

# Notes on Least Squares

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## I. LEAST SQUARES

Consider the general measurement equation

$$\mathbf{y} = \mathbf{H}\mathbf{x} + \boldsymbol{\eta} + \mathbf{e}$$

where  $\mathbf{y} \in \mathbb{R}^{m \times 1}$ ,  $\mathbf{H} \in \mathbb{R}^{m \times n}$  where  $m > n$  and  $\text{rank}(\mathbf{H}) = n$ ,  $\mathbf{x} \in \mathbb{R}^{n \times 1}$ , with Gaussian noise  $\boldsymbol{\eta} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I}) \in \mathbb{R}^{n \times 1}$ , and deterministic errors  $\mathbf{e} \sim \mathcal{N}(\boldsymbol{\mu}, \sigma^2 \mathbf{I}) \in \mathbb{R}^{n \times 1}$ .

Ignoring the noise and error vectors, the estimate of  $\mathbf{x}$  is found by

$$\begin{aligned} \mathbf{J}_{LS}(\hat{\mathbf{x}}) &= \frac{1}{2}(\mathbf{y} - \mathbf{H}\hat{\mathbf{x}})^\top (\mathbf{y} - \mathbf{H}\hat{\mathbf{x}}) \\ &= \frac{1}{2}(\mathbf{y}^\top \mathbf{y} - 2\mathbf{y}^\top \mathbf{H}\hat{\mathbf{x}} + \hat{\mathbf{x}}^\top \mathbf{H}^\top \mathbf{H}\hat{\mathbf{x}}) \\ \frac{\partial \mathbf{J}_{LS}(\hat{\mathbf{x}})}{\partial \hat{\mathbf{x}}} &= -\mathbf{H}^\top \mathbf{y} + \mathbf{H}^\top \mathbf{H}\hat{\mathbf{x}} = 0 \\ \hat{\mathbf{x}} &= (\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top \mathbf{y} \\ &= \bar{\mathbf{H}}\mathbf{y} \end{aligned}$$

where  $\bar{\mathbf{H}} \triangleq (\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top$  is the generalized inverse, also known as the “Moore-Penrose pseudo-inverse”. Note that  $\bar{\mathbf{H}}$  transforms the measurement space to the state space. If  $\mathbf{H}$  is full column-rank, then  $\mathbf{H}$  has the following property

$$\bar{\mathbf{H}}\mathbf{H} = (\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top \mathbf{H} = \mathbf{I}_m$$

This is because  $\mathbf{H}^\top \mathbf{H} \in \mathbb{R}^{m \times m}$  with  $\text{rank}(\mathbf{H}^\top \mathbf{H}) = m$ , and therefore nonsingular. Then by the linear algebra property for the general matrix  $\mathbf{A} \in \mathbb{R}^{m \times m}$  with  $\text{rank}(\mathbf{A}) = m$ , the property  $\mathbf{A}^{-1}\mathbf{A} = \mathbf{A}\mathbf{A}^{-1} = \mathbf{I}_m$  is applied in eqn. (1).

By analysis, the estimate  $\hat{\mathbf{x}}$  is

$$\begin{aligned} \hat{\mathbf{x}} &= \bar{\mathbf{H}}\mathbf{y} \\ &= \bar{\mathbf{H}}(\mathbf{H}\mathbf{x} + \boldsymbol{\eta} + \mathbf{e}) \end{aligned}$$

The estimation error is

$$\begin{aligned} \delta \mathbf{x} &= \mathbf{x} - \hat{\mathbf{x}} \\ &= \mathbf{x} - \bar{\mathbf{H}}(\mathbf{H}\mathbf{x} + \boldsymbol{\eta} + \mathbf{e}) \\ &= -\bar{\mathbf{H}}(\boldsymbol{\eta} + \mathbf{e}) \end{aligned}$$

The measurement estimate is

$$\begin{aligned} \hat{\mathbf{y}} &= \mathbf{H}\hat{\mathbf{x}} \\ &= \mathbf{H}(\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top \mathbf{y} \\ &= \mathbf{H}(\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top (\mathbf{H}\mathbf{x} + \boldsymbol{\eta} + \mathbf{e}) \\ &= \mathbf{P}\mathbf{H}\mathbf{x} + \mathbf{P}(\boldsymbol{\eta} + \mathbf{e}) \\ &= \mathbf{H}\mathbf{x} + \mathbf{P}(\boldsymbol{\eta} + \mathbf{e}) \end{aligned}$$

where the projection matrix  $\mathbf{P} \triangleq \mathbf{H}(\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top$ .

