#### CS 471/571 (Fall 2023): Introduction to Artificial Intelligence

Lecture 24: Perceptrons, Logistic Regression, and Neural Nets

Thanh H. Nguyen

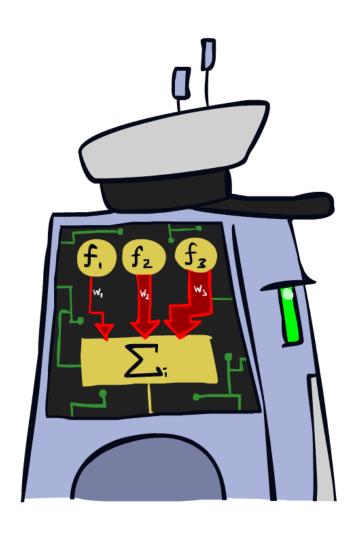
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#### Announcement and Reminder

- •Written assignment 4
  - Deadline: Wednesday, November 29<sup>th</sup>, 2023.
- Student experience survey
  - Deadline: 06:00 AM on Monday, Dec 4th, 2023
  - If >= 80% of students complete the survey, everyone will get an extra 2% credit for your final grade

Thanh H. Nguyen 11/27/23

## Linear Classifiers

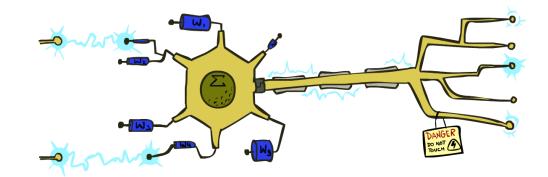


#### Feature Vectors

Input Label y Features x# free : 2
YOUR\_NAME : 0
MISSPELLED : 2 Hello, **SPAM** Do you want free printr or cartriges? Why pay more FROM\_FRIEND : 0 when you can get them ABSOLUTELY FREE! Just PIXEL-7,12 : 1 PIXEL-7,13 : 0 NUM\_LOOPS : 1

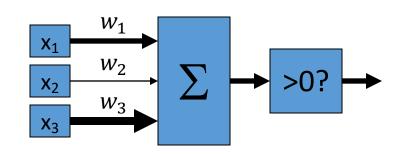
#### Linear Classifiers

- Inputs are feature values
- Each feature has a weight
- Sum is the activation



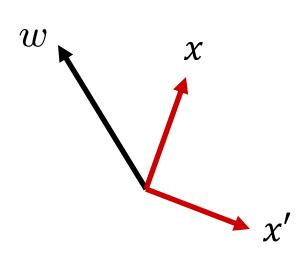
$$activation_w(x) = \sum_j w_j x_j = w \cdot x$$

- If the activation is:
  - Positive, output +1
  - Negative, output -1



## Weights

- Binary case: compare features to a weight vector
- Learning: figure out the weight vector from examples

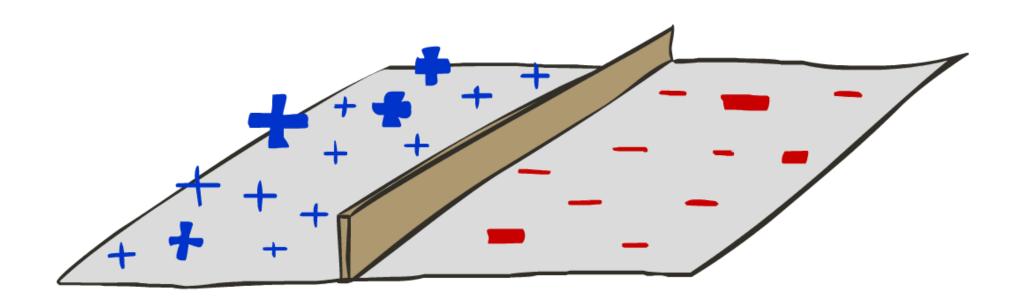


```
# free : 2
YOUR_NAME : 0
MISSPELLED : 2
FROM_FRIEND : 0
```

```
# free : 0
YOUR_NAME : 1
MISSPELLED : 1
FROM_FRIEND : 1
...
```

