#### # Dataset Access Instructions:

This project uses the **DeepSat-6 dataset**, which is publicly available on Kaggle. Due to its size (>5 GB), it cannot be uploaded directly to this repository.

### ## Steps to Access the Dataset:

Go to the Kaggle dataset page: DeepSat (SAT-6) Airborne Dataset

Log in to your Kaggle account (sign up if you don't already have one).

Click on Download to get the dataset files.

Extract the dataset into a local folder named dataset/ so that the folder structure looks like this:

#### Notes:

- 1. Ensure the dataset path matches what is used in the Jupyter notebooks (e.g., scipy.io.loadmat('dataset/sat-6-full.mat')).
- 2. Run the project scripts (e.g., VGG16.ipynb, ResNet50.ipynb) to use the data and weights.
- 3. You may need a Kaggle account and API key to download the dataset. The pre-trained weights and histories are provided for immediate use or reproducibility.

### ## Files Included in the Dataset:

**sat-6-full.mat:** The main dataset in MATLAB format, containing the satellite image data and labels used for training and testing.

**sat6annotations.csv:** A CSV file mapping class indices to human-readable category names (e.g., "road", "building", etc.).

**X\_train\_sat6.csv / X\_test\_sat6.csv:** CSV files containing the training and test input data (features/images) in a flattened or preprocessed format.

**y\_train\_sat6.csv / y\_test\_sat6.csv:** CSV files containing the training and test labels (targets/classes) corresponding to the input data.

## ## Pre-trained Model Output Files (Included in this Folder):

vgg\_baseline.weights.h5: Saved model weights for the VGG16-based model after training.

vgg\_history.csv: Training history (accuracy, loss per epoch) for the VGG16 model.

res baseline.weights.h5: Saved model weights for the ResNet50-based model after training.

res\_history.csv: Training history (accuracy, loss per epoch) for the ResNet50 model.

# **About DeepSat (SAT-6) Dataset:**

The DeepSat (SAT-6) dataset contains 405,000 aerial image patches (28×28 pixels, 4 channels: RGB + NIR) extracted from NAIP imagery over California. Each patch is manually labeled into one of 6 land cover classes, i.e. The dataset includes six classes of terrain: barren land, trees, grassland, roads, water, and buildings.

Sampled from 1500 diverse NAIP tiles (urban, rural, forest, etc.)

Designed for training and evaluating land cover classification models

Available on Kaggle: DeepSat (SAT-6) (Link to dataset mentioned above)