

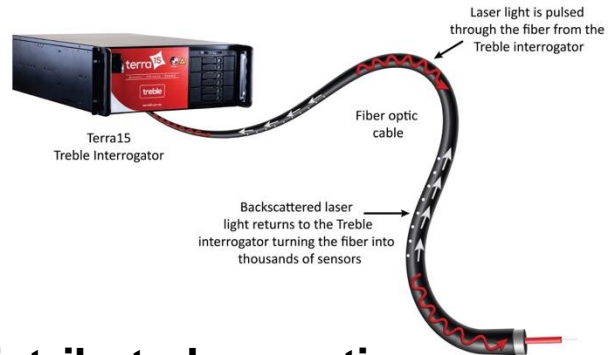


# Seismic receivers

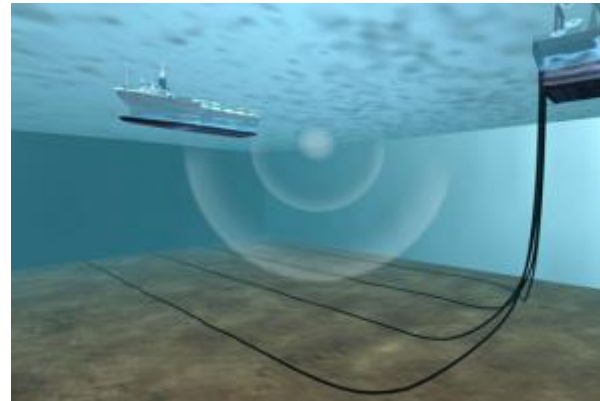
## Geophones



## Streamer



## Distributed acoustic sensing (DAS)



## Ocean bottom cables or nodes



# Seismic receivers - land

**Moving-coil  
Geophones  
(velocity)**



**Piezoelectric  
(acceleration)**



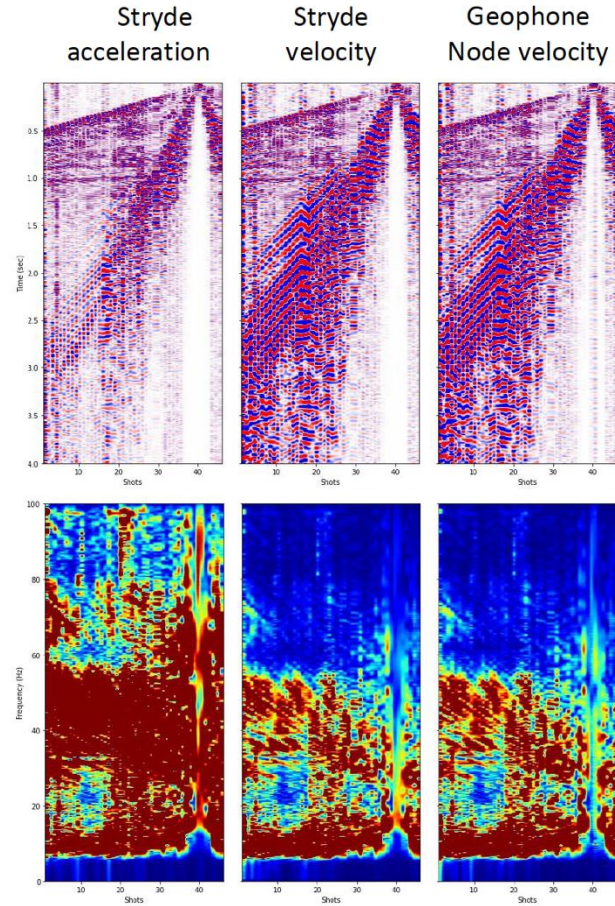
**MEMS  
(acceleration)**

# Seismic receivers - land



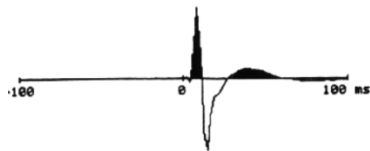
Geophones

Stryde node



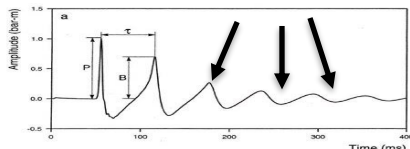
# Seismic sources - signature

## Dynamite



Easy to handle, almost ideal (spike)

## Aiguns



One main peak followed by reverberations (bubbles), due to how energy is released. Several methods to estimate and remove bubbles and spike the main peak:

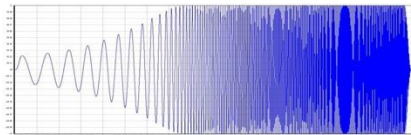
- Data-driven / statistical
- Near-field hydrophones
- Far-field signature modelling