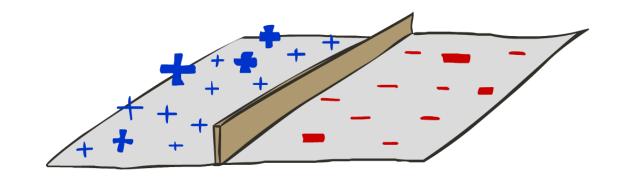
Dot product  $\mathbf{w} \cdot \mathbf{x}$  positive means the positive class

## Decision Rules



## Binary Decision Rule

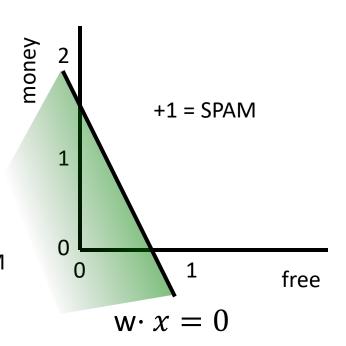
- In the space of feature vectors
  - Examples are points
  - Any weight vector is a hyperplane
  - One side corresponds to Y = +1
  - Other corresponds to Y = -1



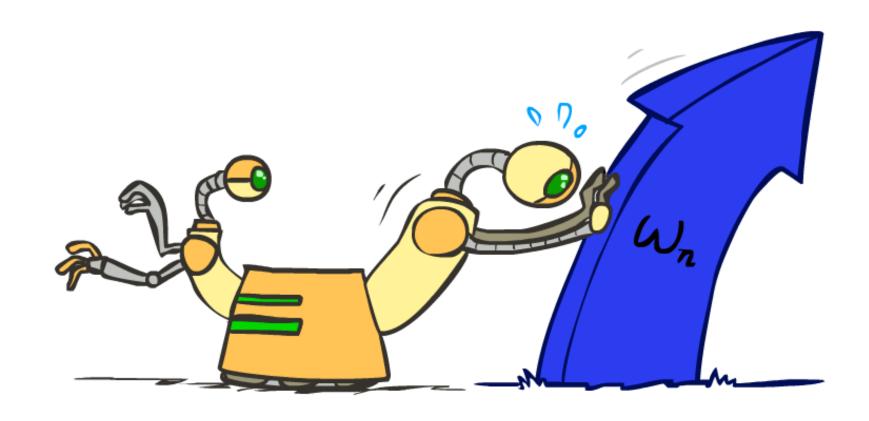
W

BIAS : -3
free : 4
money : 2

-1 = HAM



## Weight Updates

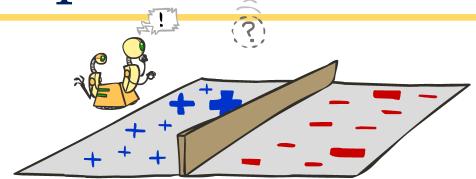


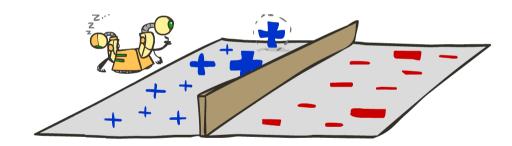
## Learning: Binary Perceptron

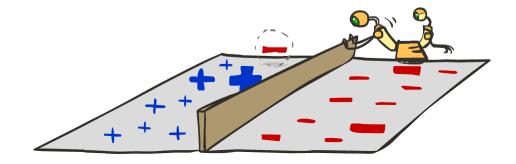
- Start with weights = 0
- For each training instance:
  - Classify with current weights

• If correct (i.e.,  $\hat{y} = y$ ), no change!

