# Notes on Probability Theory

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## I. DEFINITIONS

The *expected value*, or *mean*, of a discrete random variable (r.v. hereafter) X:

$$\mathbf{m}_{\mathbf{X}} = \mathrm{E} \langle \mathbf{X} \rangle$$

$$= \sum_{k=1}^{\infty} \boldsymbol{x}_k \ P_{\mathbf{X}}(\boldsymbol{x}_k)$$

The variance of the r.v. X:

$$\begin{aligned} \boldsymbol{\sigma}_{\mathbf{X}}^2 &= \operatorname{var} \left\langle \mathbf{X} \right\rangle \\ &= \operatorname{E} \left\langle (\mathbf{X} - \mathbf{m}_{\mathbf{X}})^2 \right\rangle \\ &= \sum_{k=1}^{\infty} (\boldsymbol{x} - \mathbf{m}_{\mathbf{X}})^2 \ P_{\mathbf{X}}(\boldsymbol{x}_k) \end{aligned}$$

which can also be expressed as

$$\begin{aligned} \operatorname{var} \left\langle \mathbf{X} \right\rangle &= \operatorname{E} \left\langle (\mathbf{X} - \mathbf{m}_{\mathbf{X}})^{2} \right\rangle \\ &= \operatorname{E} \left\langle \mathbf{X}^{2} - 2 \mathbf{m}_{\mathbf{X}} \mathbf{X} + \mathbf{m}_{\mathbf{X}}^{2} \right\rangle \\ &= \operatorname{E} \left\langle \mathbf{X}^{2} \right\rangle - 2 \mathbf{m}_{\mathbf{X}} \operatorname{E} \left\langle \mathbf{X} \right\rangle + \mathbf{m}_{\mathbf{X}}^{2} \\ &= \operatorname{E} \left\langle \mathbf{X}^{2} \right\rangle - \mathbf{m}_{\mathbf{X}}^{2} \end{aligned}$$

where  $E\langle \mathbf{X}^2 \rangle$  is the called the second moment of  $\mathbf{X}$ . The *standard deviation* of the r.v.  $\mathbf{X}$ :

$$\sigma_{\mathbf{X}} = \operatorname{std} \langle \mathbf{X} \rangle$$

$$= \sqrt{\operatorname{var} \langle \mathbf{X} \rangle}$$

For the discrete r.v.  $x \in \mathbb{R}^{m \times 1}$  and scalar variable c, the variance has the following properties, each resulting in a scalar random variable:

1) Adding a constant c, does not affect the variance of X

$$\operatorname{var} \langle \boldsymbol{x} + c \rangle = \operatorname{E} \left\langle \left( \boldsymbol{x} + c - \left( \operatorname{E} \langle \boldsymbol{x} \rangle + c \right) \right)^{2} \right\rangle$$
$$= \operatorname{E} \left\langle \left( \boldsymbol{x} - \operatorname{E} \langle \boldsymbol{x} \rangle \right)^{2} \right\rangle$$
$$= \operatorname{var} \left\langle \boldsymbol{x} \right\rangle$$

2) Multiplying by a constant c, scales the variance of  $\boldsymbol{x}$  by  $c^2$ 

$$\operatorname{var} \langle c\boldsymbol{x} \rangle = \operatorname{E} \langle (c\boldsymbol{x} - c\operatorname{E} \langle \boldsymbol{x} \rangle)^2 \rangle$$
$$= \operatorname{E} \langle c^2 (\boldsymbol{x} - \operatorname{E} \langle \boldsymbol{x} \rangle)^2 \rangle$$
$$= c^2 \operatorname{var} \langle \boldsymbol{x} \rangle$$

3) Let x = c, then the constant r.v. has zero variance

$$\operatorname{var} \langle \boldsymbol{x} \rangle = \operatorname{E} \langle (\boldsymbol{x} - c)^2 \rangle$$
$$= \operatorname{E} \langle 0 \rangle$$
$$= 0$$

For the discrete r.v.  $x, y \in \mathbb{R}^{m \times 1}$ , the covariance has the following property, resulting in a *matrix of random variables*:

$$cov \langle \boldsymbol{x}, \mathbf{y} \rangle = E \langle \boldsymbol{x} \mathbf{y} - \boldsymbol{x} E \langle \mathbf{y} \rangle - \mathbf{y} E \langle \boldsymbol{x} \rangle + E \langle \boldsymbol{x} \rangle E \langle \mathbf{y} \rangle \rangle$$
$$= E \langle \boldsymbol{x} \mathbf{y} \rangle - 2E \langle \boldsymbol{x} \rangle E \langle \mathbf{y} \rangle + E \langle \boldsymbol{x} \rangle E \langle \mathbf{y} \rangle$$
$$= E \langle \boldsymbol{x} \mathbf{y} \rangle - E \langle \boldsymbol{x} \rangle E \langle \mathbf{y} \rangle$$

If either  $\boldsymbol{x}$  or  $\mathbf{y}$  have zero mean, i.e.  $\mathrm{E} \langle \boldsymbol{x} \rangle = 0$  or  $\mathrm{E} \langle \mathbf{y} \rangle = 0$ , then  $\mathrm{cov} \langle \boldsymbol{x}, \mathbf{y} \rangle = \mathrm{E} \langle \boldsymbol{x} \mathbf{y} \rangle$ . If the correlation of  $\boldsymbol{x}$  and  $\mathbf{y}$  is zero, i.e.  $\mathrm{E} \langle \boldsymbol{x} \mathbf{y} \rangle = 0$  then  $\boldsymbol{x}$  and  $\mathbf{y}$  are orthogonal.

