# Tutorial 11: Kernels

# 1 Theory

# Non-Linear Classifier

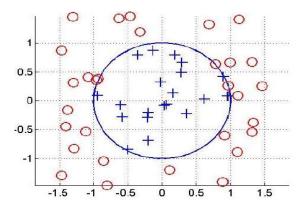
A non-linear classifier is of the form

$$sign\left(w^T\phi(x)+b\right)$$

where  $\phi(x) \triangleq [\phi_1(x) \ \phi_2(x) \ \cdots \phi_M(x)]$  with non-linear functions  $\phi_i(x) : \mathbb{R}^d \to \mathbb{R}$ .

### Example

Consider the following problem



There is no linear classifier which classify the examples with no error. However, define the transformation  $\phi(x) = [x_1^2, x_2^2]$ , the following classifier

$$sign(-x_1^2 - x_2^2 + R^2)$$

can classify the examples above with no error.

# **Kernel Functions**

The use of non-linear transformation  $\phi(x)$  allows to extend our frameworks to non-linear classifier and solve problems for which the examples are not linearly separable in the space. However, the dimension of  $\phi(x)$  might be large and even infinite, thus, leading to a huge computational load. As in SVM, When the weights can be written as

$$w = \sum_{i=1}^{n} \alpha_i y_i \phi(x_i),$$

there is no need to compute  $\phi(x)$  explicitly since the classifier requires to compute only inner products

$$\hat{f}_w(x) = sign(\sum_{i=1}^n \alpha_i y_i \phi(x_i)^T \phi(x) + b).$$

We define a kernel function on a set  $X \subseteq \mathbb{R}^d$  as a function  $K: X \times X \to \mathbb{R}$  which satisfies

- 1. Symmetric K(x, z) = K(z, x).
- 2. For every finite set of points  $\{x_1, x_2, ..., x_n\}$  the matrix  $K_{il} = K(x_i, x_l)$  is positive semi-definite (PSD).

Then, under some reasonable technical conditions, there exists a basis  $\phi(x)$  such that the kernel function is a dot product of the form  $K(x_i, x_l) = \phi(x_i)^T \phi(x_l)$ . In this case, the classifier is

$$\hat{f}_w(x) = sign(\sum_{i=1}^n \alpha_i y_i K(x_i, x) + b).$$

#### Examples of kernel functions:

- Gaussian kernel  $K(x,z) = \exp\left(-||x-z||_2^2/c\right)$  where c > 0.
- Polynomial kernel  $K(x,z) = (1 + x^T z)^p$ ) where  $p \ge 1$ .

# 2 Practice

# Question 1

(a) For  $x \in \mathbb{R}^2$  we define the following feature vector

$$\phi(x) = \begin{bmatrix} x_1^2 \\ \sqrt{2}x_1x_2 \\ x_2^2 \end{bmatrix} \in \mathbb{R}^3.$$

Prove for the kernel  $K(x,z)=(x^Tz)^2$  it holds that  $K(x,z)=\langle \phi(x),\phi(z)\rangle$ .

In the general case we have input of dimension d, that is  $x \in \mathbb{R}^d$  and the features are  $\phi_m(x) = c_m x_1^{\alpha_1} x_2^{\alpha_2} \cdots x_d^{\alpha_d}$  such that  $\alpha_i \in \mathbb{N}$  and  $\sum_{i=1}^d \alpha_i = p$ , that is, every feature is a product of p coordinates of x with possible repetitions. For example, in item (a) we saw inputs and features for d = 2 and p = 2.

(b) It is given that for the kernel  $K(x,z) = \langle x,z \rangle$  it holds that  $K(x,z) = \langle \phi(x),\phi(z) \rangle$ . What is the dimension of  $\phi(x)$  for general d,p?