• If wrong: adjust the weight vector







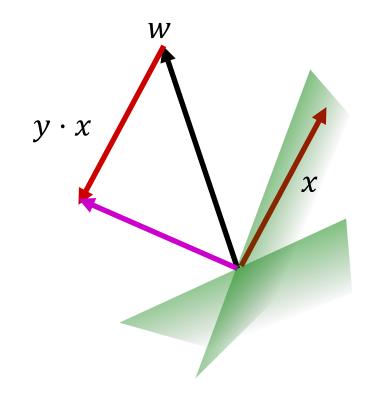
## Learning: Binary Perceptron

- Start with weights = 0
- For each training instance:
  - Classify with current weights

$$\hat{y} = \begin{cases} +1 \text{ if } w \cdot x \ge 0\\ -1 \text{ if } w \cdot x < 0 \end{cases}$$

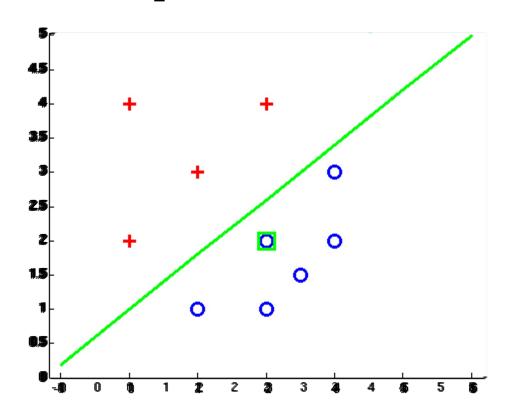
- If correct (i.e.,  $\hat{y} = y$ ), no change!
- If wrong: adjust the weight vector by adding or subtracting the feature vector. Subtract if *y* is -1.

$$w = w + y \cdot x$$



## Examples: Perceptron

#### Separable Case



#### Multiclass Decision Rule

- If we have multiple classes:
  - A weight vector for each class:

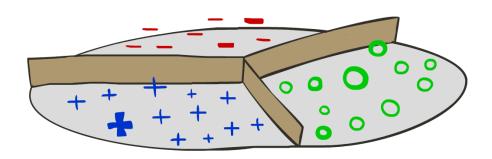
$$w_y$$

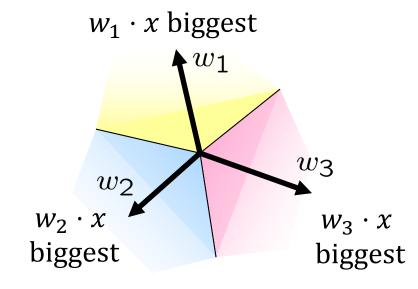
• Score (activation) of a class y:

$$w_y \cdot x$$

Prediction highest score wins

$$y = \arg\max_{y} w_y \cdot x$$







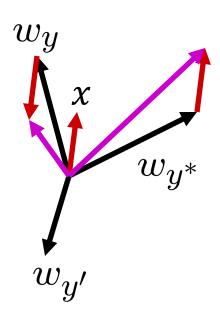
## Learning: Multiclass Perceptron

- Start with all weights = 0
- Pick up training examples one by one
- Predict with current weights

$$y = \arg\max_{y} w_{y} \cdot x$$

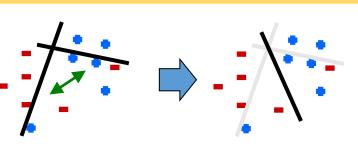
- If correct, no change!
- If wrong: lower score of wrong answer, raise score of right answer

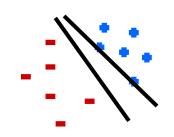
$$w_y = w_y - x$$
$$w_{y^*} = w_{y^*} + x$$

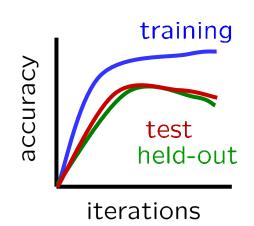


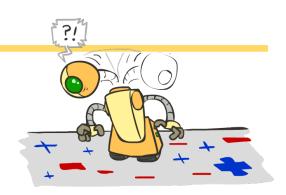
## Problems with the Perceptron

- Noise: if the data isn't separable, weights might thrash
  - Averaging weight vectors over time can help (averaged perceptron)
- Mediocre generalization: finds a "barely" separating solution
- Overtraining: test / held-out accuracy usually rises, then falls
  - Overtraining is a kind of overfitting

