Accelerating the XGBoost algorithm using GPU computing

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Outline

- Introduction
- BACKGROUND AND RELATED WORK
 - Tree boosting algorithms
 - Graphics processing units
 - Parallel primitives
 - Scan and reduce on multiple sequences
- PARALLEL TREE CONSTRUCTION
- EVALUATION
- CONCLUSION

• Input:

$$(\vec{x}_0, y_0), (\vec{x}_1, y_1) \cdots (\vec{x}_n, y_n)$$

• Output:

$$F(\vec{x}) = y$$

Decision Tree

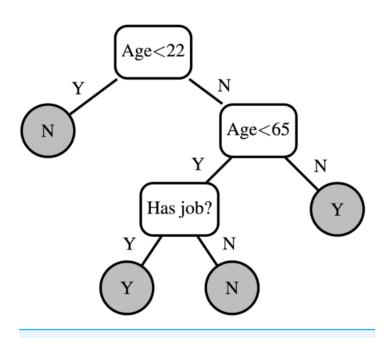


Figure 1 Example decision tree.

Table 1 Example training instances.							
Instance	Age	Has job	Owns house				
0	12	N	N				
1	32	Y	Y				
2	25	Y	Y				
3	48	N	N				
4	67	N	Y				
5	18	Y	N				

$$H(T) = -\sum_{y \in Y} P(y) \log_b P(y)$$

$$IG(T, T_{left}, T_{right}) = H_T - (n_{left}/n_{total}) * H(T_{left}) - (n_{right}/n_{total}) * H(T_{right})$$

Gradient boosting

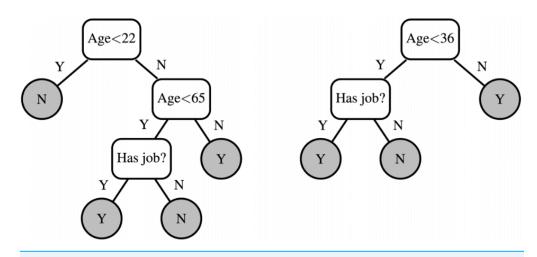


Figure 2 Decision tree ensemble.

$$F_{m+1}(x) = F_m(x) + f(x) = y$$

$$f(x) = y - F_m(x)$$

$$L(y, F(x)) = \frac{1}{2} (y - F(x))^2 \qquad J = \sum_i L(y_i, F(x_i))$$

$$\frac{dJ}{dF(x_i)} = \frac{d\sum_i L(y_i, F(x_i))}{dF(x_i)} = \frac{dL(y_i, F(x_i))}{dF(x_i)} = F_m(x_i) - y_i$$

$$f(x) = y - F_m(x) = -\frac{dL(y, F(x))}{dF(x)}$$

XGBoost

$$\begin{aligned} \text{Obj} &= \sum_{i} L(y_{i}, \hat{y}_{i}) + \sum_{k} \Omega(f_{k}) & \Omega(f_{k}) = \gamma T + \frac{1}{2} \lambda w^{2} \\ \text{Obj}^{m} &= \sum_{i} L(y_{i}, \hat{y}_{i}^{(m-1)} + f_{k}(x_{i})) + \sum_{k} \Omega(f_{k}) \\ & f(x + \triangle x) \simeq f(x) + f^{'}(x) \triangle x + \frac{1}{2} f^{''}(x) \triangle x^{2} \\ \text{Obj}^{m} &\simeq \sum_{i} [L(y_{i}, \hat{y}_{i}^{(m-1)}) + g_{i}f_{k}(x) + \frac{1}{2} h_{i}f_{k}(x)^{2}] + \sum_{k} \Omega(f_{k}) + \text{constant} \\ g_{i} &= \frac{dL(y_{i}, \hat{y}_{i}^{(m-1)})}{d\hat{y}_{i}^{(m-1)}} & h_{i} &= \frac{d^{2}L(y_{i}, \hat{y}_{i}^{(m-1)})}{d(\hat{y}_{i}^{(m-1)})^{2}} \end{aligned}$$

