

## Section 3.1: The Knapsack Problem

### Knapsack

Input:

Knapsack with a capacity  $B \in \mathbb{Z}^+$

Items  $I = \{1, 2, \dots, n\}$

Item  $i$  has size  $s_i \in \mathbb{Z}^+$  and value  $v_i \in \mathbb{Z}^+$

Objective:

Find a set of items with total size  $\leq B$   
and largest possible total value

### Greedy alg.

Consider items in order of decreasing  $s/v$  ratio

Does not have any constant approximation factor:

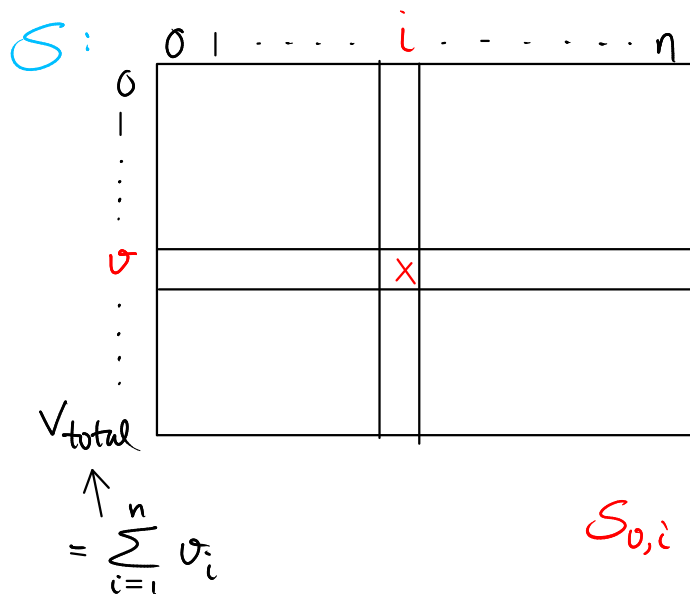
Ex:

$i$	1	2
$v_i$	1	$B-1$
$s_i$	1	$B$

$$\frac{v_1}{s_1} = 1 > \frac{v_2}{s_2} = 1 - \frac{1}{B}$$

$$\Rightarrow \text{Greedy} = 1 = \frac{1}{B-1} \cdot \text{OPT}$$

# Dynamic prg alg:



$S_{v,i}$ : smallest possible total size of a subset of  $\{1, \dots, i\}$  with total value  $v$ , i.e.,

$$S_{v,i} = \min_{I \subseteq \{1, \dots, i\}} \left\{ \sum_{j \in I} s_j \mid \sum_{j \in I} v_j = v \right\}$$

Ex:

$B=5$

$i$	1	2	3
$v_i$	3	1	2
$s_i$	2	3	2

Optimal total value  $\rightarrow$

$i \backslash v_i$	0	1	2	3
0	0	0	0	0
1	$\infty$	$\infty$	3	3
2	$\infty$	$\infty$	$\infty$	2
3	$\infty$	2	2	2
4	$\infty$	$\infty$	5	5
5	$\infty$	$\infty$	$\infty$	4
6	$\infty$	$\infty$	$\infty$	7

$4 \leq B$   
 $7 > B$

# How to fill the table

$S$ :

	0	$i-1$	$i$	$n$
0	0	...	...	...
$\infty$				
$\sigma - v_i$			x	
$\vdots$				
$\sigma$			x	x
$\vdots$				
$V_{\text{total}}$				
$\infty$				

$V_{\text{total}} \uparrow = \sum_{i=1}^n v_i$

$S_{\sigma,i}$ : smallest possible total size of a subset of  $\{1, \dots, i\}$  with total value  $\sigma$ , i.e.,

$$S_{\sigma,i} = \min_{I \subseteq \{1, \dots, i\}} \left\{ \sum_{j \in I} s_j \mid \sum_{j \in I} v_j = \sigma \right\}$$

If  $i=0$  and  $1 \leq \sigma \leq V_{\text{total}}$   
 $S_{\sigma,i} = \infty$