} Estimate

Decon or shaping to remove:  $d(t) = s(t) * r(t)$

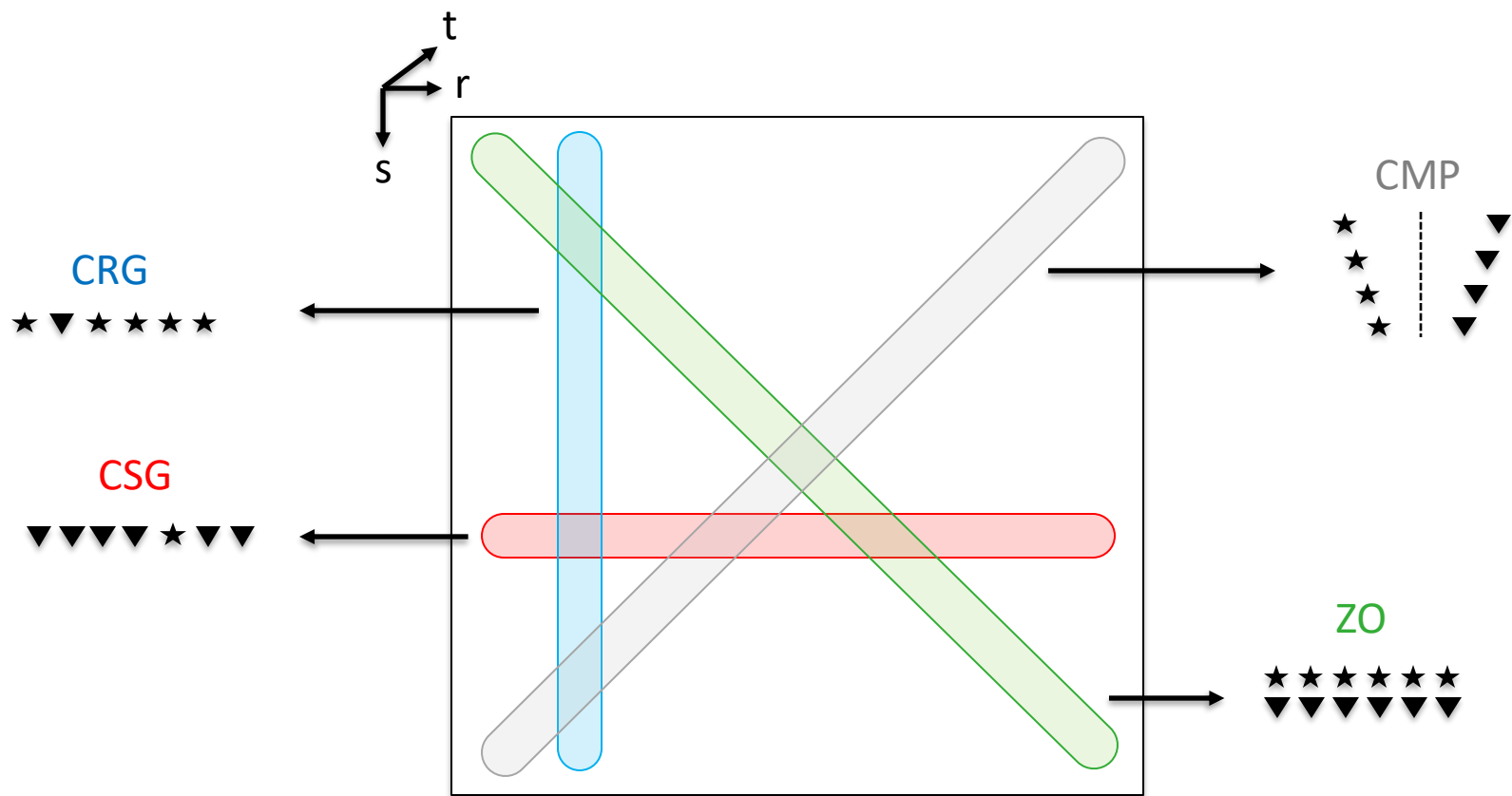
$$d_{shaped}(t) = F^{-1} \left( \frac{F(d(t)) \cdot S^*(\omega)}{|S(\omega)|^2} \right)$$

## Vibroseis



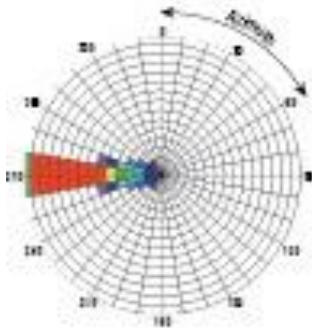
Correlation to turn chirp into spike:  $d_{shaped}(t) = d(t) * s(-t) \approx r(t)$