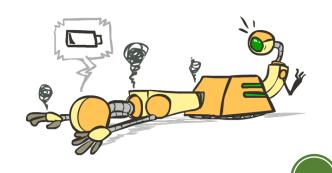




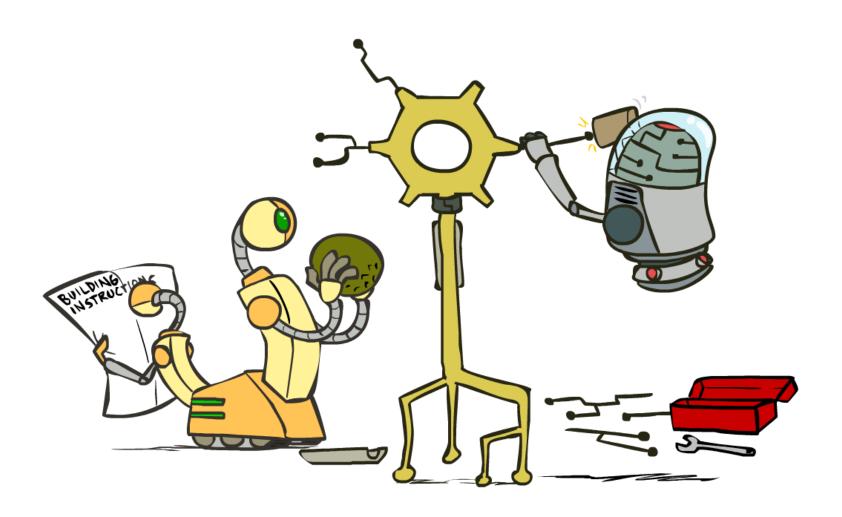




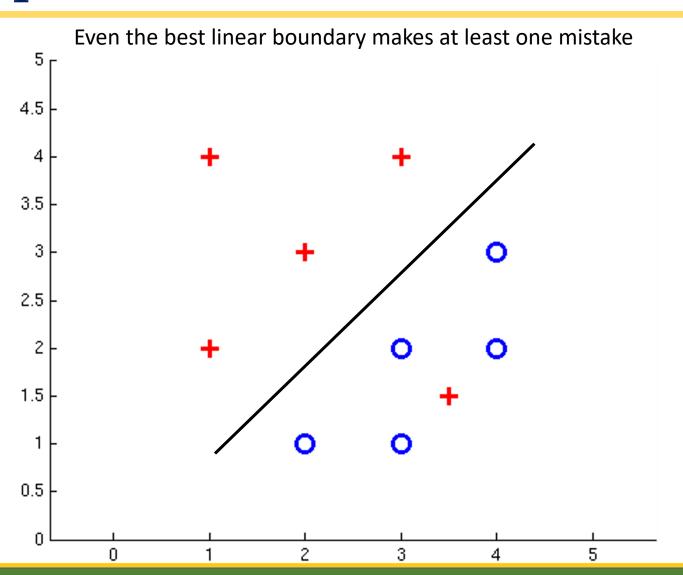




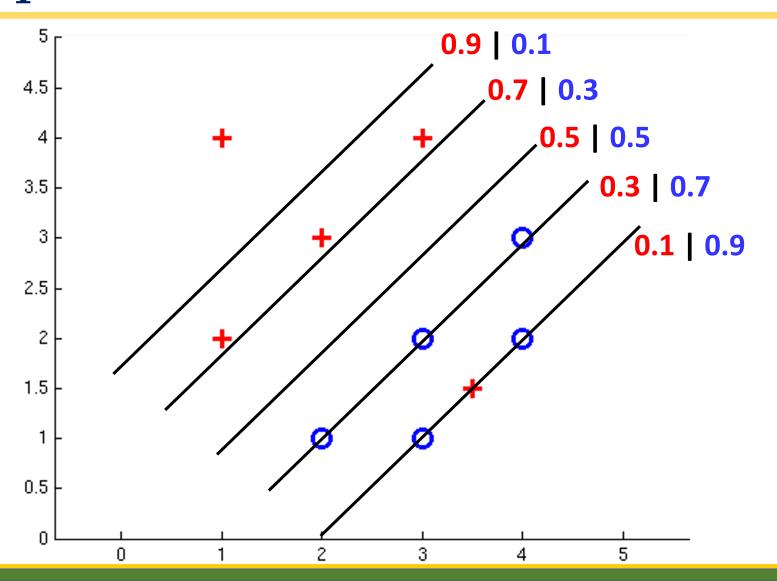
# Logistic Regression



## Non-Separable Case: Deterministic Decision



#### Non-Separable Case: Probabilistic Decision

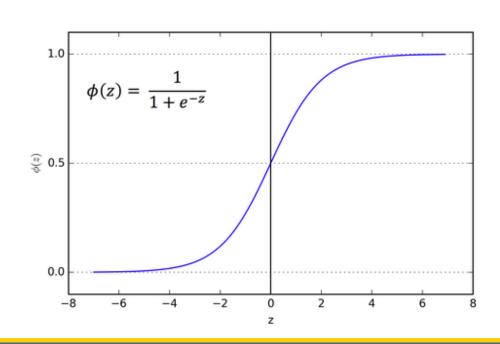


## How to get probabilistic decisions?

- Perceptron scoring:  $z = w \cdot x$
- •If  $z = w \cdot x$  very positive  $\rightarrow$  want probability going to 1
- •If  $z = w \cdot x$  very negative  $\rightarrow$  want probability going to 0

Sigmoid function

$$\phi(z) = \frac{1}{1 + e^{-z}}$$



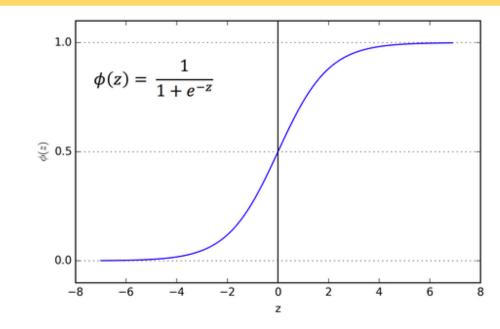
## How to get probabilistic decisions?

