

Please find below the set of algebraic equations for the flattened Explicit CBD:

$$\left\{ \begin{array}{l} \text{var}(b.O_1) = \text{var}(a.I_C) \\ \text{var}(c.O_1) = \text{var}(a.I_1) \\ \text{var}(e.O_1) = \text{var}(d.I_C) \\ \text{var}(f.O_1) = \text{var}(d.I_1) \\ \text{var}(d.O_1) = \text{var}(h.I_1) \\ \text{var}(g.O_1) = \text{var}(h.I_2) \\ \text{var}(a.O_1) = \text{var}(c.I_1) \\ \text{var}(h.O_1) = \text{var}(c.I_2) \\ \text{var}(a.O_1) = \text{var}(i.I_1) \\ \text{var}(g.O_1) = \text{var}(i.I_2) \\ \text{var}(i.O_1) = \text{var}(j.I_1) \\ \text{var}(d.O_1) = \text{var}(f.I_1) \\ \text{var}(j.O_1) = \text{var}(f.I_2) \\ \text{var}(k.O_1) = \text{var}(l.I_1) \\ \text{var}(m.O_1) = \text{var}(l.I_2) \\ \text{var}(l.O_1) = \text{var}(n.I_1) \\ \text{var}(g.O_1) = \text{var}(m.I_1) \\ \text{var}(n.O_1) = \text{var}(o.I_1) \\ \text{var}(c.O_1) = \text{var}(p.I_1) \\ \text{var}(f.O_1) = \text{var}(q.I_1) \\ \text{var}(s.s_i) = \text{var}(r.I_1) \\ \text{var}(b.O_1) = 0 \\ \text{var}(e.O_1) = 1 \\ \text{var}(g.O_1) = 0.001 \\ \text{var}(h.O_1) = \text{var}(h.I_1) \times \text{var}(h.I_2) \\ \text{var}(c.O_1) = \text{var}(c.I_1) + \text{var}(c.I_2) \\ \text{var}(i.O_1) = \text{var}(i.I_1) \times \text{var}(i.I_2) \\ \text{var}(j.O_1) = -\text{var}(j.I_1) \\ \text{var}(f.O_1) = \text{var}(f.I_1) + \text{var}(f.I_2) \\ \text{var}(l.O_1) = \text{var}(l.I_1) \times \text{var}(l.I_2) \\ \text{var}(n.O_1) = \sin(\text{var}(n.I_1)) \end{array} \right.$$

Given:

- Block **x** is represented by variable **a**
- Block **x0** is represented by variable **b**

- Block **sumX** is represented by variable **c**
- Block **y** is represented by variable **d**
- Block **y0** is represented by variable **e**
- Block **sumY** is represented by variable **f**
- Block **D** is represented by variable **g**
- Block **mulX** is represented by variable **h**
- Block **mulY** is represented by variable **i**
- Block **negDX** is represented by variable **j**
- Block **sin.time** is represented by variable **k**
- Block **sin.prodSin** is represented by variable **l**
- Block **sin.Din** is represented by variable **m**
- Block **sin.sin** is represented by variable **n**
- Block **sin.sinOut** is represented by variable **o**
- Block **xi** is represented by variable **p**
- Block **yi** is represented by variable **q**
- Block **sinOut** is represented by variable **r**
- Block **sin** is represented by variable **s**