DM865 – Heuristics (Marco) & Approximation Algorithms (Lere)

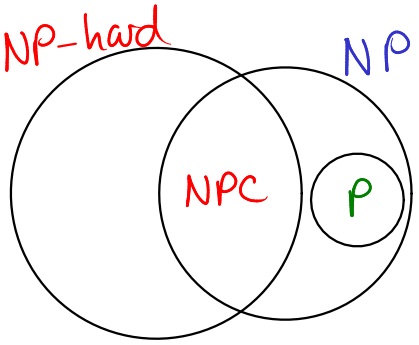
Cambinatorial problems:

First 2 weeks → Traveling Salesman (TSP)
MAX SAT
Set Cave
Knapsack
Bin packing
Scheduling

} decision version ∈ NPC

Polynomial algorithm:

algo. with running time $O(n^c)$, for some constant c.



P: The set of decision problems that allow for a poly. algo.

NP: A problem belongs to NP, if solutions can be verified in poly. time.

If <u>any</u> NP-hard problem has a poly. algo., then <u>all</u> problems in NPC have poly. algo.s.

<u>Optimal solutions</u> <u>in poly. time</u> <u>for all instances</u>

(1) (2) (3)

- Choose two! ((2) & (3))

Section 1.1

An approximation algorithm comes with a performance guarantee:

Def 1.1: α-approximation algorithm

An α-approximation algorithm for an optimization problem P is a poly. time algo. ALG s.t. for any instance I of P,

- $\frac{ALG(I)}{OPT(I)} \leq \alpha$, if P is a minimization problem
- $\frac{ALG(I)}{OPT(I)} \geq \alpha$, if P is a maximization problem

Thus, for max. problems, $0 \leq \alpha \leq 1$, and, for min. problems, $\alpha \geq 1$.

The approximation factor / approximation ratio is
- the smallest possible α (for min. problems)
- the largest possible α (for max. problems)

More precisely, the approx. factor R is

$$R = \inf\left\{\alpha \;\middle|\; \forall I : \frac{ALG(I)}{OPT(I)} \leq \alpha\right\} \text{ for min. problems}$$

$$R = \sup\left\{\alpha \;\middle|\; \forall I : \frac{ALG(I)}{OPT(I)} \geq \alpha\right\} \text{ for max. problems}$$

We will cover the rest of Section 1.1 later.

Section 2.4: TSP

The Traveling Salesman Problem (TSP)

Input: Weighted complete graph G

$c_{ij} = c_{ji}$, $i, j \in V$

$c_{ii} = 0$, $i \in V$

$c_{ij} \geq 0$, $i, j \in V$

Output: Hamiltonian cycle of min. total weight

Cycle visiting each vertex exactly once.

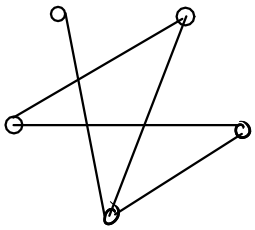
Decision version of TSP:

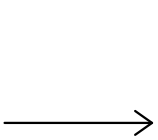
Does there exist a tour of cost $\leq X$?

Decision version of TSP is NP-hard

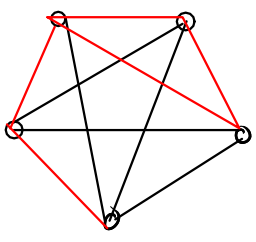
Reduction from Hamilton Cycle:

Ham. cycle





TSP



$c_{ij} = 1$

$c_{ij} = 2$

$\exists$ ham. cycle $\iff$ $\exists$ tour of cost n

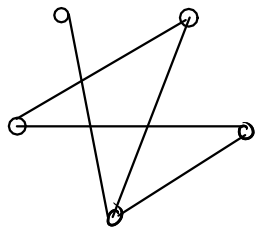
Even worse, no approximation guarantee possible:

Theorem 2.9

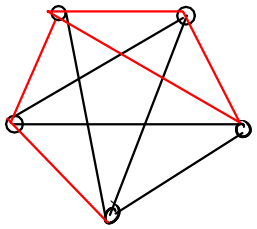
$\forall \alpha > 1$, $\nexists$ α-approx alg. for TSP (unless P = NP)

Proof: Reduction from Hamilton Cycle:

Ham. cycle



TSP



$c_{ij} = 1$

$c_{ij} = \alpha n + 1$

$\exists$ ham. cycle $\iff$ $\exists$ tour of cost n

$\iff$ α-approx. alg. gives tour of cost $\leq \alpha n$

$\iff$ α-approx. alg. returns a tour with no red edges, i.e., a tour of cost n.

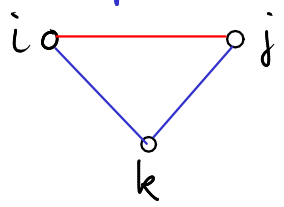
□

Note: The proof does not require α to be a constant. In fact, it could be 2^n, or <u>any</u> function computable in poly. time.

Metric TSP:

The edge weights satisfy the triangle inequality:

$$c_{ij} \leq c_{ik} + c_{kj}, \text{ for all } i, j, k \in V$$



For metric TSP, the proof of Thm 2.9 does not work (the max. possible cost of the red edges would be 2).

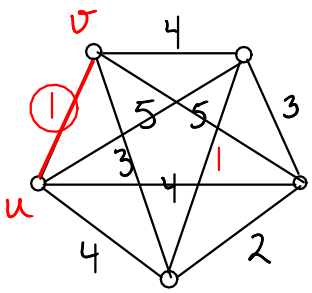
For the metric TSP problem, we will consider three algorithms:

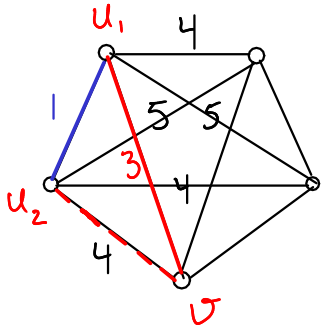
The Nearest Addition algorithm	2-approx.
The Double Tree algorithm	2-approx.
Christofide's Algorithm	3/2-approx

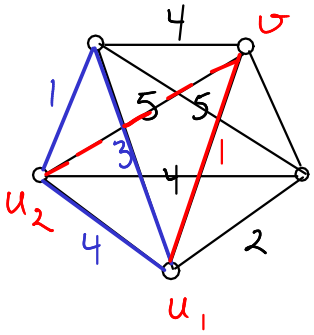
Nearest Addition (NA)

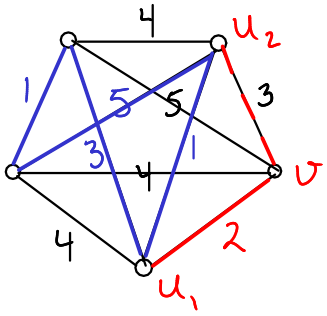
$u, v \leftarrow$ two nearest neighbors in V
Tour $\leftarrow \langle u, v, u \rangle$
For $i \leftarrow 1$ to $n-2$
  $v \leftarrow$ nearest neighbor of Tour
  $u_1 \leftarrow$ nearest neighbor of v in Tour
  $u_2 \leftarrow u_1$'s successor in Tour
  Add v to Tour between u_1 and u_2

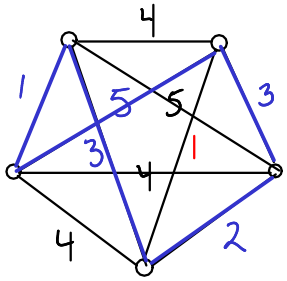
Ex:



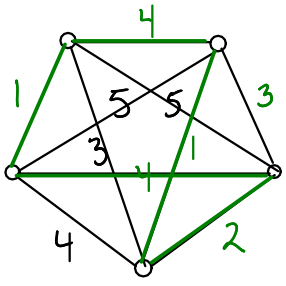








$C_{NA} = 1 + 3 + 2 + 3 + 5$
$= 14$



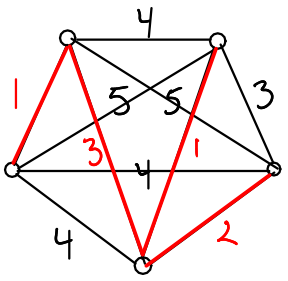
$C_{OPT} \leq 1 + 4 + 1 + 2 + 4 = 12$

Nearest Neighbor is a 2-approx. alg.:
We will prove that

(1) $C_{NA} \leq 2 \cdot c(MST)$

(2) $c(MST) \leq C_{OPT}$ (Lemma 2.10)

(1): The solid red edges are exactly those chosen by Prim's Algorithm:

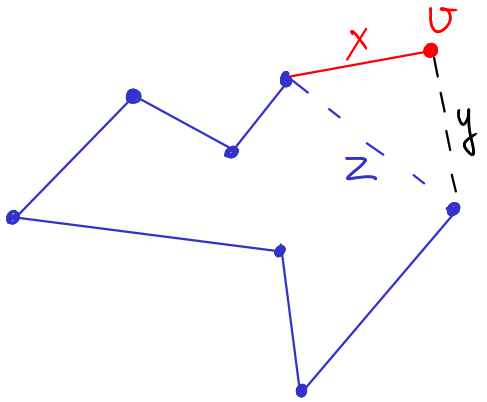


$C = 1+3+1+2 = 7$

Thus, the total cost C of these edges is that of a minimum spanning tree:

$C = c(MST)$

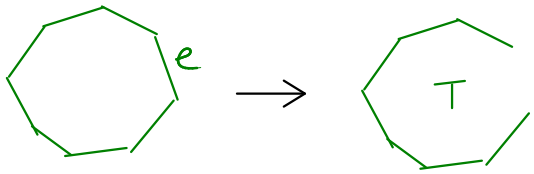
Adding a new vertex v to the tour, we add two edges and delete one:



By the Δ-ineq., $y \le x+z$
Hence, adding v costs
$x + y - z \le x + (x+z) - z = 2x$
Thus,

$$\boxed{c_{NA} \le 2C = 2c(MST)}$$

(2): Deleting any edge from a tour, we get a spanning tree:



For any spanning tree T obtained by deleting an edge e from an optimal tour,

$$\boxed{c_{OPT} \ge c(T)}, \quad \text{since } w(e) \ge 0$$
$$\ge \boxed{c(MST)}$$

Now, (1) & (2) $\Rightarrow$ $c_{NA} \le 2\,c(MST) \le 2\,c_{OPT}$

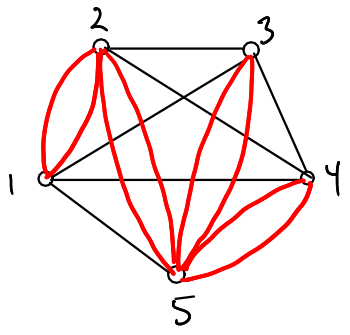
This proves:

Theorem 2.11

Nearest Addition is a 2-approx. alg.

Double Tree algorithm

Noting that NA adds the edges of a MST one by one, we could also make a MST T and traverse T, making short cuts whenever we would otherwise visit a node for the second time:

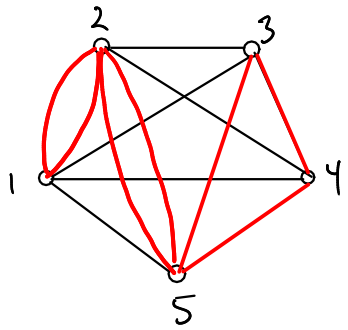


By the triangle inequality, this distance is no longer

$\langle 1, 2, 5, 3, \cancel{5}, 4, 5, 2, 1 \rangle$

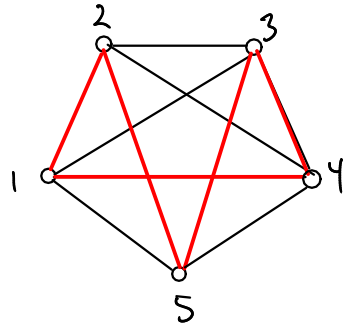
than this total distance

↓ shortcut 5



$\langle 1, 2, 5, 3, 4, 5, 2, 1 \rangle$

↓ shortcut 2 and 5 (using Δ-ineq. twice)



$\langle 1, 2, 5, 3, 4, 1 \rangle$

An Euler tour is a traversal of a graph that traverses each edge exactly once.

A graph that has an Euler tour is called eulerian.

A graph is eulerian if and only if all vertices have even degree.
Constructive proof of "if" in exercises for Thursday.

Double Tree Algorithm (DT)

```
T ← MST
DT ← T with all edges doubled
Etour ← Euler tour in DT
Tour ← vertices in order of first appearance in ETour
```

Same analysis as for NA:

$$c_{DT} \leq 2\, c(MST) \leq 2 \cdot c_{OPT}$$

Hence:

Theorem 2.12

Double Tree is a 2-approx. alg

Last time:

P: poly. time solvable
NP: poly. time checkable certificates
NP-hard: "at least as hard" as any NPC-problem
NPC: If any problem in NPC is in P, they all are.

TSP: complete graph, symm. weights, $w_{ii} = 0$, $w \geq 0$

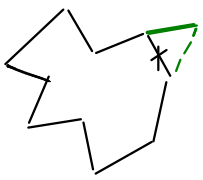
Metric weights: + Δ-ineq.

TSP inapproximable (Thm 2.9)

Metric TSP:

Nearest Addition
Double Tree
} 2-approx.

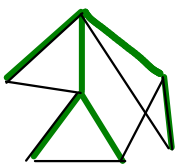
NA:

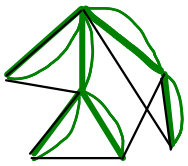


Tight:

MST OPT DT

DT:

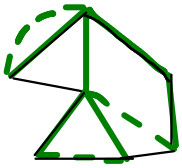




$$c_{DT} \leq 2 \cdot c(MST)$$
$$c(MST) \leq c_{OPT}$$

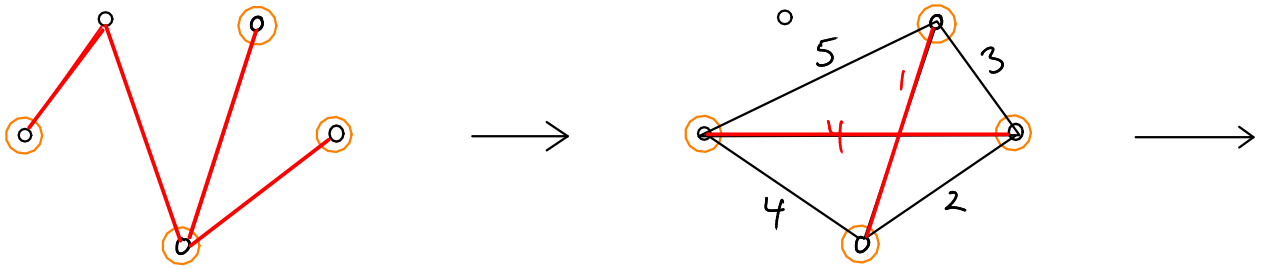
by Δ-ineq.
since a ST can be created by deleting an edge from OPT.

Christofide's Alg:



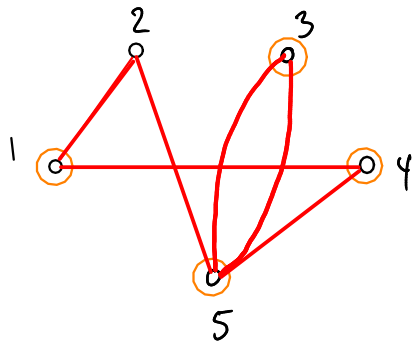
Christofide's Algorithm

Next idea: Not necessary to add n-1 edges to obtain even degree for all vertices
Instead: add a minimum perfect matching on vertices of odd degree in the MST.



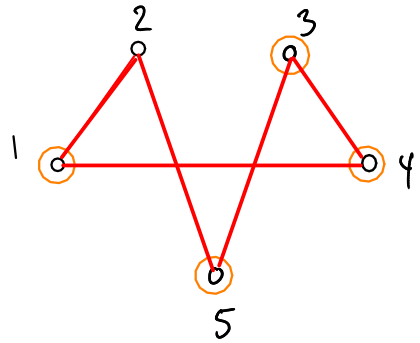
MST
Odd degree

Min. matching



Euler tour : $\langle 1,2,5,3,5,4,1 \rangle$

short cutting



TSP tour : $\langle 1,2,5,3,4,1 \rangle$

Note that it is always possible to find a perfect matching, since there is always an even # odd degree vertices in T.

Christofide's Algorithm (CA)

$T \leftarrow$ MST

$M \leftarrow$ minimum perfect matching on odd degree vertices in T

$ETour \leftarrow$ Euler tour in the subgraph $(V, E(T) \cup M)$

$Tour \leftarrow$ vertices in order of first appearance in $ETour$

Theorem 2.13

Christofide's Algorithm is a $\frac{3}{2}$-approx. alg.

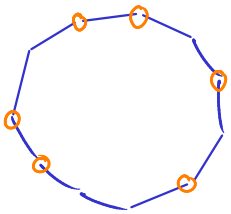
Proof:

By the triangle inequality,

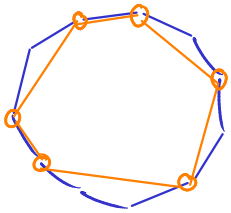
$c_{CA} \leq c(T) + c(M)$, where

$c(T) \leq c_{OPT}$, by the arguments above, and

$c(M) \leq \frac{1}{2} c_{OPT}$, by the arguments below.



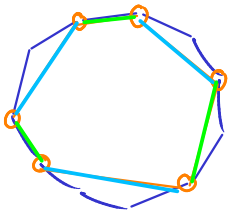
shortcutting →



Optimal TSP tour
Odd degree vertices in T

C: cost of orange cycle
$C \le c_{OPT}$, by $\triangle$-ineq.

Since the cycle on the odd degree vertices has an even #edges, it consists of two perfect matchings:



$$C = C + C$$

$$\Downarrow$$

$$\min\{C, C\} \le \frac{1}{2} \cdot C \le \frac{1}{2} \cdot c_{OPT}$$

Since M is a <u>minimum</u> matching on the odd degree vertices,

$$c(M) \le \min\{C, C\} \le \frac{1}{2} \cdot c_{OPT}$$

□

No alg. with an approx. ratio better than $3/2$ is currently known. Moreover:

Theorem 2.14

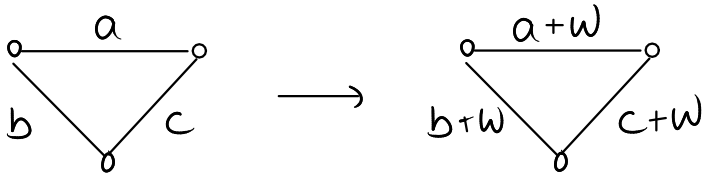
For $\alpha < \frac{220}{219}$, $\nexists$ α-approx. alg. for Metric TSP

The result of Thm 2.14 is from 2000.
In 2015, the same result was proven for $\alpha < \frac{185}{184}$.

