## Value Iteration

- Start with  $V_0(s) = 0$ ; no time steps left means an expected reward sum of zero
- Given vector of  $V_k(s)$  values, do one ply of expectimax from each state:

$$V_{k+1}(s) \leftarrow \max_{a} \sum_{s'} T(s, a, s') \left[ R(s, a, s') + \gamma V_k(s') \right]$$





- Theorem: will converge to unique optimal values
- Basic idea: approximations get refined towards optimal values
- Policy may converge long before values do