The measurement residual is

$$\begin{aligned} \mathbf{r} &= \mathbf{y} - \hat{\mathbf{y}} \\ &= (\mathbf{H}\mathbf{x} + \boldsymbol{\eta} + \mathbf{e}) - \mathbf{H}\mathbf{x} - \mathbf{H}(\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top (\boldsymbol{\eta} + \mathbf{e}) \\ &= (\mathbf{I}_m - \mathbf{H}(\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top)(\boldsymbol{\eta} + \mathbf{e}) \\ &= (\mathbf{I}_m - \mathbf{P})(\boldsymbol{\eta} + \mathbf{e}) \\ &= \mathbf{Q}(\boldsymbol{\eta} + \mathbf{e}) \\ &= \mathbf{Q}\boldsymbol{\eta} + \mathbf{Q}\mathbf{e} \end{aligned}$$

where the orthogonal projection matrix  $\mathbf{Q} \triangleq (\mathbf{I}_m - \mathbf{P})$ .

Projection matrices  $\mathbf{P}$  and  $\mathbf{Q}$  are both idempotent, and have rank  $n$  and  $m - n$  respectively. The proofs for idempotent and rank are presented in Section III.

## II. WEIGHTED LEAST SQUARES

Consider the general measurement equation

$$\mathbf{y} = \mathbf{H}\mathbf{x} + \boldsymbol{\nu}$$

where  $\mathbf{y} \in \mathbb{R}^{m \times 1}$ ,  $\mathbf{H} \in \mathbb{R}^{m \times n}$  where  $m > n$  and  $\text{rank}(\mathbf{H}) = n$ ,  $\mathbf{x} \in \mathbb{R}^{n \times 1}$ , with Gaussian noise  $\boldsymbol{\nu} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I}) \in \mathbb{R}^{n \times 1}$ .

Ignoring the noise, the estimate of  $\mathbf{x}$  is found by

$$\begin{aligned} \mathbf{J}_{WLS}(\hat{\mathbf{x}}) &= \frac{1}{2}(\mathbf{y} - \mathbf{H}\hat{\mathbf{x}})^\top \mathbf{W}(\mathbf{y} - \mathbf{H}\hat{\mathbf{x}}) \\ &= \frac{1}{2}(\mathbf{y}^\top \mathbf{W}\mathbf{y} - 2\mathbf{y}^\top \mathbf{W}\mathbf{H}\hat{\mathbf{x}} + \hat{\mathbf{x}}^\top \mathbf{H}^\top \mathbf{W}\mathbf{H}\hat{\mathbf{x}}) \\ \frac{\partial \mathbf{J}_{WLS}(\hat{\mathbf{x}})}{\partial \hat{\mathbf{x}}} &= -\mathbf{H}^\top \mathbf{W}\mathbf{y} + \mathbf{H}^\top \mathbf{W}\mathbf{H}\hat{\mathbf{x}} = 0 \\ \hat{\mathbf{x}} &= (\mathbf{H}^\top \mathbf{W}\mathbf{H})^{-1} \mathbf{H}^\top \mathbf{W}\mathbf{y} \end{aligned}$$

where  $\mathbf{W} \in \mathbb{R}^{m \times m}$  is the weighting matrix.

The estimation error is

$$\begin{aligned} \delta \mathbf{x} &= \mathbf{x} - \hat{\mathbf{x}} \\ &= \mathbf{x} - (\mathbf{H}^\top \mathbf{W}\mathbf{H})^{-1} \mathbf{H}^\top \mathbf{W}\mathbf{y} \\ &= \mathbf{x} - (\mathbf{H}^\top \mathbf{W}\mathbf{H})^{-1} \mathbf{H}^\top \mathbf{W}(\mathbf{H}\mathbf{x} + \boldsymbol{\nu}) \\ &= (\mathbf{I} - (\mathbf{H}^\top \mathbf{W}\mathbf{H})^{-1} \mathbf{H}^\top \mathbf{W}\mathbf{H}) \mathbf{x} \\ &\quad - (\mathbf{H}^\top \mathbf{W}\mathbf{H})^{-1} \mathbf{H}^\top \mathbf{W}\boldsymbol{\nu} \\ &= -(\mathbf{H}^\top \mathbf{W}\mathbf{H})^{-1} \mathbf{H}^\top \mathbf{W}\boldsymbol{\nu} \end{aligned}$$