For the discrete r.v.  $x, y \in \mathbb{R}^{m \times 1}$ , the correlation coefficient has the following property

$$\rho_{x,y} = \frac{\text{cov} \langle x, y \rangle}{\sigma_x \sigma_y}$$
$$= \frac{\text{E} \langle xy \rangle - \text{E} \langle x \rangle \text{E} \langle y \rangle}{\sigma_x \sigma_y}$$

where  $\sigma_x = \sqrt{\operatorname{var}\langle x \rangle}$ ,  $\sigma_y = \sqrt{\operatorname{var}\langle y \rangle}$ , and  $-1 \le \rho_{x,y} \le 1$ . If  $\rho_{x,y} = 0$  then x and y are said to be *uncorrelated*.

## II. LINEAR COMBINATIONS

## A. Linear Forms

Assume X and x to be a matrix and a vector of random variables. Then

$$E \langle \mathbf{A} \mathbf{X} \mathbf{B} + \mathbf{C} \rangle = \mathbf{A} \ E \langle \mathbf{X} \rangle \ \mathbf{B} + \mathbf{C}$$
$$\operatorname{var} \langle \mathbf{A} \mathbf{x} \rangle = \mathbf{A} \ \operatorname{var} \langle \mathbf{x} \rangle \ \mathbf{A}^{\mathsf{T}}$$
$$\operatorname{cov} \langle \mathbf{A} \mathbf{x}, \mathbf{B} \mathbf{y} \rangle = \mathbf{A} \ \operatorname{cov} \langle \mathbf{x}, \mathbf{y} \rangle \ \mathbf{B}^{\mathsf{T}}$$

Assume x to be a stochastic vector with mean m, then

$$E \langle \mathbf{A}\mathbf{x} + \mathbf{b} \rangle = \mathbf{A}\mathbf{m} + \mathbf{b}$$
$$E \langle \mathbf{A}\mathbf{x} \rangle = \mathbf{A}\mathbf{m}$$
$$E \langle \mathbf{x} + \mathbf{b} \rangle = \mathbf{m} + \mathbf{b}$$

## B. Quadratic Forms

Assume **A** is symmetric,  $\mathbf{c} = \mathrm{E} \langle \boldsymbol{x} \rangle$  and  $\boldsymbol{\Sigma} = \mathrm{var} \langle \boldsymbol{x} \rangle$ . Assume also that all coordinates  $x_i$  are independent, have the same central moments  $\mu_1, \mu_2, \mu_3, \mu_4$  and denote  $\mathbf{a} = \mathrm{diag}(\mathbf{A})$ . Then

$$E \langle \boldsymbol{x}^{\mathsf{T}} \mathbf{A} \boldsymbol{x} \rangle = \text{Tr}(\mathbf{A} \boldsymbol{\Sigma}) + \mathbf{c}^{\mathsf{T}} \mathbf{A} \mathbf{c}$$
$$\text{var} \langle \boldsymbol{x}^{\mathsf{T}} \mathbf{A} \boldsymbol{x} \rangle = 2\mu_2^2 \text{Tr}(\mathbf{A}^2) + 4\mu_2 \mathbf{c}^{\mathsf{T}} \mathbf{A}^2 \mathbf{c}$$
$$+ 4\mu_3 \mathbf{c}^{\mathsf{T}} \mathbf{A} \mathbf{a} + (\mu_4 - 3\mu_2^2) \mathbf{a}^{\mathsf{T}} \mathbf{a}$$

