



VISIONAIR

IOT - Air Quality Monitoring System

About our Project

Air Pollution Monitoring System addresses a vital environmental challenge with a technologically advanced, scalable, and cost-effective solution. By providing real-time, accurate data on air quality, it empowers communities and authorities to take proactive measures in combating air pollution and safeguarding public health.

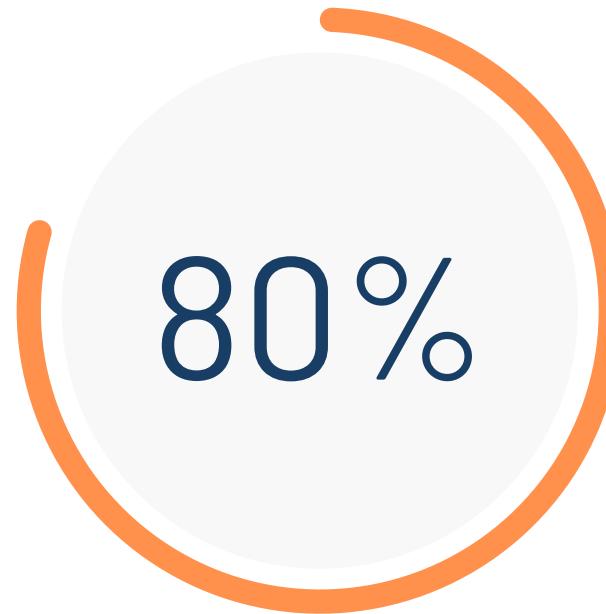


Notify



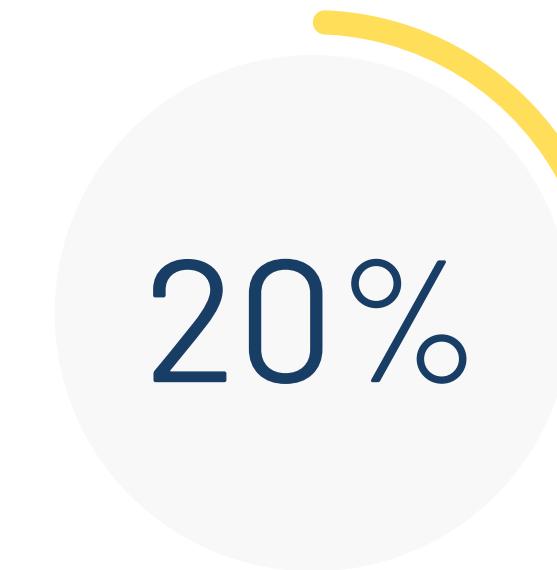
Visualise

Relevant Statistics



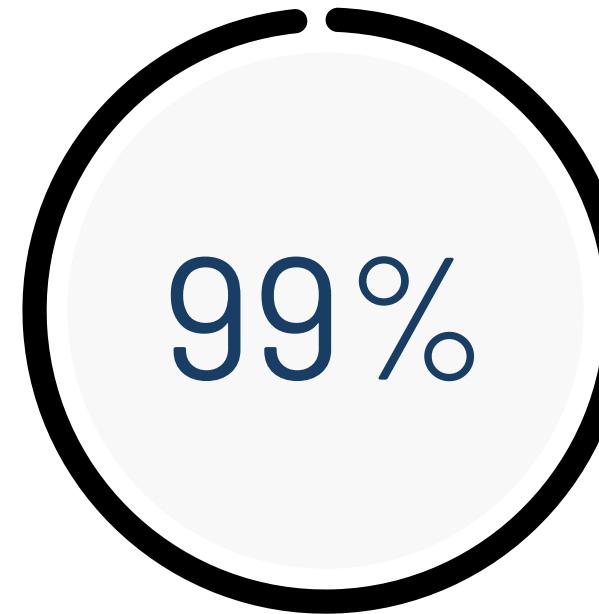
Motor Vehicles

Motor vehicles contribute 80% of air pollution in the Philippines.