# Seismic Data Arrangements

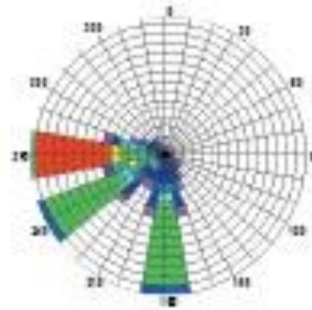


# Seismic marine geometries

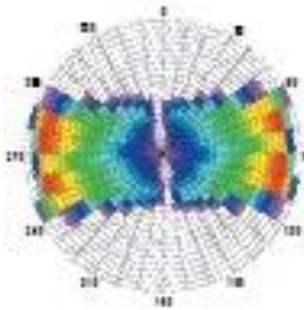
**Narrow-Azimuth**



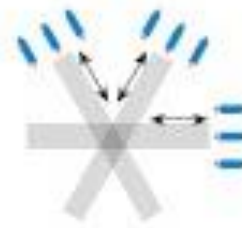
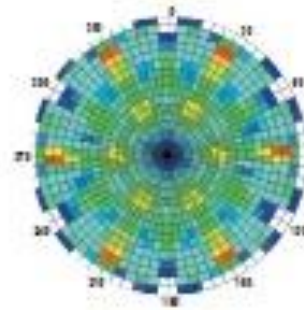
**Multiazimuth**



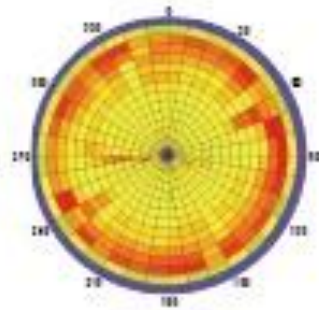
**Wide-Azimuth**



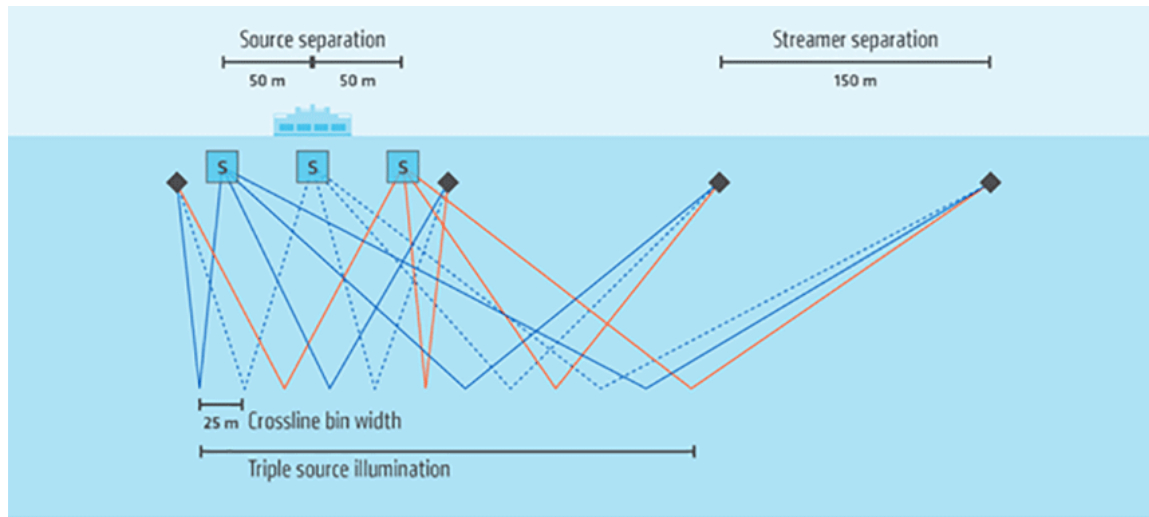
**Rich-Azimuth**



**Coil Shooting**

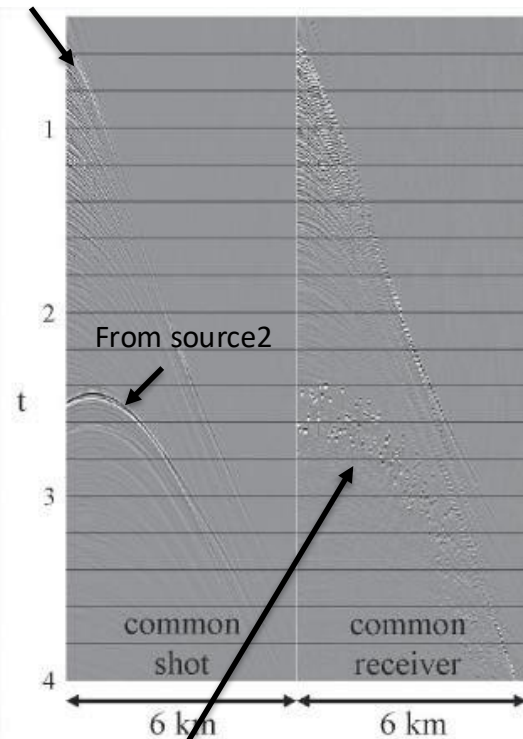


# Simultaneous shooting



$$J = \|\Gamma^H \mathbf{b} - \mathbf{L}\mathbf{m}\|_p + \varepsilon \|\mathbf{m}\|_1$$

