Section 3.2: Makespan Scheduling - A PTAS

Statch of PTAS;

- 1. Schedule long jobs (> ε ·OPT) using rounding and dyn. prg. $\Rightarrow C_{max} \leq (1+\varepsilon)OPT$
- 2. Add short jobs ($\leq \varepsilon \cdot OPT$) to the schedule using LPT. $\Rightarrow C_{max} \leq (1+\varepsilon)OPT$

How to identify long/short jobs when we don't know OPT?

- · We rud the short jobs to be $\leq \epsilon.OPT$ to ensure the approx. Jactor. For this purpose, we could use any lower bound on OPT, like l/m.
- · But we also need the long jobs to be > E.OPT to ensure the running time.

We will dwelop a family of algorithms with an algorithm B_k for each $k \in \mathbb{Z}^+$. $(\mathcal{E} = \frac{1}{k})$

Scheduling the long jobs:

- (1) "Guess" an optimal makespan T.
 The long jobs are those longer than Tk.
- (2) Round down each job size to the nearest multiple of The.
- (3) Use dyn. prg. to check whether optimal makespan = T for rounded long jobs.

Do binary search for T on the interval [L, U], where

 $L = \max \left\{ \left\lceil \frac{\rho}{m} \right\rceil, \rho_{\text{max}} \right\} \text{ and }$ $U = \left\lfloor \frac{\rho}{m} + \left(1 - \frac{1}{m}\right) \rho_{\text{max}} \right\rfloor,$ where ρ is the total size of long jobs.

B_k(I)

 $L \leftarrow \max \left\{ \left\lceil \frac{\rho}{m} \right\rceil, \rho_{\max} \right\}; \quad U \leftarrow \left\lceil \frac{\rho}{m} + \left(1 - \frac{1}{m} \right) \rho_{\max} \right\rceil$ While L+U $T \leftarrow \frac{1}{2} [L+U]$ L + U I ← fjobj ∈ I | p; > T/k } // Update set of long jobs I with each job size rounded down to nearest multiple of 1/2

Use dyn. prg. to pack I' in bins of size T IJ #bins ≤ M $U \leftarrow T$

else

L ← T+1

Si < schedule of Ii corresponding to the packing found by dyn-prg.

 $S_{\ell} \leftarrow$ schedule of I_{ℓ} corresponding to S_{ℓ} $S \leftarrow$ schedule of I obtained by adding short jobs to Se using

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Dyn. prg. as for bin packing:
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S' places = k jobs on each machine:

Each long job has size = T/k

Since T/k is a multiple of T/2, each job in I'

also has size = T/k.

There are $\leq k^2$ different job sizes in T_e , since no job is longer than T.

Hence, the configuration of a machine can be represented by a vector $(S_1, S_2, ..., S_{k^2})$, where $0 \le S_1 \le k$.

Thus, $|\mathcal{C}| \leq (k+1)^{k^2}$

Table (B);

 $\leq k^2$ dimensions (one for each size in \mathbb{T}_{k}) $n_{k}+1$ rows in dim. i $(n_{k}=\#items of size i. T_{k}^{2} in \mathbb{T}_{k}^{2})$

 $B(n_1, ..., n_{k^2}) = 1 + \min_{\vec{s} \in \mathcal{B}} \{B(n_1 - s_1, ..., n_{k^2} - s_{k^2})^{\frac{n}{2}}\}$

Running time;

table entries: O(ne2)

Time per entry: |E| = (k+1) k2

#iterations of while loop: log(U-L) = log(Pmax)

Total time: O(nk2 (k+1)k2 log (pmax))

Approximation ratio:

When B_k terminates the while loop, makespan $(S'_k) = T = OPT(I'_k)$

Since each of the <k jobs on a machine loses < The in the rounding,

makespan (S_{ℓ}) < makespan (S_{ℓ}) + $k \cdot \frac{T}{k^2}$ = $T + \frac{T}{k}$ = $(I + \frac{1}{k}) OPT(I_{\ell})$ $\leq (I + \frac{1}{k}) OPT(I)$, since $I_{\ell} \leq I$, and the job sizes are rounded down to obtain I_{ℓ} .

Thus, if the last job to finish is a long job, $B_k(I) < (1+k)OPT(I)$.

Otherwise, the last job to finish has $\rho_{\ell} \leqslant \frac{T}{k} \leqslant \frac{OPT(T_{\ell})}{k} \leqslant \frac{OPT(T)}{k}$

Hence, $B_{\epsilon}(I) < OPT(I) + P_{\epsilon} = (I+E) OPT$ By the same argument as in the analysis of 15:

Thus, in both cases, Bk(I) < (1+te) OPT.

Theorem 3.7: &Big is a PTAS

Proof: Let $k = \lceil \frac{1}{\epsilon} \rceil$. Then,

Be achieves an approx factor of 1+E with running time $O\left(\left(\left(\frac{1}{\epsilon}+1\right)n\right)^{\left(\frac{1}{\epsilon}\right)^2}\cdot\log\left(\rho_{max}\right)\right).$

If $\epsilon \in O(1)$, this is poly in the input size, since it takes $\gg \log(\rho_{\text{max}})$ bits to represent the job sizes. \square

 $\{B_k\}$ is <u>not</u> a FPTAS, since the running time is exponential in $\frac{1}{\epsilon}$. Note that we did not expect a FPTAS, since the problem is <u>strongly</u> NP-complete...

The problem is strongly NP-complete, meaning that ever the special case where ∃ polynomial q s.t. pmax ≤ q(n), for all input instances, is NP-complete.

This means that, in contrast to Knapsack, # pseudopoly. alg., unless P=NP.)

This implies that | #FPTAS, unless P=NP :

Assume to the contrary that FFPTAS for the problem, i.e., \exists family of algorithms $\{A_{\epsilon}\}$, $\epsilon>0$, with approx. Jactor $1+\epsilon$ and running time poly. in n and $\frac{1}{\epsilon}$.

Consider the special case of the problem where \exists polynomial q s.t. $p_{max} \leq q(n)$, for all instances. In this case, $P \leq n \cdot q(n) = p(n)$.

For $\varepsilon = \overline{\rho(n)}$,

- \neq is poly. in 11, so the running time of A_{ϵ} is poly. in n.
- $A_{\varepsilon}(I) \neq (1 + \frac{1}{\rho(n)}) \cdot OPT(I)$, for any input I < OPT(I)+1, Since OPT(I) < P < p(n)

Thus, since $A_{\varepsilon}(I)$ is integer, $A_{\varepsilon}(I) = OPT(I)$.

If P = NP, this contradicts the fact that the problem is strongly NP-complete.