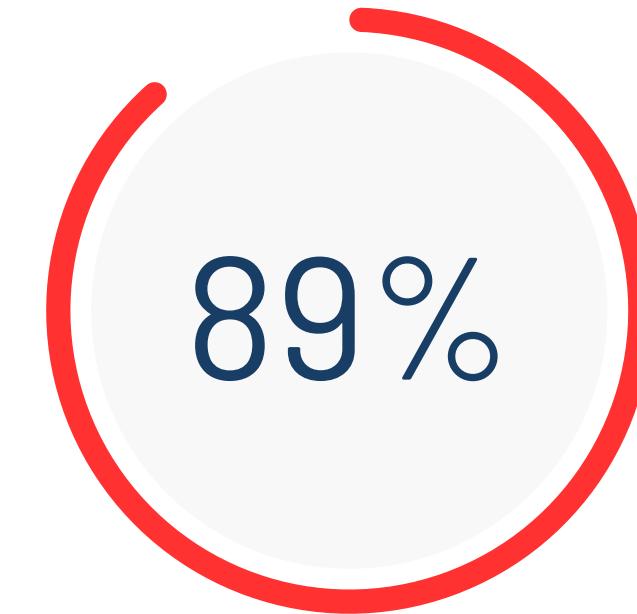
Stationary Sources

Comes from stationary sources such as factories and the open burning of organic matter.



Global Population

Global population in areas where air quality levels do not meet WHO guidelines.



Premature Deaths

Low- and middle-income countries, with the highest burden in the WHO South-East Asia and Western Pacific Regions.

Our Goals



Provide Accurate Readings



Awareness



Promote Air Quality

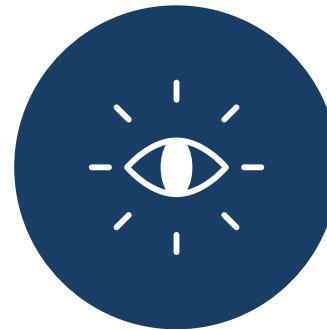


Engagement

Solution to Problem

Visualisation

Readings



The results are visualised in the form of graphs making it easy for authorities and the public to interpret the data and make informed decisions.

Alert System

Notify



Integrated into the monitoring platform to notify users when levels exceed safe thresholds, enabling timely actions to mitigate pollution exposure.

