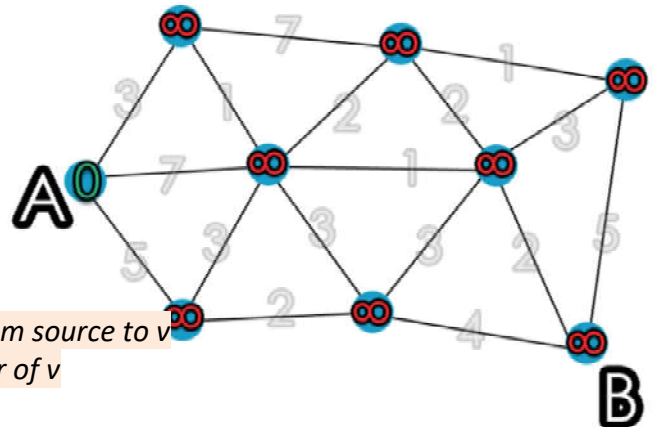


# Dijkstra + Fibonacci Heap Pseudo Code :

## Algorithm Pseudo Code

```
1. function Dijkstra(Graph, source):
2.   dist[source] ← 0           // Initialization
3.
4.   create vertex priority queue Q
5.
6.   for each vertex v in Graph:
7.     if v ≠ source
8.       dist[v] ← INFINITY    // Unknown distance from source to v
9.       prev[v] ← UNDEFINED   // Predecessor of v
10.
11.   Q.add_with_priority(v, dist[v])
```



```
10. Q := the set of all nodes in Graph // all nodes in the graph are unoptimized (thus are in Priority Queue Q)
11. while Q is not empty:              // The main loop
12.   u ← Q.extract_min()               // Remove and return best vertex
13.   for each neighbor v of u:         // only v that are still in Q : has not yet been removed from Q.
14.     alt ← dist[u] + dist_between(u, v)
15.     if alt < dist[v]                // Relax (u,v)
16.       dist[v] ← alt
17.       prev[v] ← u
18.       Q.decrease_priority(v, alt)
19. return dist, prev
```

From <[https://en.wikipedia.org/wiki/Dijkstra%27s\\_algorithm](https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm)>

From <[http://www.gitta.info/Accessibiliti/en/html/Dijkstra\\_learningObject1.html](http://www.gitta.info/Accessibiliti/en/html/Dijkstra_learningObject1.html)>

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## Reading the shortest path from source to target by reverse iteration (Using Stack):

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```
1 S ← empty sequence
2 u ← target
3 if prev[u] is defined or u = source: // Do something only if the vertex is reachable
4   while u is defined:                // Construct the shortest path with a stack S
5     insert u at the beginning of S    // Push the vertex onto the stack
6     u ← prev[u]                      // Traverse from target to source
```

From <[https://en.wikipedia.org/wiki/Dijkstra%27s\\_algorithm](https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm)>