Also, assume x to be a stochastic vector with mean m, and covariance M. Then

$$\begin{split} \mathbf{E} \left\langle (\mathbf{A}\boldsymbol{x} + \mathbf{a})(\mathbf{B}\boldsymbol{x} + \mathbf{b})^{\mathsf{T}} \right\rangle &= \mathbf{A}\mathbf{M}\mathbf{B}^{\mathsf{T}} + (\mathbf{A}\mathbf{m} + \mathbf{a})(\mathbf{B}\mathbf{m} + \mathbf{b})^{\mathsf{T}} \\ &\quad \mathbf{E} \left\langle \boldsymbol{x}\boldsymbol{x}^{\mathsf{T}} \right\rangle = \mathbf{M} + \mathbf{m}\mathbf{m}^{\mathsf{T}} \\ &\quad \mathbf{E} \left\langle \boldsymbol{x}\mathbf{a}^{\mathsf{T}}\boldsymbol{x} \right\rangle = (\mathbf{M} + \mathbf{m}\mathbf{m}^{\mathsf{T}})\mathbf{a} \\ &\quad \mathbf{E} \left\langle \boldsymbol{x}^{\mathsf{T}}\mathbf{a}\boldsymbol{x}^{\mathsf{T}} \right\rangle = \mathbf{a}^{\mathsf{T}}(\mathbf{M} + \mathbf{m}\mathbf{m}^{\mathsf{T}}) \\ &\quad \mathbf{E} \left\langle (\mathbf{A}\boldsymbol{x})(\mathbf{A}\boldsymbol{x})^{\mathsf{T}} \right\rangle = \mathbf{A}(\mathbf{M} + \mathbf{m}\mathbf{m}^{\mathsf{T}})\mathbf{A}^{\mathsf{T}} \\ &\quad \mathbf{E} \left\langle (\mathbf{A}\boldsymbol{x})(\mathbf{A}\boldsymbol{x})^{\mathsf{T}} \right\rangle = \mathbf{A}(\mathbf{M} + \mathbf{m}\mathbf{m}^{\mathsf{T}})\mathbf{A}^{\mathsf{T}} \\ &\quad \mathbf{E} \left\langle (\boldsymbol{x} + \mathbf{a})(\boldsymbol{x} + \mathbf{a})^{\mathsf{T}} \right\rangle = \mathbf{M} + (\mathbf{m} + \mathbf{a})(\mathbf{m} + \mathbf{a})^{\mathsf{T}} \\ &\quad \mathbf{E} \left\langle (\mathbf{A}\boldsymbol{x} + \mathbf{a})^{\mathsf{T}}(\mathbf{B}\boldsymbol{x} + \mathbf{b}) \right\rangle = \mathrm{Tr}(\mathbf{A}\mathbf{M}\mathbf{B}^{\mathsf{T}}) + (\mathbf{A}\mathbf{m} + \mathbf{a})^{\mathsf{T}}(\mathbf{B}\mathbf{m} + \mathbf{b}) \\ &\quad \mathbf{E} \left\langle \boldsymbol{x}^{\mathsf{T}}\boldsymbol{x} \right\rangle = \mathrm{Tr}(\mathbf{M}) + \mathbf{m}^{\mathsf{T}}\mathbf{m} \\ &\quad \mathbf{E} \left\langle (\mathbf{A}\boldsymbol{x})^{\mathsf{T}}(\mathbf{A}\boldsymbol{x}) \right\rangle = \mathrm{Tr}(\mathbf{A}\mathbf{M}\mathbf{A}^{\mathsf{T}}) + (\mathbf{A}\mathbf{m})^{\mathsf{T}}(\mathbf{A}\mathbf{m}) \\ &\quad \mathbf{E} \left\langle (\mathbf{A}\boldsymbol{x})^{\mathsf{T}}(\mathbf{A}\boldsymbol{x}) \right\rangle = \mathrm{Tr}(\mathbf{M}) + (\mathbf{m} + \mathbf{a})^{\mathsf{T}}(\mathbf{m} + \mathbf{a}) \end{split}$$

# C. Cubic Forms

Assume x to be a stochastic vector with independent coordinates, mean  $\mathbf{m}$ , covariance  $\mathbf{M}$  and central moments  $\mathbf{v}_3 = \mathrm{E} \left\langle (x - \mathbf{m})^3 \right\rangle$ . Then

$$\begin{split} & E \left\langle (\mathbf{A} \boldsymbol{x} + \mathbf{a}) (\mathbf{B} \boldsymbol{x} + \mathbf{b})^\intercal (\mathbf{C} \boldsymbol{x} + \mathbf{c}) \right\rangle \\ & = \mathbf{A} \ \mathrm{diag}(\mathbf{B}^\intercal \mathbf{C}) \mathbf{v}_3 \\ & + \mathrm{Tr}(\mathbf{B} \mathbf{M} \mathbf{C}^\intercal) (\mathbf{A} \mathbf{m} + \mathbf{a}) \\ & + \mathbf{A} \mathbf{M} \mathbf{C}^\intercal (\mathbf{B} \mathbf{m} + \mathbf{b}) \\ & + (\mathbf{A} \mathbf{M} \mathbf{B}^\intercal + (\mathbf{A} \mathbf{m} + \mathbf{a}) (\mathbf{B} \mathbf{m} + \mathbf{b})^\intercal) (\mathbf{C} \mathbf{m} + \mathbf{c}) \\ & E \left\langle \boldsymbol{x} \boldsymbol{x}^\intercal \boldsymbol{x} \right\rangle \\ & = \mathbf{v}_3 + 2 \mathbf{M} \mathbf{m} + (\mathrm{Tr}(\mathbf{M}) + \mathbf{m}^\intercal \mathbf{m}) \mathbf{m} \\ & E \left\langle (\mathbf{A} \boldsymbol{x} + \mathbf{a}) (\mathbf{A} \boldsymbol{x} + \mathbf{a})^\intercal (\mathbf{A} \boldsymbol{x} + \mathbf{a}) \right\rangle \\ & = \mathbf{A} \ \mathrm{diag}(\mathbf{A}^\intercal \mathbf{A}) \mathbf{v}_3 \\ & + [2 \mathbf{A} \mathbf{M} \mathbf{A}^\intercal + (\mathbf{A} \boldsymbol{x} + \mathbf{a}) (\mathbf{A} \boldsymbol{x} + \mathbf{a})^\intercal] (\mathbf{A} \mathbf{m} + \mathbf{a}) \\ & + \mathrm{Tr}(\mathbf{A} \mathbf{M} \mathbf{A}^\intercal) (\mathbf{A} \mathbf{m} + \mathbf{a}) \\ & + \mathrm{Tr}(\mathbf{A} \mathbf{M} \mathbf{A}^\intercal) (\mathbf{A} \mathbf{m} + \mathbf{a}) \\ & E \left\langle (\mathbf{A} \boldsymbol{x} + \mathbf{a}) \mathbf{b}^\intercal (\mathbf{C} \boldsymbol{x} + \mathbf{c}) (\mathbf{D} \boldsymbol{x} + \mathbf{d})^\intercal \right\rangle \\ & = (\mathbf{A} \boldsymbol{x} + \mathbf{a}) \mathbf{b}^\intercal (\mathbf{C} \mathbf{M} \mathbf{D}^\intercal + (\mathbf{C} \mathbf{m} + \mathbf{c}) (\mathbf{D} \mathbf{m} + \mathbf{d})^\intercal) \\ & + (\mathbf{A} \mathbf{M} \mathbf{C}^\intercal + (\mathbf{A} \mathbf{m} + \mathbf{a}) (\mathbf{C} \mathbf{m} + \mathbf{c})^\intercal) \mathbf{b} (\mathbf{D} \mathbf{m} + \mathbf{d})^\intercal) \\ & + \mathbf{b}^\intercal (\mathbf{C} \mathbf{m} + \mathbf{c}) (\mathbf{A} \mathbf{M} \mathbf{D}^\intercal - (\mathbf{A} \mathbf{m} + \mathbf{a}) (\mathbf{D} \mathbf{m} + \mathbf{d})^\intercal) \end{split}$$