IoT Connectivity

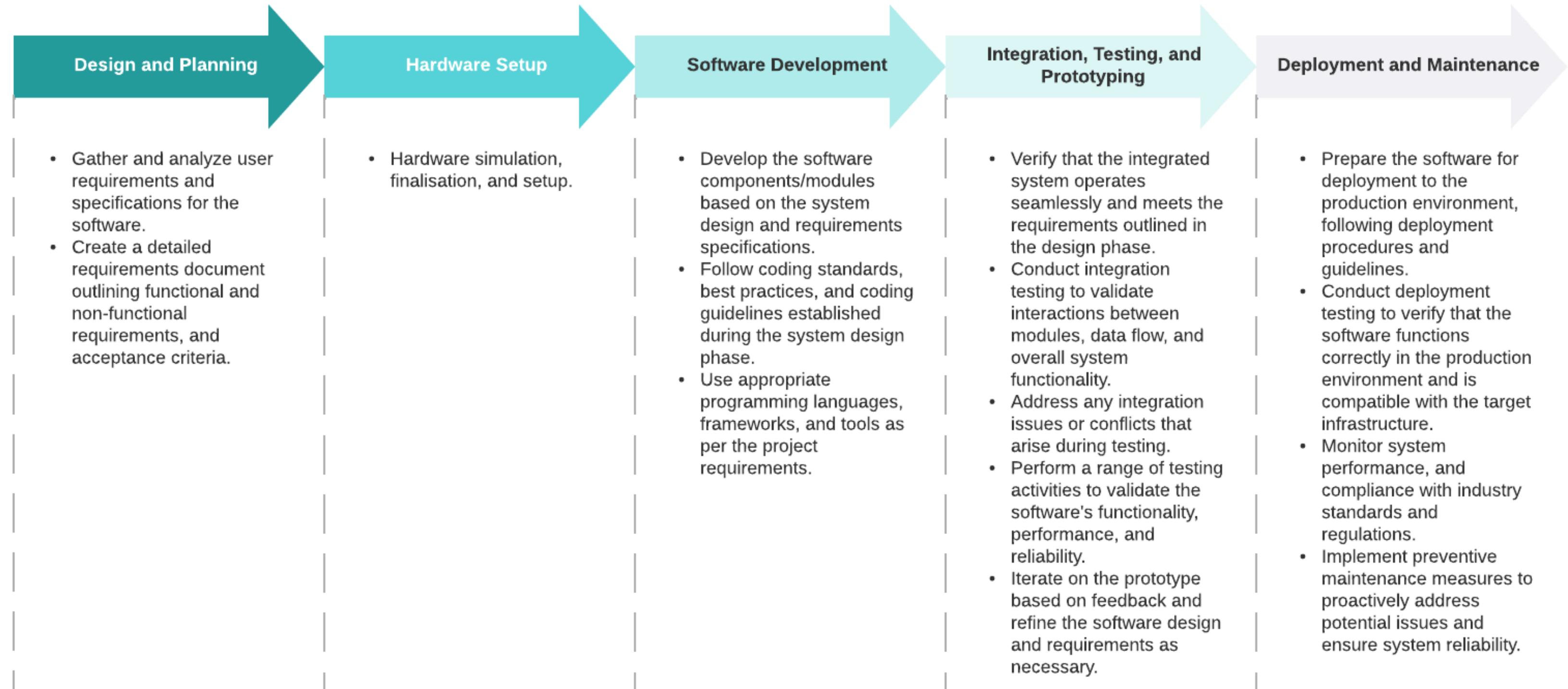
Accessibility



The real-time data is accessible via a web-based dashboard or a mobile application, allowing users to monitor air quality from anywhere at any time.

■ Direct Traffic
3,097,00 / 40,408,1

Planning

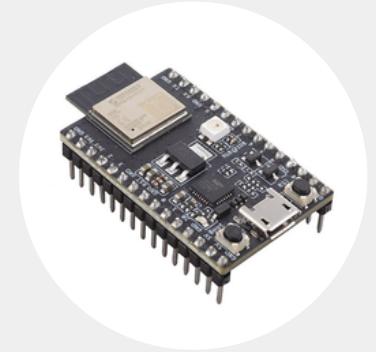


A photograph showing a person's hands working on a breadboard. The breadboard is populated with various electronic components like resistors, capacitors, and a central microcontroller board. Numerous colored wires are soldered to the breadboard, connecting the different components. In the background, there are clear plastic containers holding more electronic parts.

Materials & Methods

Our Materials

Includes Breadboard, Jumper Wires, and Enclosure*



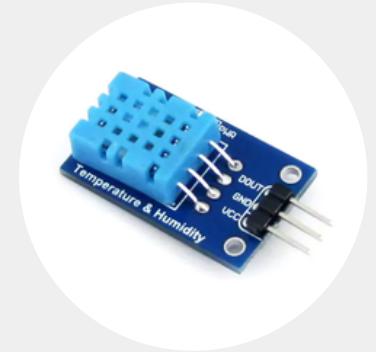
ESP32

Serves as the central processing unit, executing the code to control the air pollution monitoring system.



MQ-Series (135, 4, 7)

Detect gases like ammonia, NO₂, alcohol, benzene, smoke, and CO₂ in the air.



DHT11

Measures the ambient temperature and humidity levels.



LCD

Shows real-time data from the sensors, allowing users to visually monitor air quality metrics.

Sensors

These are the sensors used:



DHT11

Temperature and Humidity

Measures the ambient temperature and humidity levels

MQ-135

Ammonia, NO, Alcohol, Benzene

Detect various harmful gases like ammonia, NO, alcohol, benzene, smoke, and CO₂ in the air.