Sheet 1

1. a) Add $W = \max_{e \in E} \{w_e\}$ to all edge weights.

The resulting weights are metric:



$$a+W \leq 2W \leq (b+W)+(c+W)$$

b) For any tour T

T optimal in G $\Leftrightarrow$ T optimal in G'

For any tour T in G, let w(T) be the total weight of T in G and let w'(T) be the total weight of T with the modified weights.

Then $w'(T) = w(T) + nW$

only this part can vary

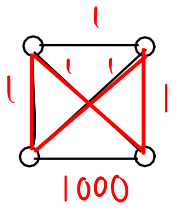
This part is the same for any tour

Hence, w' is minimized when w is minimized

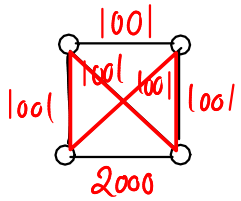
c) Contradiction with inapproximability?

The reduction to the metric case is not approx. factor preserving.

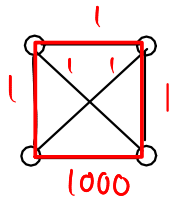
Ex:



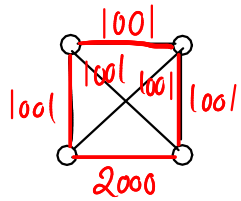
$W = 4$



$W = 4004$



$W = 1003$



$W = 5003$

ratio ≈ 250

ratio $\approx 5/4$

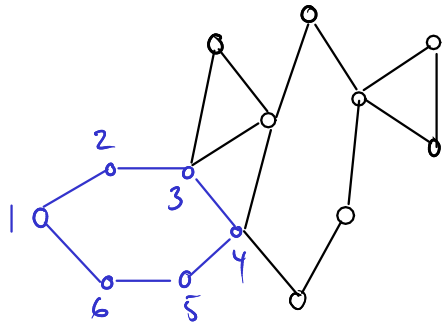
(2.) Argue that metric TSP is NP-hard.

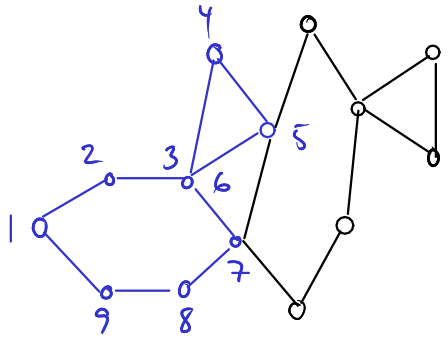
The graph used in the reduction just before Thm 2.9 in the lecture notes is metric.

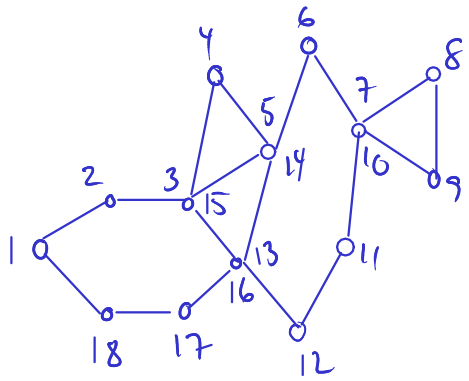
(3.) Alg. for Euler tour in connected graph

V ← any vertex in the graph
Follow non-traversed edges, starting in V, until reaching a vertex with no non-traversed edges
While ∃ non-traversed edges
    V ← vertex with both traversed and non-traversed edges
    Follow non-traversed edges, starting in V, until reaching a vertex with no non-traversed edges

Ex:







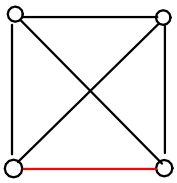
Correctness:

When reaching a vertex with no non-traversed edges, the vertex has an even #traversed edges. This can only be v, so we have produced a tour.

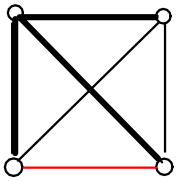
Since the graph is connected, there must be a non-traversed edge leaving the tour, if there are still non-traversed edges.

(4) Christofide's vs Double Tree

a) Example where C. does better than D.T.

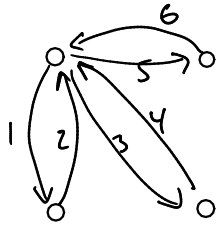


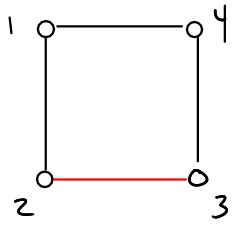
Black edges have weight 1.
Red edge has weight 2.



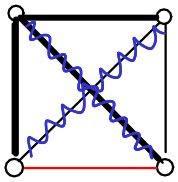
Thick edges: MST

Double Tree:

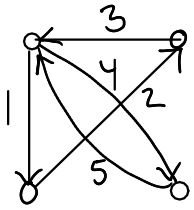


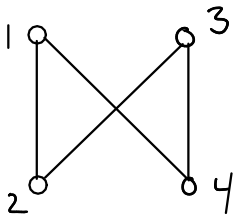


Christofide's:



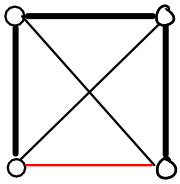
≈: minimum matching



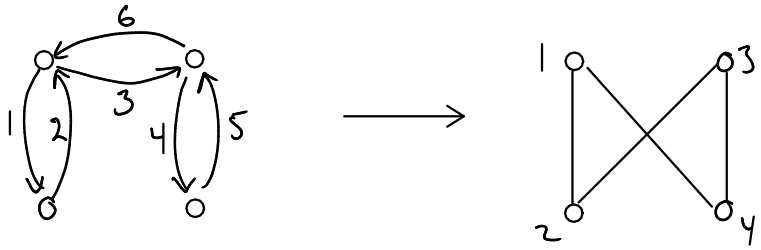


b) Example where D.T. does better than C.

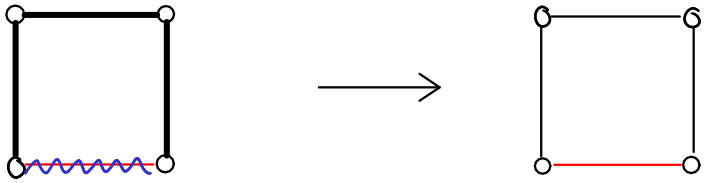
Same graph, different MST:



Double Tree:



Christofide's:



c) How many nodes are needed?

4 suffice

3 are two few, since that gives only one possible tour.

Chapter 5: Maximum Satisfiability

SAT: For a given boolean formula φ in CNF, does there exist a truth assignment satisfying φ?

Conjunctive normal form (CNF): the formula is a conjunction ($\wedge$) of disjunctions ($\vee$). Each disjunction is called a **clause**.

Ex: $\varphi \equiv \underbrace{(x_1 \vee \overline{x}_2 \vee x_3)}_{\text{clause } C_1} \wedge \underbrace{\overline{x}_3}_{C_2} \wedge \underbrace{(x_1 \vee x_2)}_{C_3}$

positive literal: x_1, x_3; negative literal: $\overline{x}_2$

x_1, x_2, x_3 are variables

C_j has length / size ℓ_j:

$\ell_1 = 3$, $\ell_2 = 1$, $\ell_3 = 2$

$x_1 \leftarrow \top$, $x_3 \leftarrow F$ will satisfy φ

MAX SAT

Input: Boolean formula φ in CNF with variables $x_1, x_2, \ldots, x_n$ and clauses $C_1, C_2, \ldots, C_m$
Each clause, C_j, has a weight w_j

Output: Truth assignment maximizing the total weight of satisfied clauses

Ex: $(x_1 \vee \bar{x}_2) \wedge x_3 \wedge (x_2 \vee \bar{x}_3) \wedge (\bar{x}_1 \vee \bar{x}_2 \vee \bar{x}_3)$

$w_1 = 2 \quad w_2 = 2 \quad w_3 = 1 \quad w_4 = 3$

$x_1 \leftarrow T$, $x_2 \leftarrow F$, $x_3 \leftarrow T$ satisfies C_1, C_2, C_4 with a total weight of 7.

This is optimal, since we cannot satisfy all clauses:

C_2 requires $x_3 \leftarrow T$
C_3 then requires $x_2 \leftarrow T$
C_1 then requires $x_1 \leftarrow T$
But then C_4 is false.

SAT, and hence, MAX SAT, is NP-hard.
How can we approximate?

Section 5.1: A simple randomized alg.

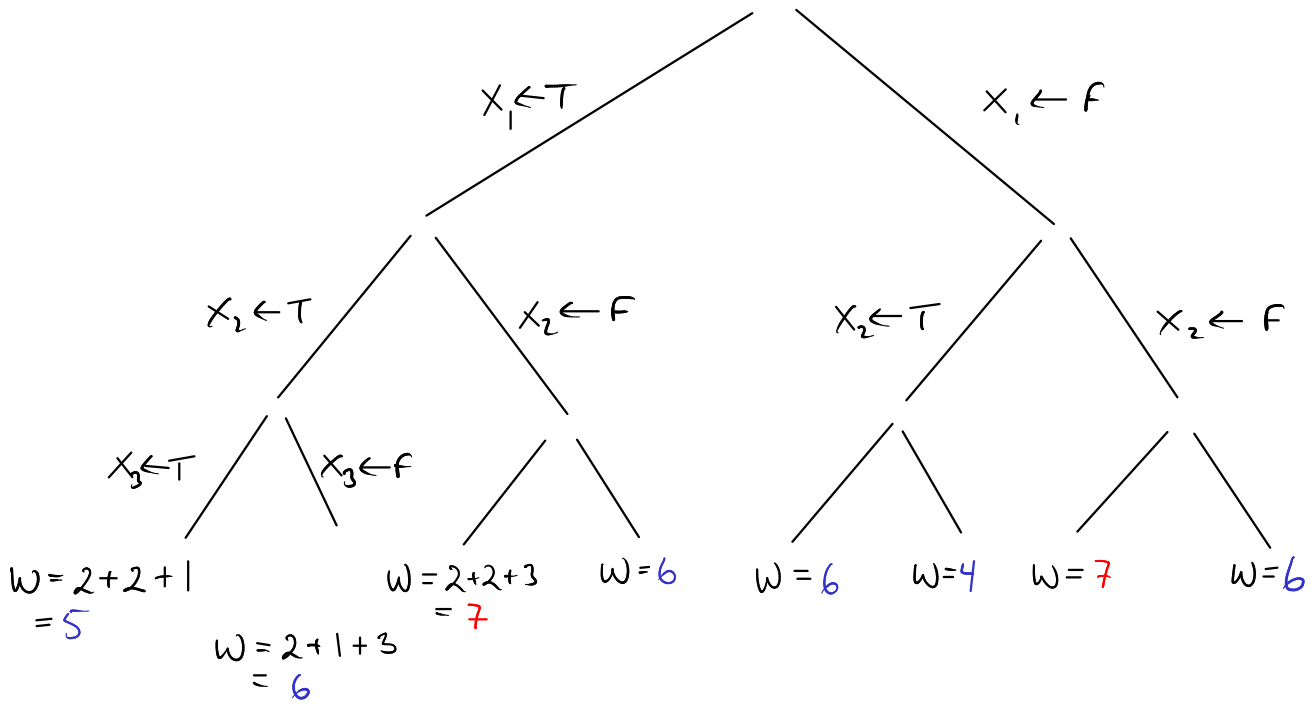
Consider the following alg:

Rand

For $i \leftarrow 1$ to n
    With prob. $\frac{1}{2}$ set x_i true

This corresponds to choosing a solution uniformly at random.

Ex: $(x_1 \vee \overline{x}_2) \wedge x_3 \wedge (x_2 \vee \overline{x}_3) \wedge (\overline{x}_1 \vee \overline{x}_2 \vee \overline{x}_3)$



Thus, for this example,

$$E[\text{Rand}] = \frac{1}{8}(5+6+7+6+6+4+7+6) = 5\frac{7}{8}$$

We don't need to calculate the weight of each possible output...

Instead, we can calculate the exp. weight of each clause:

$$(X_1 \vee \overline{X}_2) \wedge X_3 \wedge (X_2 \vee \overline{X}_3) \wedge (\overline{X}_1 \vee \overline{X}_2 \vee \overline{X}_3)$$

- $(X_1 \vee \overline{X}_2)$: satisfied, unless $X_1 \equiv F$ and $X_2 \equiv T$, i.e., satisfied with prob. $1 - \frac{1}{2} \cdot \frac{1}{2} = \frac{3}{4}$
- X_3: satisfied w. prob. $1 - \frac{1}{2} = \frac{1}{2}$
- $(X_2 \vee \overline{X}_3)$: satisfied w. prob. $\frac{3}{4}$
- $(\overline{X}_1 \vee \overline{X}_2 \vee \overline{X}_3)$: satisfied w. prob. $1 - \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2} = \frac{7}{8}$

Thus,

$$E[\text{Rand}] = \frac{3}{4} \cdot 2 + \frac{1}{2} \cdot 2 + \frac{3}{4} \cdot 1 + \frac{7}{8} \cdot 3 = 5\frac{7}{8}$$

In general, clause C_j is satisfied with prob. $1 - (\frac{1}{2})^{\ell_j}$.

We let $W = \sum_{j=1}^{m} w_j$.

Theorem 5.1: Rand is a $\frac{1}{2}$-approx. alg

Proof:

$OPT \leq W$

By linearity of expectation:

$$E[\text{Rand}] = \sum_{j=1}^{m} \left(1 - \left(\tfrac{1}{2}\right)^{\ell_j}\right) w_j$$

$$\geq \tfrac{1}{2} W \quad , \text{ since } \ell_j \geq 1$$

□

In Section 5.1 we got a simple algorithm with a guarantee on the expected performance. We can turn it into a guarantee on the worst-case performance:

Section 5.2: Derandomization

Ex from before:

$\phi: (x_1 \vee \bar{x}_2) \wedge x_3 \wedge (x_2 \vee \bar{x}_3) \wedge (\bar{x}_1 \vee \bar{x}_2 \vee \bar{x}_3)$

$w_1 = 2 \quad w_2 = 2 \quad w_3 = 1 \quad w_4 = 3$

If we let $x_1 \leftarrow T$, the formula becomes

$\phi_T: \top \wedge x_3 \wedge (x_2 \vee \bar{x}_3) \wedge (\bar{x}_2 \vee \bar{x}_3)$

and

$E[\text{Rand}(\phi_T)] = 2 + \frac{1}{2}\cdot 2 + \frac{3}{4}\cdot 1 + \frac{3}{4}\cdot 3 = 6$

Or, recalling the probability tree,

$E[\text{Rand}(\phi_T)] = \frac{1}{4}(5+6+7+6) = 6$

Similarly, if we let $x_1 \leftarrow F$, the formula becomes

$\phi_F: \bar{x}_2 \wedge x_3 \wedge (x_2 \vee \bar{x}_3) \wedge \top$

and

$E[\text{Rand}(\phi_F)] = \frac{1}{2}\cdot 2 + \frac{1}{2}\cdot 2 + \frac{3}{4}\cdot 1 + 3 = 5\frac{3}{4}$

Or $E[\text{Rand}(\phi_F)] = \frac{1}{4}(6+4+7+6) = 5\frac{3}{4}$

Note that $E[\text{Rand}]$ is the average of 6 and $5\frac{3}{4}$:

$E[\text{Rand}] = \frac{1}{2}\cdot E[\text{Rand}(\phi_T)] + \frac{1}{2}\cdot E[\text{Rand}(\phi_F)]$

Thus,

$\max\{E[\text{Rand}(\phi_T)], E[\text{Rand}(\phi_F)]\} \geq E[\text{Rand}]$

I.e., one of the leaves in the left part of the probability tree must have an exp. value of ≥ 6.

ϕ: $(X_1 \vee \bar{X}_2) \wedge X_3 \wedge (X_2 \vee \bar{X}_3) \wedge (\bar{X}_1 \vee \bar{X}_2 \vee \bar{X}_3)$

$E[\text{Rand}(\phi)] = 5\frac{7}{8}$

$X_1 \leftarrow T$ | $X_1 \leftarrow F$

ϕ_T: $T \wedge X_3 \wedge (X_2 \vee \bar{X}_3) \wedge (\bar{X}_2 \vee \bar{X}_3)$

$E[\text{Rand}(\phi_T)] = 6$

ϕ_F: $\bar{X}_2 \wedge X_3 \wedge (X_2 \vee \bar{X}_3) \wedge T$

$E[\text{Rand}(\phi_F)] = 5\frac{3}{4}$

$X_2 \leftarrow T$ | $X_2 \leftarrow F$

ϕ_{TT}: $T \wedge X_3 \wedge T \wedge \bar{X}_3$

$E[\text{Rand}(\phi_{TT})] = 5\frac{1}{2}$

ϕ_{TF}: $T \wedge X_3 \wedge \bar{X}_3 \wedge T$

$E[\text{Rand}(\phi_{TF})] = 6\frac{1}{2}$

$X_3 \leftarrow T$ | $X_3 \leftarrow F$

ϕ_{TFT}: $T \wedge T \wedge F \wedge T$

$\text{Rand}(\phi_{TFT}) = 7$

ϕ_{TFF}: $T \wedge F \wedge T \wedge T$

$\text{Rand}(\phi_{TFF}) = 6$

In general:

$$\max\{E[\text{Rand}(\phi_T)], E[\text{Rand}(\phi_F)]\} \geq E[\text{Rand}] \geq \tfrac{1}{2}W,$$

The same is true for ϕ_T and ϕ_F:

$$\max\{E[\text{Rand}(\phi_{TT})], E[\text{Rand}(\phi_{TF})]\} \geq E[\text{Rand}(\phi_T)]$$

and

$$\max\{E[\text{Rand}(\phi_{FT})], E[\text{Rand}(\phi_{FF})]\} \geq E[\text{Rand}(\phi_F)]$$

Inductively, this proves that the following alg. is a $\frac{1}{2}$-approx. alg.:

DeRand(ϕ)

For $i \leftarrow 1$ to n

  If $E[\text{Rand}(\phi_{x_1 \cdots x_{i-1} T})] \geq E[\text{Rand}(\phi_{x_1 \cdots x_{i-1} F})]$

    $x_i \leftarrow T$

  Else

    $x_i \leftarrow F$

This method of derandomization is sometimes called the method of conditional expectations. (We calculate the conditional exp. of Rand given that $x_i \leftarrow T$ and given that $x_i \leftarrow F$.)

Note that short clauses are „harder" than long clauses:

If all clauses have $\ell \geq 2$, (DE)Rand is a $3/4$-approx. alg.
(In Section 5.3, we will pursue the obs. to obtain a ≈ 0.6-approx. alg.)