## III. GAUSSIANS

The following section contains some useful relations from statistics theory.

## A. Density and normalization

The density of  $x \sim \mathcal{N}(\mathbf{m}, \Sigma)$  is

$$p(\boldsymbol{x}) = \frac{1}{\sqrt{\det(2\pi\boldsymbol{\Sigma})}} \exp\left[-\frac{1}{2}(\boldsymbol{x} - \mathbf{m})^{\intercal}\boldsymbol{\Sigma}^{-1}(\boldsymbol{x} - \mathbf{m})\right]$$

Note that if x is d-dimensional, then  $\det(2\pi\Sigma) = (2\pi)^d \det(\Sigma)$ .

Integration and normalization is given by:

$$\int \exp\left[-\frac{1}{2}(\boldsymbol{x} - \mathbf{m})^{\mathsf{T}} \boldsymbol{\Sigma}^{-1}(\boldsymbol{x} - \mathbf{m})\right] d\boldsymbol{x}$$

$$= \sqrt{\det(2\pi \boldsymbol{\Sigma})}$$

$$\int \exp\left[-\frac{1}{2} \boldsymbol{x}^{\mathsf{T}} \mathbf{A} \boldsymbol{x} + \mathbf{b}^{\mathsf{T}} \boldsymbol{x}\right] d\boldsymbol{x}$$

$$= \sqrt{\det(2\pi \mathbf{A}^{-1})} \exp\left[\frac{1}{2} \mathbf{b}^{\mathsf{T}} \mathbf{A}^{-1} \mathbf{b}\right]$$

$$\int \exp\left[-\frac{1}{2} \text{Tr}(\mathbf{S}^{\mathsf{T}} \mathbf{A} \mathbf{S}) + \text{Tr}(\mathbf{B}^{\mathsf{T}} \mathbf{S})\right] d\mathbf{S}$$

$$= \sqrt{\det(2\pi \mathbf{A}^{-1})} \exp\left[\frac{1}{2} \text{Tr}(\mathbf{B}^{\mathsf{T}} \mathbf{A}^{-1} \mathbf{B})\right]$$

The derivatives of the density are

$$\begin{split} &\frac{\partial p(\boldsymbol{x})}{\partial \boldsymbol{x}} = -p(\boldsymbol{x})\boldsymbol{\Sigma}^{-1}(\boldsymbol{x} - \mathbf{m}) \\ &\frac{\partial^2 p}{\partial \boldsymbol{x} \partial \boldsymbol{x}^{\mathsf{T}}} = p(\boldsymbol{x}) \left(\boldsymbol{\Sigma}^{-1}(\boldsymbol{x} - \mathbf{m})(\boldsymbol{x} - \mathbf{m})^{\mathsf{T}}\boldsymbol{\Sigma}^{-1} - \boldsymbol{\Sigma}^{-1}\right) \end{split}$$