XGBoost

$$Obj^{m} = \sum_{i} [g_{i}f_{k}(x) + \frac{1}{2}h_{i}f_{k}(x)^{2}] + \sum_{k} \Omega(f_{k})$$

$$Obj^{m} = \sum_{j=1}^{T} \left[\left(\sum_{i \in I_{j}} g_{i} \right) w_{q(x)} + \frac{1}{2} \left(\sum_{i \in I_{j}} h_{i} \right) w_{q(x)}^{2} \right] + \gamma T + \frac{1}{2} \lambda \sum_{j=1}^{T} w^{2}$$

$$G_{j} = \sum_{i \in I_{j}} g_{i} \quad H_{j} = \sum_{i \in I_{j}} h_{i}$$

$$Obj^{m} = \sum_{j=1}^{T} \left[G_{j}w_{j} + \frac{1}{2} (H_{j} + \lambda)w_{j}^{2} \right] + \gamma T$$

XGBoost

$$w_{j} = -\frac{G_{j}}{H_{j} + \lambda} \qquad \text{Obj}^{m} = -\frac{1}{2} \sum_{j=1}^{T} \frac{G_{j}^{2}}{H_{j} + \lambda} + \gamma T$$

$$\text{Obj}_{leaf} = -\frac{1}{2} \frac{G_{j}^{2}}{H_{j} + \lambda} + \gamma \qquad \text{Obj}_{split} = -\frac{1}{2} \left(\frac{G_{jL}^{2}}{H_{jL} + \lambda} + \frac{G_{jR}^{2}}{H_{jR} + \lambda} \right) + 2\gamma$$

$$Gain = Obj_{leaf} - Obj_{split} = \frac{1}{2} \left[\frac{G_L^2}{H_L + \lambda} + \frac{G_R^2}{H_R + \lambda} - \frac{\left(G_L + G_R\right)^2}{H_L + H_R + \lambda} \right] - \gamma$$

• GPU

```
Listing 1 Example CUDA kernel

__global__ void example(float *d_a, float *d_b,
float *d_output, int n) {

// Calculate global thread index
// blockIdx.x - the current thread block number
// blockDim.x - the thread block size
// threadIdx.x - the thread index within the current block
int global_tid = blockIdx.x * blockDim.x + threadIdx.x;

if(global_tid < n) {
    d_output[global_tid] = d_a[global_tid] + d_b[global_tid];
}

}
```

K20:

Global Memory: 440 clocks

Shared Memory: 48 clocks

Reduction

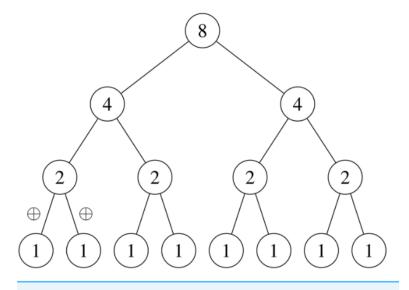
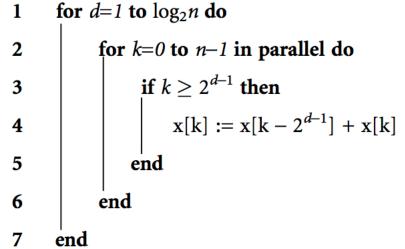


Figure 3 Sum parallel reduction.

```
__device__
float warp_reduce(float x) {
    for (int d = 16; d > 0; d /= 2)
        x += __shfl_down(x, d);
    return x;
}
```

Parallel prefix sum

Algorithm 1 Simple scan



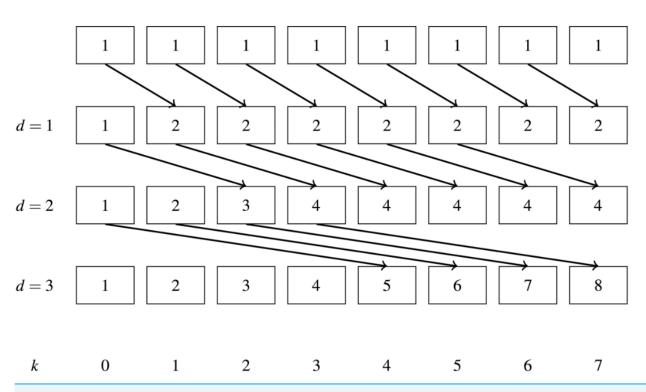


Figure 4 Simple parallel scan example.