If all clauses have $\ell \geq 3$, (DE)Rand is a $7/8$-approx alg.

In some sense, this is optimal:

MAX E3SAT: The special case of MAX SAT where $\ell = 3$ for all clauses.

Theorem 5.2:

$\exists \varepsilon > 0 : \exists \left(\frac{7}{8} + \varepsilon\right)$-approx alg for MAX E3SAT $\Rightarrow$ P = NP

Section 5.3: A biased rand. alg.

Since unit clauses (clauses of exactly one literal) are the "hardest", we should focus on these to obtain a better approx. ratio.

For each i, $1 \le i \le n$, we define:

$$u_i = \begin{cases} \text{weight of unit clause } x_i, \text{ if it exists} \\ 0, \text{ otherwise} \end{cases}$$

$$v_i = \begin{cases} \text{weight of unit clause } \bar{x}_i, \text{ if it exists} \\ 0, \text{ otherwise} \end{cases}$$

Idea: If $u_i \ge v_i$, set x_i true with prob. $> \frac{1}{2}$, and vice versa.

For ease of presentation, assume that

$$u_i \ge v_i, \quad 1 \le i \le n$$

Why is this not a restriction?

Thus, each variable will be set true with prob. $> \frac{1}{2}$:

For any $p > \frac{1}{2}$, we define the following alg:

Rand p

For $i \leftarrow 1$ to n
    With prob. p set x_i true

What is an optimal value of p?

Lemma 5.4

For any clause C_j which does not consist of one negated variable,
Rand p satisfies C_j with prob $\geq \min\{p, 1-p^2\}$

Proof:
If $l_j = 1$, C_j consists of one unnegated variable.
In this case, C_j is satisfied with prob. p.

If $l_j = 2$, the worst case is if both literals are negated variables, since $p > \frac{1}{2}$. Thus, in this case, C_j is satisfied with prob. $\geq 1-p^2$.

If $l_j \geq 3$, the prob. of C_j being satisfied is at least the worst-case prob. for $l_j = 2$.

□

Lemma 5.6: $OPT \leq W - \sum_{i=1}^{n} v_i$

Proof:
By assumption, $u_i \geq v_i$, for all i.
Thus, if $v_i > 0$, there is both an x_i- and an $\bar{x}_i$- clause. Both clauses cannot be satisfied.
Thus, for each $v_i > 0$, there is an unsatisfied clause of weight $\geq \min\{u_i, v_i\} = v_i$. □

We can obtain an alg. with approx. ratio $\frac{1}{2}(\sqrt{5}-1) \approx 0{,}618$:

Theorem 5.7:

For $\rho = \frac{1}{2}(\sqrt{5}-1)$, Randp is a ρ-approx. alg.

Proof:

Total weight of clauses that are not negated unit clauses

By Lemma 5.4,

$$E[\text{Rand}_\rho] \geq \min\{\rho, 1-\rho^2\} \cdot \left(W - \sum_{i=1}^{n} v_i\right)$$

$$= \rho\left(W - \sum_{i=1}^{n} v_i\right), \text{ for } \rho = \tfrac{1}{2}(\sqrt{5}-1):$$

$$1 - \left(\tfrac{1}{2}(\sqrt{5}-1)\right)^2 = 1 - \tfrac{1}{4}(5+1-2\sqrt{5}) = 1 - \tfrac{3}{2} + \tfrac{1}{2}\sqrt{5}$$

$$= \tfrac{1}{2}(\sqrt{5}-1)$$

By Lemma 5.6, $\text{OPT} \leq W - \sum_{i=1}^{n} v_i$.

Hence, for $\rho = \tfrac{1}{2}(\sqrt{5}-1)$, $\frac{E[\text{Rand}_\rho]}{\text{OPT}} \geq \rho$ □

Note that

Rand$_\rho$ can be derandomized exactly like Rand

Section 5.4: Randomized rounding

In Section 5.3 we saw that biasing the prob. of setting each variable true resulted in a better approx. guarantee.
The approximation ratio can be further improved by allowing a different bias for each variable
We will develop an LP-formulation of the problem

For each clause, C_j, we define:
P_j: the set of indices of variables that occur positively in C_j
N_j: " " negatively " "
Then, C_j can be written as

$$\bigvee_{i \in P_j} x_i \vee \bigvee_{i \in N_j} \bar{x}_i$$

If $y_i = 0$ corresponds to $x_i \equiv F$ and $y_i = 1$ corresponds to $x_i \equiv T$, then C_j is true, iff

$$\sum_{i \in P_j} y_i + \sum_{i \in N_j} (1 - y_i) \geq 1$$

This leads to the following IP-formulation:

IP_ϕ:

$$\max \quad \sum_{j=1}^{m} z_j w_j$$

subject to

$$\sum_{i \in P_j} y_i + \sum_{i \in N_j} (1 - y_i) \geq z_j, \quad 1 \leq j \leq m$$

$$y_i \in \{0,1\}, \quad 1 \leq i \leq n$$

$$z_j \in \{0,1\}, \quad 1 \leq j \leq m$$

Let LP_ϕ be the LP-relaxation of IP_ϕ, i.e.,

LP_ϕ:

$$\max \quad \sum_{j=1}^{m} z_j w_j$$

subject to

$$\sum_{i \in P_j} y_i + \sum_{i \in N_j} (1 - y_i) \geq z_j, \quad 1 \leq j \leq m$$

$$0 \leq y_i \leq 1, \quad 1 \leq i \leq n$$

$$0 \leq z_j \leq 1, \quad 1 \leq j \leq m$$

Clearly, $Z^*_{LP_\phi} \geq Z^*_{IP_\phi} = OPT$

- $Z^*_{LP_\phi}$: value of opt. sol. to LP_ϕ
- $Z^*_{IP_\phi}$: value of opt. sol. to IP_ϕ
- OPT: value of opt. sol. to corresponding MAXSAT problem

RandRounding (ϕ)

$(\vec{y}^*, \vec{z}^*) \leftarrow$ opt. sol. to LP_ϕ
For $i \leftarrow 1$ to n
    Set x_i true with prob. y_i^*

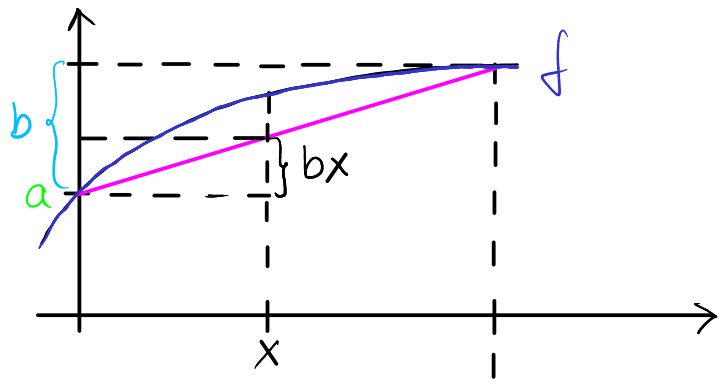
The approx. ratio of RandRounding is at least $1 - \frac{1}{e} \approx 0.632$.
For proving this, we will use the following two facts:

Fact 5.8 (Arithmetic-geometric mean inequality):
For any $a_1, a_2, \ldots, a_k \geq 0$,

$$\left(\prod_{i=1}^{k} a_i\right)^{1/k} \leq \frac{1}{k}\sum_{i=1}^{k} a_i$$

A function f is concave on an interval I, if $f''(x) \leq 0$ for any $x \in I$. (the slope is nonincreasing)

Fact 5.9:
f is concave on $[0,1]$, $f(0) = a$, $f(1) = a+b$ $\Rightarrow$ $f(x) \geq a + bx$, for $x \in [0,1]$



Theorem 5.10: RandRounding is a $(1-\frac{1}{e})$-approx. alg

Proof:

For $1 \le j \le m$, let p_j be the probability that C_j is satisfied, and let $\overline{p}_j = 1 - p_j$.

Our goal is to show that $p_j \ge (1-\frac{1}{e}) z_j^*$.

This will establish the approx. factor, since $OPT \le \sum_{j=1}^{m} z_j^* w_j$

$$\overline{p}_j = \prod_{i \in P_j} (1 - y_i^*) \prod_{i \in N_j} y_i^*$$

$$\le \left(\frac{1}{\ell_j} \left(\sum_{i \in P_j} (1 - y_i^*) + \sum_{i \in N_j} y_i^* \right) \right)^{\ell_j}, \text{ by Fact 5.8}$$

$$= \left(\frac{1}{\ell_j} \left(|P_j| - \sum_{i \in P_j} y_i^* + \sum_{i \in N_j} (1 - 1 + y_i^*) \right) \right)^{\ell_j}$$

$$= \left(\frac{1}{\ell_j} \left(|P_j| - \sum_{i \in P_j} y_i^* + |N_j| - \sum_{i \in N_j} (1 - y_i^*) \right) \right)^{\ell_j}$$

$$= \left(1 - \frac{1}{\ell_j} \left(\sum_{i \in P_j} y_i^* + \sum_{i \in N_j} (1 - y_i^*) \right) \right)^{\ell_j}, \text{ since } |P_j| + |N_j| = \ell_j$$

$$\le \left(1 - \frac{z_j^*}{\ell_j} \right)^{\ell_j}, \text{ since } (\vec{y}^*, \vec{z}^*) \text{ is a solution to LP}_\phi$$

Thus, $p_j \ge 1 - \left(1 - \frac{z_j^*}{\ell_j} \right)^{\ell_j} \equiv f(z_j^*)$

which is a concave function of z_j^*:

$$f'(z_j^*) = -\ell_j \left(1 - \frac{z_j^*}{\ell_j}\right)^{\ell_j - 1} \cdot \left(-\frac{1}{\ell_j}\right) = \left(1 - \frac{z_j^*}{\ell_j}\right)^{\ell_j - 1}$$

$$f''(z_j^*) = (\ell_j - 1)\left(1 - \frac{z_j^*}{\ell_j}\right)^{\ell_j - 2} \cdot \left(-\frac{1}{\ell_j}\right) = \underbrace{\left(\frac{1}{\ell_j} - 1\right)}_{\le 0} \underbrace{\left(1 - \frac{z_j^*}{\ell_j}\right)^{\ell_j - 2}}_{\ge 0} \le 0$$

Note that

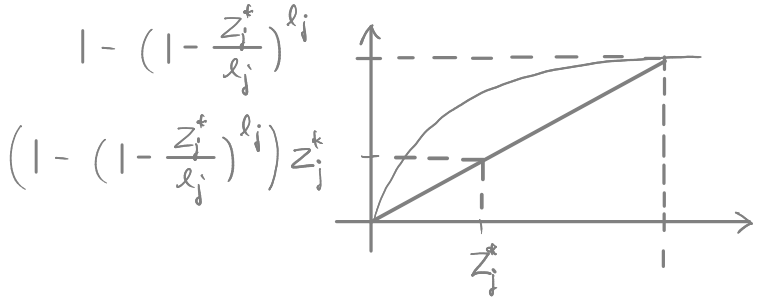
$$f(0) = 1 - \left(1 - \frac{0}{\ell_j}\right)^{\ell_j} = 1 - 1 = 0$$

$$f(1) = 1 - \left(1 - \frac{1}{\ell_j}\right)^{\ell_j} =$$

Thus, using Fact 5.9 with $a = f(0)$ and $b = f(1) - f(0)$,

$$p_j \geq 1 - \left(1 - \frac{z_j^*}{\ell_j}\right)^{\ell_j}$$

$$\geq \left(1 - \left(1 - \frac{1}{\ell_j}\right)^{\ell_j}\right) z_j^*$$

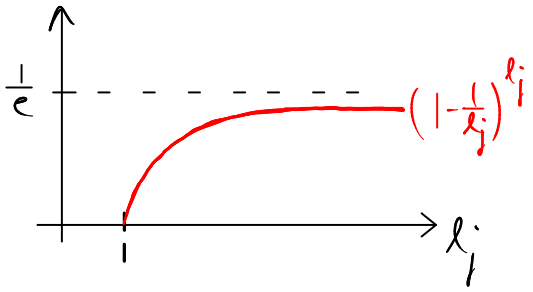


Hence,

$$E[\text{Rand Rounding}] = \sum_{j=1}^{m} p_j w_j$$

$$\geq \sum_{j=1}^{m} \left(1 - \left(1 - \frac{1}{\ell_j}\right)^{\ell_j}\right) z_j^* w_j$$

$$\geq \left(1 - \frac{1}{e}\right) \cdot \underbrace{\sum_{j=1}^{m} z_j^* w_j}_{= Z^*_{LP_\Phi} \geq OPT}$$



□

Note that

> Rand Rounding can be derandomized exactly like Rand and Randp

Section 5.5 : Choosing the better of two solutions

Combining the alg.s of Sections 5.1 and 5.4 gives a better approx. factor than using any one of them separately. This is because they have different worst-case inputs:

Rand satisfies clause C_j with prob. $p_R = 1 - (\frac{1}{2})^{l_j}$.

RandRounding satisfies C_j with prob. $p_{RR} \geq (1 - (1 - \frac{1}{l_j})^{l_j}) z_j^*$.

While p_R increases with l_j, the lower bound on p_{RR} decreases with l_j.

BestOfTwo (ϕ)

$\vec{X}_R \leftarrow$ Rand(ϕ)

$\vec{X}_{RR} \leftarrow$ RandRounding(ϕ)

If $w(\phi, \vec{X}_R) \geq w(\phi, \vec{X}_{RR})$

  Return $\vec{X}_R$

Else

  Return $\vec{X}_{RR}$

Note that

BestOfTwo is derandomized by using the derandomized versions of Rand and RandRounding.

Section 5.5 : Choosing the better of two solutions

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If $w(\phi, \vec{X}_R) \geq w(\phi, \vec{X}_{RR})$

  Return $\vec{X}_R$

Else

  Return $\vec{X}_{RR}$

Note that

BestOfTwo is derandomized by using the derandomized versions of Rand and RandRounding.

Theorem 5.11: BestOfTwo is a 3/4-approx. alg.

Proof:

$$\mathbb{E}[\text{BestOfTwo}(\phi)] = \mathbb{E}\left[\max\{\text{Rand}(\phi), \text{RandRanding}(\phi)\}\right]$$

$$\geq \mathbb{E}\left[\tfrac{1}{2}\text{Rand}(\phi) + \tfrac{1}{2}\text{RandRanding}(\phi)\right]$$

$$= \tfrac{1}{2}\mathbb{E}[\text{Rand}(\phi)] + \tfrac{1}{2}\mathbb{E}[\text{RandRanding}(\phi)], \text{ by lin. of exp.}$$

$$\geq \tfrac{1}{2}\sum_{j=1}^{m}\left(1-2^{-\ell_j}\right)w_j + \tfrac{1}{2}\sum_{j=1}^{m}\left(1-\left(1-\tfrac{1}{\ell_j}\right)^{\ell_j}\right)z_j^* w_j$$

$$\geq \sum_{j=1}^{m} z_j^* w_j \cdot \underbrace{\tfrac{1}{2}\left(1-2^{-\ell_j} + 1-\left(1-\tfrac{1}{\ell_j}\right)^{\ell_j}\right)}_{\equiv \rho_j}, \text{ since } z_j^* \leq 1.$$

For $\ell_j = 1$, $\rho_j = \frac{1}{2}\left(1-\frac{1}{2}+1-0\right) = \frac{3}{4}$

For $\ell_j = 2$, $\rho_j = \frac{1}{2}\left(1-\frac{1}{4}+1-\left(1-\frac{1}{2}\right)^2\right) = \frac{3}{4}$

For $\ell_j \geq 3$, $\rho_j \geq \frac{1}{2}\left(1-\frac{1}{8}+1-\frac{1}{e}\right) > \frac{3}{4}$

Hence,

$$\mathbb{E}[\text{BestOfTwo}] \geq \sum_{j=1}^{m} z_j^* w_j \cdot \frac{3}{4} \geq \frac{3}{4}\cdot \text{OPT}$$

□

Section 5.6: Nonlinear randomized rounding

RandRounding$_f(\phi)$

$(\vec{y}^*, \vec{z}^*) \leftarrow$ opt. sol. to LP_ϕ
For $i \leftarrow 1$ to n
    Set x_i true with prob. $f(y_i^*)$

Theorem 5.12

RandRounding$_f$ is a $3/4$-approx. alg., if $1 - 4^{-x} \le f(x) \le 4^{x-1}$

Proof:

Prob. that C_j is not satisfied:

$$\begin{aligned}
\bar{p}_j &= \prod_{i \in P_j} (1 - f(y_i^*)) \prod_{i \in N_j} f(y_i^*) \\
&\le \prod_{i \in P_j} 4^{-y_i^*} \prod_{i \in N_j} 4^{y_i^* - 1} \\
&= 4^{-\left(\sum_{i \in P_j} y_i^* + \sum_{i \in N_j} 1 - y_i^*\right)} \\
&\le 4^{-z_j^*}
\end{aligned}$$

Prob. that C_j is satisfied:

$$\begin{aligned}
p_j = 1 - \bar{p}_j &\ge 1 - 4^{-z_j^*} \\
&\ge 0 + \left(\tfrac{3}{4} - 0\right) z_j^*, \quad \text{by Fact 5.9} \\
&= \tfrac{3}{4} z_j^*
\end{aligned}$$

□

Ex: $\phi \equiv (x_1 \vee x_2) \wedge (x_1 \vee \bar{x}_2) \wedge (\bar{x}_1 \vee x_2) \wedge (\bar{x}_1 \vee \bar{x}_2)$

$w_1 = w_2 = w_3 = w_4 = 1$

$OPT = 3$

$y_1 = y_2 = \frac{1}{2} \Rightarrow Z = 4$

Hence, the integrality gap for the IP problem for MaxSat is

$$\min_{\psi} \left\{ \frac{Z^*_{IP_\psi}}{Z^*_{LP_\psi}} \right\} \leq \frac{Z^*_{IP_\phi}}{Z^*_{LP_\phi}} = \frac{3}{4}$$

On the other hand, the proof that $Rand_f$ is a $3/4$-approx. alg. shows that for any instance ψ of MaxSat, $Rand_f(\psi) \geq \frac{3}{4} Z^*_{LP_\psi}$. Hence,

$$\frac{Z^*_{IP_\psi}}{Z^*_{LP_\psi}} \geqslant \frac{Rand_f(\psi)}{Z^*_{LP_\psi}} \geqslant \frac{3}{4}$$

Hence, the integrality gap is exactly $\frac{3}{4}$.