From source1



Dithered source = Noise



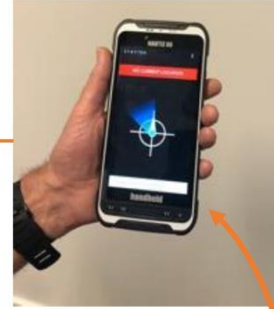
# Seismic acquisition in KAUST



# Seismic acquisition in KAUST



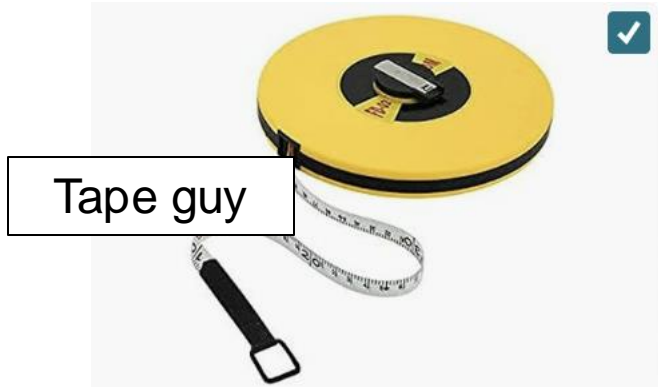
NAVIGATOR tablet



Initialisation device

# Seismic acquisition in KAUST

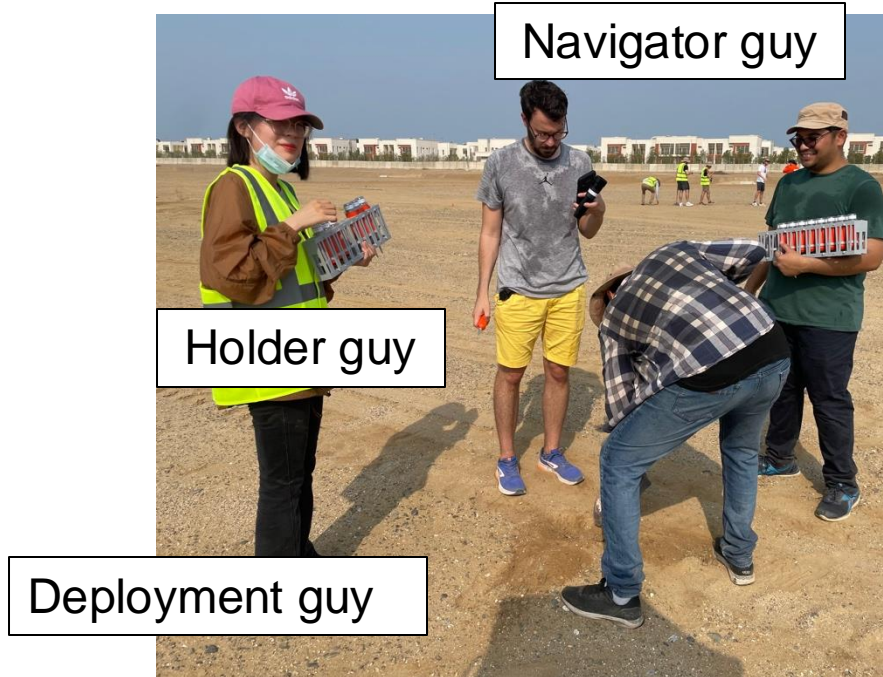
Survey 'identification': 2 teams of 3 people





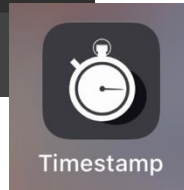
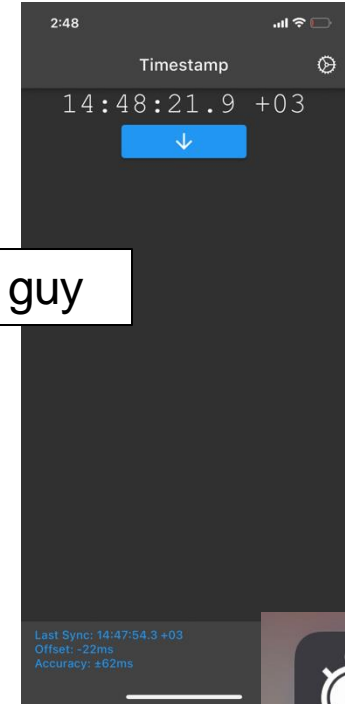
# Seismic acquisition in KAUST

Sensor deployment: 2 teams of 3 people (will rotate...)

