

HW # 10.

①

Problem 1

We start with the LL equation,

$$\frac{dM}{dt} = -\gamma M \times H_{eff} - \frac{\alpha |\gamma|}{M} M \times M \times H_{eff} \rightarrow (3)$$

to linearize the equation for small rotations, we assume that the magnetization vector can be expressed as some

$M = \underbrace{M_0}_{\rightarrow 0} + \delta M$ where M_0 is a constant equilibrium value and δM is a small deviation from this value.

$$\text{likewise, } H_{eff} = H_{eq} + \delta H \rightarrow (2)$$

where we assume that the effective magnetic field can be expressed as a sum of constant equilibrium field and a small oscillating field δH .

Substituting (1), (2) in (3),

$$\frac{d(M_0 + \delta M)}{dt} = -\gamma (M_0 + \delta M) \times H_{eff} - \frac{\alpha |\gamma|}{M_0 + \delta M} (M_0 + \delta M) \times (M_0 + \delta M) (H_{eq} + \delta H)$$

expanding the cross products above we get.

$$\begin{aligned} \frac{d(M_0 + \delta M)}{dt} = & -\gamma M_0 H_{eq} - \gamma M_0 \times \delta H - \gamma \delta M H_{eq} - \gamma \delta M \times \delta H \\ & - \frac{\alpha \gamma}{M} (M_0 \times M_0 \times H_{eq}) + M_0 \times \delta M \times H_{eq} + \delta M \times M_0 \times H_{eq} \\ & + \delta M \times \delta M \times H_{eq} + M_0 \times M_0 \times \delta H + M_0 \times \delta M \times \delta H \\ & + \delta M \times M_0 \times \delta H + \delta M \times \delta M \times \delta H \end{aligned}$$

(2)

Terms involving $\delta H \times \delta H$ and $\delta M \times \delta M \times H_{eq}$ are of higher order than δM and δH , hence they can be neglected (because we are interested in studying small deviations from the equilibrium state, small angles of rotation)

this leaves us with.

$$\frac{d(M_0 + \delta M)}{dt} = -\gamma M_0 \times \delta H - \gamma \delta M \times H_{eq} - \frac{\alpha \gamma}{M} (M_0 \times \delta M) \times H_{eq} \quad \hookrightarrow (4)$$

The last term $-\frac{\alpha \gamma}{M} (M_0 \times \delta M) \times H_{eq}$ can be re-written as:
(expanding the cross product)

$$\frac{\alpha \gamma}{M} (M_0 \times \delta M) \times H_{eq} = \frac{\alpha \gamma}{M} (M_0 \times \delta M \times H_{eq} + \delta M \times M_0 \times H_{eq})$$

cross product is anticommutative, hence $\delta M \times M_0 \times H_{eq} = -M_0 \times \delta M \times H_{eq}$

$$\frac{\alpha |\gamma|}{M} (M_0 \times \delta M) \times H_{eq} = \frac{\alpha |\gamma|}{M} (2 M_0 \times \delta M \times H_{eq})$$

(4) can now be written as

$$\frac{d\delta M}{dt} = -\gamma M_0 \times \delta H - \gamma \delta M \times H_{eq} - \frac{\alpha |\gamma|}{M} (2 M_0 \times \delta M \times H_{eq})$$

we can ignore $\delta M \times M_0 \times H_{eq}$ because $\gg \delta M$.

$$\therefore \text{ we get } \frac{d\delta M}{dt} = -\gamma M_0 \times \delta H - \gamma \delta M \times H_{eq} - \frac{\alpha \gamma}{M} (M_0 \times \delta M) \times H_{eq} \quad \hookrightarrow (5)$$

$\delta H = 1 + y_0 e^{i\omega t} \Rightarrow \delta M = \delta m_x + i \delta m_y$ where δm_x and δm_y are components of deviation in x and y directions.

Substituting (5) in (6), we get

considering only the ~~y~~ component after substituting, (3)

$$\frac{dS_{mx}}{dt} = -\gamma(M_0 \times \delta u_y + M_0 y \delta H_x) - \gamma(\delta m_y M_z - \delta m_z M_y),$$

$$\delta u = \delta m_x x + \delta m_y y + \delta m_z z \rightarrow (3)$$

Putting (3) in (2),

$$\frac{dS_{mx}}{dt} = \gamma(M_0 \times \delta u_y + M_0 y \delta H_x) - \gamma(\delta m_y M_z - \delta m_z M_y)$$

$$- \frac{\gamma}{M} [(M_0 \times \delta m_y - M_0 y \delta m_x) H_z - (M_0 \times \delta m_z - M_0 z \delta m_x) H_y$$

$$+ (\delta m_x M_z - \delta m_z M_x) H_z - (\delta m_x M_y - \delta m_y M_x) H_y].$$

grouping the terms on both sides and taking the

time derivative of the above, we get.

$$\frac{d^2 \delta m_x}{dt^2} + \alpha |\gamma| \frac{dS_{mx}}{dt} + \omega_0^2 \delta m_x = -\gamma^2 M_0 \delta H_y e^{i\omega t}$$

if we consider $\phi = \delta m_x$.