The upper bound of $\frac{3}{4}$ on the integrality gap shows that we cannot prove an approx. factor better than $\frac{3}{4}$, if the approximation guarantee is based on a comparison to Z^*_{LP}:

$$\min_{\psi} \left\{ \frac{ALG(\psi)}{Z^*_{LP_\psi}} \right\} \leq \min_{\psi} \left\{ \frac{OPT(\psi)}{Z^*_{LP_\psi}} \right\} \leq \frac{3}{4}$$

Techniques: (with Set Cover as an example)

- Solve LP and round solution (Sec. 1.3 + 1.7)
- Primal-dual alg.: combinatorial alg. based on LP formulation (Sec. 1.4 + 1.5)
- Greedy alg. (Sec. 1.6)

Section 1.2: Set Cover as an LP

Set Cover

Input:

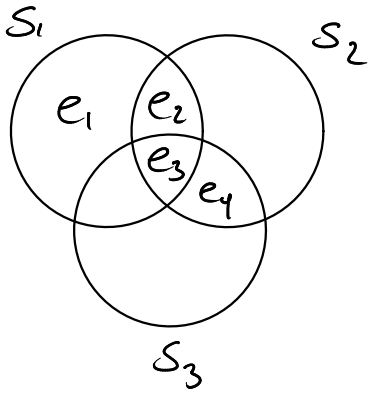
$E = \{e_1, e_2, \dots, e_n\}$

$\mathcal{S} = \{S_1, S_2, \dots, S_m\}$, where $S_j \subseteq E$ has weight w_j.

Objective: Find a cheapest possible subset of $\mathcal{S}$ covering all elements

OPT: value (total weight) of optimum solution

Ex:



$w_1 = 1$

$w_2 = 2$

$w_3 = 3$

$\{S_1, S_2\}$ is a sol. of total weight 3.

This is optimal, so OPT = 3 for this instance of Set Cover.

To cover e_1, we need S_1

—"— e_2 —"— S_1 or S_2

—"— e_3 —"— S_1, S_2 or S_3

—"— e_4 —"— S_2 or S_3

IP-formulation:

$$\min \quad x_1 w_1 + x_2 w_2 + x_3 w_3$$

$$\text{s.t.} \quad x_1 \geq 1$$

$$x_1 + x_2 \geq 1$$

$$x_1 + x_2 + x_3 \geq 1$$

$$x_2 + x_3 \geq 1$$

$$x_1, x_2, x_3 \in \{0, 1\}$$

More generally:

IP for Set Cover

$$\min \quad \sum_{j=1}^{m} x_j w_j$$

$$\text{s.t.} \quad \sum_{j: e_i \in S_j} x_j \geq 1, \qquad i = 1, 2, \ldots, n$$

$$x_j \in \{0, 1\}, \qquad j = 1, 2, \ldots, m$$

Z^*_{IP} : optimum solution value, i.e., $Z^*_{IP} = OPT$

LP-relaxation

$$\min \quad \sum_{j=1}^{m} x_j w_j$$

$$\text{s.t.} \quad \sum_{j: e_i \in S_j} x_j \geq 1, \qquad i = 1, 2, \ldots, n$$

$$0 \leq x_j \leq 1, \qquad j = 1, 2, \ldots, m$$

redundant

Z^*_{LP} : Optimum solution value

Note that $Z^*_{LP} \leq Z^*_{IP} = OPT$

Section 1.3: A deterministic rounding algo.

The frequency of an element e is the #sets containing e:

$$f_e = |\{S \in \mathcal{S} \mid e \in S\}|$$

The frequency of an instance of Set Cover:

$$f = \max_{e \in E} \{f_e\}$$

Alg. 1 for Set Cover: LP-rounding

Solve LP

$I \leftarrow \{j \mid x_j \geq \frac{1}{f}\}$

We prove that Alg 1 produces a set cover (Lemma 1.5) of total weight $\leq f \cdot OPT$ (Thm 1.6)

Lemma 1.5

$\{S_j \mid j \in I\}$ is a set cover

Proof:

For each $e_i \in E$, $\sum_{j : e_i \in S_j} x_j \geq 1$.

Since $\sum_{j : e_i \in S_j} x_j$ has at most f terms, at least one of the terms is at least $\frac{1}{f}$.

Thus, there is a set S_j s.t. $e_i \in S_j$ and $x_j \geq \frac{1}{f}$.

This j is included in I □

Thm 1.6

Alg. 1 is an f-approx. algo. for Set Cover.

Proof:

Correct by Lemma 1.5

Poly, since LP-solving is poly.

Approx. factor f:

Each x_j is rounded up to 1, only if it is already at least $\frac{1}{f}$.

Thus, each x_j is multiplied by at most f, i.e.,

$$\sum_{j \in I} w_j \leq \sum_{j \in I} f \cdot x_j \cdot w_j \leq \sum_{j=1}^{n} f \cdot x_j \cdot w_j = f \cdot Z^*_{LP} \leq f \cdot OPT$$

□

The Vertex Cover problem is a special case of Set Cover:

Vertex Cover

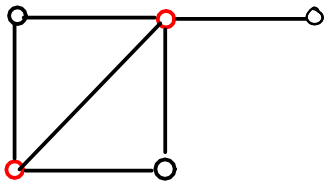
Input:

$G = (V, E)$

Objective:

Find a min. card. vertex set $C \subseteq V$ s.t. each edge $e \in E$ has at least one endpoint in C.

Ex:



With $\mathcal{S} = V$ and $E = E$,
Alg. 1 is a 2-approx. alg. for Vertex Cover.

One of the exercises for Tuesday:
Write down LP for Vertex Cover.

Section 1.4: The dual LP

What is a dual ?

Ex:

P

$$\begin{aligned} \min \quad & 7x_1 + x_2 + 5x_3 \\ \text{s.t.} \quad & x_1 - x_2 + 3x_3 \geq 10 \\ & 5x_1 + 2x_2 - x_3 \geq 6 \\ & x_1, x_2, x_3 \geq 0 \end{aligned}$$

Primal

$$7x_1 + x_2 + 5x_3 \geq x_1 - x_2 + 3x_3 \geq 10$$

$$\begin{aligned} 7x_1 + x_2 + 5x_3 &\geq x_1 - x_2 + 3x_3 + 5x_1 + 2x_2 - x_3 \\ &\geq 10 + 6 = 16 \end{aligned}$$

$$\begin{aligned} 7x_1 + x_2 + 5x_3 &\geq 2(x_1 - x_2 + 3x_3) + 5x_1 + 2x_2 - x_3 \\ &\geq 2 \cdot 10 + 6 = 26 \end{aligned}$$

To find a largest possible lower bound on $7x_1 + x_2 + 5x_3$, we should determine y_1 and y_2 maximizing $10y_1 + 6y_2$, under the constraints that

$$\begin{aligned} 7x_1 + x_2 + 5x_3 &\overset{(*)}{\geq} y_1 \underbrace{(x_1 - x_2 + 3x_3)}_{\geq 10} + y_2 \underbrace{(5x_1 + 2x_2 - x_3)}_{\geq 6} \\ &= \underbrace{(y_1 + 5y_2)}_{\leq 7} x_1 + \underbrace{(-y_1 + 2y_2)}_{\leq 1} x_2 + \underbrace{(3y_1 - y_2)}_{\leq 5} x_3 \end{aligned}$$

necessary to satisfy (*)

and $y_1, y_2, y_3 \geq 0$ otherwise

"$\geq$" becomes "$\leq$"

Thus, we arrive at the following problem:

D

$$\begin{aligned} \max \quad & 10y_1 + 6y_2 \\ \text{s.t.} \quad & y_1 + 5y_2 \leq 7 \\ & -y_1 + 2y_2 \leq 1 \\ & 3y_1 - y_2 \leq 5 \\ & y_1, y_2 \geq 0 \end{aligned}$$

Dual

In general:

Primal:

$$\begin{aligned} \min \quad & c_1 x_1 + c_2 x_2 + \dots + c_n x_n \\ \text{s.t.} \quad & a_{i1} x_1 + a_{i2} x_2 + \dots + a_{in} x_n \geq b_i, \quad i = 1, 2, \dots, m \\ & x_j \geq 0, \quad j = 1, 2, \dots, n \end{aligned}$$

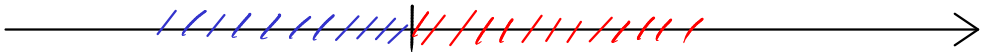
Dual:

$$\begin{aligned} \max \quad & b_1 y_1 + b_2 y_2 + \dots + b_m y_m \\ \text{s.t.} \quad & a_{1j} y_1 + a_{2j} y_2 + \dots + a_{mj} y_m \leq c_1, \quad j = 1, 2, \dots, n \\ & y_i \geq 0, \quad i = 1, 2, \dots, m \end{aligned}$$

Returning to the example above:

The constraints of D ensure that the value of any sol. to D is a lower bound on the value of any sol. to P, i.e., for any pair x, y of sol. to P and D resp.,

$$10y_1 + 6y_2 \leq 7x_1 + x_2 + 5x_3$$ Weak duality



opt. value for both problems — Strong duality

Consider again the inequality leading to the constraints of the dual:

$$y_1 = 0 \;\vee\; x_1 - x_2 + 3x_3 = 0 \qquad y_2 = 0 \;\vee\; 5x_1 + 2x_2 - x_3 = 6$$

$$7x_1 + x_2 + 5x_3 \overset{(*)}{\geq} \underbrace{y_1}_{=10y_1}\underbrace{(x_1 - x_2 + 3x_3)}_{\geq 10} + \underbrace{y_2}_{=6y_2}\underbrace{(5x_1 + 2x_2 - x_3)}_{\geq 6}$$

$$= \underbrace{(y_1 + 5y_2)}_{\leq 7}x_1 + \underbrace{(-y_1 + 2y_2)}_{\leq 1}x_2 + \underbrace{(3y_1 - y_2)}_{\leq 5}x_3$$

$$\underbrace{(y_1 + 5y_2)x_1}_{=7x_1} + \underbrace{(-y_1 + 2y_2)x_2}_{=x_2} + \underbrace{(3y_1 - y_2)x_3}_{=5x_3}$$

$$y_1 + 5y_2 = 7 \;\vee\; x_1 = 0 \qquad -y_1 + 2y = 1 \;\vee\; x_2 = 0 \qquad 3y_1 - y_2 = 5 \;\vee\; x_3 = 0$$

$\Downarrow$

$(*)$ becomes $=$

Thus,

$$7x_1 + x_2 + 5x_3 = 10y_1 + 6y_2$$

$$\Updownarrow$$

Complementary Slackness Conditions

$$\begin{cases} x_1 > 0 \Rightarrow y_1 + 5y_2 = 7 \\ x_2 > 0 \Rightarrow -y_1 + 2y_2 = 1 \\ x_3 > 0 \Rightarrow 3y_1 - y_2 = 5 \end{cases} \quad \text{primal C.S.C.}$$

$$\begin{cases} y_1 > 0 \Rightarrow x_1 - x_2 + 3x_3 = 10 \\ y_2 > 0 \Rightarrow 5x_1 + 2x_2 - x_3 = 6 \end{cases} \quad \text{dual C.S.C.}$$

By The Strong Duality Theorem (which we will not prove), there exist solutions fulfilling the C.S.C.

Moreover, if the c.s.c. are „close" to being satisfied, the values of the primal and dual sol. are „close":

Relaxed Complementary Slackness Conditions

$$\begin{cases} x_1 > 0 \Rightarrow y_1 + 5y_2 \geq 7/b \\ x_2 > 0 \Rightarrow -y_1 + 2y_2 \geq 1/b \\ x_3 > 0 \Rightarrow 3y_1 - y_2 \geq 5/b \\ y_1 > 0 \Rightarrow x_1 - x_2 + 3x_3 \leq 10c \\ y_2 > 0 \Rightarrow 5x_1 + 2x_2 - x_3 \leq 6c \end{cases}$$

$$\Downarrow$$

$$7x_1 + x_2 + 5x_3 \leq bc(10y_1 + 6y_2)$$

Proof:

$$(y_1 + 5y_2)x_1 + (-y_1 + 2y_2)x_2 + (3y_1 - y_2)x_3$$

$$\geq \frac{7}{b}x_1 + \frac{1}{b}x_2 + \frac{5}{b}x_3, \text{ by the Primal relaxed c.s.c.}$$

$$= \frac{1}{b}(7x_1 + x_2 + 5x_3)$$

$$\Downarrow$$

$$7x_1 + x_2 + 5x_3 \leq b\left((y_1 + 5y_2)x_1 + (-y_1 + 2y_2)x_2 + (3y_1 - y_2)x_3\right)$$

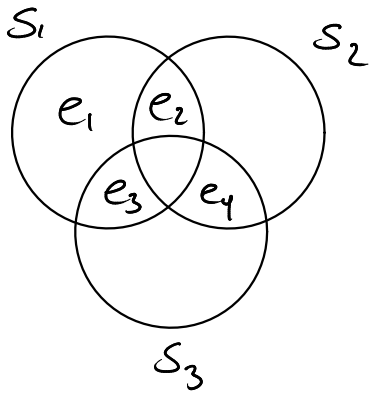
$$= b\left((x_1 - x_2 + 3x_3)y_1 + (5x_1 + 2x_2 - x_3)y_2\right)$$

$$\leq b(10cy_1 + 6cy_2), \text{ by the Dual r.c.s.c.}$$

$$= bc(10y_1 + 6y_2)$$

What is the dual of the Set Cover LP?

Ex:



$w_1 = 1$

$w_2 = 2$

$w_3 = 3$

Primal:

$$\begin{aligned} \min \quad & x_1 + 2x_2 + 3x_3 \\ \text{s.t.} \quad & x_1 \geq 1 \\ & x_1 + x_2 \geq 1 \\ & x_1 + x_3 \geq 1 \\ & x_2 + x_3 \geq 1 \\ & x_1, x_2, x_3 \geq 0 \end{aligned}$$

OPT = 3:

$x_1 = x_2 = 1$

Dual:

$$\begin{aligned} \max \quad & y_1 + y_2 + y_3 + y_4 \\ \text{s.t.} \quad & y_1 + y_2 + y_3 \leq 1 \\ & y_2 + y_4 \leq 2 \\ & y_3 + y_4 \leq 3 \\ & y_1, y_2, y_3, y_4 \geq 0 \end{aligned}$$

OPT = 3:

$y_1 = 1$, $y_4 = 2$ or $y_3 = 1$, $y_4 = 2$

Set Cover Primal

$$\min \sum_{j=1}^{m} x_j w_j$$

$$\text{s.t.} \sum_{j: e_i \in S_j} x_j \geq 1, \quad i = 1, 2, \ldots, n$$

$$x_j \geq 0, \quad j = 1, 2, \ldots, m$$

Covering problem

Set Cover Dual

$$\max \sum_{i=1}^{n} y_i$$

$$\text{s.t.} \sum_{e_i \in S_j} y_i \leq w_j, \quad j = 1, 2, \ldots, m$$

$$y_i \geq 0, \quad i = 1, 2, \ldots, n$$

Packing problem

Recall that the dual is constructed such that the value of any solution to the dual is a lower bound on the value of any solution to the primal:

$$z_{Primal} \geq z_{Dual}$$ (weak duality property)

In fact,

$$z^*_{Primal} = z^*_{Dual}$$ (strong duality property)

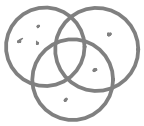
Set Cover - recap.

LP-relax: $\min \sum_{j=1}^{m} x_j w_j$

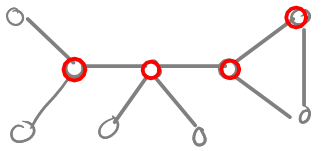
$$\text{s.t.} \sum_{j : e_i \in S_j} x_j \geq 1, \quad 1 \leq i \leq n$$

$$x_j \geq 0, \quad 1 \leq j \leq m$$

Deterministic rounding: f-approx. alg.

Eks:  $f = 2$

Vertex Cover

Ex: 

Exercises

Recap ctd.:

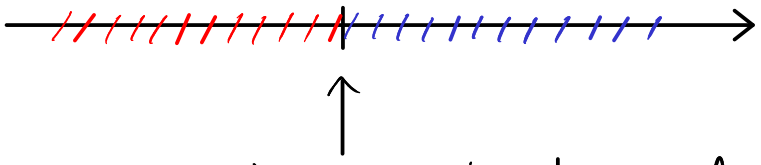
Dual LP: $\max \sum_{i=1}^{n} y_i$

$$\text{s.t.} \sum_{e_i \in S_j} y_i \leq w_j, \quad 1 \leq j \leq m$$

$$y_i \geq 0, \quad 1 \leq i \leq n$$

For any pair $\vec{x}, \vec{y}$ to the primal / dual problems:

$$\sum_{i=1}^{n} y_i \leq \sum_{j=1}^{m} x_j w_j \quad \text{(weak duality)}$$



optimum objective value for both problems

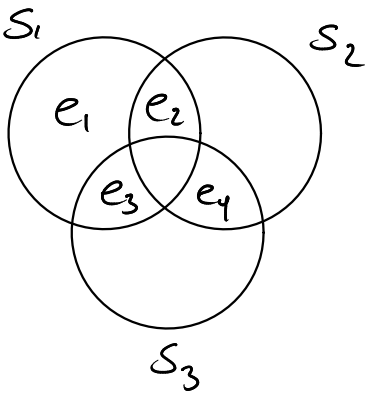
(strong duality)

(Relaxed) Complementary Slackness Conditions:

Primal c.s.c. $x_j > 0 \Rightarrow \sum_{e_i \in S_j} y_i = w_j \quad \left(\geq \frac{1}{b} w_j \right), \quad 1 \leq j \leq m$

Dual c.s.c. $y_i > 0 \Rightarrow \sum_{j : e_i \in S_j} x_j = 1 \quad (\leq c), \quad 1 \leq i \leq n$

Ex:



$w_1 = 1$

$w_2 = 2$

$w_3 = 3$

Primal:

$$\begin{aligned} \min \quad & x_1 + 2x_2 + 3x_3 \\ \text{s.t.} \quad & x_1 \geq 1 \\ & x_1 + x_2 \geq 1 \\ & x_1 + x_3 \geq 1 \\ & x_2 + x_3 \geq 1 \\ & x_1, x_2, x_3 \geq 0 \end{aligned}$$

OPT = 3:

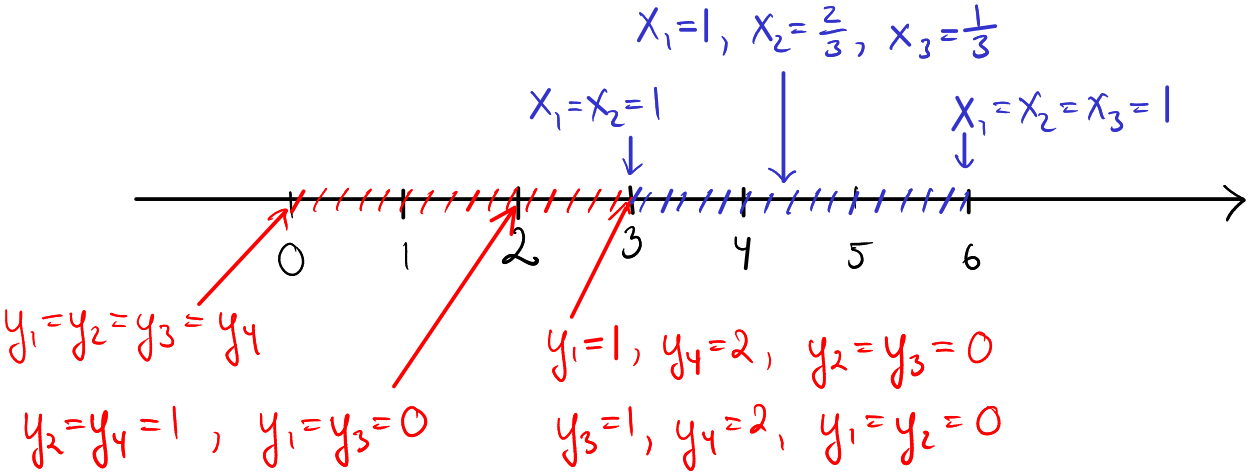
$x_1 = x_2 = 1$

Dual:

$$\begin{aligned} \max \quad & y_1 + y_2 + y_3 + y_4 \\ \text{s.t.} \quad & y_1 + y_2 + y_3 \leq 1 \\ & y_2 + y_4 \leq 2 \\ & y_3 + y_4 \leq 3 \\ & y_1, y_2, y_3, y_4 \geq 0 \end{aligned}$$

OPT = 3:

$y_1 = 1$, $y_4 = 2$ or $y_3 = 1$, $y_4 = 2$



Alg. 2 for Set Cover

$\vec{y}^* \leftarrow$ opt. sol. to dual LP

$I' \leftarrow \{ j \mid \sum_{e_i \in S_j} y_i = w_j \}$

In the ex. above:

with $y_1^* = 1$, $y_4^* = 2$, Alg 2 would choose S_1 and S_2 with a total weight of 3.

with $y_3^* = 1$, $y_4^* = 2$, Alg. 2 would choose S_1, S_2, and S_3 with a total weight of 6.

