

Tutorial 12 : Deep Learning

1 Remainder

Matrix Trace

Let $A \in \mathbb{R}^{n \times n}$. Then the trace of A is defined as

$$\text{Tr}(A) \triangleq \sum_{i=1}^n A_{ii}.$$

Properties:

- Trace is a linear mapping.
- Trace is invariant under cyclic permutations - $\text{Tr}(ABC) = \text{Tr}(CAB) = \text{Tr}(BCA)$.
- $\text{Tr}(A) = \sum_{i=1}^n \lambda_i$.

External Definition of Gradient

Let $f(x) : \mathbb{R}^n \rightarrow \mathbb{R}$ be a differentiable function for which

$$df = \langle g(x), dx \rangle.$$

Then $g(x)$ is the gradient of $f(x)$.

Element-wise Function

Consider a vector $x \in \mathbb{R}^n$ and a differentiable scalar function $\phi : \mathbb{R} \rightarrow \mathbb{R}$ whose derivative is denoted by $\phi'(x)$. We define the element-wise function $\Phi : \mathbb{R}^n \rightarrow \mathbb{R}^n$ as

$$\Phi(x) \triangleq \begin{bmatrix} \phi(x_1) \\ \phi(x_2) \\ \vdots \\ \phi(x_n) \end{bmatrix}.$$

The Jacobian of $\Phi(x)$ is given by

$$J_{\Phi} \triangleq \begin{bmatrix} \frac{\partial \phi(x_1)}{\partial x_1} & \dots & \frac{\partial \phi(x_1)}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial \phi(x_n)}{\partial x_1} & \dots & \frac{\partial \phi(x_n)}{\partial x_n} \end{bmatrix} = \begin{bmatrix} \phi'(x_1) & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \phi'(x_n) \end{bmatrix}.$$

The Jacobian is a diagonal matrix with the derivatives with respect to each coordinate on the diagonal.

2 Practice

Question 1

1. Consider the following neural network

$$y = c^T \Psi((W + V)\Phi(Wx + b)),$$

where $y \in \mathbb{R}$, $x, b, c \in \mathbb{R}^n$, $W, V \in \mathbb{R}^{n \times n}$ and Ψ and Φ are elementwise functions.

Compute the gradient of y with respect to W .

Solution

Recall that the external definition of the gradient g is given by

$$dy = \langle g, dW \rangle.$$

Notice that W is a matrix and hence also dW which implies that dy is an inner product of matrices

$$dy = \text{Tr}(g^T dW).$$

To compute dy we draw the computational graph and we define the following auxiliary variables according to it

$$\begin{aligned} z_0 &= Wx \\ z_1 &= z_0 + b \\ z_2 &= \Phi(z_1) \\ Z_3 &= W + V \\ z_4 &= Z_3 z_2 \\ z_5 &= \Psi(z_4) \\ y &= c^T z_5. \end{aligned}$$

We apply the differential operator on each of the equations:

$$\begin{aligned} z_0 &= Wx & \Rightarrow & dz_0 = dWx \\ z_1 &= z_0 + b & \Rightarrow & dz_1 = dz_0 \\ z_2 &= \Phi(z_1) & \Rightarrow & dz_2 = \Phi'(z_1)dz_1 \\ Z_3 &= W + V & \Rightarrow & dZ_3 = dW \\ z_4 &= Z_3 z_2 & \Rightarrow & dz_4 = dZ_3 z_2 + Z_3 dz_2 \\ z_5 &= \Psi(z_4) & \Rightarrow & dz_5 = \Psi'(z_4)dz_4 \\ y &= c^T z_5 & \Rightarrow & dy = c^T dz_5, \end{aligned}$$

where we neglect terms such as db and dV which are constant with respect to W . Now we "back-propagate":

$$\begin{aligned}
dy &= c^T dz_5 \\
&= c^T \Psi'(z_4) dz_4 \\
&= c^T \Psi'(z_4) (dZ_3 z_2 + Z_3 dz_2) \\
&= c^T \Psi'(z_4) dW z_2 + c^T \Psi'(z_4) Z_3 \Phi'(z_1) dz_1 \\
&= c^T \Psi'(z_4) dW z_2 + c^T \Psi'(z_4) Z_3 \Phi'(z_1) dz_0 \\
&= c^T \Psi'(z_4) dW z_2 + c^T \Psi'(z_4) Z_3 \Phi'(z_1) dW x.
\end{aligned}$$

Next, we use the following properties of the trace:

- $x = \text{Tr}(x) \quad \forall x \in \mathbb{R}.$
- $\text{Tr}(A + B) = \text{Tr}(A) + \text{Tr}(B).$
- $\text{Tr}(ABC) = \text{Tr}(CAB) = \text{Tr}(BCA).$

Therefore,

$$\begin{aligned}
dy &= c^T \Psi'(z_4) dW z_2 + c^T \Psi'(z_4) Z_3 \Phi'(z_1) dW x \\
&= \text{Tr} \left(c^T \Psi'(z_4) dW z_2 + c^T \Psi'(z_4) Z_3 \Phi'(z_1) dW x \right) \\
&= \text{Tr} \left(c^T \Psi'(z_4) dW z_2 \right) + \text{Tr} \left(c^T \Psi'(z_4) Z_3 \Phi'(z_1) dW x \right) \\
&= \text{Tr} \left(z_2 c^T \Psi'(z_4) dW \right) + \text{Tr} \left(x c^T \Psi'(z_4) Z_3 \Phi'(z_1) dW \right) \\
&= \text{Tr} \left(\underbrace{\left(z_2 c^T \Psi'(z_4) + x c^T \Psi'(z_4) Z_3 \Phi'(z_1) \right)}_{g^T} dW \right)
\end{aligned}$$

Finally we got that

$$\begin{aligned}
g &= \Psi'(z_4) c z_2^T + \Phi'(z_1) Z_3^T \Psi'(z_4) c x^T \\
&= \Psi' \left((W + V) \Psi(Wx + b) \right) c \Psi(Wx + b)^T + \Phi'(Wx + b) (W + V)^T \Psi' \left((W + V) \Psi(Wx + b) \right) c x^T.
\end{aligned}$$