# Solution

(a) We compute the following inner product:

$$\phi(x)^T \phi(z) = \begin{bmatrix} x_1^2 & \sqrt{2}x_1x_2 & x_2^2 \end{bmatrix} \begin{bmatrix} z_1^2 \\ \sqrt{2}z_1z_2 \\ z_2^2 \end{bmatrix}$$
$$= x_1^2 z_1^2 + 2x_1x_2z_1z_2 + x_2^2 z_2^2$$
$$= (x_1z_1 + x_2z_2)^2$$
$$= (x^T z)^2 = K(x, z).$$

(b) In each coordinate of the features vector the sum of exponents is  $p \to \sum_{i=1}^d \alpha_i$ . Hence, the number of coordinates is determined by the number of possible partitions of p exponents to d components. This problem can be described by the following illustration:

$$| \alpha_1 | \alpha_2 | \cdots | \alpha_i | \cdots | \alpha_d |$$

where we have d+1 dividers for d components. the left most and right most dividers does not affect the partition, hence, we have d-1 dividers and p exponents to arrange. Thus, the number of possible partitions is  $\frac{((p+d-1)!}{p!(d-1)!} = \binom{p+d-1}{p}$ . This implies the dimension of  $\phi(x)$  is exponential in p and using the kernel function can reduce the computation significantly.

## Question 2

Consider the following two examples

$$x_1 = (+1, +1), y_1 = +1,$$
  
 $x_2 = (-1, -1), y_2 = -1.$ 

Compute the separating plane for the Gaussian kernel

$$K(x,z) = \exp(-||x-z||_2^2).$$

## Solution

Recall that the classification is given by

$$sign(w^T\phi(x)) = sign\left(\sum_{i=1}^n \alpha_i y_i K(x_i, x)\right).$$

Therefore, the separating plane is defined by the following equation:

$$\sum_{i=1}^{n} \alpha_i y_i K(x_i, x) = 0.$$

To find the coefficients  $\{\alpha_i\}$  we solve the dual problem:

$$\max_{\alpha} \sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i=1}^{n} \sum_{l=1}^{n} \alpha_i \alpha_l y_i y_l K(x_i, x_l)$$

$$s.t. \quad \alpha_i \ge 0, \ i = 1, 2, ..., n,$$

$$\sum_{i=1}^{n} \alpha_i y_i = 0.$$

In our case, we have

$$\max_{\alpha} \quad \alpha_1 + \alpha_2 - \frac{1}{2} \left( \alpha_1^2 K(x_1, x_1) + \alpha_2^2 K(x_2, x_2) - 2\alpha_1 \alpha_2 K(x_1, x_2) \right)$$
s.t.  $\alpha_i \ge 0, \ i = 1, 2,$ 

$$\alpha_1 - \alpha_2 = 0.$$

Notice that  $K(x_1, x_1) = K(x_2, x_2) = 1$  and  $K(x_1, x_2) = e^{-||x_1 - x_2||_2^2} = e^{-8} \le 1$ . In additions, the second constraint implies that  $\alpha_1 = \alpha_2$ , hence we get

$$\max_{\alpha_1} 2\alpha_1 - \alpha_1^2 (1 - e^{-8})$$
s.t.  $\alpha_1 > 0$ .

The objective function is a simple quadratic function, hence, we compute the derivative and set it to zero:

$$\alpha_1(1 - e^{-8}) = 1 \implies \alpha_1 = \frac{1}{1 - e^{-8}} > 0.$$

Thus, the separating plane is given by

$$\begin{split} \sum_{i=1}^{n} \alpha_{i} y_{i} K(x_{i}, x) &= 0, \\ \Rightarrow \alpha_{1} \left( K(x_{1}, x) - K(x_{2}, x) \right) &= 0, \\ \Rightarrow K(x_{1}, x) &= K(x_{2}, x), \\ \Rightarrow e^{-||x - x_{1}||_{2}^{2}} &= e^{-||x - x_{2}||_{2}^{2}}, \\ \Rightarrow ||x - x_{1}||_{2}^{2} &= ||x - x_{2}||_{2}^{2}, \end{split}$$

which is a line in  $\mathbb{R}^2$  as expected.