# B. Marginal Distribution

Assume  $x \sim \mathcal{N}_{x}(\mu, \Sigma)$  where

$$egin{aligned} x &= \left[egin{array}{c} x_a \ x_b \end{array}
ight] \ \mu &= \left[egin{array}{c} \mu_a \ \mu_b \end{array}
ight] \ \Sigma &= \left[egin{array}{c} \Sigma_a & \Sigma_c \ \Sigma_b^ o & \Sigma_b \end{array}
ight] \end{aligned}$$

then

$$p(\boldsymbol{x}_a) = \mathcal{N}_{\boldsymbol{x}_a}(\boldsymbol{\mu}_a, \boldsymbol{\Sigma}_a)$$
$$p(\boldsymbol{x}_b) = \mathcal{N}_{\boldsymbol{x}_b}(\boldsymbol{\mu}_b, \boldsymbol{\Sigma}_b)$$

# C. Conditional Distribution

Assume  $x \sim \mathcal{N}_{x}(\mu, \Sigma)$  where

$$egin{aligned} oldsymbol{x} &= \left[egin{array}{c} oldsymbol{x}_a \ oldsymbol{x}_b \end{array}
ight] \ oldsymbol{\mu} &= \left[egin{array}{c} oldsymbol{\mu}_a \ oldsymbol{\mu}_b \end{array}
ight] \ oldsymbol{\Sigma} &= \left[egin{array}{c} oldsymbol{\Sigma}_a \ oldsymbol{\Sigma}_a \end{array} oldsymbol{\Sigma}_c \ oldsymbol{\Sigma}_a \end{array} oldsymbol{\Sigma}_b \end{array}
ight]$$

then

$$p(\boldsymbol{x}_a|\boldsymbol{x}_b) = \mathcal{N}_{\boldsymbol{x}_a}(\hat{\boldsymbol{\mu}}_a, \hat{\boldsymbol{\Sigma}}_a)$$
$$p(\boldsymbol{x}_b|\boldsymbol{x}_a) = \mathcal{N}_{\boldsymbol{x}_b}(\hat{\boldsymbol{\mu}}_b, \hat{\boldsymbol{\Sigma}}_b)$$

where

$$egin{aligned} \hat{oldsymbol{\mu}}_a &= oldsymbol{\mu}_a + oldsymbol{\Sigma}_c oldsymbol{\Sigma}_b^{-1} (oldsymbol{x}_b - oldsymbol{\mu}_b) \ \hat{oldsymbol{\Sigma}}_a &= oldsymbol{\Sigma}_a - oldsymbol{\Sigma}_c oldsymbol{\Sigma}_b^{-1} oldsymbol{\Sigma}_a^{-1} (oldsymbol{x}_a - oldsymbol{\mu}_a) \ \hat{oldsymbol{\Sigma}}_b &= oldsymbol{\Sigma}_b - oldsymbol{\Sigma}_c oldsymbol{\Sigma}_a^{-1} oldsymbol{\Sigma}_c^{\mathsf{T}} \end{aligned}$$

D. Linear combination

Assume 
$$\boldsymbol{x} \sim \mathcal{N}(\mathbf{m}_x, \boldsymbol{\Sigma}_x)$$
 and  $\mathbf{y} \sim \mathcal{N}(\mathbf{m}_y, \boldsymbol{\Sigma}_y)$ 

$$egin{aligned} \mathbf{A}x + \mathbf{B}\mathbf{y} + \mathbf{c} \ &\sim \mathcal{N}(\mathbf{A}\mathbf{m}_x + \mathbf{B}\mathbf{m}_y + \mathbf{c}, \ \mathbf{A}\mathbf{\Sigma}_x\mathbf{A}^\intercal + \mathbf{B}\mathbf{\Sigma}_y\mathbf{B}^\intercal) \end{aligned}$$

E. Rearranging Means

$$\mathcal{N}_{\mathbf{A}\boldsymbol{x}}\left[\mathbf{m}, \boldsymbol{\Sigma}\right] = \frac{\sqrt{\det(2\pi(\mathbf{A}^{\mathsf{T}}\boldsymbol{\Sigma}^{-1}\mathbf{A})^{-1})}}{\sqrt{\det(2\pi\boldsymbol{\Sigma})}}$$
$$\times \mathcal{N}_{\boldsymbol{x}}\left[\mathbf{A}^{-1}\mathbf{m}, \ (\mathbf{A}^{\mathsf{T}}\boldsymbol{\Sigma}^{-1}\mathbf{A})^{-1}\right]$$

F. Rearranging into squared form

If A is symmetric, then

$$-\frac{1}{2}\mathbf{x}^{\mathsf{T}}\mathbf{A}\mathbf{x} + \mathbf{b}^{\mathsf{T}}\mathbf{x}$$

$$= -\frac{1}{2}(\mathbf{x} - \mathbf{A}^{-1}\mathbf{b})^{\mathsf{T}}\mathbf{A}(\mathbf{x} - \mathbf{A}^{-1}\mathbf{b})^{\mathsf{T}} + \frac{1}{2}\mathbf{b}^{\mathsf{T}}\mathbf{A}^{-1}\mathbf{b}$$

$$-\frac{1}{2}\mathrm{Tr}(\mathbf{X}^{\mathsf{T}}\mathbf{A}\mathbf{X}) + Tr(\mathbf{B}^{\mathsf{T}}\mathbf{X})$$

$$= -\frac{1}{2}[(\mathbf{X} - \mathbf{A}^{-1}\mathbf{B})^{\mathsf{T}}\mathbf{A}(\mathbf{X} - \mathbf{A}^{-1}\mathbf{B})] + \frac{1}{2}\mathrm{Tr}(\mathbf{B}^{\mathsf{T}}\mathbf{A}^{-1}\mathbf{B})$$

