

Tello SDK를 이용한 파이썬 코딩(1)

DJITelloPy 모듈

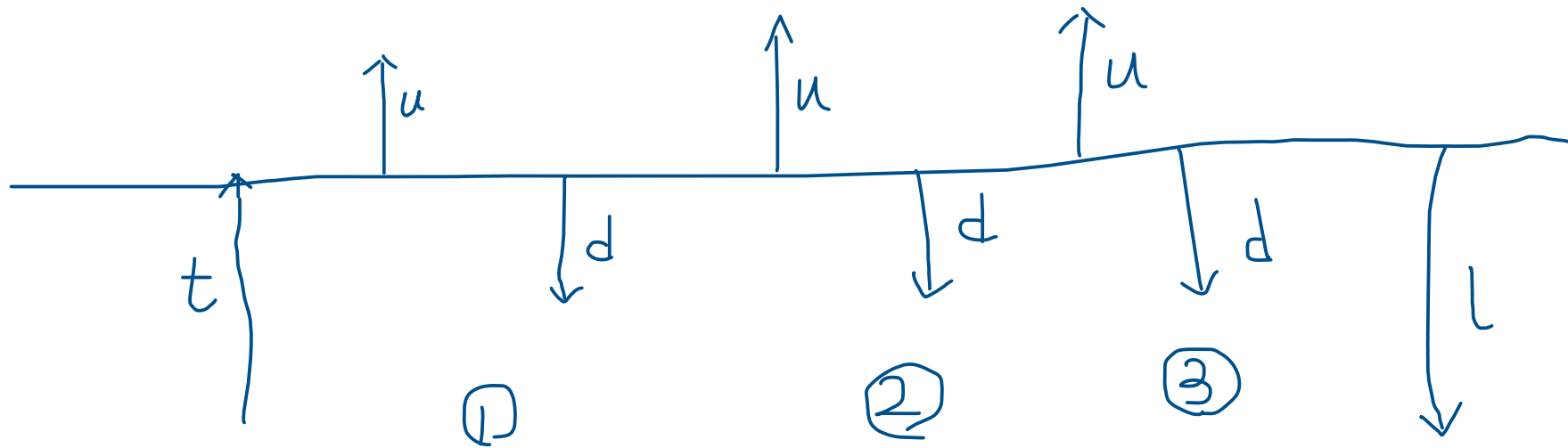
- API : <https://djitelloy.readthedocs.io/en/latest/tello/>
- DJITelloPy 모듈 설치
 - 터미널
 - pip install djitelloy
 - 파이참
 - [setting]->[Project]->[Python Interpreter] -> + 'djitelloy'

기본 동작 제어

- takeoff/ land
 - `takeoff()`, `land()`
- move up/ down
 - `move_up()`, `move_down()`
- move left/ right
 - `move_left()`, `move_right()`
- rotate_cw_ccw
 - `rotate_clockwise()`, `rotate_counter_clockwise()`
- send_rc_control_async
 - `send_rc_control(self, left_right_velocity, forward_backward_velocity, up_down_velocity, yaw_velocity)`