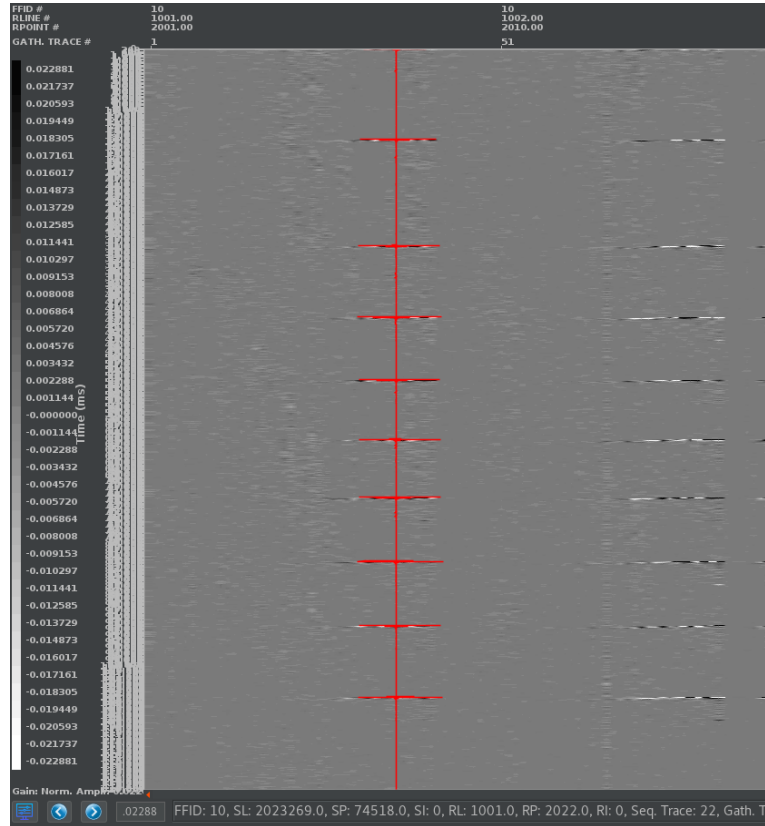


# Seismic acquisition in KAUST

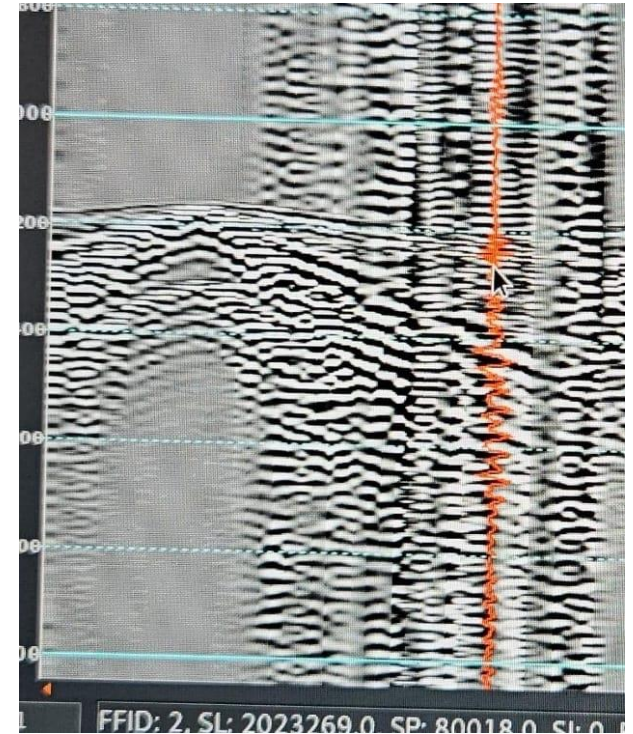
Shooting: 1 team of 3 people (will rotate...)



