Permittivity of free space:  $\epsilon_0=8.854\times 10^{-12}$  — Proton mass:  $1.673\cdot 10^{-27}$  Elementary charge:  $e=1.602\cdot 10^{-19}$  — Electron mass:  $9.11\cdot 10^{-31}$  Speed of light:  $c=3\cdot 10^8$  — Permeability constant:  $\mu_0=1.26\times 10^{-6}$   $k=9\times 10^9$ 

$$\lambda = \frac{Q}{L} \quad \eta = \frac{Q}{A} \quad \rho = \frac{Q}{V}$$

$$E = \frac{kq}{r^2} \quad F = qE = \frac{kq_1q_2}{r^2} \quad V = \frac{kq}{r} \quad U = qV = \frac{kq_1q_2}{r} \quad \text{(point)}$$

$$E_{\text{wire}} = \frac{2k|\lambda|}{r} = \frac{2kQr^2}{R^3L} \quad E_{\text{plane}} = \frac{\eta}{2\epsilon_0} \quad E_{\text{ring}} = \frac{kzQ}{(z^2 + r^2)^{3/2}}$$

$$E_{\text{disk}} = \frac{\eta}{2\epsilon_0} \left(1 - \frac{z}{\sqrt{z^2 + R^2}}\right) \quad E_{\text{sphere}} = \begin{cases} \frac{kQ}{r^2} & \text{for } r > = R \\ \frac{kQr}{R^3} & \text{for } r < R \end{cases}$$

$$\text{Dipole} \begin{cases} p = qd \quad E = -\frac{2kp}{r^3} \text{(on axis)} \quad E = -\frac{kp}{r^3} \text{(on bisecting plane)} \\ \tau = pE \sin \theta \quad V = -pE \cos \theta \end{cases}$$

Parallel-Plate Capacitor 
$$\begin{cases} E = \frac{V}{d} = \frac{Q}{\epsilon_0 A} \text{(positive to negative plate)} \\ s = \text{distance from negative plate} \\ U = qEs = qV \quad V = \frac{s}{d} \Delta V_C \end{cases}$$

$$\begin{split} \Phi_{\rm enc} &= EA = \frac{Q_{\rm in}}{\epsilon_0} \quad E_{\rm conductor \ surface} = \frac{\eta}{\epsilon_0} \\ W &= -q\Delta V \quad \Delta V = -Ed \quad V_{\rm sphere} = \frac{4}{3}\pi r^3 \quad A_{\rm sphere} = 4\pi r^2 \\ W &= Q \times V \quad C = \frac{Q}{\Delta V_C} \end{split}$$

$$C = rac{\epsilon_0 A}{d}$$
  $Q = rac{\epsilon_0 A}{d} \Delta V_C$  (parallel-plate capacitor)  $C_{
m eq} = egin{cases} C_1 + C_2 + \cdots & ext{(parallel)} \ (rac{1}{C_1} + rac{1}{C_2} + \cdots)^{-1} & ext{(sequential)} \ C = \kappa C_0 \end{cases}$ 

$$i_e = n_e A v_d$$
  $I = n \times A \times e \times v_d$   $n =$  electron density

Current density = 
$$J = \frac{I}{A} = n_e e v_d$$
  $I = JA = \sigma A E$   $\sigma = \text{conductivity}$ 

$$\rho = \frac{1}{\sigma} = \text{resistivity} \quad R = \rho \frac{L}{A} \quad I = \frac{A}{\rho L} \Delta V \quad \Delta V = IR$$

$$R_{\text{eq}} = \begin{cases} \left(\frac{1}{R_1} + \frac{1}{R_2} + \cdots\right)^{-1} & \text{(parallel)} \\ R_1 + R_2 + \cdots & \text{(sequential)} \end{cases}$$

If one branch in a parallel circuit is opened, the current through the other stays the same

All parts of a sequential wire have the same current

$$P = \Delta V_R \times I = I^2 \times R = \frac{(\Delta V_R)^2}{R}$$

$$\tau = RC \quad Q = Q_0 e^{-t/\tau} \quad \Delta V_C = \Delta V_0 e^{-t/\tau}$$