Parallel prefix sum

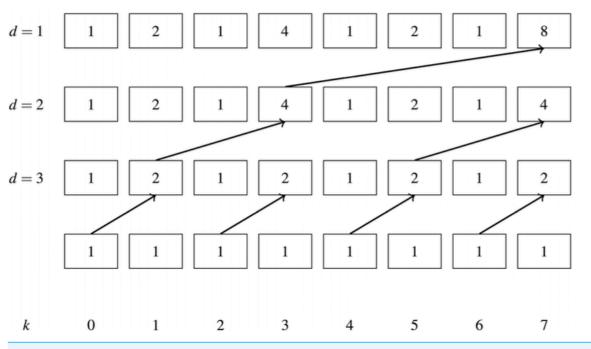


Figure 5 Blelloch scan upsweep example.

Algorithm 2 Blelloch scan—upsweep

```
offset = 1
        for d = \log_2 n to 1 do
3
             for k=0 to n-1 in parallel do
                  if k < 2^{d-1} then
                        ai = offset \times (2 \times k + 1) - 1
5
                        bi = offset \times (2 \times k + 2) - 1
                        x[bi] = x[bi] + x[ai]
8
                   end
9
             end
             offset = offset *2
10
11
        end
```

Parallel prefix sum

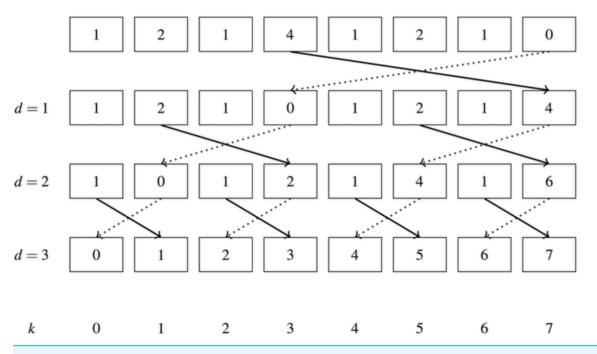


Figure 6 Blelloch scan downsweep example.

Algorithm 3 Blelloch scan—downsweep

```
offset = 2^{\log_2 n - 1}
       x[n-1] := 0
       for d=1 to \log_2 n do
            for k=0 to n-1 in parallel do
4
                if k < 2^{d-1} then
5
                      ai = offset \times (2 \times k + 1) - 1
6
                      bi = offset \times (2 \times k + 2) - 1
8
                     t = x[ai]
9
                     x[ai] = x[bi]
10
                     x[bi] = x[bi] + t
11
                end
12
            end
13
            offset = offset/2
14
      end
```

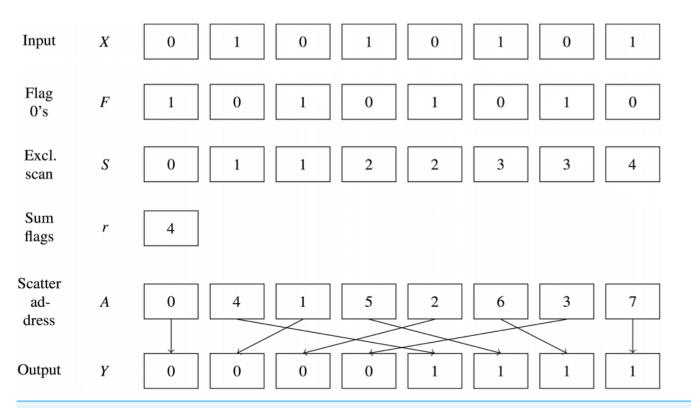
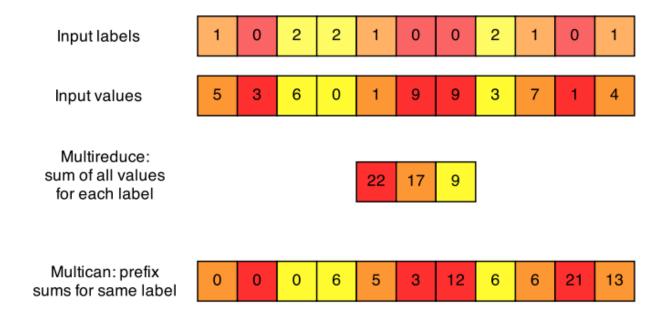


Figure 7 Radix sort example.