Otherwise,

$$S_{\sigma,i} = \begin{cases} S_{\sigma,i-1}, & \text{if } 0 \leq \sigma < v_i \\ \min \left\{ \underbrace{S_{\sigma,i-1}}_{\text{best solution without item } i}, \underbrace{S_{\sigma-v_i,i-1} + s_i}_{\text{best solution with item } i} \right\}, & \text{if } \sigma \geq v_i \end{cases}$$

Not necessary to fill in the  $\infty$ -entries  
 (  $A[i]$  corresponds to column  $i$  ):

Alg 3.1:

```
A[1] ← { (0,0), (s1, v1) }  
for i ← 2 to n  
    A[i] ← A[i-1]  
    for each (S, V) ∈ Aprev  
        if S + si ≤ B  
            A[i] ← A[i] ∪ { (S + si, V + vi) }  
    Remove dominated pairs from A[i]  
Return max(S,V) ∈ A[n] { V }
```

B = 5

i	1	2	3
v <sub>i</sub>	3	1	2
s <sub>i</sub>	2	3	2

$$A[1] = \{ (0,0), (3,2) \}$$

$$\begin{aligned} A[2] &= A[1] \cup \{ (1,3), (4,5) \} \\ &= \{ (0,0), (1,3), (3,2), (4,5) \} \end{aligned}$$

$$\begin{aligned} A[3] &= A[2] \cup \{ (2,2), (3,5), (5,4) \} \\ &= \{ (0,0), (1,3), (2,2), (3,2), (3,5), (4,5), (5,4) \} \end{aligned}$$

dominated  
by

## Analysis

Running time:  $O(n \cdot V_{\text{total}})$

Input size:  $O(\log B + n(\log M + \log S))$ , where

$$M = \max_{1 \leq i \leq n} \{v_i\} \quad \text{and} \quad S = \max_{1 \leq i \leq n} \{s_i\}.$$

Poly. time?

Ex: Consider a family of instances where

$$V_{\text{total}} = 2^n \quad \text{and}$$

$$B, S \leq 2^n$$

Then

Running time  $T(n) \in \Omega(n \cdot 2^n)$  and

Input size  $S(n) \in O(n^2)$

$$\Rightarrow T(n) \in \Omega((S(n))^{c\sqrt{n}})$$

No

But if the **numeric part** of the input (i.e.,  $B, v_i, s_i$ ) were **written in unary**, the input size would be  $\Theta(B + V_{\text{total}} + S_{\text{total}})$ , and the running time would be poly. in the input size.

Hence, the running time is **pseudopolynomial**.

**Note:** if  $V_{\text{total}}$  is poly. in  $n$  for all possible input instances, the dyn. prg. alg. is poly.

Leading to the following idea...

## Idea for approximation algorithm:

Round values st. there are only a poly. number of (equidistant) values:

- Choose a value  $\mu$
- Round down each item value to the nearest multiple of  $\mu$
- Do dyn. prg. on the rounded values

How to choose  $\mu$ ?

- Approximation:

When rounding, each item loses a value of less than  $\mu$ . Hence, the value of any solution is changed by less than  $n\mu$ .

Thus, if we want a precision of  $\epsilon$ ,

$$\mu = \frac{\epsilon M}{n}$$

will do, since then  $n\mu = \epsilon M \leq \epsilon \cdot \text{OPT}$ .

(We will add more detail to this argument in the proof of Thm 3.5.)