#### Sigmoid function

$$z = w \cdot x$$

$$\phi(z) = \frac{1}{1 + e^{-z}}$$

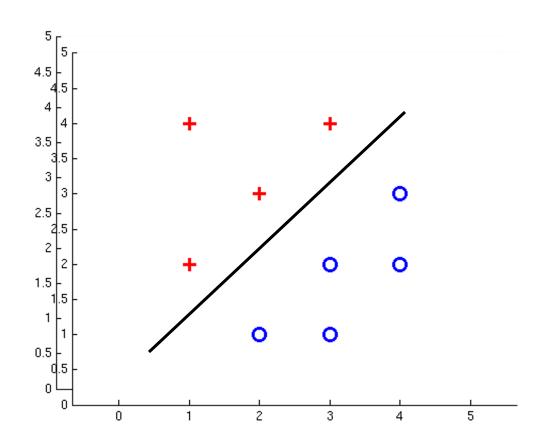
Probabilistic decision

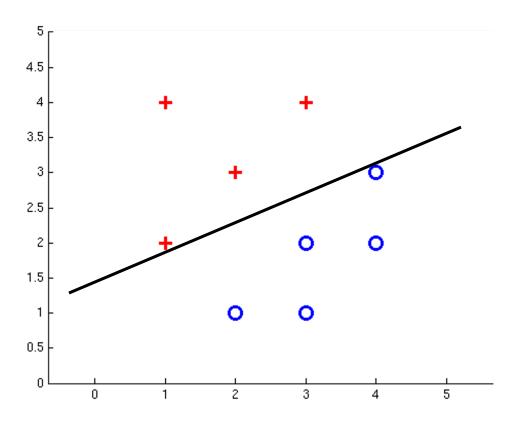


$$P(y^{(i)} = +1|x^{(i)}; w) = \frac{1}{1 + e^{-w \cdot x^{(i)}}}$$

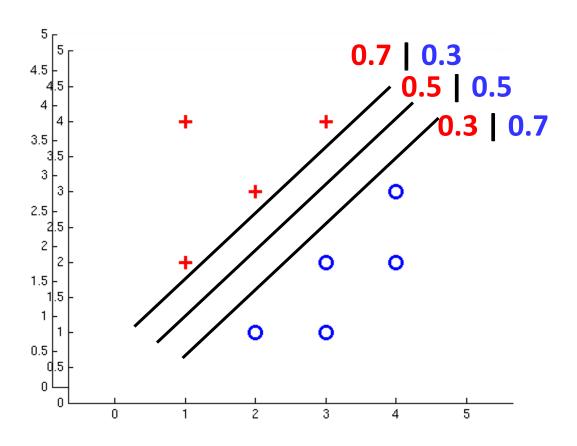
$$P(y^{(i)} = -1|x^{(i)}; w) = 1 - \frac{1}{1 + e^{-w \cdot x^{(i)}}}$$

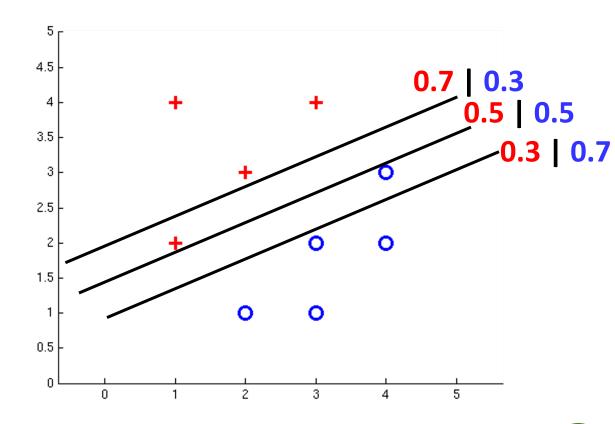
## Separable Case: Deterministic Decision – Many Options





# Separable Case: Probabilistic Decision – Clear Preference





#### Determine Best Weights: Maximum Likelihood Estimation

• Maximum likelihood estimation: choose w so as to make the data as high probability as possible.

$$\max_{w} \ ll(w) = \max_{w} \ \sum_{i} \log P(y^{(i)}|x^{(i)};w)$$

with:

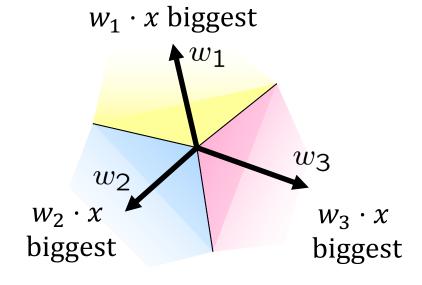
$$P(y^{(i)} = +1|x^{(i)}; w) = \frac{1}{1 + e^{-w \cdot x^{(i)}}}$$

$$P(y^{(i)} = -1|x^{(i)}; w) = 1 - \frac{1}{1 + e^{-w \cdot x^{(i)}}}$$

## Multiclass Logistic Regression

#### • Recall Perceptron:

- A weight vector for each class:  $w_y$
- Score (activation) of a class y:  $z_y = w_y \cdot x$
- Prediction highest score wins  $y = \arg \max_{y} w_{y} \cdot x$



• How to make the scores into probabilities?

$$z_1, z_2, z_3 \to \frac{e^{z_1}}{e^{z_1} + e^{z_2} + e^{z_3}}, \frac{e^{z_2}}{e^{z_1} + e^{z_2} + e^{z_3}}, \frac{e^{z_3}}{e^{z_1} + e^{z_2} + e^{z_3}}$$

#### Best w?

• Maximum likelihood estimation:

$$\max_{w} \ ll(w) = \max_{w} \ \sum_{i} \log P(y^{(i)}|x^{(i)};w)$$

with the likelihood of each data point:

$$P(y^{(i)}|x^{(i)};w) = \frac{e^{w_{y^{(i)}} \cdot x^{(i)}}}{\sum_{y} e^{w_{y} \cdot x^{(i)}}}$$