The first solution is optimal, and the latter is a 2-approximation (i.e., an f-approximation).

Alg. 2 is an f-approximation algo.:

If the algo. chooses S_1, S_2, and S_3, the total weight is $W = w_1 + w_2 + w_3$, and

$$w_1 + w_2 + w_3 = (y_1^* + y_2^* + y_3^*) + (y_2^* + y_4^*) + (y_3^* + y_4^*),$$

since the algo. chooses exactly those sets that have LHS = RHS.

Since each y_i is present in at most f constraints,

$$\begin{aligned} W &\le f \cdot (y_1^* + y_2^* + y_3^* + y_4^*) \\ &= f \cdot Z_{dual}^* \\ &\le f \cdot Z_{primal}^*, \text{ by the weak duality property} \\ &= f \cdot OPT \end{aligned}$$

Lemma 1.7

Alg. 2 produces a set cover

Proof:

Assume for the sake of contradiction that some element e_k is not covered by $\{S_j \mid j \in I'\}$.

Then $\sum_{e_i \in S_j} y_i < w_j$ for all S_j containing e_k.

These are exactly the constraints involving y_k.

Thus, none of the constraints involving y_k are tight.

This means that y_k can be increased without violating any constraint.

Since this will increase the value $\sum_{i=1}^{n} y_i$ of the sol., we conclude that the solution $\vec{y}$ was not optimal.

□

Ex:

In the ex. above, assume

$y_1 = y_2 = y_3 = 0$

$y_4 = 2$

Then, only the second constraint is tight, so only S_2 is picked:

$$y_1 + y_2 + y_3 = 0 < 1$$
$$y_2 + y_4 = 2$$
$$y_3 + y_4 = 2 < 3$$

e_4 is not covered, since none of the two constraints involving y_4 are tight.

We can increase y_3 from 0 to 1 without violating any constraints
(Then two other constraints become tight.)
This increases the sol. value from 2 to 3.
Thus, the sol. above was not optimal.

Or we could increase y_1 from 0 to 1.
Then only the first constraint becomes tight, resulting in an optimal solution.

This illustrates the idea of the primal-dual alg of Section 1.5.

We now give a more formal proof that Alg 2 is an f-approximation algo.

Thm 1.8

Alg. 2 is an f-approx. algo.

Proof:

The correctness follows from Lemma 1.7.

Approx. guarantee:

$$\sum_{j \in I'} w_j = \sum_{j \in I'} \sum_{e_i \in S_j} y_i^* \qquad (y_i^* \text{ appears once for each set in the sol. containing } e_i)$$

$$= \sum_{i=1}^{n} |\{ j \in I' \mid e_i \in S_j \}| \cdot y_i^* \qquad (|\{\cdots\}| = \#\text{sets in the sol. containing } e_i)$$

$$\leq \sum_{i=1}^{n} f_{e_i} \cdot y_i^* \qquad (f_{e_i} = \#\text{sets containing } e_i)$$

$$\leq \sum_{i=1}^{n} f \cdot y_i^*$$

$$= f \cdot Z^*_{\text{dual}}$$

$$\leq f \cdot Z^*_{\text{primal}}, \quad \text{by the weak duality property}$$

$$\leq f \cdot OPT$$

□

Note that for proving the above theorem, we could also use the relaxed C.S.C. (with $b=1$, $c=f$), since

$$\sum_{j : e_i \in S_j} x_j \leq f, \quad \text{for all } i = 1, 2, \ldots, n$$

Note that, on any instance of Set Cover, $I \subseteq I'$:

Since the LP is solved optimally,

$x_j > 0 \Rightarrow$ constraint j is tight $\Rightarrow j \in I'$.

Thus, $j \in I \Rightarrow x_j \geq \frac{1}{f} \Rightarrow j \in I'$

Thus, Alg. 1 is always at least as good as Alg. 2.

Both Alg. 1 and Alg. 2 rely on solving an LP (optimally). In Section 1.5, we will study a more time efficient alg.

The key observation is that in the proof of Thm 1.8, we did not need the fact that $\vec{y}^*$ is optimal, since $Z_{dual} \leq Z^*_{primal}$, for any feasible dual solution.

Thus, the crux is to obtain an index set I'' s.t.

- $\bigcup_{j \in I''} S_j$ is a vertex cover
- $\sum_{j \in I''} w_j = \sum_{j \in I''} \sum_{e_i \in S_j} y_i$, for some feasible sol. $\vec{y}$ to the dual LP

without solving an LP optimally.

Section 1.5 : A Primal-Dual Alg. for Set Cover

Alg. 1.1 for Set Cover : Primal-Dual

$I'' \leftarrow \emptyset$

$\vec{y} \leftarrow \vec{0}$

While $\exists e_k \notin \bigcup_{j \in I''} S_j$

Increase y_k until some constraint, l, becomes tight, i.e., $\sum_{e_i \in S_l} y_i = w_l$

$I'' \leftarrow I'' \cup \{l\}$

Note that $e_k \in S_l$

Thm 1.9

Alg. 1.1 is an f-approx. alg. for Set Cover

Proof:

Alg. 3 produces a set cover, since as long as some element is not covered, the corresponding dual constraints are non-tight.

The approx. guarantee follows from the same calculations as in the proof of Thm. 1.8, since

$$\sum_{j \in I''} w_j = \sum_{j \in I''} \sum_{e_i \in S_j} y_i \leq f \cdot Z_{dual} \leq f \cdot Z^*_{dual}$$

□

In contrast to Alg. 2 from Section 1.4, Alg. 1.1 does not necessarily produce an optimal dual solution:
In the example above, it might do the following.

$y_2 \leftarrow 1$ (S_1 is picked, e_4 still uncovered)
$y_4 \leftarrow 1$ (S_2 is picked)

(This is fine, since the proof of Thm. 1.8 does not use that $\sum y_i = OPT$, only that $\sum y_i \leq OPT$, which is true for <u>any</u> feasible sol. to the dual.)

Primal-dual recap.

Primal-dual alg

Create a feasible dual sol., e.g., $\vec{y} \leftarrow \vec{0}$

(Based on the dual solution,) create an (infeasible) primal solution, e.g., $\vec{x} \leftarrow \vec{0}$

While the primal solution is infeasible

Modify dual solution to increase dual obj. value, maintaining feasibility

Modify primal solution "accordingly"

Primal-dual for Set Cover

For Set Cover, we increased a dual variable corresponding to an uncovered element, until a constraint became tight.

Then, we picked the corresponding set.

Analysis

(a) Correctness:

As long as some element e is uncovered, all constraints containing y_e are nontight.

(b) Approx.:

The resulting primal obj. value is a sum of optimal dual variables, where each y_i^* appears $\leq f$ times

Alternative analysis of (b)

Recall that (b) follows from the fact that y_e appears only in constraints corresponding to sets containing e and that there are at most f such sets.

Note that, similarly, each constraint in the primal has at most f terms.

This trivially implies that we fulfill the relaxed dual c.s.c. with $c = f$.

Since we only choose sets corresponding to tight dual constraints, we also fulfill the primal c.s.c. ($b = 1$).

Thus, we could also use the relaxed c.s.c. to prove that the alg. is an f-approx. alg.

Section 17: Randomized Rounding

Alg RR_1

Solve LP
$I \leftarrow \emptyset$
For $j \leftarrow 1$ to m
  With probability x_j
    $I \leftarrow I \cup \{j\}$

Expected cost $= Z^*_{LP} \leq OPT$, but the result is most likely not a set cover.

Alg RR_2

Solve LP
$I \leftarrow \emptyset$
For $i \leftarrow 1$ to $2 \cdot \ln(n)$
  For $j \leftarrow 1$ to m
    With probability x_j
      $I \leftarrow I \cup \{j\}$

Expected cost $\leq 2 \cdot \ln(n) \cdot Z^*_{LP} \leq 2 \cdot \ln(n) \cdot OPT$, and high probability that all elements are covered.
(Calculations below)

Alg RR_3

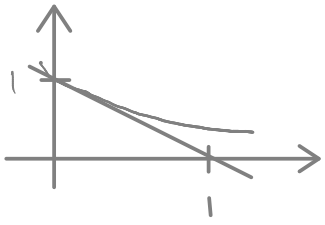
Solve LP
Repeat
  $I \leftarrow \emptyset$
  For $i \leftarrow 1$ to $2 \cdot \ln(n)$
    For $j \leftarrow 1$ to m
      With probability x_j
        $I \leftarrow I \cup \{j\}$
Until $\{S_j \mid j \in I\}$ is a set cover and $w(I) \leq 4 \ln(n) Z^*_{LP}$

Cost $\leq 4 \cdot \ln(n) \cdot OPT$
Result is a set cover.
Expected running time is polynomial.
(Calculations below)

p_i: prob. that e_i is covered
$\overline{p_i} = 1 - p_{k(i)}$: prob. that e_i is <u>not</u> covered

Alg RR_1:

$$\overline{p_i} = \prod_{j: e_i \in S_j} \underbrace{(1-x_j)}_{\leq e^{-x_j}, \text{ for any } x_j \in \mathbb{R}}$$



$$\leq \prod_{j: e_i \in S_j} e^{-x_j}$$

$$= e^{\underbrace{-\sum_{j: e_i \in S_j} x_j}_{\leq -1, \text{ by the LP constraint corresponding to } e_i}}$$

$$\leq e^{-1}$$

Alg RR_2:

$$\overline{p_i} = (\overline{p_i})^{2\ln n} \leq e^{-2\ln n} = \left(e^{-\ln n}\right)^2 = n^{-2}$$

$$\Pr[\text{not set cover}] \leq \sum_{i=1}^{n} \overline{p_i} \leq \sum_{i=1}^{n} n^{-2} = n \cdot n^{-2} = n^{-1}$$

$\Pr[\omega(I) \geq 4 \cdot \ln(n) \cdot Z^*_{LP}] \leq \frac{1}{2}$, by Markov's Inequality:

$> \frac{1}{2}$ would give $E[\omega(I)] > 2 \cdot \ln(n) \cdot Z^*_{LP}$ ↯

Alg RR_3:

$$\Pr[\text{„not set cover" or „too expensive"}] \leq n^{-1} + \frac{1}{2}$$

Thus,

$$E[\#\text{iterations}] \leq \frac{1}{1 - (n^{-1} + \frac{1}{2})} \approx 2$$

Sometimes randomized algorithms are simpler / easier to describe/come up with.
Sometimes randomized algorithms can be derandomized as we saw in Chapter 5.
Exercise for Tuesday: derandomize $Alg\,RR_3$ (Ex. 5.7)

Section 1.6: A Greedy Algorithm

A natural greedy choice would be to „pay" as little as possible for each additional covered element:

Alg 1.2 for Set Cover: Greedy

$I \leftarrow \emptyset$

For $j \leftarrow 1$ to m

  $\hat{S}_j \leftarrow S_j$ (uncovered part of S_j)

While $\{S_j \mid j \in I\}$ is not a set cover

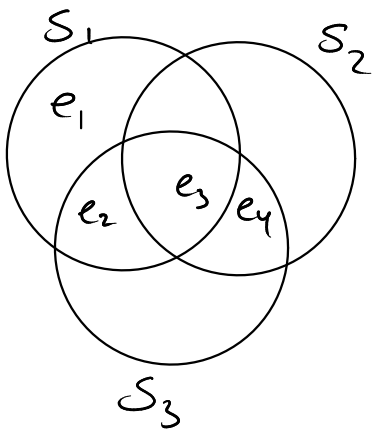
  $\ell \leftarrow \arg\min_{j : \hat{S}_j \neq \emptyset} \frac{w_j}{|\hat{S}_j|}$ (S_ℓ: set with smallest cost per uncovered element)

  $I \leftarrow I \cup \{\ell\}$

  For $j \leftarrow 1$ to m

    $\hat{S}_j \leftarrow \hat{S}_j - S_\ell$

Ex:



$w_1 = 12$

$w_2 = 4$

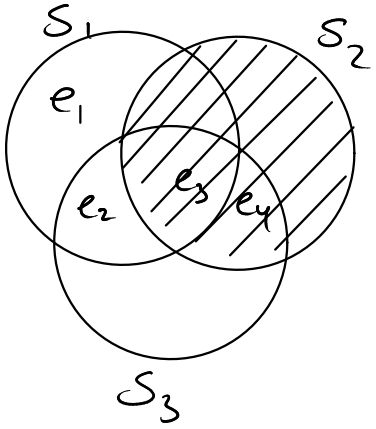
$w_3 = 9$

$\frac{w_1}{|S_1|} = \frac{12}{3} = 4,$

$\frac{w_2}{|S_2|} = \frac{4}{2} = 2$ ← price per element in first iteration

$\frac{w_3}{|S_3|} = \frac{9}{3} = 3$

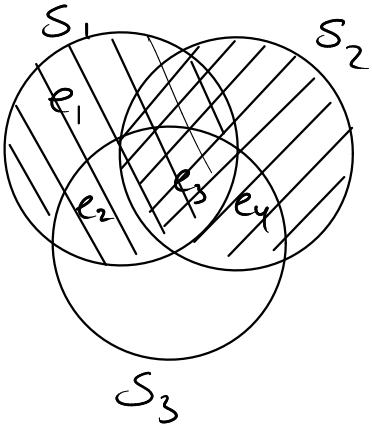
→ Pick S_2



$\frac{w_1}{|\hat{S}_1|} = \frac{12}{2} = 6$ ← price per element in second iteration

$\frac{w_3}{|\hat{S}_3|} = \frac{9}{1} = 9$

→ Pick S_1



Total weight $= \sum_{i=1}^{4} \text{price}(e_i) = 2+2+6+6$

$= w_2 + w_1 = 4 + 12$

$= 16$

The greedy alg. is an H_n-approx. alg

Recall: $H_n = 1+\frac{1}{2}+\frac{1}{3}+\ldots+\frac{1}{n} \approx \ln(n)$

It is „likely" that no significantly better approx. ratio can be obtained:

Thm 1.13:

Approx. factor $\frac{\ln n}{c}$, $c>1$, for unweighted Set Cover

$\Rightarrow$ $\underbrace{n^{O(\log\log n)}}_{\sim k^{\log n}}$ - approx alg. for NPC

Thm 1.11

Alg. 1.2 is an H_n-approx. alg. for Set Cover

Proof:

n_k: # uncovered elements at the beginning of the k'th iteration

In the ex. above:

$n = 4$

$n_1 = 4, \quad n_2 = 2, \quad n_3 = 0$

$n_1 - n_2 = 2, \quad n_2 - n_3 = 2$

Any algorithm, including OPT, has to cover these n_k elements using only sets in $\mathcal{S} - \{S_j \mid j \in I\}$, since none of them are contained in $\{S_j \mid j \in I\}$.

Hence, there must be at least one element with a price of at most OPT/n_k. Otherwise, OPT would not be able to cover the n_k elements (and certainly not all n elements) at a cost of only OPT.

Hence, the $n_k - n_{k+1}$ elements covered in iteration k cost at most $(n_k - n_{k+1})\, OPT/n_k$ in total.

Thus, the cost of the set cover produced by the greedy alg. is

$$\sum_{j \in I} w_j \le \sum_{k=1}^{r} \frac{n_k - n_{k+1}}{n_k} \, OPT \quad \leftarrow \#\text{ iterations}$$

$$= OPT \sum_{k=1}^{r} (n_k - n_{k+1}) \cdot \frac{1}{n_k}$$

$$\le OPT \sum_{k=1}^{r} \underbrace{\left(\frac{1}{n_k} + \frac{1}{n_k - 1} + \dots + \frac{1}{n_{k+1}+1} \right)}_{n_k - n_{k+1} \text{ terms that are each} \ge \frac{1}{n_k}}$$

$$= OPT \sum_{s=1}^{n} \frac{1}{s}$$

$$= OPT \cdot H_n \qquad \square$$

Ex from before:

$OPT = w_1 + w_2 = 12 + 4 = 16$

The cost of the greedy alg is

$$w_2 + w_1 = 4 + 12$$
$$= 2+2+6+6$$
$$\le \left(\frac{16}{4} + \frac{16}{4}\right) + \left(\frac{16}{2} + \frac{16}{2}\right)$$
$$\le \left(\frac{16}{4} + \frac{16}{3}\right) + \left(\frac{16}{2} + \frac{16}{1}\right)$$
$$= 16 \cdot \left(\frac{1}{4} + \frac{1}{3} + \frac{1}{2} + \frac{1}{1}\right)$$
$$= 16 \cdot H_4$$

Exercise 5.7:

Derandomize the rounding alg. from Section 1.7, using the method of conditional expectations.