For  $\boldsymbol{\nu} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I})$ ,  $\mathbf{W} = \mathbf{R}^{-1}$

$$\begin{aligned} \mathbb{E} \langle \delta \mathbf{x} \rangle &= \mathbf{0} \\ \text{var} \langle \delta \mathbf{x} \rangle &= (\mathbf{H}^\top \mathbf{W}\mathbf{H})^{-1} \mathbf{H}^\top \mathbf{W} \mathbf{R} \mathbf{W} \mathbf{H} (\mathbf{H}^\top \mathbf{W}\mathbf{H})^{-1} \end{aligned}$$

For  $\mathbf{W} = \mathbf{I}_m$ , the Least Squares (LS) estimate results

$$\begin{aligned} \hat{\mathbf{x}} &= (\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top \mathbf{y} \\ \mathbb{E} \langle \delta \mathbf{x} \rangle &= \mathbf{0} \\ \text{var} \langle \delta \mathbf{x} \rangle &= (\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top \mathbf{R} \mathbf{H} (\mathbf{H}^\top \mathbf{H})^{-1} \end{aligned}$$

For  $\mathbf{W} = \mathbf{R}^{-1}$ , the Maximum Likelihood Estimate (MLE) results

$$\begin{aligned}\hat{\mathbf{x}} &= (\mathbf{H}^T \mathbf{R}^{-1} \mathbf{H})^{-1} \mathbf{H}^T \mathbf{R}^{-1} \mathbf{y} \\ \mathbb{E} \langle \delta \mathbf{x} \rangle &= \mathbf{0} \\ \text{var} \langle \delta \mathbf{x} \rangle &= (\mathbf{H}^T \mathbf{R}^{-1} \mathbf{H})^{-1} \mathbf{H}^T \mathbf{R}^{-1} \mathbf{R} \mathbf{R}^{-1} \mathbf{H} (\mathbf{H}^T \mathbf{R}^{-1} \mathbf{H})^{-1} \\ &= (\mathbf{H}^T \mathbf{R}^{-1} \mathbf{H})^{-1} \\ &= \mathbf{C}\end{aligned}$$

where  $\mathbf{C}$  is the covariance matrix, and  $\mathbf{C}^{-1} = \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H}$  is the information matrix.

### III. PROOF OF MATRIX RANK USING THE SVD

#### A. Proof of idempotent $\mathbf{P}$

For the matrix  $\mathbf{P}$  to be idempotent, it must be the case that  $\mathbf{P} = \mathbf{P}^T \mathbf{P} = \mathbf{P} \mathbf{P}$ , where  $\mathbf{P} \triangleq \mathbf{H}(\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T$ , and  $\mathbf{H} \in \mathbb{R}^{m \times n}$ , with  $m > n$ . Thus we can show:

$$\begin{aligned}\mathbf{P}^T &= (\mathbf{H}(\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T)^T \\ &= \mathbf{H}(\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \\ &= \mathbf{P} \\ \mathbf{P} \mathbf{P} &= \mathbf{H}(\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \mathbf{H} (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \\ &= \mathbf{H}(\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \\ &= \mathbf{P} \\ \therefore \mathbf{P}^T \mathbf{P} &= \mathbf{P} \mathbf{P} = \mathbf{P}.\end{aligned}$$

