

Permittivity of free space:  $\epsilon_0 = 8.854 \times 10^{-12}$   
 Elementary charge:  $e = 1.602 \cdot 10^{-19}$   
 Proton mass:  $1.673 \cdot 10^{-27}$   
 Electron mass:  $9.11 \cdot 10^{-31}$   
 Speed of light:  $c = 3 \cdot 10^8$   
 Permeability constant:  $\mu_0 = 1.26 \times 10^{-6}$

### Moving Conductor

$$I = \frac{\Delta V}{R} = \frac{\varepsilon}{R} = \frac{v l B}{R}$$

$$F_{\text{mag}} = F_{\text{pull}} = I l B = \frac{v l^2 B^2}{R}$$

$$P_{\text{input}} = P_{\text{dissipated}} = I^2 R = \frac{v^2 l^2 B^2}{R}$$

$$\Phi_m = \vec{A} \cdot \vec{B} = |A||B| \cos \theta \quad (\text{uniform magnetic field})$$

- Increasing flux: The induced magnetic field points opposite the applied magnetic field.
- Decreasing flux: The induced magnetic field points in the same direction as the applied magnetic field.
- Steady flux: There is no induced magnetic field.

$$\varepsilon_{\text{induced}} = \frac{d\Phi_m}{dt} \quad I_{\text{induced}} = \frac{\varepsilon_{\text{induced}}}{R}$$

$$E_{\text{inside}} = \frac{r}{2} \left| \frac{dB}{dt} \right| \quad \text{Solenoid}$$

$$\frac{V_2}{V_1} = \frac{N_2}{N_1} \quad \text{Transformers}$$

### Inductors

$$L = \frac{\Phi_m}{I} \quad \text{henry (H)}$$

$$\Delta V_L = -L \frac{dI}{dt} \quad U_L = L \int_0^I IdI = \frac{1}{2} LI^2$$

### LC Circuits

$$I = -\frac{dQ}{dt} \quad Q(t) = Q_0 \cos \omega t$$

$$\omega = \frac{1}{\sqrt{LC}} \quad f = \omega / 2\pi$$

### LR Circuits

$$I = I_0 e^{-t/(L/R)}$$

$$\tau = \frac{L}{R} \quad \text{where current has decreased to } e^{-1}$$

### Right-hand rule (wire)

- Point thumb in the direction of current
- Point fingers in the direction of magnetic field
- Point palm in the face of force on wire

$$\vec{E}_B = \vec{E}_A + \vec{v}_{BA} \times \vec{B}_A$$

$$\vec{B}_B = \vec{B}_A - \frac{1}{c^2} \vec{v}_{BA} \times \vec{E}_A$$

$$a \times b = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$

$$I_{\text{disp}} = \epsilon_0 \frac{d\Phi_e}{dt} = \epsilon_0 \frac{dE \cdot A}{dt}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{\text{in}}}{\epsilon_0} \quad \text{Gauss's Law}$$

$$\oint \vec{B} \cdot d\vec{A} = 0 \quad \text{Gauss's Law for Magnetism}$$

$$\oint \vec{E} \cdot d\vec{s} = -\frac{d\Phi_m}{dt} \quad \text{Faraday's Law}$$

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{\text{through}} + \epsilon_0 \mu_0 \frac{d\Phi_e}{dt} \quad \text{Ampere-Maxwell Law}$$

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \quad \text{Lorentz Force Law}$$

$$E(x, t) = E_0 \cos(kx - \omega t + \phi)$$

$$1. \quad k = \frac{2\pi}{\lambda} \quad \text{where } k \text{ is wave number and } \lambda \text{ is wavelength}$$

$$2. \quad T = \frac{2\pi}{\omega} \quad \text{where } T \text{ is period and } \omega \text{ is angular frequency}$$

$$3. \quad f = \frac{1}{T} \quad \text{where } f \text{ is frequency}$$

$$4. \quad v = f\lambda \quad \text{where } v \text{ is the propagation speed}$$

$$5. \quad v = \frac{E_0}{B_0} \quad \text{where } E_0 \text{ and } B_0 \text{ are the electric and magnetic field components}$$

$$E = cB$$

$$I = \frac{P}{4\pi r^2} = \frac{c\epsilon_0 E_0^2}{2}$$

$$\langle S \rangle = \frac{1}{\mu_0} EB \sin \theta$$

### Right-hand rule (electromagnetic waves)

- Point index finger in the direction of electric field
- Point middle finger in the direction of magnetic field
- Point thumb in the direction of motion

$$I_{\text{transmitted}} = \frac{1}{2} I_0 \quad \text{unpolarized}$$

$$I_{\text{transmitted}} = I_0 \cos^2 \theta \quad \text{polarized}$$

$$\varepsilon = \varepsilon_0 \cos \omega t \quad \omega = 2\pi f$$

$$v_R = i_R R \quad (\text{AC circuit}) \quad \text{and } V_R \text{ is the maximum voltage}$$

### Capacitor circuit

$$v_C = V_C \cos \omega t$$

$$q = C v_C$$

$$i_C = -\omega C V_C \sin \omega t = \omega C V_C \cos(\omega t + \frac{\pi}{2})$$

$$X_C = \frac{1}{\omega C} \quad I_C = \frac{V_C}{X_C} \quad (X_C \text{ is Capacitive reactance})$$

$$\omega C = \frac{1}{RC} \quad (\text{RC Circuit})$$

### Inductor circuit

$$i_L = I_L \cos(\omega t - \frac{\pi}{2})$$

$$X_L = \omega L \quad I_L = \frac{V_L}{X_L} \quad (X_L \text{ is Inductive reactance})$$

### Series RLC Circuit

$$Z = \sqrt{R^2 + (X_L - X_C)^2} \quad (\text{impedance})$$

$$I_{\text{peak}} = \frac{\varepsilon_0}{Z}$$

$$\phi = \tan^{-1} \left( \frac{X_L - X_C}{R} \right) \quad (\text{angle between emf and current})$$

$$\omega_0 = \frac{1}{\sqrt{LC}} \quad (\text{resonance frequency})$$

- If  $V_C > V_L$ , the circuit operates below resonance frequency
- If  $V_L > V_C$ , the circuit operates above resonance frequency

$$p = i\varepsilon \quad (\text{AC circuit})$$

$i$  and  $\varepsilon$  are instantaneous current and potential difference

$$P_R = \frac{1}{2} I_R^2 R = I_{\text{rms}} V_{\text{rms}}$$

$$x_{\text{rms}} = \frac{x}{\sqrt{2}}$$

$$P_{\text{source}} = \frac{1}{2} I \varepsilon_0 \cos \phi = I_{\text{rms}} \varepsilon_{\text{rms}} \cos \phi = P_{\text{max}} \cos^2 \phi$$

$\cos \phi$  is the power factor,  $\phi$  is the phase between current and emf,  $P_{\text{mas}} = \frac{1}{2} I_{\text{max}} \varepsilon_0$ .

In an AC circuit with a capacitor, the current leads the voltage by  $\frac{\pi}{2}$  so current reaches maximum  $\frac{T}{4}$  before voltage.

In an AC circuit with an inductor, the current lags the voltage by  $\frac{\pi}{2}$  so current reaches maximum  $\frac{T}{4}$  after voltage.