Hint: Use the following obj. fct. with random variables X_j, $1 \le j \le m$, and Z.

$$\int = \sum_{j=1}^{m} X_j w_j + \lambda Z$$

λ: $n \cdot \ln n \cdot Z^*_{LP}$

X_j: $\begin{cases} 1, & \text{if } S_j \text{ incl.} \\ 0, & \text{otherwise} \end{cases}$

Z: $\begin{cases} 0, & \text{if set cover} \\ 1, & \text{otherwise} \end{cases}$

With this obj. fct.,

any infeasible sol. has $\int \ge \lambda = n \cdot \ln n \cdot Z^*_{LP}$ (*)

For Alg RR_2,

$$\begin{aligned} E[\int] &= E[\sum_{j=1}^{m} X_j w_j] + \lambda E[Z], \text{ by lin. of exp.} \\ &\le 2 \cdot \ln n \cdot Z^*_{LP} + \cancel{n} \cdot \ln n \cdot Z^*_{LP} \cdot \cancel{n^{-1}}, \text{ by the analysis in Sec. 1.7} \\ &= 3 \cdot \ln n \cdot Z^*_{LP} \end{aligned}$$

Thus, using the method of cond. exp., we can find a sol with $\int \le E[\int] \le 3 \cdot \ln n \cdot Z^*_{LP}$, and by (*), such a sol is a set cover.

To derandomize the alg. we must be able to calculate conditional exp values, i.e., calculate $E[f]$, given that decisions about $S_1, \ldots, S_\ell$ have already been made:

$$E[f \mid \vec{X}_\ell] = \sum_{j=1}^{\ell} X_j w_j + \sum_{j=\ell+1}^{m} x_j w + \lambda E[z \mid \vec{X}_\ell]$$

where $\vec{X}_\ell = (X_1, X_2, \ldots, X_\ell)$, and $E[z \mid \vec{X}_\ell]$ can be calculated in the following way.

For each element e_i

$$\Pr[e_i \text{ covered} \mid \vec{X}_\ell]$$

$$= \begin{cases} 1, & \text{if } e_i \text{ is contained in a set } S_j \text{ s.t. } j \le \ell \text{ and } X_j = 1 \quad (\text{i.e., } e_i \text{ is covered by one of the sets } S_1, \ldots, S_\ell) \\ 1 - \underbrace{\prod_{j : e_i \in S_j \wedge j > \ell} (1 - x_j)}, & \text{otherwise} \end{cases}$$

prob. that e_i will not be covered by any of the sets $S_{\ell+1}, \ldots, S_m$

$$E[z \mid \vec{X}_\ell] = 1 - \prod_{i=1}^{n} \Pr[e_i \text{ covered} \mid \vec{X}_\ell]$$

DeRR$_2$

Solve LP optimally

For $i \leftarrow 1$ to n

If $E[f \mid (x_1, x_2, \ldots, x_{i-1}, 0)] \leq E[f \mid (x_1, x_2, \ldots, x_{i-1}, 1)]$

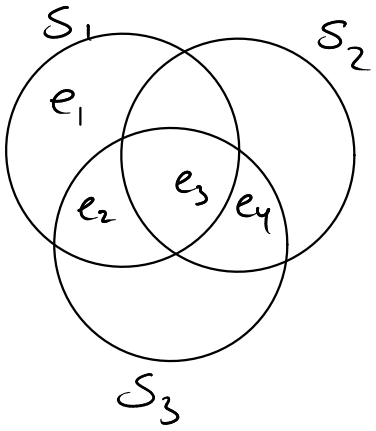
$x_i \leftarrow 0$

Else

$x_i \leftarrow 1$

Greedy recap.

Ex:



	Price per element	
	1. it.	2. it.
$w_1 = 12$	4	(6)
$w_2 = 4$	(2)	–
$w_3 = 9$	3	9

1. Pick S_2 $\rightarrow$ $price(e_3) = price(e_4) = 2$
2. Pick S_1 $\rightarrow$ $price(e_1) = price(e_2) = 6$

Total weight

$= w_2 + w_1$

$= (price(e_3) + price(e_4)) + (price(e_1) + price(e_2))$

$= (2+2) + (6+6)$

$= 16$

Let $g = \max\{|S_j| \mid S_j \in \mathcal{S}\}$.

Thm 1.12

Alg. 1.2 is an H_g-approx. alg. for Set Cover

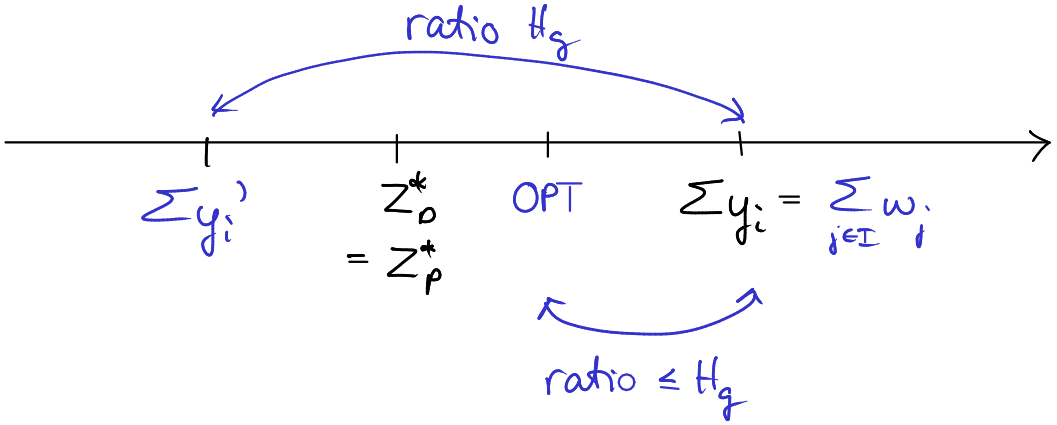
Proof: By Dual Fitting:
Consider the dual D of the LP for Set Cover.
We will construct an infeasible solution $\vec{y}$ and a feasible solution $\vec{y}'$ such that

- $\sum_{i=1}^{n} y_i = \sum_{j \in I} w_j$
- $y_i' = \frac{y_i}{H_g}$, $1 \le i \le n$

Then,

$$\sum_{j \in I} w_j = \sum_{i=1}^{n} y_i = H_g \sum_{i=1}^{n} y_i' \le H_g Z_D^* \le H_g \cdot OPT,$$

proving the claimed approximation factor.



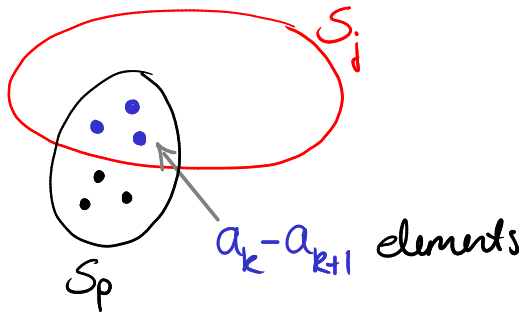
For $1 \le i \le n$, let $y_i = \text{price}(e_i)$. Then,

$$\sum_{1 \le i \le n} y_i = \sum_{j \in I} w_j$$

Hence, we just need to show that $\vec{y}$ is feasible:

Consider an arbitrary set S_j.

Let a_k be #uncovered elements in S_j at the beginning of the k'th iteration.
Let S_p be the set chosen by Greedy in the k'th iteration.
S_p covers $a_k - a_{k+1}$ previously uncovered elements in S_j



The price per element in S_j covered in the k'th iteration is at most

$$\frac{w_p}{|\hat{S}_p|} \le \frac{w_j}{a_k}$$

since otherwise S_j would be a more greedy choice. ↯

Thus,

$$\sum_{e_i \in S_j} y_i \leq \overbrace{\sum_{k=1}^{r} (a_k - a_{k+1}) \frac{w_j}{a_k}}^{\text{Total \#items} = |S_j|, \text{ since } a_1 = |S_j| \text{ and } a_{r+1} = 0}$$

$$\leq w_j \sum_{i=1}^{|S_j|} \frac{1}{i}, \quad \text{by the same arguments as in the proof of Thm 1.12.}$$

$$\leq w_j \sum_{i=1}^{g} \frac{1}{i}$$

$$= w_j \cdot H_g$$

Hence,

$$\sum_{e_i \in S_j} y_i' = \frac{1}{H_g} \sum_{e_i \in S_j} y_i \leq w_j$$

□

Compare the proof of Thm 1.12 (dual fitting) to the proof of Thm 1.11:

- Simpler: Compare prices to w_j instead of OPT
- Stronger result: H_g instead of H_n
  (could also have been obtained with the technique of the proof of Thm 1.11)

Ex from before:

$y_3 = y_4 = 2$

$y_1 = y_2 = 6$

$H_3 = 1 + \frac{1}{2} + \frac{1}{3} = \frac{11}{6}$

$y_3' = y_4' = \frac{1}{H_3} \cdot 2 = \frac{6}{11} \cdot 2 = \frac{12}{11}$

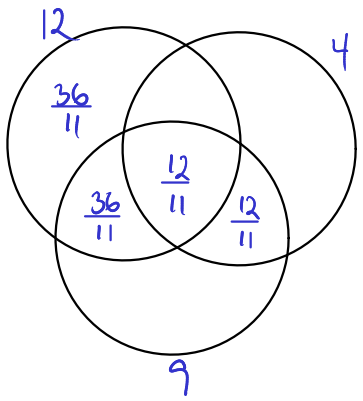
$y_1' = y_2' = \frac{6}{11} \cdot 6 = \frac{36}{11}$

$\vec{y'}$ is feasible:

$y_1' + y_2' + y_3' = 2 \cdot \frac{36}{11} + \frac{12}{11} < 8 \leq w_1$

$y_3' + y_4' = 2 \cdot \frac{12}{11} < 3 \leq w_2$

$y_2' + y_3' + y_4' = \frac{36}{11} + 2 \cdot \frac{12}{11} < 6 \leq w_3$

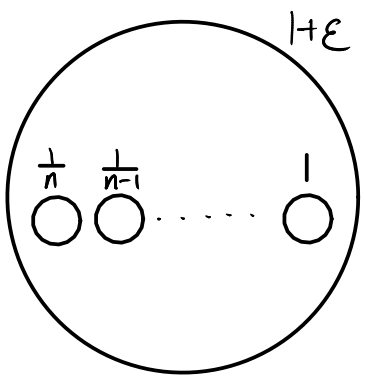


Is the upper bound of H_n tight?

If it is, the matching lower bound must come from an instance with

- one set containing all elements
  (follows from the upper bound of H_3)
- only one additional element covered in each it.
  (otherwise, some of the terms in $\frac{1}{n} + \frac{1}{n-1} + \dots + 1$ would be replaced by smaller terms.)

Ex:



Section 3.1: The Knapsack Problem

Knapsack

Input:

Knapsack with a capacity $B \in \mathbb{Z}^+$

Items $I = \{1, 2, \ldots, n\}$

Item i has size $s_i \in \mathbb{Z}^+$ and value $v_i \in \mathbb{Z}^+$

Objective:

Find a set of items with total size $\leq B$ and largest possible total value

Greedy alg.:

Consider items in order of decreasing v/s-ratio

Does not have any constant approx. ratio:

Ex:

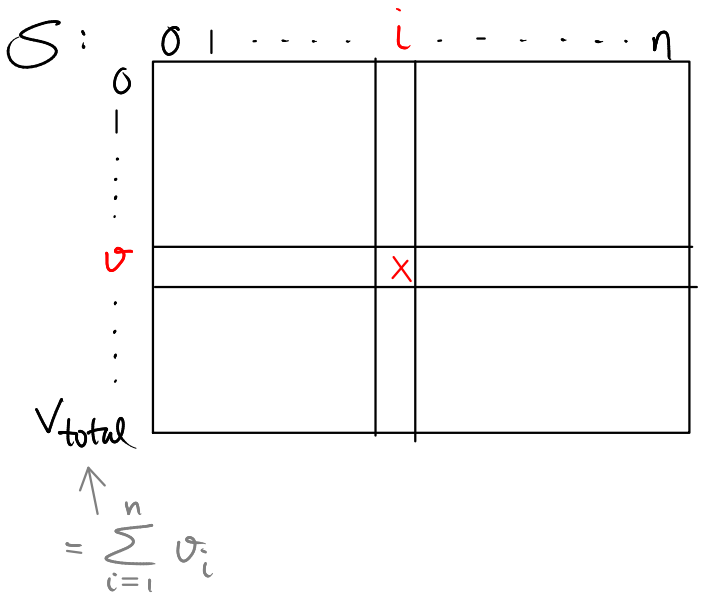
$s_1 = v_1 = 1 \longrightarrow v_1/s_1 = 1$

$s_2 = B, \; v_2 = B-1 \longrightarrow v_2/s_2 = 1 - \frac{1}{B}$

Greedy $= 1$

OPT $= B-1$

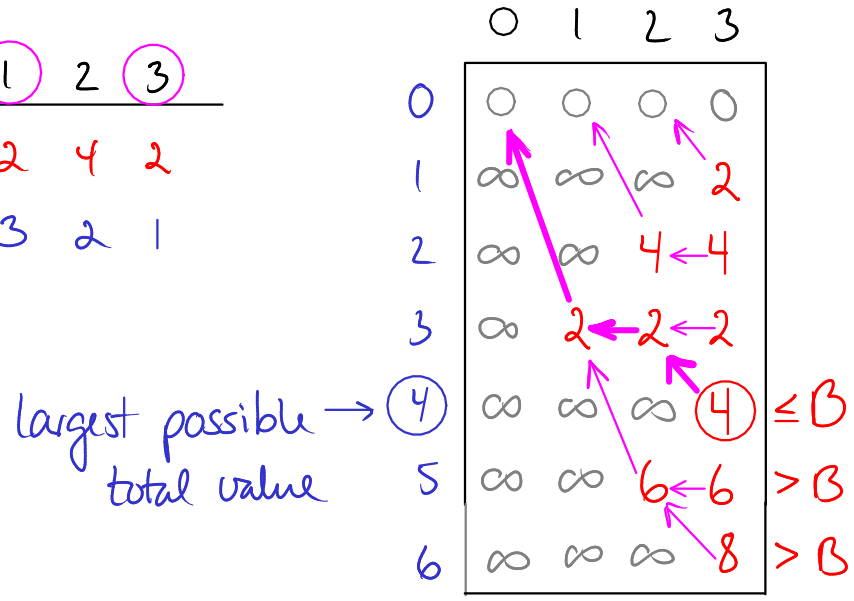
Dynamic prg alg:



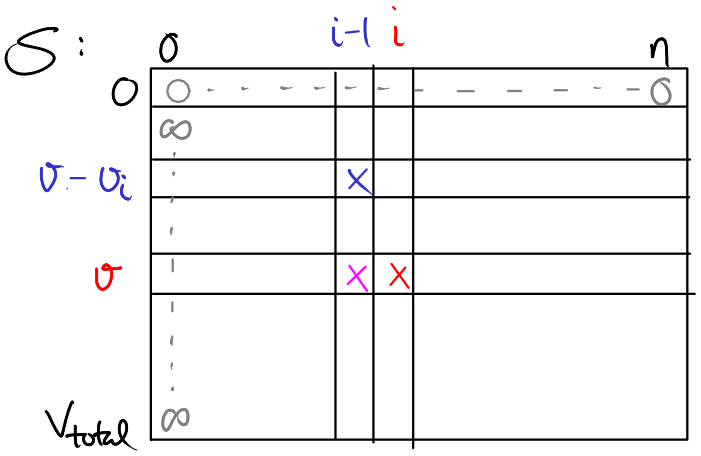
$S_{v,i}$: smallest possible total size of subset of items $1, \ldots, i$ with total value v.

Ex: $B = 5$

	1	2	3
size	2	4	2
value	3	2	1



What are the rules for filling the table?



$S_{v,i}$: smallest possible total size of subset of items $1, \ldots, i$ with total value v.

If $i = 0$ and $1 \le v \le V_{total}$

$S_{v,i} = \infty$

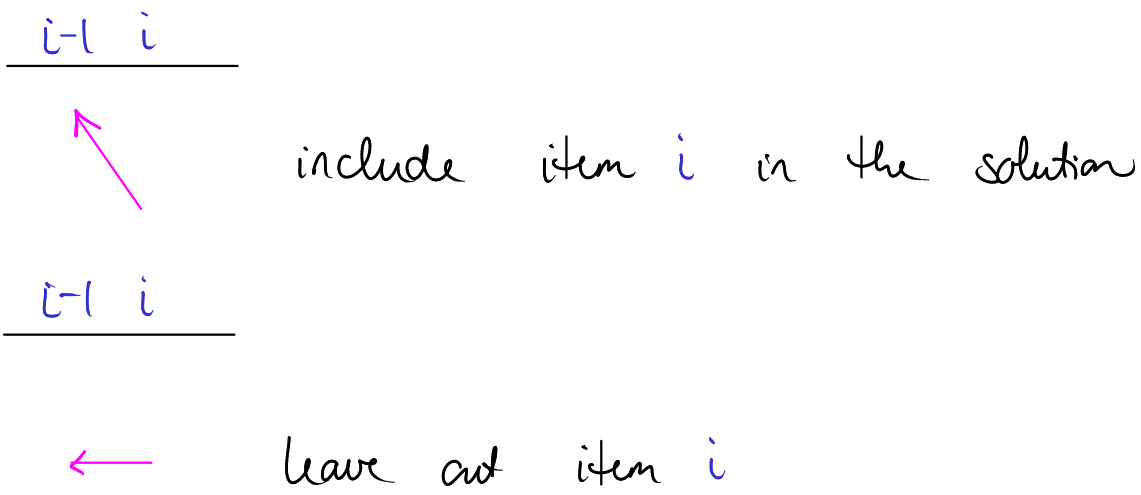
Otherwise,

$$S_{v,i} = \begin{cases} 0, & \text{if } v = 0 \\ S_{v,i-1}, & \text{if } 0 < v < v_i \\ \min\{S_{v,i-1}, S_{v-v_i,i-1} + s_i\}, & \text{if } v \ge v_i \end{cases}$$

$S_{v,i-1}$: best solution without item i

$S_{v-v_i,i-1} + s_i$: best solution with item i

How do we determine which items to select to obtain the optimal value?



We don't have to store all columns, and we don't necessarily have to fill in all entries:

Alg 3.1:

$A[1] \leftarrow \{(0,0), (s_1, v_1)\}$
For $i \leftarrow 2$ to n
  $A[i] \leftarrow A[i-1]$
  For each $(S,V) \in A_{prev}$
    If $S + s_i \leq B$
      $A[i] \leftarrow A[i] \cup \{(S+s_i, V+v_i)\}$
  Remove dominated pairs from $A[i]$
Return $\max_{(S,V) \in A[n]} \{V\}$

Note that the alg. returns only the value of an optimal solution, not the corresponding set of items.