#### Best w?

- Optimization
  - i.e., how do we solve:

$$\max_{w} \ ll(w) = \max_{w} \ \sum_{i} \log P(y^{(i)}|x^{(i)};w)$$

No closed-form expression of optimal w

#### Gradient Ascent

- Perform update in uphill direction for each coordinate
- The steeper the slope (i.e. the higher the derivative) the bigger the step for that coordinate
- E.g., consider:  $g(w_1, w_2)$ 
  - Updates:

$$w_1 \leftarrow w_1 + \alpha * \frac{\partial g}{\partial w_1}(w_1, w_2)$$

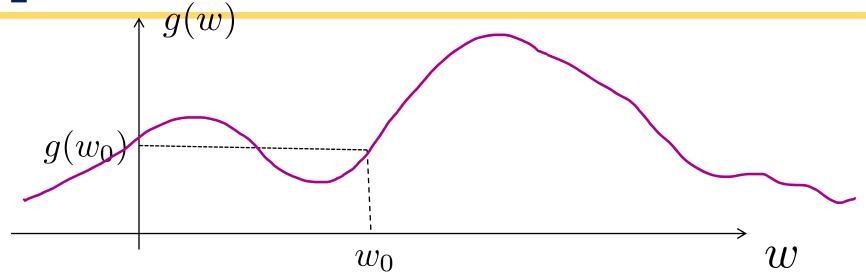
$$w_2 \leftarrow w_2 + \alpha * \frac{\partial g}{\partial w_2}(w_1, w_2)$$

Updates in vector notation:

$$w \leftarrow w + \alpha * \nabla_w g(w)$$

with: 
$$\nabla_w g(w) = \begin{vmatrix} \frac{\partial g}{\partial w_1}(w) \\ \frac{\partial g}{\partial w_2}(w) \end{vmatrix}$$
 = gradient

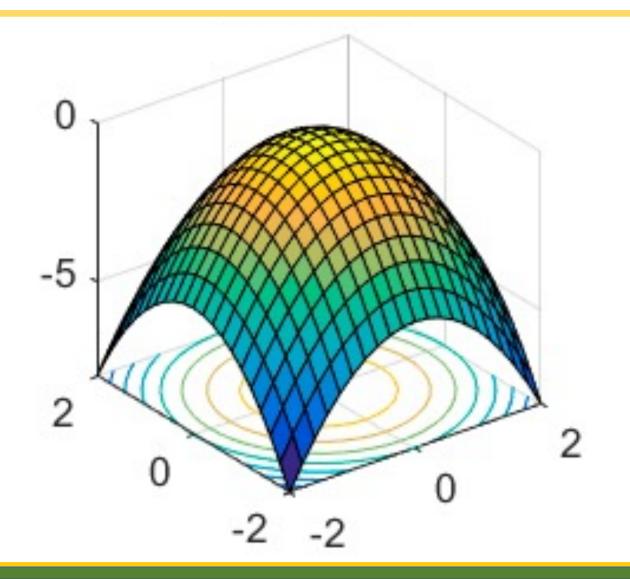
# 1-D Optimization



- •Could evaluate  $g(w_0 + h)$  and  $g(w_0 h)$ 
  - Then step in best direction
- •Or, evaluate derivative:  $\frac{\partial g(w_0)}{\partial w} = \lim_{h\to 0} \frac{g(w_0+h) g(w_0-h)}{2h}$ 
  - Tells which direction to step into



## 2-D Optimization



#### Gradient Ascent

- Perform update in uphill direction for each coordinate
- The steeper the slope (i.e. the higher the derivative) the bigger the step for that coordinate
- E.g., consider:  $g(w_1, w_2)$ 
  - Updates:

$$w_1 \leftarrow w_1 + \alpha * \frac{\partial g}{\partial w_1}(w_1, w_2)$$

$$w_2 \leftarrow w_2 + \alpha * \frac{\partial g}{\partial w_2}(w_1, w_2)$$

Updates in vector notation:

$$w \leftarrow w + \alpha * \nabla_w g(w)$$

with: 
$$\nabla_w g(w) = \begin{vmatrix} \frac{\partial g}{\partial w_1}(w) \\ \frac{\partial g}{\partial w_2}(w) \end{vmatrix}$$
 = gradient