#### B. Proof of rank $\mathbf{P}$

We can prove that  $\text{rank}(\mathbf{P}) = n$ . First recall that  $\mathbf{H} \in \mathbb{R}^{m \times n}$ , with  $m > n$  and full column rank, i.e.  $\text{rank}(\mathbf{H}) = n$ . Let the SVD of  $\mathbf{H}$  be defined as

$$\begin{aligned}\mathbf{H} &= \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T \\ &= [\mathbf{U}_1, \mathbf{U}_2] \begin{bmatrix} \mathbf{\Sigma}_1 \\ \mathbf{\Sigma}_0 \end{bmatrix} \mathbf{V}^T\end{aligned}\quad (1)$$

where  $\mathbf{\Sigma} \in \mathbb{R}^{m \times m}$ ,  $\mathbf{\Sigma}_1 = \text{diag}(\sigma_1, \dots, \sigma_n) \in \mathbb{R}^{n \times n}$ , and  $\mathbf{\Sigma}_0 = \mathbf{0} \in \mathbb{R}^{(m-n) \times n}$ , where  $\sigma_i$  for  $i = 1, \dots, n$  are the singular values of  $\mathbf{H}$ . Both  $\mathbf{U} \in \mathbb{R}^{m \times m}$  and  $\mathbf{V} \in \mathbb{R}^{n \times n}$  are unitary matrices, therefore  $\mathbf{U} \mathbf{U}^T = \mathbf{U}^T \mathbf{U} = \mathbf{I} \in \mathbb{R}^{m \times m}$  and  $\mathbf{V} \mathbf{V}^T = \mathbf{V}^T \mathbf{V} = \mathbf{I} \in \mathbb{R}^{n \times n}$ . The columns of  $\mathbf{U}_1 \in \mathbb{R}^{m \times n}$  form an orthonormal basis for the range-space of  $\mathbf{H}$ , and the columns of  $\mathbf{U}_2 \in \mathbb{R}^{m \times (m-n)}$  form the null-space of  $\mathbf{H}^T$ . Similarly the first  $n$  columns of  $\mathbf{V}$  form an orthonormal basis for the range of  $\mathbf{H}^T$ , and the  $m - n$  columns of  $\mathbf{V}$  form an orthonormal basis for the null-space of  $\mathbf{H}$ . Finally, the eigenvectors  $\mathbf{V}$  of the matrix  $\mathbf{H}^T \mathbf{H}$  are the right singular values of  $\mathbf{H}$ , and the singular values of  $\mathbf{H}$  squared are the corresponding nonzero eigenvalues:  $\sigma_i = \sqrt{\lambda_i(\mathbf{H}^T \mathbf{H})}$ . Similarly, the eigenvectors of  $\mathbf{H} \mathbf{H}^T$  are the left singular vectors  $\mathbf{U}$  of matrix  $\mathbf{H}$ , and the singular values of  $\mathbf{H}$  squared are the nonzero eigenvalues of  $\mathbf{H} \mathbf{H}^T$ :  $\sigma_i = \sqrt{\lambda_i(\mathbf{H} \mathbf{H}^T)}$ .

Define  $\mathbf{P}$  in terms of the SVD of  $\mathbf{H}$ :

$$\begin{aligned}\mathbf{P} &= \mathbf{H}(\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \\ &= (\mathbf{U} \mathbf{\Sigma} \mathbf{V}^T)(\mathbf{V} \mathbf{\Sigma}^T \mathbf{U}^T \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T)^{-1} (\mathbf{V} \mathbf{\Sigma}^T \mathbf{U}^T) \\ &= (\mathbf{U} \mathbf{\Sigma} \mathbf{V}^T)(\mathbf{V} \mathbf{\Sigma}^T \mathbf{\Sigma} \mathbf{V}^T)^{-1} (\mathbf{V} \mathbf{\Sigma}^T \mathbf{U}^T) \\ &= (\mathbf{U} \mathbf{\Sigma} \mathbf{V}^T)(\mathbf{V} \mathbf{\Sigma}_1^2 \mathbf{V}^T)^{-1} (\mathbf{V} \mathbf{\Sigma}^T \mathbf{U}^T) \quad (2) \\ &= (\mathbf{U} \mathbf{\Sigma} \mathbf{V}^T)(\mathbf{V})^{-1} (\mathbf{\Sigma}_1^2)^{-1} (\mathbf{V}^T)^{-1} (\mathbf{V} \mathbf{\Sigma}^T \mathbf{U}^T) \quad (3) \\ &= \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T \mathbf{V} \mathbf{\Sigma}_1^{-2} \mathbf{V}^T \mathbf{V} \mathbf{\Sigma}^T \mathbf{U}^T \quad (4) \\ &= \mathbf{U} \mathbf{\Sigma}_1 \mathbf{\Sigma}_1^{-2} \mathbf{\Sigma}_1^T \mathbf{U}^T \quad (5) \\ &= \mathbf{U} \mathbf{\Sigma}_1 \mathbf{\Sigma}_1^{-1} \mathbf{\Sigma}_1^{-1} \mathbf{\Sigma}_1^T \mathbf{U}^T \quad (6) \\ &= \mathbf{U} \mathbf{I}_{n \times n} \mathbf{U}^T \\ &= [\mathbf{U}_1 \mathbf{U}_2] \begin{bmatrix} \mathbf{I}_{n \times n} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{U}_1^T \\ \mathbf{U}_2^T \end{bmatrix} \\ &= \mathbf{U}_1 \mathbf{U}_1^T.\end{aligned}$$