It is, however, possible to find the optimal solution set in asymptotically the same time and in $O(V_{total})$ space.

Analysis:

Running time: $O(n \cdot V_{total})$

Input size: $O(\log B + n(\log M + \log S))$, where

$M = \max_{1 \le i \le n} \{v_i\}$ and $S = \max_{1 \le i \le n} \{s_i\}$.

Poly. time?

Ex: $V_{total} = 2^n$

$\log B = \log M = \log S = n$

$\Rightarrow$ Running time $O(n \cdot 2^n)$

Input size $O(n^2)$

No.

But if the numeric part of the input (i.e., B, v_i, s_i) were written in unary, the input size would be $\Theta(B + V_{total} + S_{total})$, and the running time would be poly. in the input size.
Hence, the running time is pseudopolynomial.

Note: if V_{total} is poly. in n for all possible input instances, the dyn. prg. alg. is poly.
Leading to the following idea.

Idea for approximation algorithm:

Round values s.t. there are only a poly. number of (equidistant) values:

- Choose a value μ
- Round down each item value to the nearest multiple of μ
- Do dyn. prg. on the rounded values

How to choose μ?

- Approximation:
  When rounding, each item looses a value of less than μ. Hence, the value of any solution is changed by less than $n\mu$.
  Thus, if we want a precision of ε,
  $$\mu = \frac{\varepsilon M}{n}$$
  will do, since then $n\mu = \varepsilon M \leq \varepsilon \cdot OPT$.
  (We will add more detail to this argument in the proof of Thm 3.5.)

- Running time:
  $$n \cdot \frac{V_{total}}{\mu} \leq n \cdot \frac{nM}{\mu} = \frac{1}{\varepsilon} \cdot n^3$$

Since each rounded value is a multiple of μ, we might as well scale by a factor of $\frac{1}{\mu}$ s.t. the possible values will be $1, 2, \ldots, \lfloor \frac{V_{total}}{\mu} \rfloor$ instead of $\mu, 2\mu, \ldots, \lfloor \frac{V_{total}}{\mu} \rfloor \mu$:

Alg 3.2

$M \leftarrow \max_{1 \le i \le n} v_i$

$\mu \leftarrow \frac{\varepsilon M}{n}$

for $i \leftarrow 1$ to n

$\quad v_i' \leftarrow \lfloor \frac{v_i}{\mu} \rfloor$

Do dyn. prg. with values v_i' (and sizes s_i)

Theorem 3.5

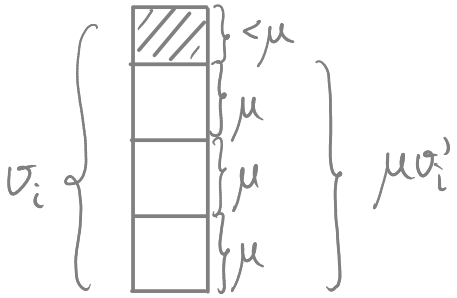
Alg. 3.2 is a $(1-\varepsilon)$-approx. alg. with a running time poly. in both input size and $\frac{1}{\varepsilon}$

Proof:

Approximation ratio:

For each item i, $\mu v_i'$ equals v_i rounded down to the nearest multiple of μ. (*)

Thus, $v_i - \mu v_i' < \mu$ (each item "loses" less than μ in the rounding.) (**)



Let S be the set of items selected by Alg. 3.2

This is an optimal solution to the instance with values v_i', and hence, to the instance with values $\mu v_i'$. (***)

Let O be the set of items in an optimal solution to the original instance with values v_i.

The total value produced by Alg. 3.2 is

$$\begin{aligned}
\sum_{i \in S} v_i &\geq \sum_{i \in S} \mu v_i', && \text{by } (*) \\
&\geq \sum_{i \in O} \mu v_i', && \text{by } (***) \\
&> \sum_{i \in O} (v_i - \mu), && \text{by } (**) \\
&\geq \left(\sum_{i \in O} v_i\right) - n\mu, && \text{since } |O| \leq n \\
&= \mathrm{OPT} - \varepsilon M \\
&\geq (1-\varepsilon)\,\mathrm{OPT}, && \text{since } \mathrm{OPT} \geq M
\end{aligned}$$

Running time:
See above.

□

According to Thm 3.5, Alg. 3.2 is a

fully polynomial time approximation scheme (FPTAS)

- fully: also poly. in $1/\varepsilon$
- polynomial time: poly. in input size
- approximation scheme: Family $\{A_\varepsilon\}$ of alg., where A_ε has precision ε.

($(1-\varepsilon)$-approx. alg for max. problems, $(1+\varepsilon)$-approx. alg for min. problems)

fully: Def. 3.4

polynomial time approximation scheme (FPTAS): Def. 3.3

Thus, Thm 3.5 could also be stated like this:

Theorem 3.5: Alg 3.2 is a FPTAS

In the Multiple Knapsack problem, there are a fixed number of knapsacks.

Bin Packing can be seen as a dual problem of Multiple Knapsack:

In the **Bin Packing** problem, there is an unlimited supply of bins, all of size 1. The aim is to pack all items in as few bins as possible.

Simple approx. algs:		Asymptotic approx. ratio
Next-Fit	(NF)	2
First-Fit	(FF)	1.7
Best-Fit	(BF)	1.7
Next-Fit-Decreasing	(NFD)	≈ 1.69
First-Fit-Decreasing	(FFD)	1.222...
Best-Fit-Decreasing	(BFD)	1.222...

Approx. scheme?

Can we do the same kind of rounding for Bin Packing as we did for Knapsack?

Section 3.3 : The Bin Packing Problem

Last time we discussed simple approx. alg.s
Today we will develop an approximation scheme.

Approximation scheme $\{A_\varepsilon\}$:

1. Transform $I \to I''$:
   a. Remove all items smaller than $\varepsilon/2$. $(I \to I')$
      $\Rightarrow O(\frac{1}{\varepsilon})$ items fit in one bin
   b. Round up sizes of remaining items $(I' \to I'')$
      $\Rightarrow O(1)$ different item sizes
2. Do dyn. prg. on I''
   $\Rightarrow A_\varepsilon(I'') = OPT(I'')$
3. Add small items to the packing using First-Fit (or any other Any-fit alg.)

Adding small items to the packing (3.)

Lemma 3.10

$$A_\varepsilon(I) \le \max\left\{A_\varepsilon(I''), \frac{2}{2-\varepsilon}\,size(I)+1\right\}$$

Proof:

If no extra bin is needed for adding the small items, $A_\varepsilon(I) = A_\varepsilon(I'')$.

Otherwise, all bins, except possibly the last one, are filled to more than $1-\varepsilon/2$.

In this case,

$$A_\varepsilon(I) \le \left\lceil \frac{size(I)}{1-\varepsilon/2} \right\rceil \le \frac{size(I)}{1-\varepsilon/2} + 1$$

$$= \frac{2}{2-\varepsilon}\,size(I) + 1$$

□

Section 3.3: The Bin Packing Problem

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Today we will develop an approximation scheme.

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   b. Round up sizes of remaining items $(I' \to I'')$
      $\Rightarrow O(\frac{1}{\varepsilon^2})$ different item sizes
2. Do dyn. prg. on I''
   $\Rightarrow A_\varepsilon(I'') = OPT(I'')$
3. Add small items to the packing using First-Fit (or any other Any fit alg.)

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$$= \frac{2}{2-\varepsilon}\,size(I) + 1$$

□

Rounding scheme (1.b)

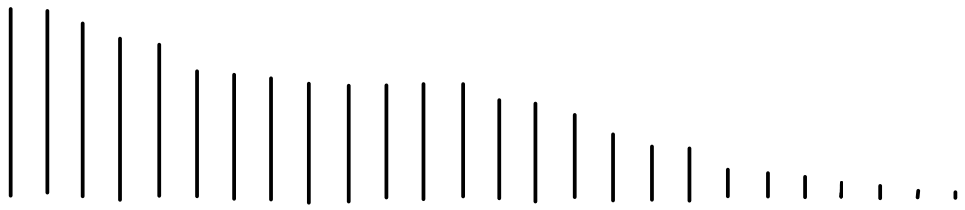
Last time we saw that a rounding scheme similar to the one we used for Knapsack would at best yield an approx. factor of 1.5.
Instead, we will use:

Linear grouping:
- Sort items in I' by decreasing sizes.
- Partition items in groups of k consecutive items. (k will be determined later)
- For each group, round up item sizes to largest size in the group.

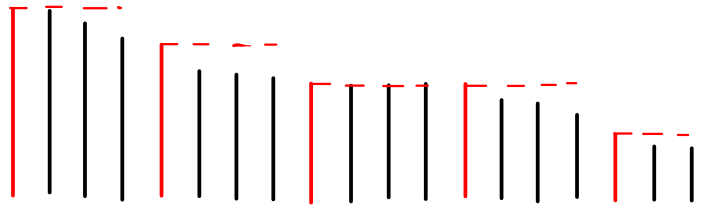
The result is called I''.

Ex: ($k=4$)

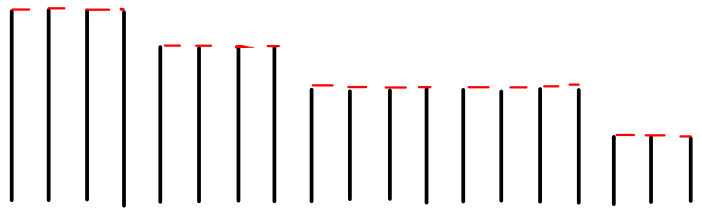
I:



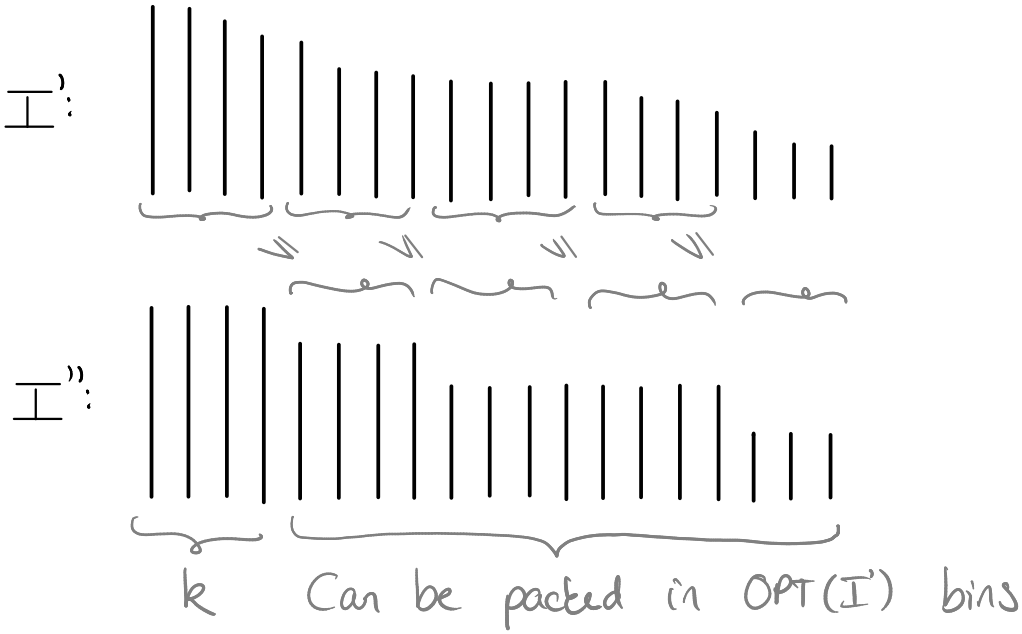
I':



I'':



Each item in the i'th group of I' is at least as large as any item in the $(i+1)$st group of I'':



Thus, for any packing of I', there is a packing of all but the first group of I'' using the same number of bins.
Since the first group of I'' can be packed in at most k bins, this proves:

Lemma 3.11: $OPT(I'') \leq OPT(I') + k$

Packing I'' using dyn. prg. (2.)

We will use the same approach as in Section 3.2:

Since all items in I'' have size at least $\varepsilon/2$, at most $2/\varepsilon$ items fit into each bin.

There are $N \leq \lceil n/k \rceil$ different item sizes $s_1, s_2, \ldots, s_N$ in I''.

Hence, any packing of a bin can be represented by a vector $(m_1, m_2, \ldots, m_N)$, $m_i \leq 2/\varepsilon$, where m_i is the number of items of size s_i in the bin.
A vector representing the contents of a bin is called a bin configuration.
Let $\mathcal{C}$ be the set of possible bin configurations.
Note that $|\mathcal{C}| < (2/\varepsilon)^N$.

For the dyn. prg. we will use an N-dimensional table B with n_i+1 rows in the i'th dimension, where n_i is the number of items of size s_i in I''.
$B[m_1, m_2, \ldots, m_N]$ will be the minimum number of bins required to pack m_i items of size s_i, $1 \leq i \leq N$.

Ex:

$\varepsilon = 0.4$

$I = 0.6, 0.5, 0.4, 0.4, 0.3, \underbrace{0.1, 0.1}_{< \varepsilon/2}$

Choosing $k=3$, we obtain

$I' = \underbrace{0.6, 0.5, 0.4}, \underbrace{0.4, 0.3}$

$I'' = 0.6, 0.6, 0.6, 0.4, 0.4$

$s_1 = 0.6, \quad s_2 = 0.4$

$n_1 = 3, \quad n_2 = 2$

$\mathcal{C} = \{(0,1), (0,2), (1,0), (1,1)\}$

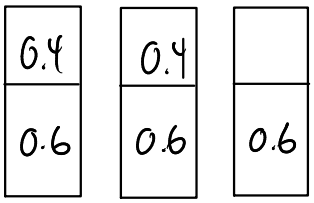
B:

0.6 \ 0.4	0	1	2
0	0	1	1
1	1	1	2
2	2	2	2
3	3	3	3

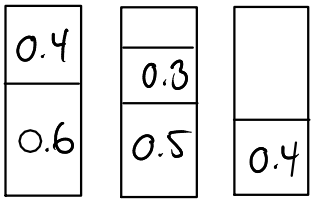
$$B[3,2] = 1 + \min_{(m_1,m_2)\in\mathcal{C}} \{B[3-m_1, 2-m_2]\}$$

$$= 1 + \min\{B[3,1], B[3,0], B[2,2], B[2,1]\}$$

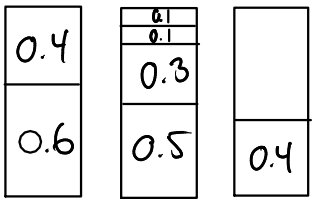
Packing of I'' :



Packing of I':



Packing of I:



Approximation

$$A_\varepsilon(I) \le \max\left\{ A_\varepsilon(I''),\ \frac{2}{2-\varepsilon}\,\text{size}(I)+1 \right\},\ \text{by Lemma 3.10}$$

$$\le \max\left\{ OPT(I''),\ \frac{2}{2-\varepsilon}\,OPT(I)+1 \right\},\ \text{since}$$

$$A_\varepsilon(I'') = OPT(I'') \text{ and } OPT \ge \text{size}(I)$$

$$\le \max\left\{ OPT(I')+k,\ \frac{2}{2-\varepsilon}\,OPT(I)+1 \right\},\ \text{by Lemma 3.11}$$

$$\le \max\left\{ OPT(I)+k,\ \frac{2}{2-\varepsilon}\,OPT(I)+1 \right\},\ \text{since } I' \le I$$

$$\frac{2}{2-\varepsilon} \le 1+\varepsilon \iff 2 \le (2-\varepsilon)(1+\varepsilon)$$

$$\iff 2 \le 2+\varepsilon-\varepsilon^2$$

$$\iff \varepsilon \le 1$$

Thus, we just need to choose an appropriate value of k to obtain $k \le \varepsilon \cdot OPT(I)$:

$$k = \lfloor \varepsilon \cdot \text{size}(I) \rfloor$$

With this value of k

$$A_\varepsilon(I) \le (1+\varepsilon)\cdot OPT(I) + 1$$

asymptotic approximation scheme

Running time

$k = \lfloor \varepsilon \cdot size(I) \rfloor \geq \lfloor \varepsilon \cdot n' \cdot \frac{\varepsilon}{2} \rfloor \geq n' \cdot \frac{\varepsilon^2}{4}$, where $n' = |I'|$,
since all items in I' have size at least $\varepsilon/2$.

$N \leq \lceil \frac{n'}{k} \rceil \leq \lceil \frac{4}{\varepsilon^2} \rceil$

Table size $\leq (n')^N \leq n^N$

Time per entry $O(|\mathcal{C}|) \leq O((\frac{2}{\varepsilon})^N)$

Running time $O((\frac{2}{\varepsilon})^N n^N) \leq O((\frac{2n}{\varepsilon})^{\lceil 4/\varepsilon^2 \rceil})$

not fully poly. time

Hence, $\{A_\varepsilon\}$ is an
Asymptotic poly. time approx. scheme (APTAS)

This proves:

Theorem 3.12: There is an APTAS for Bin Packing

There is no PTAS for Bin Packing:

Theorem 3.8

No approx alg. for Bin Packing has an absolute approx. ratio better than $3/2$, unless $P = NP$.

Proof:

Reduction from Partition Problem (given a set S of integers, can S be partitioned into two sets S_1 and S_2 such that $\sum_{s \in S_1} s = \sum_{s \in S_2} s$?)

Let $B = \sum_{s \in S} s$.

Scale each integer by $\frac{2}{B}$, resulting in a set of numbers with sum 2.
Use these numbers as input for the bin packing problem.

Clearly, at least 2 bins are needed, and 2 bins are sufficient, if and only if the instance of the Partition problem is a yes-instance.