MQ-4

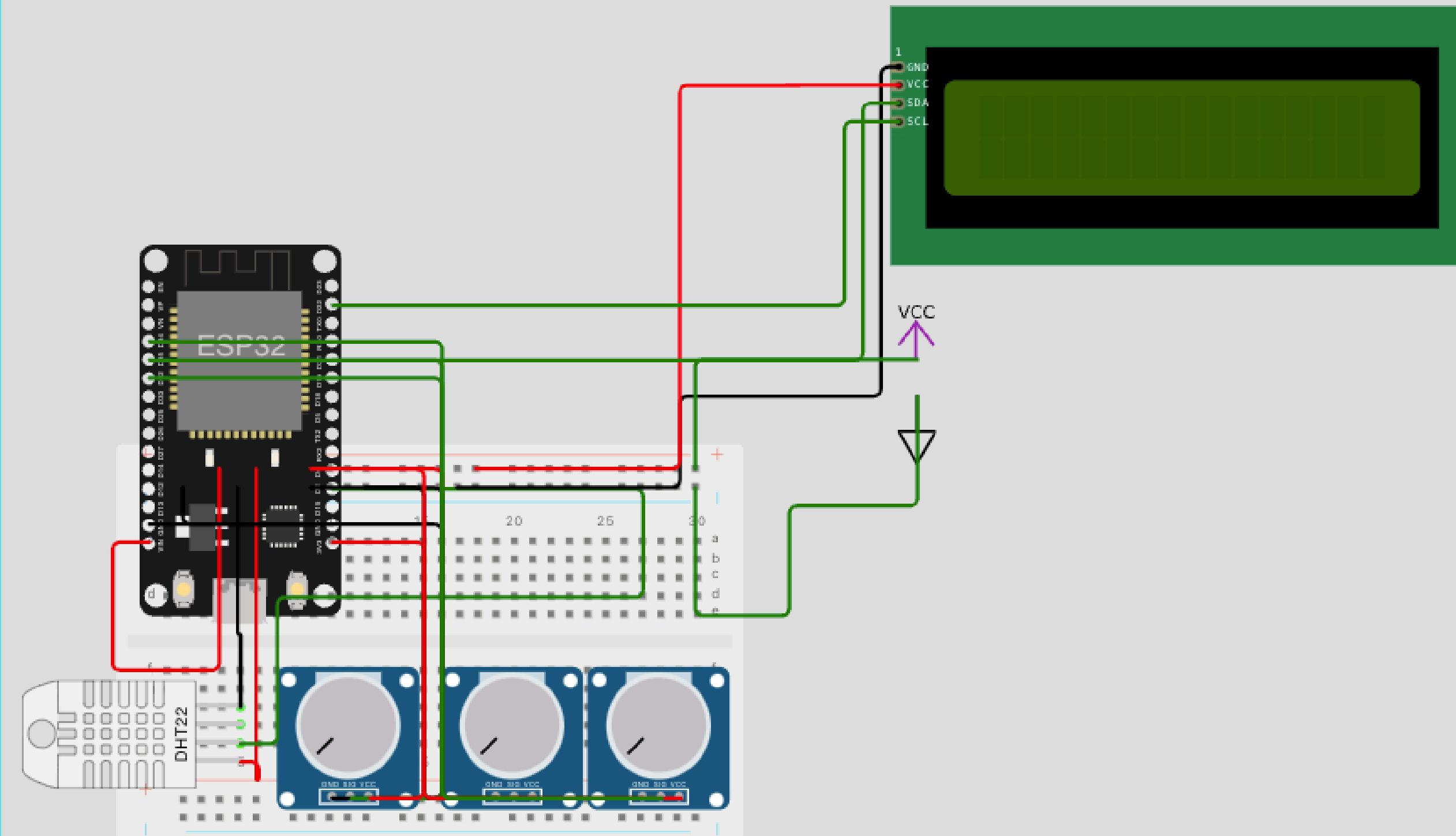
Methane and LPG

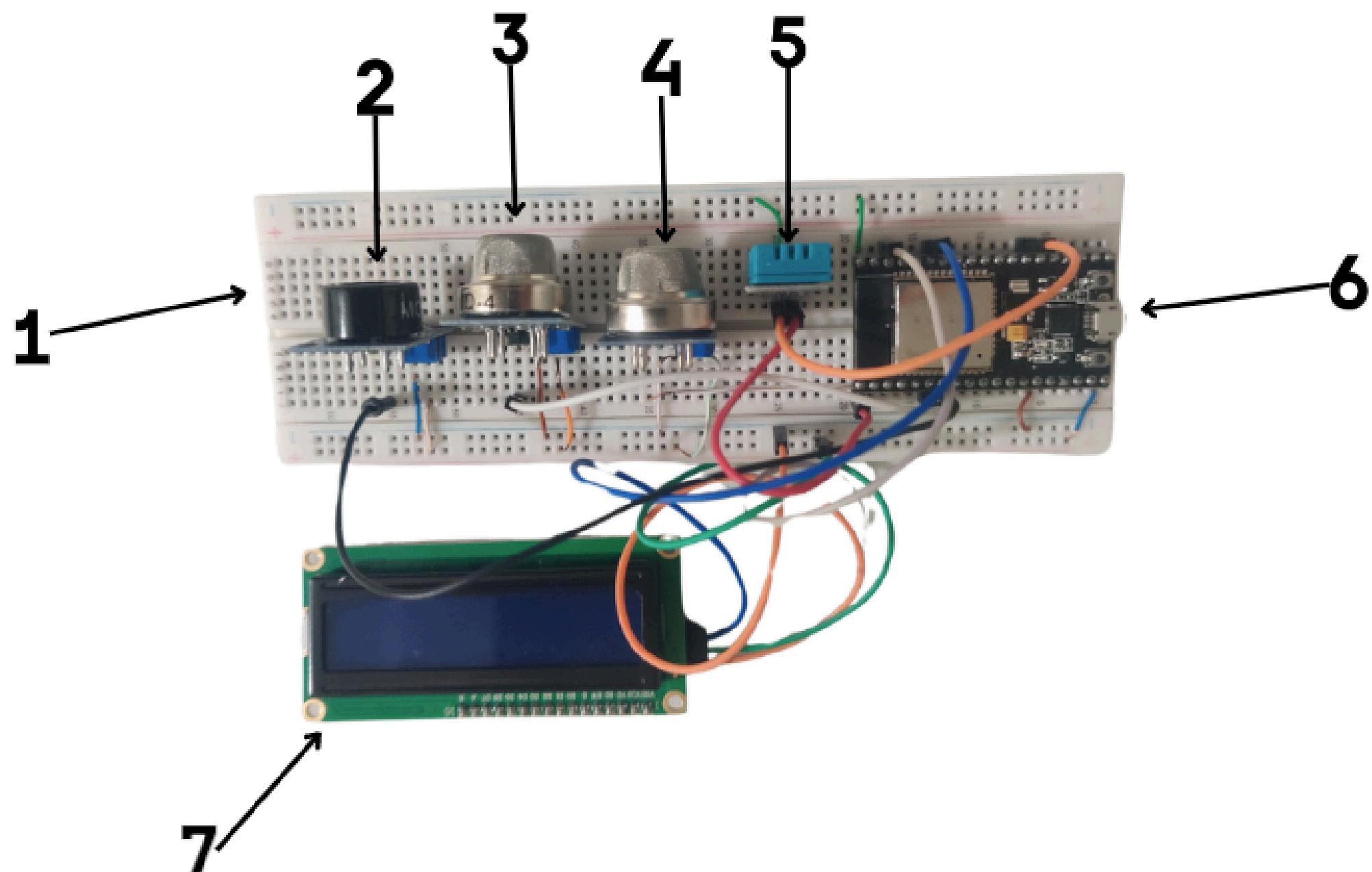
Detects Methane, and can also sense other gases such as LPG and natural gas.

MQ-7

CO and Hydrogen Gas

Detects Carbon Monoxide (CO) and can also sense hydrogen gas.





- a breadboard (1)
- an MQ-7 gas sensor (2)
- an MQ-4 gas sensor (3)
- an MQ-135 gas sensor (4)
- a DHT11 sensor (5)
- an ESP32 module (6)
- an LCD display (7)

System & Algorithm



Algorithm

Threshold



Triggers actions or alerts when sensor readings exceed predefined limits, ensuring timely responses to significant changes in air quality.

SMA

Simple Moving Average



Smooths sensor data by averaging a set number of recent readings, filtering out short-term fluctuations to reveal clearer trends.

Hysteresis



Introduces buffer zones around thresholds to prevent frequent toggling of actions due to minor fluctuations, ensuring more stable system responses.

Threshold-Based Algorithm

```
initialise variable threshold_value to predefined limit
initialise array alert_messages

for each data_point in sensor_data:
    if data_point > threshold_value:
        append "High pollution alert!" to alert_messages
    else:
        append "Pollution levels normal" to alert_messages

return alert_messages
```

