

Tehnici de Optimizare

Facultatea de Matematica si Informatica

Universitatea Bucuresti

- Department Informatica-

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Algoritmi pentru probleme de programare convexa

Algoritmi

- Modelul convex: $\min_x f(x) \quad s.l. \quad h(x) \leq 0$
- $h_i(x) \geq h_i(x^k) + \nabla h_i(x^k)^T (x - x^k)$

Metoda Gradient Proiectat cu Liniarizare:

$$x^{k+1} = \operatorname{argmin}_x \nabla f(x^k)^T (x - x^k) + \frac{1}{2\alpha_k} \|x - x^k\|^2$$
$$s.l. \quad h_i(x^k) + \nabla h_i(x^k)^T (x - x^k) \leq 0, \quad \forall i$$

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THEOREM 1. Let the set X^* of solutions of problem (1) be nonempty, let the functions $f(x)$, $g_i(x)$ be differentiable, let their gradients satisfy a Lipschitz condition, and let Slater's condition hold. Then we can find a $\bar{\gamma} > 0$ such that for $0 < \gamma < \bar{\gamma}$ method (7) converges to a point $x^* \in X^*$. If, also, $f(x)$ is strongly convex, then $\|x^k - x^*\| \leq cq^k$, $0 \leq q < 1$. \square

Algoritmi

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La fiecare iteratie se rezolva:

$$\begin{aligned} \min_x & \frac{1}{2} \|x - (x^k - \alpha_k \nabla f(x^k))\|^2 = \frac{1}{2} \|x - y^k\|^2 \\ \text{s. l. } & Ax \leq b \end{aligned}$$

$$\text{unde } A = \begin{bmatrix} \nabla h_1(x^k)^T \\ \dots \\ \nabla h_p(x^k)^T \end{bmatrix}, b = Ax^k - h(x^k)$$

Conditia Slater are loc!

MPGL

$$\begin{aligned} & \min_x \frac{1}{2} \|x - y^k\|^2 \\ & \quad s.l. \ Ax \leq b \\ & \quad x^{k+1} = y^k - A^T \tilde{u}^k \\ L(x, \mu) &= \frac{1}{2} \|x - y^k\|^2 + \mu^T (Ax - b) \\ \nabla_x L(x, \mu) &= 0 \Rightarrow x(\mu) = y^k - A^T \mu \\ \max_{\mu \geq 0} \phi(\mu) &= (QP) \\ \tilde{\mu}^k &\approx \operatorname{argmax}_{\mu \geq 0} -\frac{1}{2} \|A^T \mu\|^2 + \mu^T (Ay^k - b) \end{aligned}$$

Complexitate: $O(\log(1/\epsilon))$ iteratii necesare pentru a atinge: $\|x^k - x^*\| \leq \epsilon$

Metoda Gradient Dual

Modelul convex: $\min_x f(x) \quad s. l. \quad h(x) \leq 0, Ax = b$

Problema duala:

$$\max_{\lambda, \mu \geq 0} \phi(\lambda, \mu) = -\min_{\lambda, \mu \geq 0} -\phi(\lambda, \mu)$$

- Pp: Problema convexa, conditia Slater are loc!
- Constrangeri doar pe μ !
- Daca functia obiectiv primala f este tare convexa (σ_f) atunci ϕ este diferentiabila cu gradient Lipschitz;

$$\begin{bmatrix} \lambda^{k+1} \\ \mu^{k+1} \end{bmatrix} = \pi_Q \left(\begin{bmatrix} \lambda^k \\ \mu^k \end{bmatrix} + \alpha_k \nabla \phi \left(\begin{bmatrix} \lambda^k \\ \mu^k \end{bmatrix} \right) \right)$$

Metoda Gradient Proiectat Dual:

$$\begin{aligned} \lambda^{k+1} &= \lambda^k + \alpha_k \nabla_{\lambda} \phi(\lambda^k, \mu^k) \\ \mu^{k+1} &= \pi_+ \left(\mu^k + \alpha_k \nabla_{\mu} \phi(\lambda^k, \mu^k) \right) \end{aligned}$$