# Seismic processing in KAUST

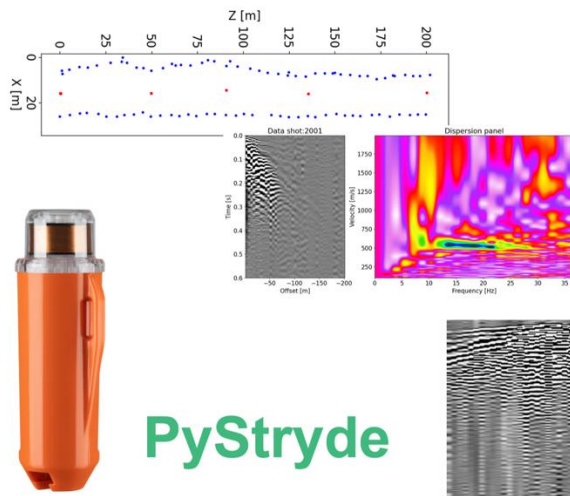


Create shot  
records





# Seismic processing in KAUST

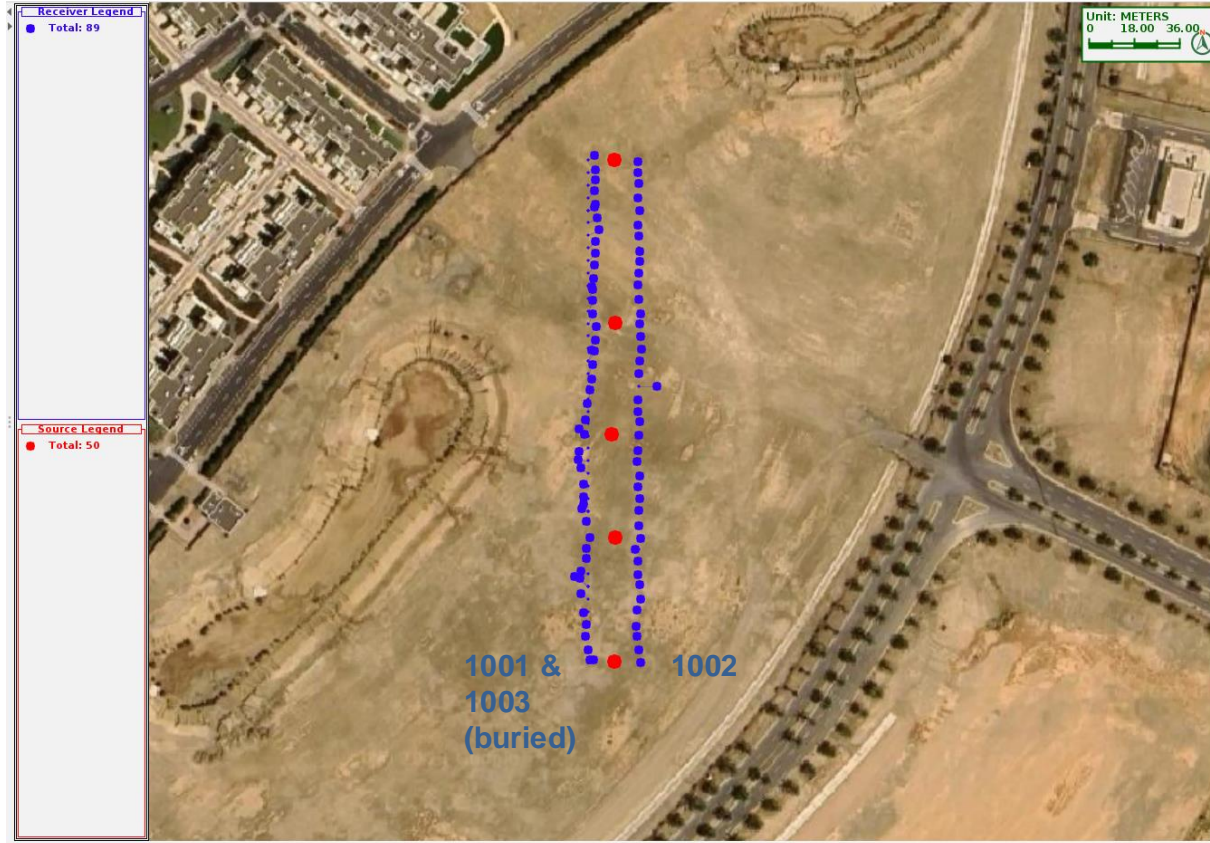


This repository contains all the routines that our group has created to manipulate and visualize SEG-Y data produced by STRYDE SeismicQC software.

Moreover, all the notebooks created to perform basic analysis of the data acquired over time are also available for others to get started with the associated data.

<https://github.com/DIG-Kaust/StrydeProjects>

# A sneak peek from our first experiment



## Receivers:

2 lines of 41 planted receivers each, equally spaced by 5m for a total length of 200m (lines separated by 20m).

1 line of 7 buried receivers spaced 30m apart

## Shots:

5 Shots placed in between 2 lines at Point 2041, 2028, 2019, 2011, 2001 in order of shooting.

10 shots per source starting at time:

2041: 10:45

2028: 10:51

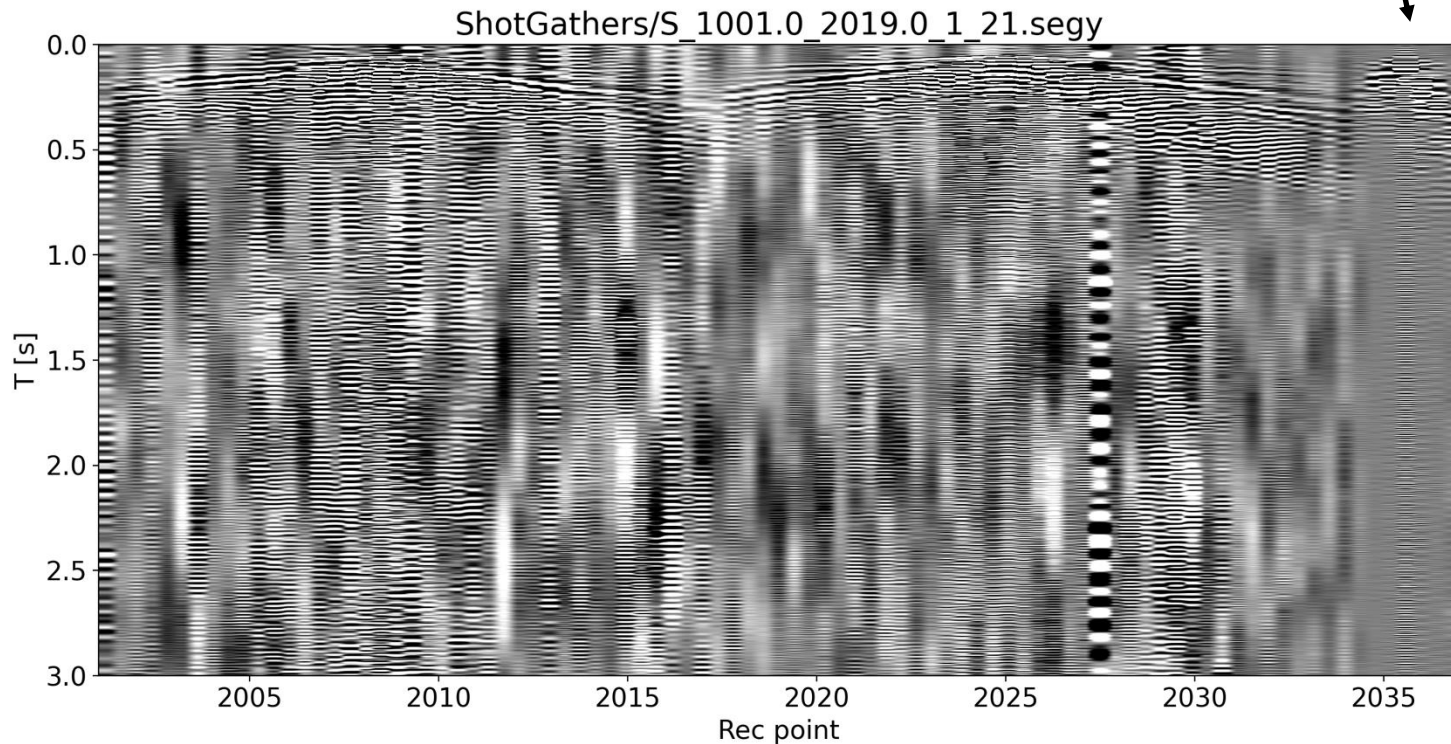
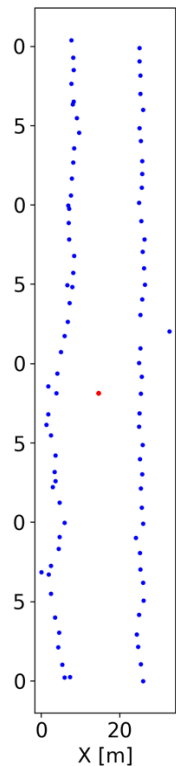
2019: 10:56

