



Deok-Kyeong (DK), JANG
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ABOUT

I'm a Co-founder/CTO at movin and also a Postdoc in Motion Computing Lab at KAIST. Before that, I interned at Meta Reality Labs. My research goal is to improve the quality of digital character motion in computer graphics and AR/VR systems using deep learning methods. I currently focus on the real-time motion characterization and 3D full-body motion capture using a single LiDAR.

EDUCATION

- Korea Advanced Institute of Science and Technology (KAIST)** *2017-2022 / South Korea*
Ph.D. in Computer Graphics / Motion Computing Laboratory / Advisor: Sung-Hee Lee
• Research on virtual motion stylization/characterization, motion synthesis/control and manifold space.
- Korea Advanced Institute of Science and Technology (KAIST)** *2015-2017 / South Korea*
M.S. in Computer Graphics / Motion Computing Laboratory / Advisor: Sung-Hee Lee
• Research on regression-based landmark detection of Human Models.
- Korea Advanced Institute of Science and Technology (KAIST)** *2009-2015 / South Korea*
B.S. in Physics and Mathematics
• Research on modeling the prey-predator system.

PUBLICATION

- Motion Puzzle: Arbitrary Motion Style Transfer by Body Part** *2022*
ACM Transactions on Graphics (TOG) / ACM SIGGRAPH 2022
[Deok-Kyeong Jang](#), Soomin Park and Sung-Hee Lee
- Diverse Motion Stylization for Multiple Style Domains via Spatial-Temporal Graph-Based Generative Model** *2021*
Proceedings of the ACM on Computer Graphics and Interactive Techniques (PACMCGIT) / SCA
Soomin Park, [Deok-Kyeong Jang](#), and Sung-Hee Lee
- Constructing Human Motion Manifold With Sequential Networks** *2020*
Computer Graphics Forum (CGF) / Eurographics 2021
[Deok-Kyeong Jang](#) and Sung-Hee Lee
- Regression-Based Landmark Detection on Dynamic Human Models** *2017*
Computer Graphics Forum (CGF) / Pacific graphics
[Deok-Kyeong Jang](#) and Sung-Hee Lee

WORK EXPERIENCE

- CTO / Co-founder** *2023.03 - now / movin*
Product: 3D full-body motion capture solution using a single LiDAR.
• Developed real-time full-body motion capture framework based on a single LiDAR, incorporating global translation tracking. Constructing a high-quality dataset featuring diverse subjects, containing synchronized LiDAR point cloud and optical motion capture data for a wide range of actions.
- Research Science Intern** *2022.05 - 2022.10 / Meta Reality Lab, Redmond, USA*
Manager: Yuting Ye, Research Scientist in Gemini team
Collaborators: Dr.Jungdam Won, Research Scientist from Meta AI

- Research on motion characterization in real-time, enhancement of motion style transfer and retargeting with various input sensors.

PROJECTS

Motion tracking and characterization research for virtual avatars

2022 - 2023

Meta Platforms Technologies

- As a researcher of the project, developed real-time motion characterization framework for virtual avatars.

Study of styled motion generation for non-verbal communication of virtual human agents

2020 - 2022

National Research Foundation of Korea

- As a leading researcher of the project, developed humanoid agent's appearance-style customizable motion generation framework.

Development of 4D Reconstruction and Dynamic Deformable Action Model based Hyper Realistic Service Technology

2017 - 2021

Ministry of Science, ICT and Future Planning, Giga Korea Project

- As a leading researcher of the project, developed motion style transfer method and plugins to automatically generate stylized motion.

Development of Simulation Software for Human Body-Sport Gear Complex for Rapidly Prototyping Customized Sports Gear

2015 - 2017

Ministry of Culture, Sports and Tourism

- As a main developer of the project, developed an sports gear modeling technique that fits the personalized foot shape and sports gear interaction.

PAPER REVIEWER

SIGGRAPH, SIGGRAPH ASIA, Pacific Graphics, Computer Graphics Forum, IEEE Transactions on Visualization and Computer Graphics (TVCG)

TECHNICAL SKILLS

Programming Languages	Python C# C/C++ Matlab
Operating Systems	Mac OS X Linux/Unix Windows
Frameworks & Libraries	PyTorch Tensorflow Eigen igl Numpy etc.
Tools	Unity Blender Docker System etc.