Algorithm 4 Radix sort pass

```
Input:X
      Output:Y
      for i = 0 to n - 1 in parallel do
2
         F[i] := bit_flip(X[i])
3
      end
      S := exclusive\_scan(F)
4
      r := S[n-1] + F[n-1]
5
6
      for i = 0 to n - 1 in parallel do
         if X[i] = 0 then
7
8
             A[i] := S[i]
9
          else if X/i = 1 then
10
             A[i] := i - S[i] + r
      end
11
      for i = 0 to n - 1 in parallel do
12
13
           Y[A[i]] := X[i]
14
      end
```

• Scan and reduce on multiple sequences



• Phase 1: find splits

Table 9 Device memory layout: feature values.									
	f0			fl	f2				
Node id	0	0	0	0	0	0	0	0	
Instance id	0	2	3	3	2	0	1	3	
Feature value	0.1	0.5	0.9	5.2	3.1	3.6	3.9	4.7	
Table 10 Device	e memory l	ayout: grad	lient pairs.						
Instance id		0		1		2		3	
Gradient pair		Po		p_1		p_2		p_3	

• Phase 1: find splits

Table 11 A single thread block evaluating splits.									
	Thread block 0				\Rightarrow				
	\downarrow	\downarrow	\downarrow	\downarrow					
	f0								
Instance id	0	2	3	1	7	5	6	4	
Feature value	0.1	0.2	0.3	0.5	0.5	0.7	0.8	0.8	
Gradient pair	p_0	p ₂	p 3	p_1	p 7	p 5	p 6	p_4	

• Phase 1: find splits

Table 12 Interleaved node buckets.								
	f0			fl	f2			
Node id	2	1	2	2	1	2	1	2
Instance id	0	2	3	3	2	0	1	3
Feature value	0.1	0.5	0.9	5.2	3.1	3.6	3.9	4.7

Table 13 Sorted node buckets.								
	f0			fl	f2			
Node id	1	2		2	1		2	
Instance id	0	2	3	3	2	1	0	3
Feature value	0.5	0.1	0.9	5.2	3.1	3.9	3.6	4.7

Phase 2: update node positions

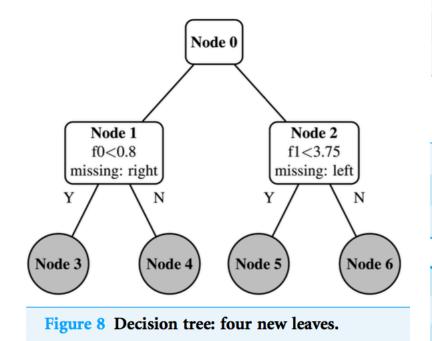


Table 16 Updated missing direction.						
Instance id	0	1	2	3		
Node id	4	5	5	4		

Table 17 Node I	Table 17 Node ID map: update based on feature value.							
	Instance id	0	1	2	3			
	Node id	> 3	5 '	< <u>-</u> 6←	4			
	f0			fl		``\		
Node id	1 /	2	2	1	1	2	2	
Instance id	0′	2	1	3	1	``1	` - 2	
Feature value	0.75	0.5	0.9	2.7	4.1	3.6	3.9	

• Phase 3: sort node buckets

Table 18 Per feature value array: updated.								
	f0			f1				
Node id	3	6	5	4	3	5	6	
Instance id	0	2	1	3	0	1	2	
Feature value	0.75	0.5	0.9	2.7	4.1	3.6	3.9	

Hardware

Table 19 Hardware configurations.							
Configuration	CPU	GHz	Cores	CPU arch.			
#1	Intel i5-4590	3.30	4	Haswell			
#2	Intel i7-6700K	4.00	4	Skylake			
#3	2× Intel Xeon E5-2695 v2	2.40	24	Ivy Bridge			
Configuration	GPU	GPU memory	(GB)	GPU arch.			
#1	GTX970	4		Maxwell			
#2	Titan X	12		Pascal			
#3	-	_		_			