2011: 11:00

2001: 11:06

# Raw shot gather

Local geometry

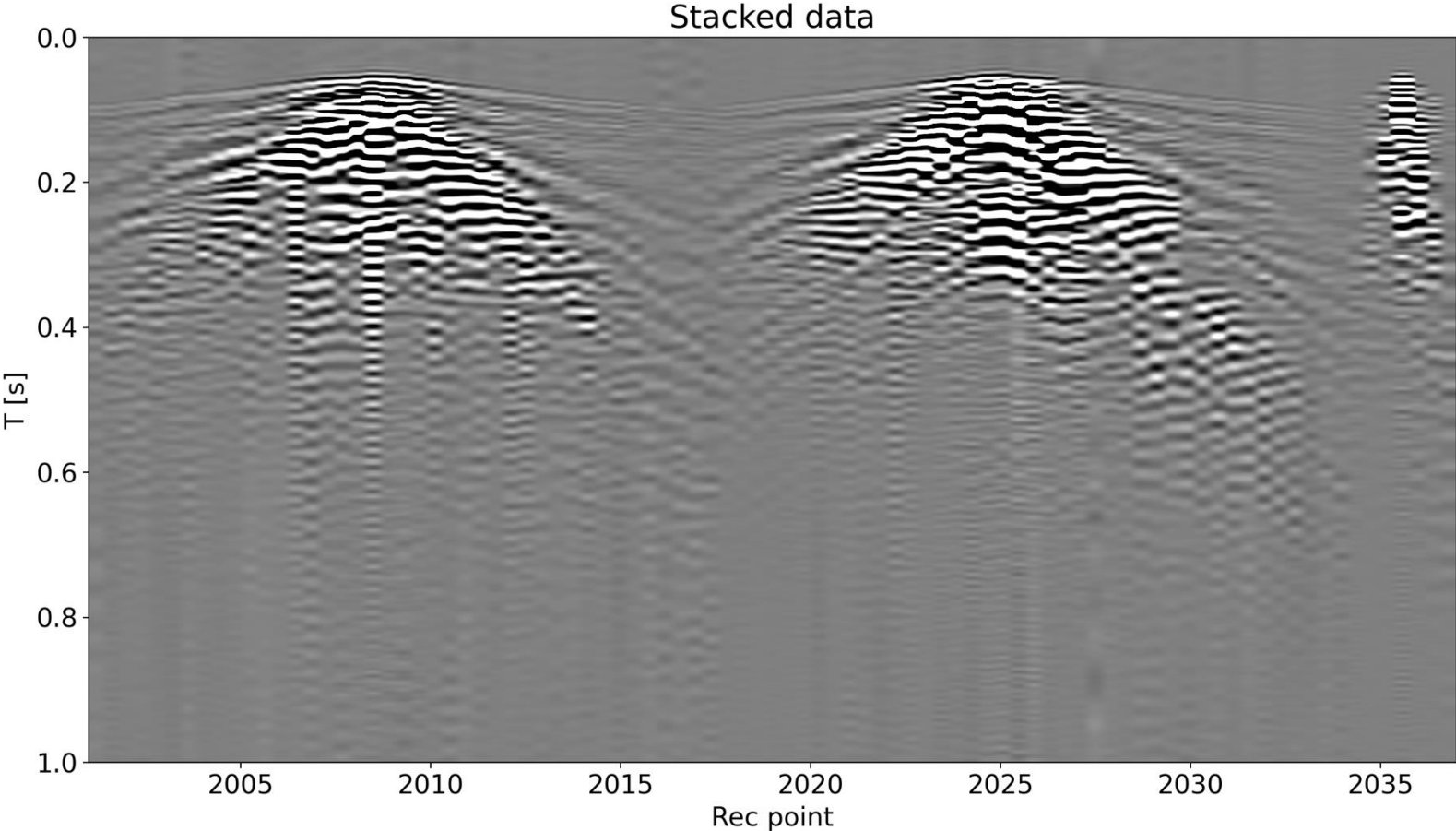


Buried! Let's bury...



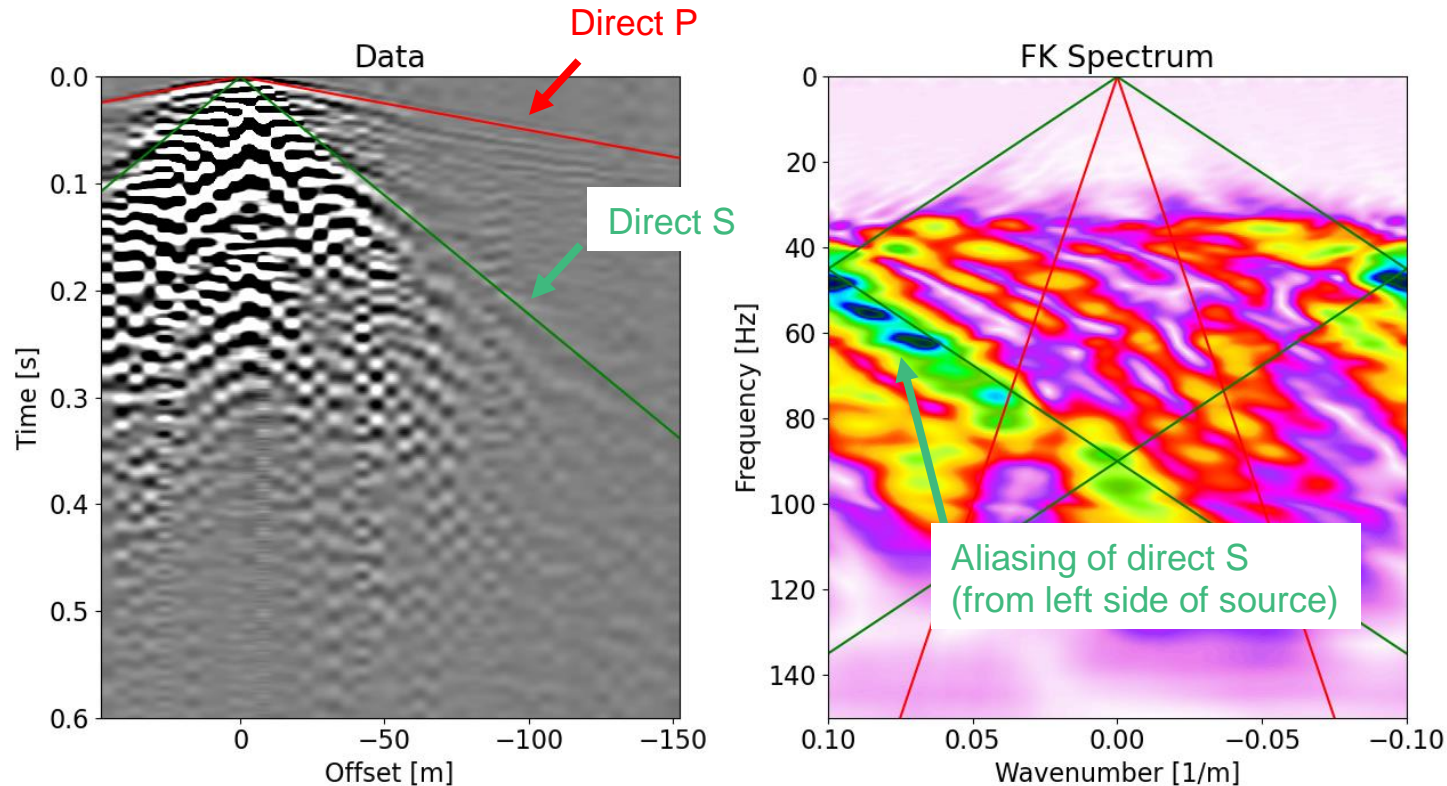
All analysis is done here on shot 2019

# Stacked shot gather





# Data analysis



Use shot at 2011 as aliasing is more visible (easier to explain)