- Running time:

$$n \cdot \frac{V_{\text{total}}}{\mu} \leq n \cdot \frac{nM}{\mu} = n \cdot nM \cdot \frac{n}{\epsilon M} = \frac{1}{\epsilon} \cdot n^3$$

Since each rounded value is a multiple of  $\mu$ , we might as well scale by a factor of  $\frac{1}{\mu}$  s.t. the possible values will be  $1, 2, \dots, \lfloor \frac{V_{total}}{\mu} \rfloor$  instead of  $\mu, 2\mu, \dots, \lfloor \frac{V_{total}}{\mu} \rfloor \mu$ :

### Alg 3.2

$$M \leftarrow \max_{1 \leq i \leq n} v_i$$

$$\mu = \frac{\epsilon M}{n}$$

for  $i \leftarrow 1$  to  $n$

$$v_i' \leftarrow \lfloor \frac{v_i}{\mu} \rfloor$$

Do dyn. prg. with values  $v_i'$  (and sizes  $s_i$ )

### Theorem 3.5

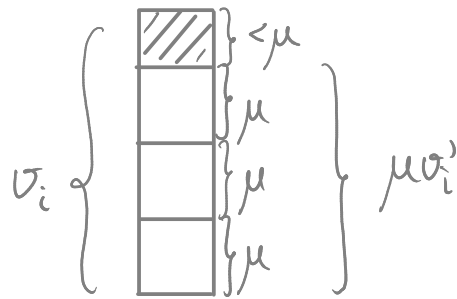
Alg. 3.2 is a  $(1-\epsilon)$ -approx. alg. with a running time poly. in both input size and  $\frac{1}{\epsilon}$

Proof:

Approximation ratio:

For each item  $i$ ,  $\mu v_i'$  equals  $v_i$  rounded down to the nearest multiple of  $\mu$ . (\*)

Thus,  $v_i - \mu v_i' < \mu$  (each item "loses" less than  $\mu$  in the rounding.) (\*\*)



Let  $A$  be the set of items selected by Alg. 3.2

This is an optimal solution to the instance with values  $v_i'$ , and hence, to the instance with values  $\mu v_i'$ . (\*\*\*)

Let  $O$  be the set of items in an optimal solution to the original instance with values  $v_i$ .



The total value produced by Alg. 3.2 is

$$\begin{aligned}\sum_{i \in A} v_i &\geq \sum_{i \in A} \mu v_i', \quad \text{by } (*) \\ &\geq \sum_{i \in O} \mu v_i', \quad \text{by } (***) \\ &> \sum_{i \in O} (v_i - \mu), \quad \text{by } (**) \\ &\geq \left( \sum_{i \in O} v_i \right) - n\mu, \quad \text{since } |O| \leq n \\ &= \text{OPT} - n \cdot \frac{\epsilon M}{n} \\ &= \text{OPT} - \epsilon M \\ &\geq (1 - \epsilon) \text{OPT}, \quad \text{since } \text{OPT} \geq M\end{aligned}$$

Running time:

$O(\frac{1}{\epsilon} \cdot n^3)$  as proven above.

□

According to Thm 3.5, Alg. 3.2 is a  
fully polynomial time approximation scheme (FPTAS)  
also poly. in  $1/\epsilon$       poly. in input size      Family  $\{A_\epsilon\}$  of alg., where  $A_\epsilon$  has precision  $\epsilon$ .  
( $(1-\epsilon)$ -approx. alg for max. problems,  
( $(1+\epsilon)$ -approx. alg for min. problems)

Def. 3.4

Def. 3.3

Thus, Thm 3.5 could also be stated like this:

**Theorem 3.5:** Alg 3.2 is a FPTAS

Multiple Knapsack problem: Fixed #knapsacks

Bin Packing can be seen as a dual version of Multiple Knapsack.

### Bin Packing

Input:  $n$  items with sizes between 0 and 1.

Objective: Pack items in bins of size 1,  
using as few bins as possible.

### Simple approximation algorithms:

Alg.	Running time	Asymp. approx. factor
Next-Fit	$O(n)$	2
First-Fit	$O(n \log n)$	1.7
Best-Fit	— " —	— " —
Next-Fit - Decreasing	— " —	$\approx 1.69$
First-Fit - Decreasing	— " —	$1.\bar{2}$
Best-Fit - Decreasing	— " —	— " —

### Approximation scheme?

Can we do the same kind of rounding for Bin Packing as we did for Knapsack?