G. Sum of two squared forms

In vector form (assuming  $\Sigma_1$ ,  $\Sigma_2$  are symmetric)

$$\begin{split} &-\frac{1}{2}(\boldsymbol{x}-\mathbf{m}_1)^{\intercal}\boldsymbol{\Sigma}_1^{-1}(\boldsymbol{x}-\mathbf{m}_1)\\ &-\frac{1}{2}(\boldsymbol{x}-\mathbf{m}_2)^{\intercal}\boldsymbol{\Sigma}_2^{-1}(\boldsymbol{x}-\mathbf{m}_2)\\ &=-\frac{1}{2}(\boldsymbol{x}-\mathbf{m}_c)^{\intercal}\boldsymbol{\Sigma}_c^{-1}(\boldsymbol{x}-\mathbf{m}_c)+C\\ \boldsymbol{\Sigma}_c^{-1}&=\boldsymbol{\Sigma}_1^{-1}+\boldsymbol{\Sigma}_2^{-1}\\ \mathbf{m}_c&=(\boldsymbol{\Sigma}_1^{-1}+\boldsymbol{\Sigma}_2^{-1})^{-1}(\boldsymbol{\Sigma}_1^{-1}\mathbf{m}_1+\boldsymbol{\Sigma}_2^{-1}\mathbf{m}_2)\\ C&=\frac{1}{2}(\mathbf{m}_1^{\intercal}\boldsymbol{\Sigma}_1^{-1}+\mathbf{m}_2^{\intercal}\boldsymbol{\Sigma}_2^{-1})(\boldsymbol{\Sigma}_1^{-1}+\boldsymbol{\Sigma}_2^{-1})^{-1}\\ &(\boldsymbol{\Sigma}_1^{-1}\mathbf{m}_1+\boldsymbol{\Sigma}_2^{-1}\mathbf{m}_2)-\frac{1}{2}(\mathbf{m}_1^{\intercal}\boldsymbol{\Sigma}_1^{-1}\mathbf{m}_1+\mathbf{m}_2^{\intercal}\boldsymbol{\Sigma}_2^{-1}\mathbf{m}_2) \end{split}$$

In a trace form (assuming  $\Sigma_1$ ,  $\Sigma_2$  are symmetric)

$$\begin{split} &-\frac{1}{2}\mathrm{Tr}\left[(\mathbf{X}-\mathbf{M}_1)^{\intercal}\boldsymbol{\Sigma}_1^{-1}(\mathbf{X}-\mathbf{M}_1)\right]\\ &-\frac{1}{2}\mathrm{Tr}\left[(\mathbf{X}-\mathbf{M}_2)^{\intercal}\boldsymbol{\Sigma}_2^{-1}(\mathbf{X}-\mathbf{M}_2)\right]\\ &=-\frac{1}{2}\mathrm{Tr}\left[(\mathbf{X}-\mathbf{M}_c)^{\intercal}\boldsymbol{\Sigma}_c^{-1}(\mathbf{X}-\mathbf{M}_c)\right]+C\\ \boldsymbol{\Sigma}_c^{-1}&=\boldsymbol{\Sigma}_1^{-1}+\boldsymbol{\Sigma}_2^{-1}\\ \boldsymbol{M}_c&=(\boldsymbol{\Sigma}_1^{-1}+\boldsymbol{\Sigma}_2^{-1})^{-1}(\boldsymbol{\Sigma}_1^{-1}\mathbf{M}_1+\boldsymbol{\Sigma}_2^{-1}\mathbf{M}_2)\\ C&=\frac{1}{2}\mathrm{Tr}[(\mathbf{M}_1^{\intercal}\boldsymbol{\Sigma}_1^{-1}+\mathbf{M}_2^{\intercal}\boldsymbol{\Sigma}_2^{-1})(\boldsymbol{\Sigma}_1^{-1}+\boldsymbol{\Sigma}_2^{-1})^{-1}\\ &(\boldsymbol{\Sigma}_1^{-1}\mathbf{M}_1+\boldsymbol{\Sigma}_2^{-1}\mathbf{M}_2)]-\frac{1}{2}(\mathbf{M}_1^{\intercal}\boldsymbol{\Sigma}_1^{-1}\mathbf{M}_1\\ &+\mathbf{M}_2^{\intercal}\boldsymbol{\Sigma}_2^{-1}\mathbf{M}_2)\end{split}$$