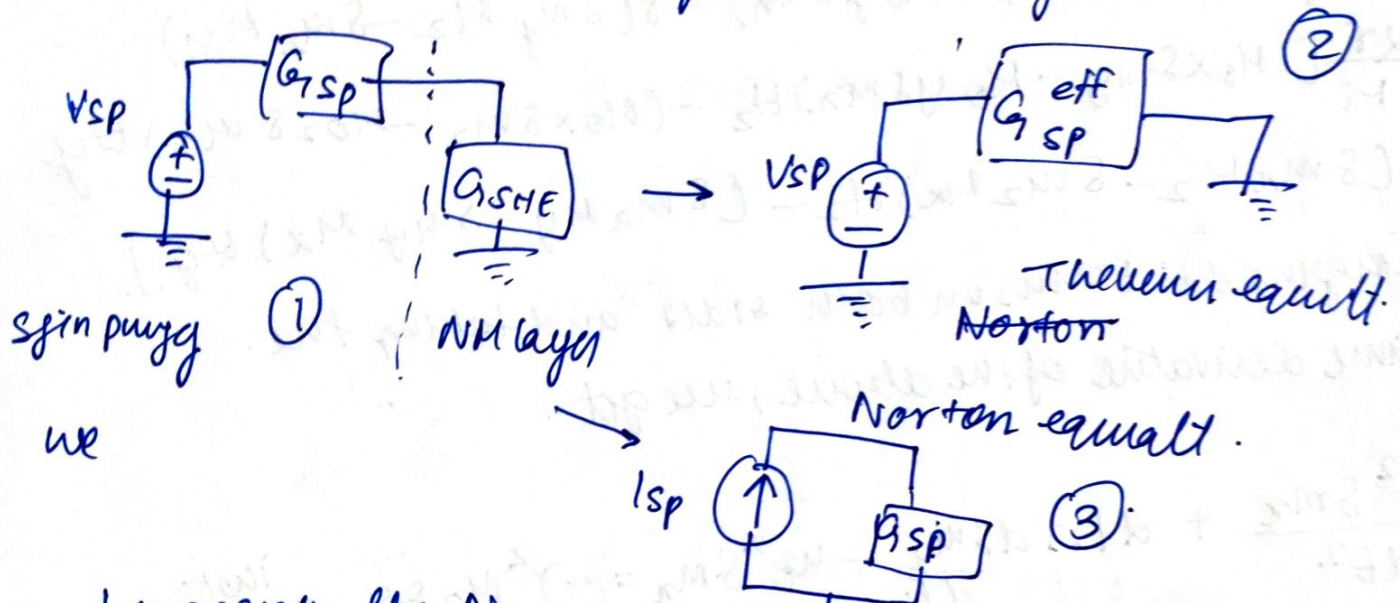
$$\frac{d^2 \phi}{dt^2} + \alpha |\gamma| M \frac{d\phi}{dt} + \omega_0^2 \phi = |\gamma|^2 M H_0 e^{i\omega t}$$

where $\omega_0 = \gamma |H_0|$ is the Larmor frequency.

Problem 2

We need to derive the expression of eff. spin mixing g_{eff} conductance and the ISHE Voltage due to spin pumping

The instantaneous 3 component spin current with voltage V_{sp} acts as a spin battery. G_{sp} is the interfacial spin mixing conductance between the magnetic & SHE layer.