The middle product in eqn. (2) can be separated because it is an  $n \times n$  matrix with rank  $n$ , and it is non-singular. In eqns. (2)-(6), we need only consider  $\mathbf{\Sigma}_1$  as  $\mathbf{\Sigma}_0$  drops out.

The rank of matrix  $\mathbf{P}$  is defined as the number of non-zero singular values of  $\mathbf{P}$ . Thus,  $\text{rank}(\mathbf{P}) = n$ . Similarly, because  $\mathbf{P}$  is idempotent,  $\text{rank}(\mathbf{P}) = \text{tr}(\mathbf{P})$ , then  $\text{rank}(\mathbf{P}) = n$ . ■

#### C. Proof of idempotent $\mathbf{Q}$

For the matrix  $\mathbf{Q}$  to be idempotent, it must be the case that  $\mathbf{Q} = \mathbf{Q}^T \mathbf{Q} = \mathbf{Q} \mathbf{Q}$ , where  $\mathbf{Q} \triangleq (\mathbf{I} - \mathbf{P})$ , and  $\mathbf{P} \in \mathbb{R}^{m \times m}$ . Thus we can show:

$$\begin{aligned}\mathbf{Q} \mathbf{Q} &= (\mathbf{I} - \mathbf{P})(\mathbf{I} - \mathbf{P}) \\ &= \mathbf{I} - \mathbf{P} \\ &= \mathbf{Q} \\ \mathbf{Q}^T \mathbf{Q} &= (\mathbf{I} - \mathbf{P})^T (\mathbf{I} - \mathbf{P}) \\ &= (\mathbf{I} - \mathbf{P}^T)(\mathbf{I} - \mathbf{P}) \\ &= \mathbf{I} - \mathbf{P} - \mathbf{P}^T + \mathbf{P}^T \mathbf{P}, \quad \mathbf{P} = \mathbf{P}^T \mathbf{P} \\ &= \mathbf{I} - \mathbf{P} - \mathbf{P}^T + \mathbf{P}, \quad \mathbf{P}^T = \mathbf{P} \\ &= \mathbf{I} - \mathbf{P} \\ &= \mathbf{Q} \\ \therefore \mathbf{Q}^T \mathbf{Q} &= \mathbf{Q} \mathbf{Q} = \mathbf{Q}\end{aligned}$$

#### D. Proof of rank $\mathbf{Q}$

We can prove that  $\text{rank}(\mathbf{Q}) = m - n$  by the SVD of  $\mathbf{H}$ . Apply the result from the proof for the rank of  $\mathbf{P}$ , where  $\mathbf{P} \in \mathbb{R}^{m \times m}$  and  $\mathbf{I} \in \mathbb{R}^{m \times m}$ . Using the inner product we can define  $\mathbf{I}$  in terms of  $\mathbf{U}$

$$\begin{aligned}\mathbf{I} &= \mathbf{U} \mathbf{U}^T \\ &= [\mathbf{U}_1 \mathbf{U}_2] \begin{bmatrix} \mathbf{U}_1^T \\ \mathbf{U}_2^T \end{bmatrix} \\ &= \mathbf{U}_1 \mathbf{U}_1^T + \mathbf{U}_2 \mathbf{U}_2^T.\end{aligned}$$