H. Product of Gaussian densities

Let  $\mathcal{N}_{x}(\mathbf{m}, \Sigma)$  denote a density of x, then

$$\mathcal{N}_{\boldsymbol{x}}(\mathbf{m}_1, \boldsymbol{\Sigma}_1) \cdot \mathcal{N}_{\boldsymbol{x}}(\mathbf{m}_2, \boldsymbol{\Sigma}_2) = c_c \mathcal{N}_{\boldsymbol{x}}(\mathbf{m}_c, \boldsymbol{\Sigma}_c)$$

$$c_c = \mathcal{N}_{\mathbf{m}_1}(\mathbf{m}_1, (\mathbf{\Sigma}_1 + \mathbf{\Sigma}_2))$$

$$= \frac{1}{\sqrt{\det(2\pi(\mathbf{\Sigma}_1 + \mathbf{\Sigma}_2))}}$$

$$\exp\left[-\frac{1}{2}(\mathbf{m}_1 - \mathbf{m}_2)^{\mathsf{T}}(\mathbf{\Sigma}_1 + \mathbf{\Sigma}_2)^{-1}(\mathbf{m}_1 - \mathbf{m}_2)\right]$$

$$\mathbf{m}_c = (\mathbf{\Sigma}_1^{-1} + \mathbf{\Sigma}_2^{-1})^{-1}(\mathbf{\Sigma}_1^{-1}\mathbf{m}_1 + \mathbf{\Sigma}_2^{-1}\mathbf{m}_2)$$

$$\mathbf{\Sigma}_c = (\mathbf{\Sigma}_1^{-1} + \mathbf{\Sigma}_2^{-1})^{-1}$$

# IV. MOMENTS

A. Mean and covariance of linear forms

First and second moments. Assume  $m{x} \sim \mathcal{N}(\mathbf{m}, m{\Sigma})$ 

$$E\langle \boldsymbol{x}\rangle = \mathbf{m} \tag{1}$$

then

$$\begin{aligned} \operatorname{Cov} \left\langle \boldsymbol{x}, \boldsymbol{x} \right\rangle &= \operatorname{Var} \left\langle \boldsymbol{x} \right\rangle \\ &= \boldsymbol{\Sigma} \\ &= \operatorname{E} \left\langle \boldsymbol{x} \boldsymbol{x}^{\mathsf{T}} \right\rangle - \operatorname{E} \left\langle \boldsymbol{x} \right\rangle \operatorname{E} \left\langle \boldsymbol{x}^{\mathsf{T}} \right\rangle \\ &= \operatorname{E} \left\langle \boldsymbol{x} \boldsymbol{x}^{\mathsf{T}} \right\rangle - \mathbf{m} \mathbf{m}^{\mathsf{T}} \end{aligned}$$

As for any other distribution is holds for gaussians that

$$\begin{split} \operatorname{E} \left\langle \mathbf{A} \boldsymbol{x} \right\rangle &= \mathbf{A} \operatorname{E} \left\langle \boldsymbol{x} \right\rangle \\ \operatorname{Var} \left\langle \mathbf{A} \boldsymbol{x} \right\rangle &= \mathbf{A} \operatorname{Var} \left\langle \boldsymbol{x} \right\rangle \mathbf{A}^{\intercal} \\ \operatorname{Cov} \left\langle \mathbf{A} \boldsymbol{x}, \mathbf{B} \mathbf{y} \right\rangle &= \mathbf{A} \operatorname{Cov} \left\langle \boldsymbol{x}, \mathbf{y} \right\rangle \mathbf{B}^{\intercal} \end{split}$$

B. Mean and variance of square forms

Mean and variance of square forms. Assume  $m{x} \sim \mathcal{N}(\mathbf{m}, m{\Sigma})$ 

$$\begin{split} \mathrm{E} \left\langle \boldsymbol{x} \boldsymbol{x}^{\mathsf{T}} \right\rangle &= \boldsymbol{\Sigma} + \mathbf{m} \mathbf{m}^{\mathsf{T}} \\ \mathrm{E} \left\langle \boldsymbol{x}^{\mathsf{T}} \mathbf{A} \boldsymbol{x} \right\rangle &= \mathrm{Tr}(\mathbf{A} \boldsymbol{\Sigma}) + \mathbf{m}^{\mathsf{T}} \mathbf{A} \mathbf{m} \\ \mathrm{Var} \left\langle \boldsymbol{x}^{\mathsf{T}} \mathbf{A} \boldsymbol{x} \right\rangle &= 2\sigma^{4} \mathrm{Tr}(\mathbf{A}^{2}) + 4\sigma^{2} \mathbf{m}^{\mathsf{T}} \mathbf{A}^{2} \mathbf{m} \\ \mathrm{Cov} \left\langle (\boldsymbol{x} - \mathbf{m}')^{\mathsf{T}} \mathbf{A} (\boldsymbol{x} - \mathbf{m}') \right\rangle &= (\boldsymbol{x} - \mathbf{m}')^{\mathsf{T}} \mathbf{A} (\boldsymbol{x} - \mathbf{m}') + \mathrm{Tr}(\mathbf{A} \boldsymbol{\Sigma}) \end{split}$$

Assume  $x \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I})$  and **A** and **B** to be symmetric, then

$$\operatorname{Cov} \langle \boldsymbol{x}^{\mathsf{T}} \mathbf{A} \boldsymbol{x}, \boldsymbol{x}^{\mathsf{T}} \mathbf{B} \boldsymbol{x} \rangle = 2\sigma^{4} \operatorname{Tr}(\mathbf{A} \mathbf{B})$$