Incorporating the Norton current in the spin pumping eqn, we

In this figure, $V_{\text{sp}} = \frac{\hbar \omega}{2e} \sin^2 \theta$

$G_{\text{sp}} = \frac{2e^2}{\hbar} g \uparrow \downarrow$

$G_{\text{NM}} = G_1 + \frac{G_1 G_2}{G_1 + G_2} = \frac{1}{\frac{1}{\sigma \lambda \omega} \coth(\frac{L}{\lambda})}$

From the above we have

$$G_{\text{SHE}} = \frac{G_1^2 + G_1 G_2}{G_1^2} \quad G_{\text{SHE}} = \frac{G_1 + G_1 G_2}{G_1 + G_2} = \frac{G_x}{\coth(L/\lambda)} \rightarrow \text{C1}$$

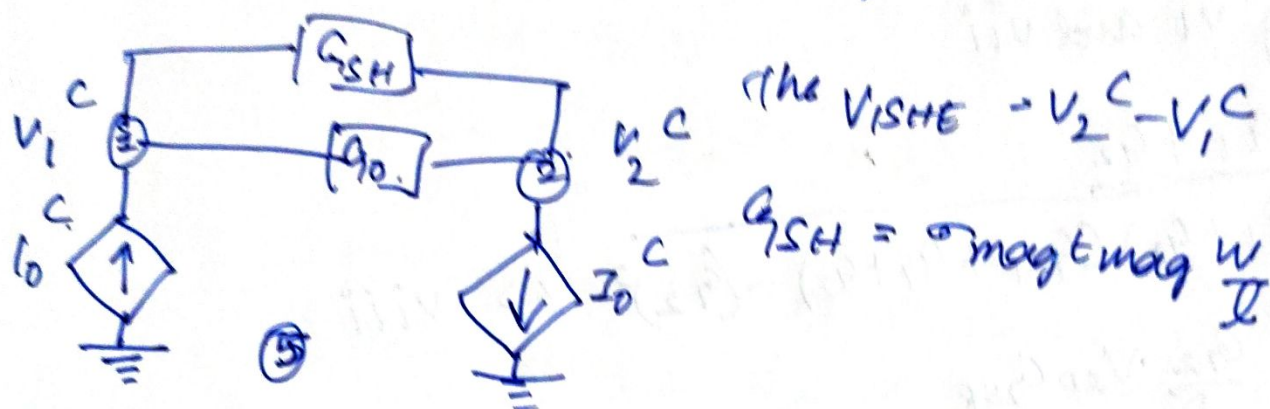
and from figure 1, we have $G_{\text{sp, eff}} = \frac{G_{\text{sp}} G_{\text{SHE}}}{G_{\text{sp}} + G_{\text{SHE}}} \rightarrow \text{C2}$

$$= \frac{\hbar \omega}{2e} \left(\frac{2e^2}{\hbar} \right) g_{\text{eff}} \uparrow \downarrow$$

Combining equations i and ii

$$g_{eff}^{\uparrow\downarrow} = \frac{g^{\uparrow\downarrow}}{1 + \frac{\lambda}{\sigma} \frac{2e^2}{h} g^{\uparrow\downarrow} \coth\left(\frac{t}{\lambda}\right)}$$

To calculate the ISHE voltage,



In circuit ④ from the previous page, charge current depends on spin potential difference between node 3 and 4 as $I_0^C = \beta G_0 (V_3^C - V_4^C) \rightarrow \text{iii}$ and $G_0 = \frac{\sigma t w}{l}$, $\beta = \frac{\theta_{SH} l}{t}$ where θ_{SH} is the spin hall angle.

In circuit ⑤, we apply KCL at node ① to get.

$$I_0^C = (V_1^C - V_2^C) (G_0 + G_{SH}) \rightarrow v$$

$$\text{and } V_{ISHE} = V_2^C - V_1^C \rightarrow \text{iv}$$

substituting iii and iv in v,

$$V_{ISH} = -\beta \left(\frac{G_0}{G_0 + G_{SH}} \right) (V_3 - V_4) \rightarrow (x)$$

To calculate $(V_3^C - V_4^C)$, apply KCL at nodes 3, 4 in circuit ④ from previous page.

to get

$$(V_3 - V_{sp})G_{sp} + V_3 G_1 + (V_3 - V_4)G_2 = 0 \quad \hookrightarrow v_i$$

and

$$V_4 G_1 + (V_4 - V_3)G_2 = 0 \quad \hookrightarrow v_{ii}$$

Solving v_i and v_{ii}

$$V_3 = \underline{G_1 + G_2}$$

$$(G_1 + G_2)(G_{sp} + G_1 + G_2) - (G_2)^2 \quad \hookrightarrow v_{iii}$$

$$\text{and } V_4 = \frac{G_2}{D} \cdot V_{sp} G_{sp} \quad \hookrightarrow \hat{x}$$

Substituting (viii) and (ix) in (x)

$$V_{isHE} = \frac{-\theta_{SH} \ell k e \tilde{S} \omega g^{\uparrow\downarrow} \sin^2 \theta \tanh\left(\frac{c}{2d}\right)}{2\pi(\sigma_t + \sigma_{mag t_{mag}}) \left[1 + \frac{\lambda}{\sigma} \frac{2e^2}{h} g^{\uparrow\downarrow} \coth\left(\frac{c}{2d}\right) \right]}$$

Problem 3.