SMA Algorithm

```
initialise array data_window
initialise variable window_size to desired window length
initialise variable sum to 0
initialise array sma_values

for each new data_point in sensor_data:
    if data_window has less than window_size elements:
        append data_point to data_window
        add data_point to sum
        sma = sum / length of data_window
    else:
        remove the oldest data point from data_window
        subtract the oldest data point from sum
        append data_point to data_window
        add data_point to sum
        sma = sum / window_size

    append sma to sma_values

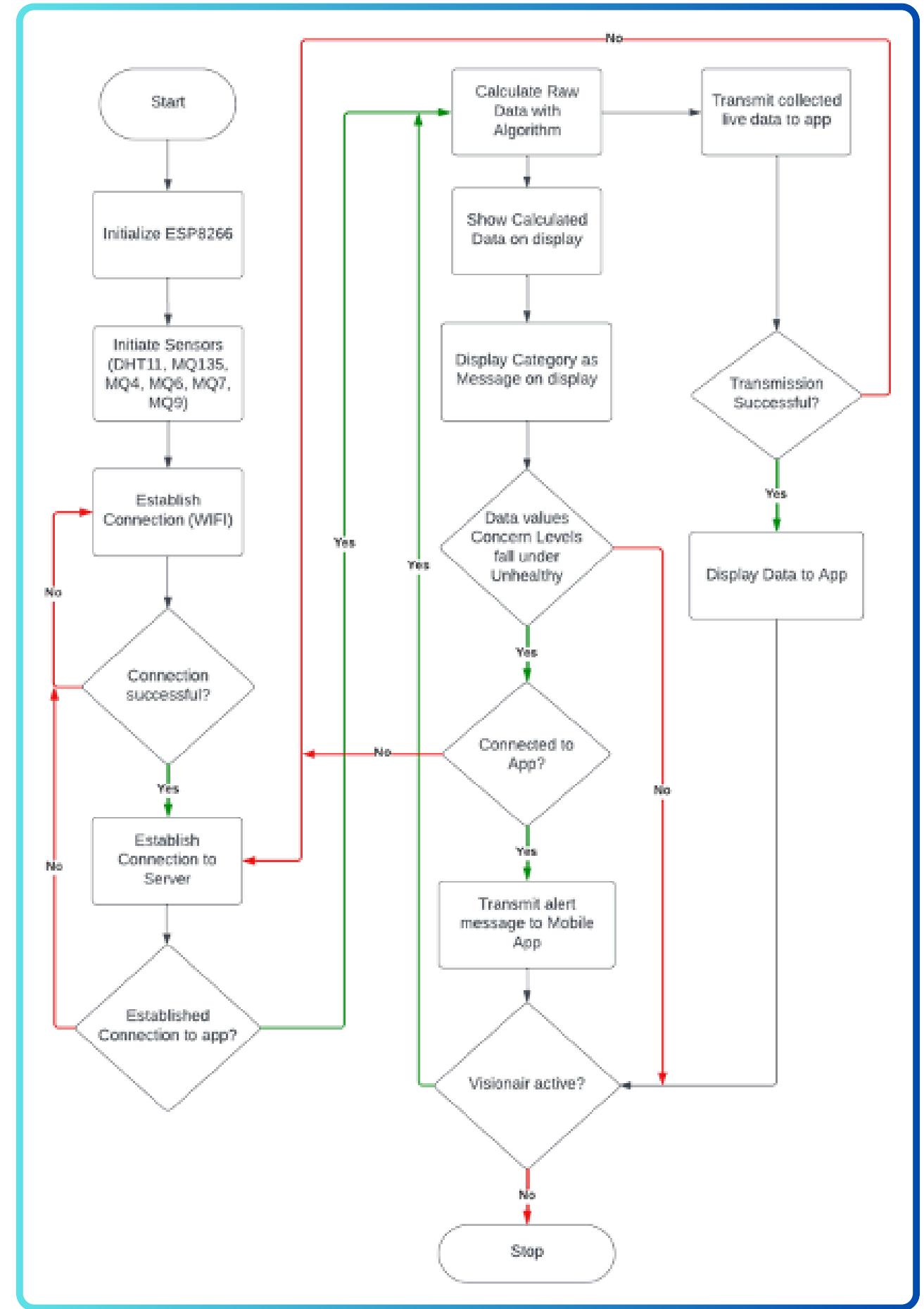
return sma_values
```

