Exp. No: 12 Decision tree classification.

Aim:

To implement the decision tree classification

```
from google.colab import drive
    drive.mount("/content/gdrive")

import Pandas as pd
import numpy as NP
import matplotlib-pyplot as PH
import Seaborn as SNS
%.matplotlib - inline

X,Y = make_regression (N_sample =1000,
    Noise =0.05, N. features =100)

X-shape, y.shape = (1000,100); (1000)]

X-train, X-test, y_train, y-test = train_test.
Split (X, y, test_size =0.2, shuffle = true, random_
    state =42)

if = MLP regressor (MAX_ITR = 1000)

1, stop = x_set [:,0] max() + 1, step 0.01)
Np.arrange (start = x_set [:,1].min():1,
Stop = x.set [:,1].max() + 1, step=0.01)
```

```
plt.contourf(X1, X2, classifier.predict)
    (np.array[X1.ravel(), X2.ravel()])
    reshape(X1.shape), alpha=0.75
    cmap = ListedColormap(('red', 'green'))
plt.xlim(X1.min(), X1.max())
plt.ylim(X2.min(), Y2.max())
for i, j in enumerate(np.unique(y_set));
    plt.scatter(X_set[y_set == j, 0],
    X_set[y_set == j, 1], c = listed colormap
    ('red', 'green')
plt.show()
```

O/P

Images of this

Result:

The program is successfully executed and O/P is verified