X spin is not parallel to B_z . Hence, at $t=0$, spin is not eigenstate of the Hamiltonian describing the system.

The spin polarization hence shall change with time

In absence of dissipative forces, ϕ will obey time dependent Pauli's eqⁿ.

$$\left[i\hbar \frac{\partial}{\partial t} + \langle H_0 \rangle + \frac{q}{2} \mu_B \vec{B} \cdot \vec{\sigma} \right] [\phi] = 0$$

The solution can be written in the matrix form with E_- , E_+ as eigenvalues

$$\begin{aligned} [\phi](t) &= e^{[-i(\langle H_0 \rangle + (q/2) \mu_B B \cdot \sigma)t/\hbar]} [\phi](0) \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} e^{-iE_+ t/\hbar} & 0 \\ 0 & e^{-iE_- t/\hbar} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} [\phi](0). \end{aligned}$$

$\hookrightarrow \textcircled{1}$

$E_{\pm} = \langle H_0 \rangle \pm \left(\frac{q}{2}\right) \mu_B B$ where $\langle H_0 \rangle = \langle \phi_0 | H_0 | \phi_0 \rangle$

and corresponding eigenspinors are $|1\rangle = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ and $|0\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$\textcircled{1}$ is the eigenspinor at some time t .

$[\phi](0)$ is the x -polarized state $\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -i \end{bmatrix}^T$,

$$\therefore [\phi](t) = \begin{bmatrix} e^{-iE_+ t/\hbar} \\ -e^{-iE_- t/\hbar} \end{bmatrix}$$

8

$$S_x(t) = [\phi]^\dagger(t) [\sigma_x] [\phi]^\dagger(t) \text{ is the spin component along } x$$

$$= \begin{bmatrix} \frac{e^{iE_+t/\hbar}}{\sqrt{2}} & -\frac{e^{iE_-t/\hbar}}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{e^{-iE_+t/\hbar}}{\sqrt{2}} \\ -\frac{e^{-iE_-t/\hbar}}{\sqrt{2}} \end{bmatrix}$$

$$= -\cos\theta \quad \text{since } \theta = \frac{(E_+ - E_-)t}{\hbar} = \frac{g\mu_B B t}{\hbar}$$

likewise,

$$S_y(t) = [\phi]^\dagger(t) [\sigma_y] [\phi]^\dagger(t)$$

$$= \begin{bmatrix} \frac{e^{iE_+t/\hbar}}{\sqrt{2}} & -\frac{e^{iE_-t/\hbar}}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} \frac{e^{-iE_+t/\hbar}}{\sqrt{2}} \\ -\frac{e^{-iE_-t/\hbar}}{\sqrt{2}} \end{bmatrix}$$

$$= -\sin\theta$$

and

$$S_z(t) = [\phi]^\dagger(t) [\sigma_z] [\phi]^\dagger(t)$$

$$= \begin{bmatrix} \frac{e^{iE_+t/\hbar}}{\sqrt{2}} & -\frac{e^{iE_-t/\hbar}}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \frac{e^{-iE_+t/\hbar}}{\sqrt{2}} \\ -\frac{e^{-iE_-t/\hbar}}{\sqrt{2}} \end{bmatrix}$$

$$= 0.0 = 0.$$

(9)

$$\frac{dS}{dt} = x \frac{dS_x}{dt} + y \frac{dS_y}{dt} + z \frac{dS_z}{dt}$$

$$= -x \frac{d(\cos\theta)}{dt} - y \frac{d(\sin\theta)}{dt}$$

$$= \frac{d\theta}{dt} [\hat{n} \sin\theta - \hat{y} \cos\theta]$$

$$= \frac{q}{2} \frac{eB}{m} [\sin\theta \hat{n} - \cos\theta \hat{y}]$$

$$= \frac{eB}{m^*} [\sin\theta \hat{n} - \cos\theta \hat{y}] \rightarrow (3)$$

$$\Omega \times S = \frac{eB}{m^*} \times S = \frac{eB}{m^*} [-\hat{n} S_y + \hat{y} S_x]$$

$$= \frac{eB}{m^*} [\sin\theta \hat{n} - \cos\theta \hat{y}] \rightarrow (4)$$

From (3), (4).

$$\frac{dS}{dt} = \Omega \times S //$$