letous along a direction
$$V_q = \frac{\partial H}{\partial p_q}$$

$$\frac{1}{2m^{2}} \left[(p_{n} - eb_{2}y)^{2} + p_{y}^{2} + (p_{2} + eb_{3}y)^{2} \right] + v(y)$$

$$- \frac{9}{2} \mu_{B} [b_{n}\sigma_{2} + b_{2}\sigma_{2}] - \frac{1}{2} [(p_{n} - eb_{2}y)\sigma_{2} - (p_{2} + eb_{3}y)\sigma_{3})$$

$$- \frac{1}{2} [(p_{n} - eb_{2}y)\sigma_{3} - (p_{2} + eb_{3}y)\sigma_{2}]$$

$$\sqrt{x} = \frac{\partial H}{\partial p_x} = \frac{1}{2m} \times \left[(1 - 2eB_z y) \right] - \frac{M}{h} \left(1 - 2eB_z y \right) \sigma_z$$

$$- \frac{2}{h} \left[(1 - 2eB_z y) \sigma_z \right]$$

=
$$\langle \psi^{\dagger} | p_n | \psi^{\dagger} \rangle$$
 - $\frac{M}{\pi} \langle \psi^{\dagger} | \sigma_2 | \psi^{\dagger} \rangle$ - $\frac{N}{\pi} \langle \psi^{\dagger} | \sigma_n | \psi^{\dagger} \rangle$
 $\psi^{\dagger} = \left[-\sin(\theta_R) \right] \quad \theta_R = \frac{1}{2} \operatorname{arctan} \left[\frac{(g/2)}{g/2} \frac{M_B B_Z}{M_B B_Z} - M_{KZ} + N_{KZ} \right]$
 $\langle \psi^{\dagger} | p_n | \psi^{\dagger} \rangle = \frac{1}{2} \frac{\cos(\theta_R)}{\sin(\theta_R)}$

$$\frac{\langle y^{\dagger}|p_{n}|\psi^{\dagger}\rangle}{\langle y^{\dagger}|p_{n}|\psi^{\dagger}\rangle} = \frac{[-\sin(\theta_{k})\cos(\theta_{k})]}{(-\sin(\theta_{k})\cos(\theta_{k}))} + \frac{(y^{\dagger}|p_{n}|\psi^{\dagger})}{(-\sin(\theta_{k})\cos(\theta_{k}))} + \frac{(y^{\dagger}|p_{n}|\psi^$$

$$\langle \psi^{\dagger} | \sigma_{2} | \psi^{\dagger} \rangle = \left\{ \begin{array}{c} \sin \theta_{R} \\ \cos \theta_{R} \end{array} \right\} \left[\begin{array}{c} \cos \theta_{R} \\ \cos \theta_{R} \end{array} \right] \left[\begin{array}{c} -\sin \theta_{R} \\ -\cos \theta_{R} \end{array} \right] = \left[\begin{array}{c} -\sin \theta_{R} \\ -\cos \theta_{R} \end{array} \right]$$

$$\begin{bmatrix} c - \sin \theta_{\mathcal{K}} & \cos \theta_{\mathcal{K}} \end{bmatrix} \begin{bmatrix} -\sin \theta_{\mathcal{K}} \\ -\cos \theta_{\mathcal{K}} \end{bmatrix} = \begin{bmatrix} \sin^2 \theta & -\cos^2 \theta \end{bmatrix} = -\cos \theta_{\mathcal{K}}$$