Table 20 Datasets.			
Dataset	Training instances	Test instances	Features
YLTR ^a	473,134	165,660	700
Higgs ^b	10,500,000	500,000	28
Bosch ^c	1,065,373	118,374	968

Table 21	Table 21 Parameters.							
Dataset	Objective	eval_metric	max_depth	Eta	Boosting iterations			
YLTR	rank:ndcg	ndcg@10	6	0.1	500			
Higgs	binary:logistic	auc	12	0.1	500			
Bosch	binary:logistic	auc	6	0.1	500			

Accuracy

Table 22 Accuracy benchmarks.							
Dataset	Subset	Metric	CPU accuracy	GPU accuracy			
YLTR	0.75	ndcg@10	0.7784	0.7768			
Higgs	0.25	auc	0.8426	0.8426			
Bosch	0.35	auc	0.6833	0.6905			

Table 23 Accuracy benchmarks—sorting version only.				
Dataset	Subset	Metric	GPU accuracy (sorting version only)	
YLTR	0.75	ndcg@10	0.7776	
Higgs	0.25	auc	0.8428	
Bosch	0.35	auc	0.6849	

Speed

Table 24 Configuration #1 speed benchmarks.				
Dataset	Subset	CPU time (s)	GPU time (s)	Speedup
YLTR	0.75	1,577	376	4.19
Higgs	0.25	7,961	1,201	6.62
Bosch	0.35	1,019	249	4.09

Table 25 Configuration #2 speed benchmarks.				
Dataset	Subset	CPU time (s)	GPU time (s)	Speedup
YLTR	1.0	877	277	3.16
Higgs	1.0	14,504	3,052	4.75
Bosch	1.0	3,294	591	5.57

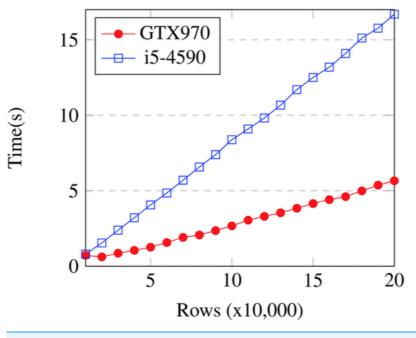


Figure 9 Bosch: time vs problem size.

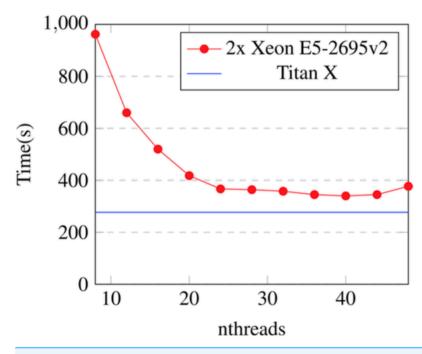


Figure 10 Yahoo LTR: n-threads vs time.

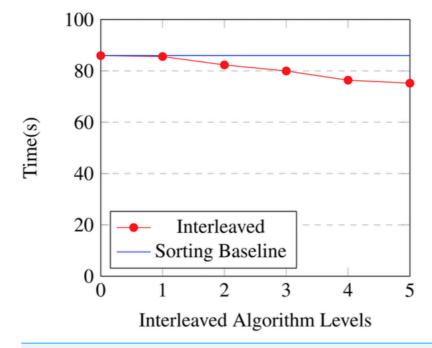


Figure 11 Bosch: interleaved algorithm threshold.

Table 27 Memory: GPU algorithm.	
Dataset	Device memory (GB)
YLTR	4.03
Higgs	11.32
Bosch	8.28

Table 28 Memory: CPU algorithm.	
Dataset	Host memory (GB)
YLTR	1.80
Higgs	6.55
Bosch	3.28

CONCLUSION

- The algorithm is built on top of efficient parallel primitives and switches between two modes of operation depending on tree depth.
- All nodes in a level concurrently.
- Sparsity aware.
- Problem:
 - The entire input matrix must fit in device memory and device memory consumption is approximately twice that of the host memory used by the CPU algorithm.
 - The number of streaming multiprocessors is limited.
 - Shared memory capacity.

Thank you! Q&A