Thus, any Bin Packing alg. with an approx. ratio smaller than $3/2$ will use exactly 2 bins, if and only if the input to the Partition problem is a yes-instance. □

Section 2.3: Scheduling to minimize makespan

Makespan Scheduling on Parallel Machines

Input:

m machines

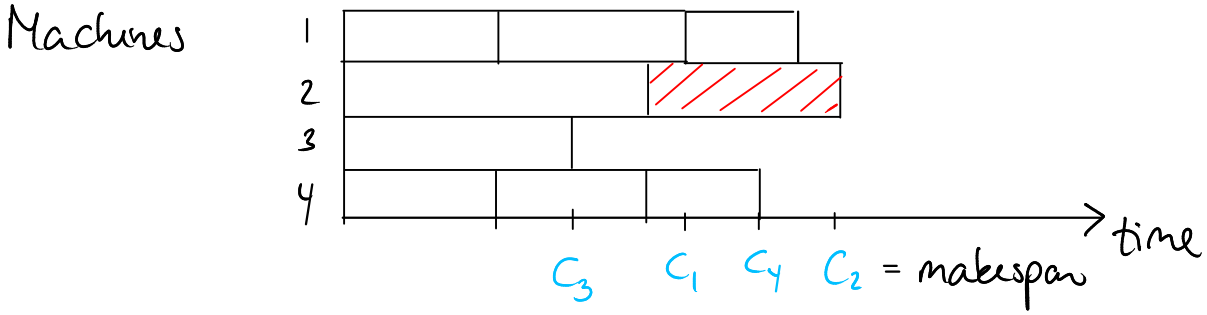
n jobs with processing times $p_1, p_2, \ldots, p_n \in \mathbb{Z}^+$

Output:

Assignment of jobs to machines s.t. the makespan is minimized

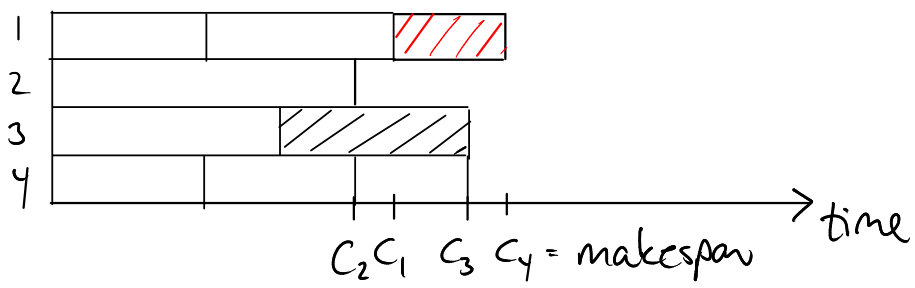
↑ time when last job finishes

Ex:



$$\text{makespan} = \max\{C_1, C_2, C_3, C_4\} = C_2$$

How could this schedule be improved?



Local Search Alg:

Repeat
  job $\ell \leftarrow$ job that finishes last
  If there is any machine i where job ℓ would finish earlier
    Move job ℓ to machine i
Until job ℓ is not moved

Theorem 2.5

The local search alg. is a $(2-\frac{1}{m})$-approx. alg.

Proof:

Lower bounds on OPT:

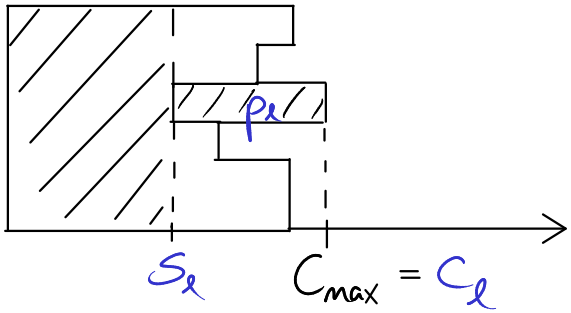
$OPT \geq p_{max} = \max_{1 \leq j \leq n} p_j$,

because the machine i with the largest job j has $C_i \geq p_j$.

$OPT \geq \frac{P}{m}$, where $P = \sum_{j=1}^{n} p_j$

since this is the average completion time of the machines.

Upper bound on alg.'s makespan:



$P \geq m \cdot S_\ell + p_\ell$, since all machines are busy until S_ℓ

$\Downarrow$

$$S_\ell \leq \frac{P - p_\ell}{m}$$

$$p_\ell \leq p_{max}$$

$$\begin{aligned} C_{max} &= S_\ell + p_\ell \\ &\leq \frac{P - p_\ell}{m} + p_\ell \\ &= \frac{P}{m} + \left(1 - \frac{1}{m}\right) p_\ell \\ &\leq OPT + \left(1 - \frac{1}{m}\right) OPT \\ &= \left(2 - \frac{1}{m}\right) OPT \end{aligned}$$

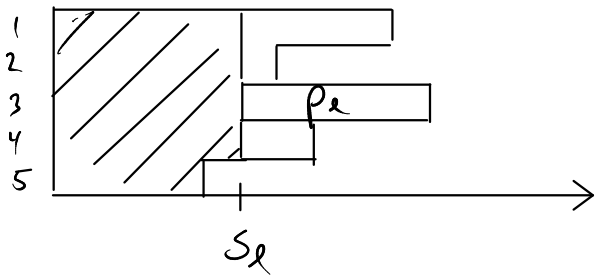
□

What would be a natural greedy alg.?

List Scheduling (LS)

For $j \leftarrow 1$ to n
    Schedule job j on currently least loaded machine

What is the approx. ratio of LS?
What properties of the local search alg. did we use to prove $2-\frac{1}{m}$?
We used only the fact that all machines are busy at least until S_ℓ.
Is this also true for LS?
Yes:



LS would not have placed job ℓ on machine 3.

Theorem 2.6: LS is a $(2-\frac{1}{m})$-approx. alg.

Note that $\frac{C_\ell}{OPT} < 2-\frac{1}{m}$, unless $\rho_\ell = \rho_{max}$

Thus, it seems advantageous to schedule short jobs last.

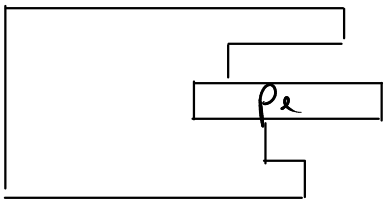
Longest Processing Time (LPT)

For each job j, in order of decreasing processing times
Schedule job j on currently least loaded machine

Theorem 2.7: LPT is a $(4/3 - \frac{1}{3m})$-approx. alg.

Proof:
Number the jobs s.t. $p_1 \geq p_2 \geq \dots \geq p_n$.
Then the indices indicate the order in which the jobs are scheduled.

Let job l be a job to finish last:



We can assume that $l = n$:
Let $I = \{p_1, p_2, \dots, p_n\}$ and $I' = \{p_1, p_2, \dots, p_l\}$.
Then, $LPT(I) = LPT(I')$, since jobs $l+1, \dots, n$ finish no later than job l.
Moreover, $OPT(I') \leq OPT(I)$.
Thus, if we prove $LPT(I')/OPT(I') \leq 4/3$, we have proven $LPT(I)/OPT(I) \leq 4/3$ (since $LPT(I)/OPT(I) \leq LPT(I')/OPT(I')$).

(Or said in a different way, we can ignore the jobs $l+1, \dots, n$.)

Thus, we can assume that no job is shorter than job l. (This will be used in Case 2 below.)

Case 1: $p_\ell \le \frac{1}{3} \cdot OPT$

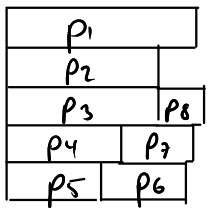
By the proof of Thm 2.5,

$$LPT \le OPT + \frac{m-1}{m} p_\ell \le OPT + \frac{m-1}{m} \cdot \frac{1}{3} OPT$$
$$= \left(\frac{4}{3} - \frac{1}{3m}\right) OPT$$

Case 2: $p_\ell > \frac{1}{3} \cdot OPT$

In this case, all jobs are longer than $\frac{1}{3} \cdot OPT$. Hence, in OPT's schedule, each machine has ≤ 2 jobs, i.e., $n \le 2m$.

In this case, $LPT = OPT$:



Proof of this claim: Exercise 22

□

From the proof of Thm 2.7 we learned:
If job ℓ is longer than $\frac{1}{3} \cdot OPT$, then $LPT = OPT$.
Otherwise, $LPT \leq OPT + p_\ell \leq \frac{4}{3} \cdot OPT$.
(Recall that job ℓ is the job to finish last.)

Could we balance the two cases better?

What if we first schedule all jobs of length $\geq \frac{1}{4} \cdot OPT$ optimally, and then use LPT for the remaining jobs?
What would the approximation ratio be?
Does the schedule of the long jobs have to be optimal?

Section 3.2: Makespan Scheduling - A PTAS

Idea for PTAS:

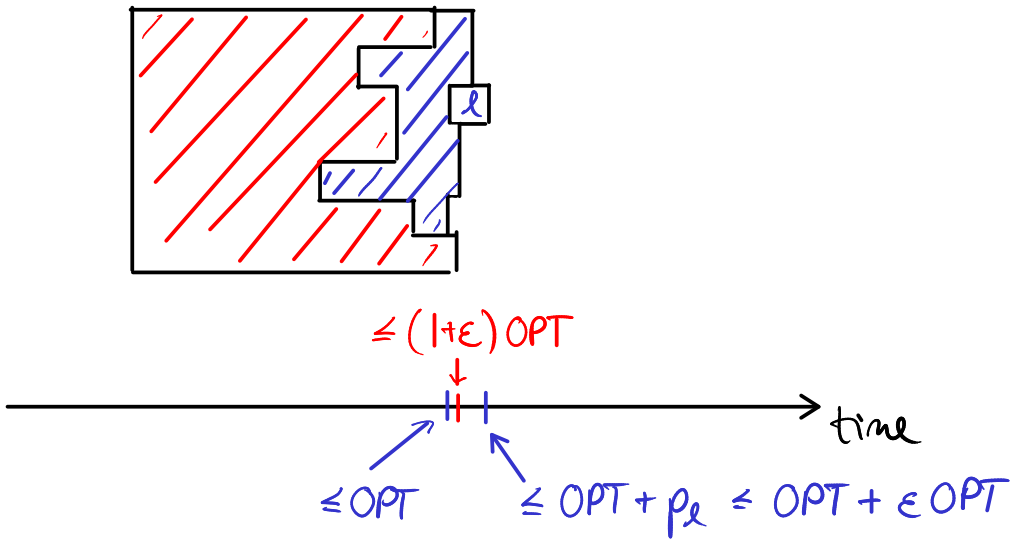
Partition the jobs into two sets (long and short jobs):

$> \varepsilon \cdot OPT$ $\quad$ $\leq \varepsilon \cdot OPT$

$p_1, p_2, \ldots, p_x$ $\quad$ $p_{x+1}, \ldots, p_n$

Schedule using rounding and dyn. prg. as for bin packing

Then use LPT



We will derive a family of algorithms with an algorithm, B_k, for each $k \in \mathbb{Z}^+$. $(\varepsilon = \frac{1}{k})$

How to identify long/short jobs when we don't know OPT?

Scheduling the long jobs:

(1) „Guess" an optimal makespan T

(2) The long jobs are those longer than T/k^2.
Round down each job size to the nearest multiple of T/k^2.

(3) Use dyn. prg. to check whether optimal makespan $\leq T$ for rounded long jobs.

Do binary search for T on the interval $[L, U]$, where

$$L = \max\left\{\left\lceil \frac{P}{m} \right\rceil, p_{max}\right\}$$

$$U = \left\lfloor \frac{P - p_{max}}{m} + p_{max} \right\rfloor = \left\lfloor \frac{P + (m-1)\, p_{max}}{m} \right\rfloor$$

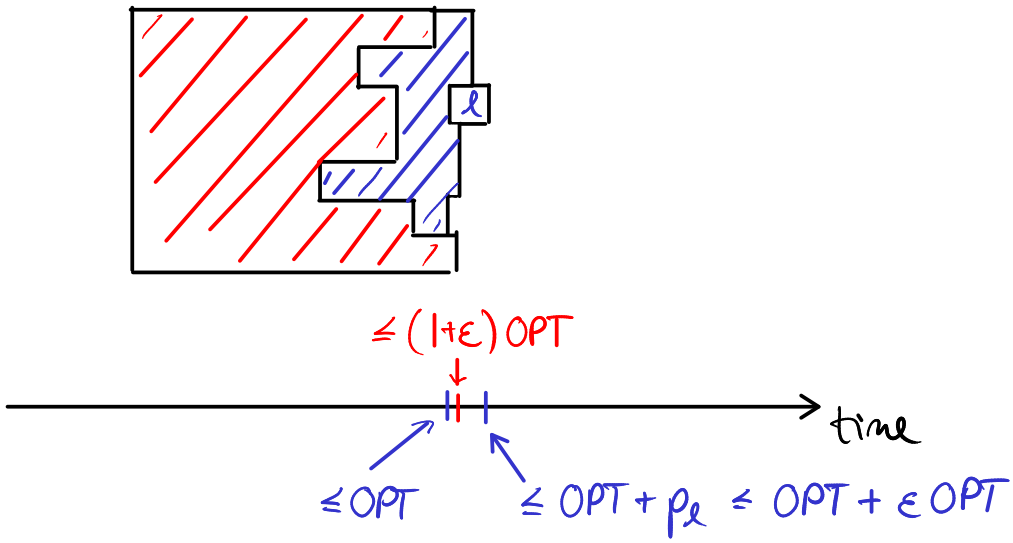
Section 3.2: Makespan Scheduling - A PTAS

Idea for PTAS:

Partition the jobs into two sets (long and short jobs):

$> \varepsilon \cdot OPT$: $p_1, p_2, \ldots, p_x$ — Schedule using rounding and dyn. prg. as for bin packing

$\leq \varepsilon \cdot OPT$: $p_{x+1}, \ldots, p_n$ — Then use LPT



We will derive a family of algorithms with an algorithm, B_k, for each $k \in \mathbb{Z}^+$. $(\varepsilon = \frac{1}{k})$

How to identify long/short jobs when we don't know OPT?

We need the short jobs to be $\leq \varepsilon \cdot OPT$ to ensure the approx. factor. For this purpose, we could use any lower bound on OPT, like P/m.

But we also need the long jobs to be $\geq \varepsilon \cdot OPT$ to ensure the approx. factor as well as the running time.

Scheduling the long jobs:

(1) „Guess" an optimal makespan T

(2) The long jobs are those longer than T/k^2.
Round down each job size to the nearest multiple of T/k^2.

(3) Use dyn. prg. to check whether optimal makespan $\leq T$ for rounded long jobs.

Do binary search for T on the interval $[L, U]$, where

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$B_k(I)$

$L \leftarrow \max\left\{ \lceil \frac{P}{m} \rceil, p_{max} \right\}$; $U \leftarrow \left\lceil \frac{P + (m-1)\, p_{max}}{m} \right\rceil$

Binary search for T:

While $L \neq U$

$T \leftarrow \frac{1}{2} \lceil L+U \rceil$

$I' \leftarrow \{ \text{job } j \in I \mid p_j > T/k \}$ // Update set of long jobs

$I'' \leftarrow$ I' with each job size rounded down to nearest multiple of T/k^2

Use dyn. prg. to pack I'' in bins of size T

If #bins $\leq m$

$U \leftarrow T$

else

$L \leftarrow T+1$

$S'' \leftarrow$ schedule of I'' corresponding to the packing found by dyn. prg.

$S' \leftarrow$ schedule of I' corresponding to S''

$S \leftarrow$ schedule of I obtained by adding short jobs to S' using LPT

Dyn. prg. as for bin packing:

S" places $\leq k$ jobs on each machine:

Each long job has size $\geq T/k$

Since T/k is a multiple of T/k^2, each job in I" also has size $\geq T/k$.

There are $\leq k^2$ different job sizes in I", since no job is longer than T.

Hence, the configuration of a machine can be represented by a vector $(s_1, s_2, \ldots, s_{k^2})$, where $0 \leq s_i \leq k$.

Thus, $|\mathcal{C}| \leq (k+1)^{k^2}$.

Table (B):

$\leq k^2$ dimensions (one for each size in I")

n_i+1 rows in dim. i (n_i = # items of size $i \cdot T/k^2$ in I")

$$B(n_1, \ldots, n_{k^2}) = 1 + \min_{\vec{s} \in \mathcal{C}} \{ B(n_1 - s_1, \ldots, n_{k^2} - s_{k^2}) \}$$

Running time:

table entries: $O(n^{k^2})$

Time per entry: $|\mathcal{C}| \leq (k+1)^{k^2}$

iterations of while loop: $\log(U-L) \leq \log(p_{max})$

Total time: $O(n^{k^2} (k+1)^{k^2} \log(p_{max}))$

Approximation ratio:

When B_k terminates the while loop,

$$\text{makespan}(S'') = T = OPT(I)$$

Since each of the $\le k$ jobs on a machine loses less than T/k^2 in the rounding,

$$\begin{aligned}\text{makespan}(S') &< \text{makespan}(S'') + k \cdot \frac{T}{k^2} \\ &= T + \frac{T}{k} \\ &= \left(1 + \frac{1}{k}\right) OPT(I'') \\ &\le \left(1 + \frac{1}{k}\right) OPT(I)\end{aligned}$$

Thus, if the last job to finish is a long job,

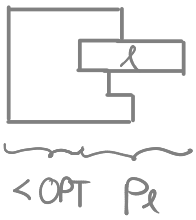
$$B_k(I) < \left(1 + \frac{1}{k}\right) OPT(I).$$

Otherwise, the last job to finish has $p_l \le \frac{I}{k} \le \frac{OPT(I)}{k}$.

Hence,

$$B_k(I) < OPT(I) + p_l \le \left(1 + \frac{1}{k}\right) OPT$$

By the same argument as in the analysis of LS:



Thus, in both cases, $B_k(I) < \left(1 + \frac{1}{k}\right) OPT$.

Theorem 3.7 : $\{B_k\}$ is a PTAS

Proof:

B_k achieves an approx. factor of $1+\varepsilon$ with running time

$$O\left(\left(\left(\frac{1}{\varepsilon}+1\right)n\right)^{\left(\frac{1}{\varepsilon}\right)^2} \cdot n \cdot \log(p_{max})\right).$$

If $\varepsilon \in O(1)$, this is poly. in the input size, since it takes $\geq \log(p_{max})$ bits to represent the job sizes. □

$\{B_k\}$ is <u>not</u> a FPTAS, since the running time is exponential in $\frac{1}{\varepsilon}$.

Note that we did not expect a FPTAS, since the problem is <u>strongly</u> NP-complete...

The problem is strongly NP-complete, meaning that even the special case where $\exists$ polynomial q s.t. $p_{max} \leq q(n)$, for all input instances, is NP-complete.

This implies that $\nexists$FPTAS, unless $P = NP$

Assume to the contrary that $\exists$FPTAS for the problem, i.e.,
$\forall \varepsilon > 0 : \exists$ $(1+\varepsilon)$-approx alg. A_ε with running time poly. in n and $\frac{1}{\varepsilon}$.

Consider the special case of the problem where $\exists$ polynomial q s.t. $p_{max} \leq q(n)$, for all instances.
In this case, $P \leq n \cdot q(n) \equiv p(n)$.

For $\varepsilon = \frac{1}{p(n)}$,

- $\frac{1}{\varepsilon}$ is poly. in n, so the running time of A_ε is poly. in n.
- $A_\varepsilon(I) \leq \left(1 + \frac{1}{p(n)}\right) \cdot OPT(I)$, for any input I
  $< OPT(I) + 1$, since $OPT(I) < P \leq p(n)$

  Thus, since $A_\varepsilon(I)$ is integer, $A_\varepsilon(I) = OPT(I)$.

If $P \neq NP$, this contradicts the fact that the problem is strongly NP-complete.