C. Cubic forms

$$\begin{aligned} \mathrm{E} \left\langle \boldsymbol{x} \mathbf{b}^{\mathsf{T}} \boldsymbol{x} \boldsymbol{x}^{\mathsf{T}} \right\rangle &= \mathbf{m} \mathbf{b}^{\mathsf{T}} (\mathbf{M} + \mathbf{m} \mathbf{m}^{\mathsf{T}}) + (\mathbf{M} + \mathbf{m} \mathbf{m}^{\mathsf{T}}) \mathbf{b} \mathbf{m}^{\mathsf{T}} \\ &+ \mathbf{b}^{\mathsf{T}} \mathbf{m} (\mathbf{M} - \mathbf{m} \mathbf{m}^{\mathsf{T}}) \end{aligned}$$

D. Moments

$$\begin{split} & \operatorname{E} \left\langle \boldsymbol{x} \right\rangle = \sum_{k} \rho_{k} \mathbf{m}_{k} \\ & \operatorname{Cov} \left\langle \boldsymbol{x} \right\rangle = \sum_{k} \sum_{k'} \rho_{k} \rho_{k'} (\boldsymbol{\Sigma}_{k} + \mathbf{m}_{k} \mathbf{m}_{k}^{\intercal} + \mathbf{m}_{k'} \mathbf{m}_{k'}^{\intercal}) \end{split}$$

## V. WHITENING

Assume  $x \sim \mathcal{N}(\mathbf{m}, \Sigma)$ , then

$$\mathbf{z} = \mathbf{\Sigma}^{-1/2}(oldsymbol{x} - \mathbf{m}) \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

Conversely having  $x \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  one can generate data  $x \sim \mathcal{N}(\mathbf{m}, \mathbf{\Sigma})$  by setting

$$x = \Sigma^{1/2}z + m \sim \mathcal{N}(m, \Sigma)$$

Note that  $\Sigma^{1/2}$  means the matrix which fulfills  $\Sigma^{1/2}\Sigma^{1/2} = \Sigma$ , and that it exists and is unique since  $\Sigma$  is positive definite.

#### VI. CHI-SQUARE

Assume  $x \sim \mathcal{N}(\mathbf{m}, \Sigma)$  and x to be n dimensional, then

$$z = (\mathbf{x} - \mathbf{m})^{\mathsf{T}} \mathbf{\Sigma}^{-1} (\mathbf{x} - \mathbf{m}) \sim \chi_n^2$$

where  $\chi^2_n$  denotes the Chi square distribution with n degrees of freedom.

# VII. MIXTURE OF GAUSSIANS

## A. Density

The variable x is distributed as a mixture of gaussians if it has the density

$$p(\boldsymbol{x}) = \sum_{k=1}^{K} \rho_k \frac{1}{\sqrt{\det(2\pi\boldsymbol{\Sigma}_k)}} \exp\left[-\frac{1}{2}(\boldsymbol{x} - \mathbf{m}_k)^{\mathsf{T}}\boldsymbol{\Sigma}_k^{-1}(\boldsymbol{x} - \mathbf{m}_k)\right]$$

where  $\rho_k$  sum to 1 and the  $\Sigma_k$  all are positive definite.

# B. Derivatives

Defining 
$$p(s) = \sum_{k} \rho_{k} \mathcal{N}_{s}(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})$$
, then 
$$\frac{\partial \ln p(s)}{\partial \rho_{j}} = \frac{\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})}{\sum_{k} \rho_{k} \mathcal{N}_{s}(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})} \frac{\partial}{\partial \rho_{j}} \ln[\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})]$$

$$= \frac{\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})}{\sum_{k} \rho_{k} \mathcal{N}_{s}(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})} \frac{1}{\rho_{j}}$$

$$\frac{\partial \ln p(s)}{\partial \boldsymbol{\mu}_{j}} = \frac{\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})}{\sum_{k} \rho_{k} \mathcal{N}_{s}(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})} \frac{\partial}{\partial \boldsymbol{\mu}_{j}} \ln[\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})]$$

$$= \frac{\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})}{\sum_{k} \rho_{k} \mathcal{N}_{s}(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})} [-\boldsymbol{\Sigma}_{k}^{-1}(s - \boldsymbol{\mu}_{k})]$$

$$\frac{\partial \ln p(s)}{\partial \boldsymbol{\Sigma}_{j}} = \frac{\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})}{\sum_{k} \rho_{k} \mathcal{N}_{s}(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})} \frac{\partial}{\partial \boldsymbol{\Sigma}_{j}} \ln[\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})]$$

$$= \frac{\rho_{j} \mathcal{N}_{s}(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})}{\sum_{k} \rho_{k} \mathcal{N}_{s}(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})}$$

$$\frac{1}{2} [\boldsymbol{\Sigma}_{j}^{-1} + \boldsymbol{\Sigma}_{j}^{-1}(s - \boldsymbol{\mu}_{j})(s - \boldsymbol{\mu}_{j})^{T} \boldsymbol{\Sigma}_{j}^{-1}]$$

Note,  $\rho_k$  and  $\Sigma_k$  must be constrained.