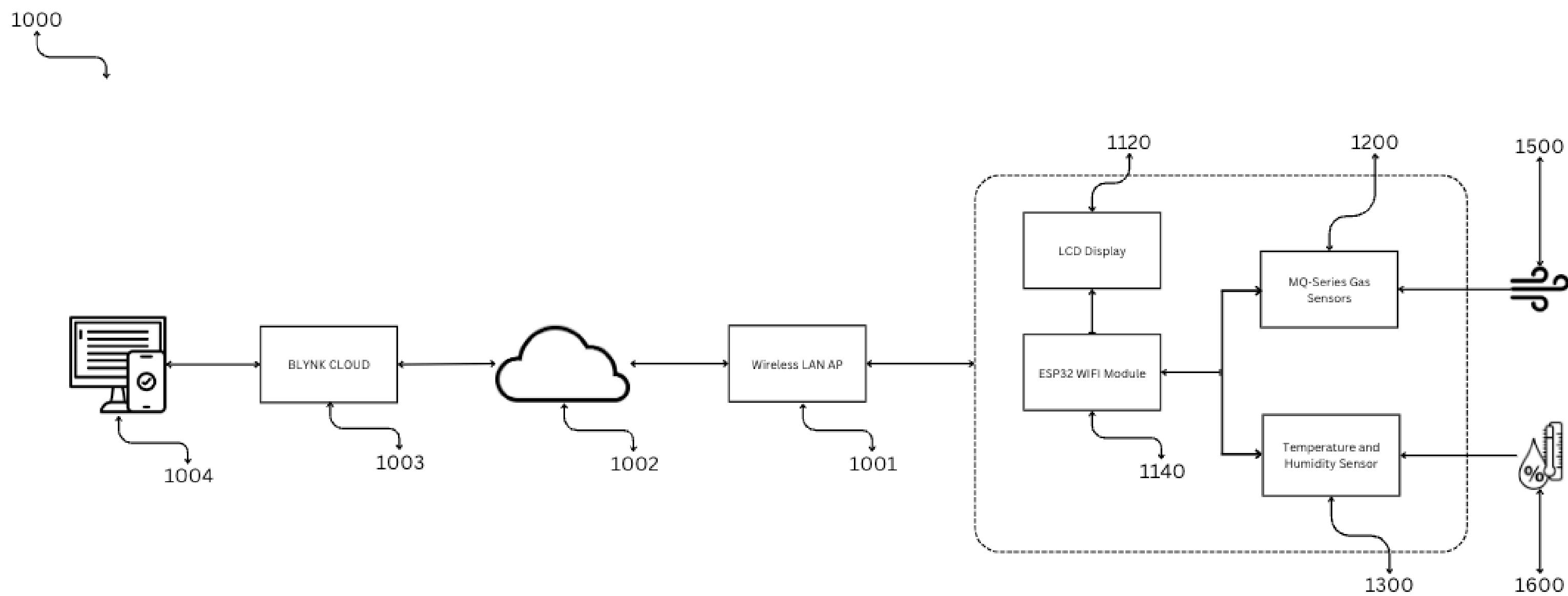
Hysteresis Algorithm

```
initialize variable upper_threshold to high limit
initialize variable lower_threshold to low limit
initialize variable alert_status to False
initialize array hysteresis_alerts

for each data_point in sensor_data:
    if data_point > upper_threshold:
        if alert_status is False:
            append "High pollution alert!" to hysteresis_alerts
            set alert_status to True
    elif data_point < lower_threshold:
        if alert_status is True:
            append "Pollution levels normal" to hysteresis_alerts
            set alert_status to False

return hysteresis_alerts
```







Blynk Cloud

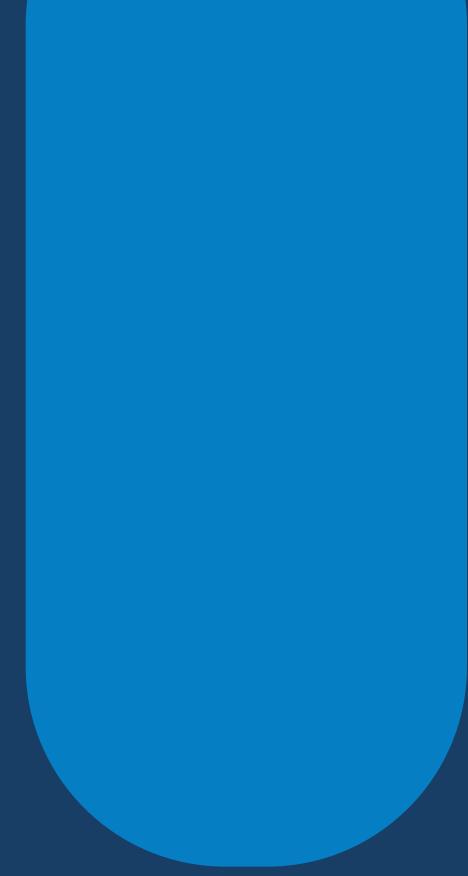






POLLUTION SHOULD NEVER BE THE
PRICE OF PROSPERITY

AL GORE



Fin

Canarias | Sanchez | Mandap