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$$\phi(\lambda, \mu) = \min_x f(x) + \lambda^T g(x) + \mu^T h(x) \rightarrow x(\lambda, \mu) \text{ (solutie)}$$

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$$\nabla_{\mu} \phi(\lambda, \mu) = h(x(\lambda, \mu)) \in R^p$$

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Pentru calculul $\nabla \phi$ este necesara solutia $x(\lambda, \mu)$ a problemei $\min_x L(x, \lambda, \mu)$!

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Pentru calculul $\nabla \phi$ este necesara solutia **aproximativa** $\tilde{x}(\lambda, \mu)$ a problemei $\min_x L(x, \lambda, \mu)$!

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Daca f, h sunt diferentiabile/liniare atunci $\tilde{x}(\lambda, \mu)$ se obtine folosind orice algoritm iterative pentru probleme fara constrangeri.

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$$\phi(\lambda, \mu) = \min_x f(x) + \lambda^T g(x) + \mu^T h(x) \rightarrow x(\lambda, \mu) \text{ (solutie)}$$

Oprire: Se opreste MGPD cu acelasi criteriu ca MGP, iar iteratia finala (λ^K, μ^K) *final* se foloseste pentru $x(\lambda^K, \mu^K) \approx x^*$

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Teorema. Presupunem ca conditia Slater are loc in problema primala si f tare convexa. Atunci ϕ are gradient Lipschitz si MGPD converge:

$$\phi^* - \phi(\lambda^k, \mu^k) \leq O\left(\frac{1}{k}\right)$$

Weisfeld

$$\min_x \sum_i \omega_i ||x - a_i||^2$$

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Functia obiectiv este convexa:

$$\begin{aligned} \nabla f(x^*) &= 0 \\ \sum_i \omega_i (x^* - a_i) &= 0 \end{aligned}$$

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Funcția obiectiv este convexă:

$$\begin{aligned} \nabla f(x^*) &= 0 \\ \sum_i \omega_i (x^* - a_i) &= 0 \end{aligned}$$

$$x^* \sum_i \omega_i = \sum_i \omega_i a_i$$

$$x^* = \frac{\sum_i \omega_i a_i}{\sum_i \omega_i}$$

- $\nabla|x| = \frac{x}{|x|} = \text{sgn}(x)$, pt $x \neq 0 \Rightarrow \nabla|x - a| = \frac{x-a}{|x-a|}$
- $\nabla|0| = [-1,1]; s \in [-1,1] = \partial f(0)$ se numeste subgradient
- $|\nabla f(x) - \nabla f(y)| \leq L|x - y| \rightarrow |\text{sgn}(x) - \text{sgn}(y)| < L|x - y|$
- $x < 0, y < 0 \Rightarrow 2 \leq L|x - y| \rightarrow 0$
- $g(x) = ||x - a_i||$, g diferentiabila cu exceptia $x^* = a_i$ (nu are grad. Lipschitz)
- $\nabla g(x) = \frac{x-a_i}{||x-a_i||}$, $x \neq a_i$
- $\nabla g(a_i) = \partial g(a_i) = \{x: ||x - a_i|| \leq 1\}$

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- $\nabla g(a_i) = \partial g(a_i) = \{x: ||x - a_i|| \leq 1\}$
- $\nabla f(x^*) = \frac{\sum_i \omega_i(x^* - a_i)}{||x^* - a_i||} = 0 \Rightarrow \omega_i v = -\frac{\sum_{i \neq j} \omega_i(x^* - a_i)}{||x^* - a_i||}$, unde $||v|| \leq 1$
- $\left| \left| \frac{1}{\omega_i} \frac{\sum_{i \neq j} \omega_i(x^* - a_i)}{||x^* - a_i||} \right| \right| \leq 1$