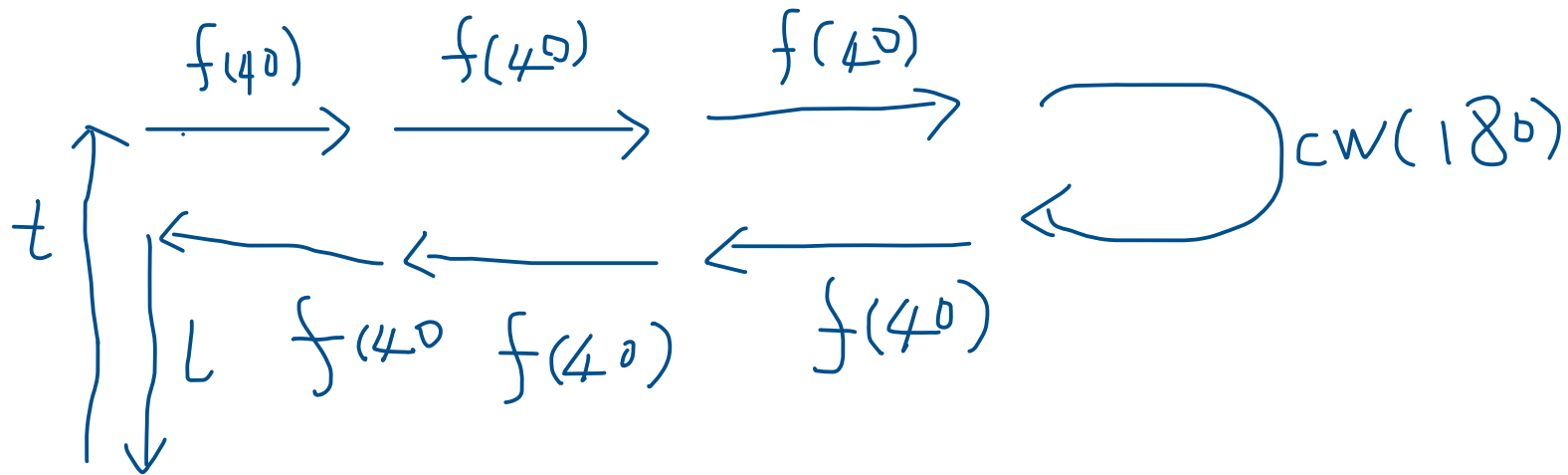
실습 01

- takeoff -> 3회 up(40) -> down(40) 반복 -> landing



실습 02

- takeoff -> fwd(40) -> fwd(40) -> fwd(40) -> cw(180)
-> fwd(40) -> fwd(40) -> fwd(40) -> land



드론 사진 촬영하기

```
import cv2
from djitellopy import Tello

tello = Tello()
tello.connect()

tello.streamon()
frame_read = tello.get_frame_read()

tello.takeoff()
cv2.imwrite("picture.png", frame_read.frame)

tello.land()
```

드론 비디오 촬영, 전송

```
from djitellopy import tello
import cv2
import time

tello = tello.Tello()
tello.connect()

battery_level = tello.get_battery()
print(f"Battery Life Percentage: {battery_level}")

time.sleep(2)

print("Turn Video Stream On")
tello.streamon()

# read a single image from the Tello video feed
print("Read Tello Image")
frame_read = tello.get_frame_read()
print(type(frame_read))

time.sleep(2)
```

```
while True:
    # read a single image from the Tello video feed
    print("Read Tello Image")

    tello_video_image = frame_read.frame

    # use opencv to write image
    if tello_video_image is not None:
        cv2.imshow("TelloVideo", tello_video_image)

        if cv2.waitKey(1) & 0xFF == ord('q'):
            break

    tello.streamoff()
    cv2.destroyWindow("TelloVideo")
    cv2.destroyAllWindows()
```

드론 키보드 제어하기

- manual-control-opencv

```
from djitellopy import Tello
import cv2, math, time
```

```
tello = Tello()
tello.connect()
```

```
tello.streamon()
frame_read = tello.get_frame_read()
```

while True:

```
img = frame_read.frame
cv2.imshow("drone", img)
```

```
key = cv2.waitKey(1) & 0xff
```

```
if key == 27: # ESC
```

```
    break
```

```
elif key == ord('t'):
```

```
    tello.takeoff()
```

```
elif key == ord('w'):
```

```
    tello.move_forward(30)
```

```
elif key == ord('s'):
```

```
    tello.move_back(30)
```

```
elif key == ord('a'):
```

```
    tello.move_left(30)
```

```
elif key == ord('d'):
```

```
    tello.move_right(30)
```

```
elif key == ord('e'):
```

```
    tello.rotate_clockwise(30)
```

```
elif key == ord('q'):
```

```
    tello.rotate_counter_clockwise(30)
```

```
elif key == ord('r'):
```

```
    tello.move_up(30)
```

```
elif key == ord('f'):
```

```
    tello.move_down(30)
```

```
tello.land()
```

```
cv2.destroyAllWindows()
```


실습 03

- '드론 키보드 제어하기'를 드론 카메라 대신, PC 웹캠을 사용하여 PC에서 비디오 스트림을 보여 주도록 만드시오
 - `cv2.VideoCapture(0)`
 - `ret, frame = cap.read()`
 - `cv2.imshow("Video":, frame)`