Alternatively, by the outer product we can define

$$\begin{aligned}\mathbf{I} &= \mathbf{U}^\top \mathbf{U} \\ &= \begin{bmatrix} \mathbf{U}_1^\top \\ \mathbf{U}_2^\top \end{bmatrix} [\mathbf{U}_1 \mathbf{U}_2] \\ &= \begin{bmatrix} \mathbf{U}_1^\top \mathbf{U}_1 & \mathbf{U}_1^\top \mathbf{U}_2 \\ \mathbf{U}_2^\top \mathbf{U}_1 & \mathbf{U}_2^\top \mathbf{U}_2 \end{bmatrix}\end{aligned}$$

where  $\mathbf{U}_1^\top \mathbf{U}_1 = \mathbf{I} \in \mathbb{R}^{n \times n}$ ,  $\mathbf{U}_2^\top \mathbf{U}_2 = \mathbf{I} \in \mathbb{R}^{(m-n) \times (m-n)}$ . Finally,  $\mathbf{U}_2 \mathbf{U}_2^\top = \mathbf{P} \in \mathbb{R}^{m \times m}$  as proved above, and  $\mathbf{U}_1 \mathbf{U}_1^\top = \mathbf{Q} \in \mathbb{R}^{m \times m}$  which is proven below.

Now define  $\mathbf{Q}$  as

$$\begin{aligned}\mathbf{Q} &= \mathbf{I} - \mathbf{P} \\ &= (\mathbf{U}_1 \mathbf{U}_1^\top + \mathbf{U}_2 \mathbf{U}_2^\top) - \mathbf{U}_1 \mathbf{U}_1^\top \\ &= \mathbf{U}_2 \mathbf{U}_2^\top.\end{aligned}$$

The rank of matrix  $\mathbf{Q}$  is defined as the number of non-zero singular values of  $\mathbf{Q}$ . Thus, for  $\mathbf{Q} \triangleq (\mathbf{I} - \mathbf{P})$ , and  $\text{rank}(\mathbf{P}) = n$ , the number of non-zero singular values of  $\mathbf{Q}$  is at most  $m - n$ , and therefore the  $\text{rank}(\mathbf{Q}) = m - n$ . ■

#### E. Physical Interpretation of $\mathbf{P}$ & $\mathbf{Q}$

The physical interpretation for  $\mathbf{P}$  and  $\mathbf{Q}$  is a mapping of the measurement and the residual, as shown in Fig. 1.  $\mathbf{P}\mathbf{y}$  projects  $\mathbf{y}$  onto the  $\text{range}(\mathbf{P})$  along the direction of  $\mathbf{y}$ . The

complementary projector is  $\mathbf{Q}$ , where  $\mathbf{Q}\mathbf{y}$  projects  $\mathbf{y}$  onto the  $\text{range}(\mathbf{Q})$  which is orthogonal to the  $\text{range}(\mathbf{P})$ .

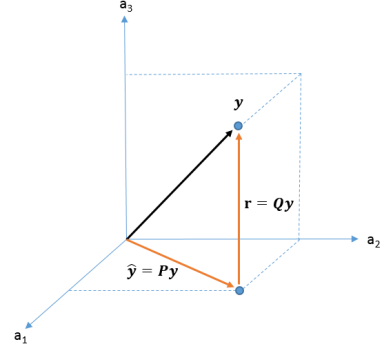


Fig. 1. For a general space in  $\mathbb{R}^3$ , the mapping  $\mathbf{P}\mathbf{y} = \hat{\mathbf{y}}$  is the estimate for  $\mathbf{y}$ , and  $\mathbf{Q}\mathbf{y} = \mathbf{r}$  is the estimation residual for  $\mathbf{y}$ .

From the SVD of  $\mathbf{H}$  we have the relations:

- 1)  $\mathbf{V}_1 \mathbf{V}_1^\top$  is the orthogonal projector onto  $[N(\mathbf{H})]^\perp = R(\mathbf{H}^\top)$ .
- 2)  $\mathbf{V}_2 \mathbf{V}_2^\top$  is the orthogonal projector onto  $N(\mathbf{H})$ .
- 3)  $\mathbf{U}_1 \mathbf{U}_1^\top$  is the orthogonal projector onto  $R(\mathbf{H})$ .
- 4)  $\mathbf{U}_2 \mathbf{U}_2^\top$  is the orthogonal projector onto  $[R(\mathbf{H})]^\perp = N(\mathbf{H}^\top)$ .