Right-hand rule for wire (wrap fingers around wire): thumb points toward current and fingers point toward magnetic field

Right-hand rule for magnetic field: thumb points toward force, palm faces magnetic field, fingers point toward motion

$$\begin{split} \oint B \cdot dl &= Bl = \frac{\mu_0 I}{2\pi r} \times 2\pi r = \mu_0 I \quad \Phi_m = BA \cos \theta \\ F_B &= qv \times B = IL \times B \\ B_{\text{point charge}} &= \frac{\mu_0 q(\vec{v} \times \vec{r})}{4\pi r^3} = \frac{\mu_0 qv \sin \theta}{4\pi r^2} \quad B_{\text{wire}} = \begin{cases} \frac{\mu_0 I}{2\pi r} & r >= R \\ \frac{\mu_0 Ir}{2\pi R^2} & r < R \end{cases} \\ B_{\text{center of current loop}} &= \frac{\mu_0 NI}{2R} \quad B_{\text{solenoid}} = \mu_0 nI \quad n = N/L \\ \vec{B}_{\text{current segment}} &= \frac{\mu_0 I \Delta \vec{s} \times \hat{r}}{4\pi r^2} \end{split}$$

Magnetic dipole moment =  $\vec{m} = (AI, \text{from south to north pole})$ 

$$\vec{B}_{\text{on axis of dipole}} = \frac{\mu_0 \vec{m}}{2\pi z^3}$$

$$A \times B = (A_y B_z - A_z B_y)\mathbf{i} + (A_z B_x - A_x B_z)\mathbf{j} + (A_x B_y - A_y B_x)\mathbf{k}$$

Metal	Electron density $(m^{-3})$	Resistivity	Conductivity
Aluminum	$18 \times 10^{28}$	$2.8 \times 10^{-8}$	$3.5 \times 10^{7}$
Iron	$17 \times 10^{28}$	$9.7 \times 10^{-8}$	$1.0 \times 10^{7}$
Copper	$8.5 \times 10^{28}$	$1.7 \times 10^{-8}$	$6.0 \times 10^{7}$
Gold	$5.9 \times 10^{28}$	$2.4 \times 10^{-8}$	$4.1 \times 10^{7}$
Silver	$5.8 \times 10^{28}$	$1.6 \times 10^{-8}$	$6.2 \times 10^{7}$

Kirchhoff's Law: Branch out from one terminal and set up equations for  $\sum \Delta V_i = 0$ 

There is no current in the ground wire

$$\Delta V = \varepsilon = vlB$$
 (moving conductor)

Increasing flux: induced magnetic field points opposite to applied Decreasing flux: induced magnetic field points same direction to applied Steady flux: no induced magnetic field

$$\begin{split} \varepsilon_{\mathrm{induced}} &= -\frac{d\Phi_m}{dt} \quad I_{\mathrm{induced}} = \frac{\varepsilon_{\mathrm{induced}}}{R} \\ E_{\mathrm{inside}} &= \frac{r}{2} \Big| \frac{dB}{dt} \Big| \quad \mathrm{solenoid} \\ \frac{V_2}{V_1} &= \frac{N_2}{N_1} \quad P_1 = P_2 \quad V_1 I_1 = V_2 I_2 \quad \frac{I_1}{I_2} = \frac{N_2}{N_1} \quad \text{(transformers)} \\ L &= \frac{\Phi_m}{I} \quad \Delta V_L = -L \frac{dI}{dt} \quad U_L = L \int_0^I I dI = \frac{1}{2} L I^2 \quad \text{(inductors)} \\ I &= -\frac{dQ}{dt} \quad Q(t) = Q_0 \cos \omega t \quad \omega = \frac{1}{\sqrt{LC}} \quad \text{(LC circuits)} \\ I &= I_0 e^{-t/\tau} \quad \tau = \frac{L}{R} \quad \text{(LR circuits)} \\ \vec{E}_B &= \vec{E}_A + \vec{v}_{BA} \times \vec{B}_A \quad \vec{B}_B = \vec{B}_A - \frac{1}{c^2} \vec{v}_{BA} \times \vec{E}_A \end{split}$$

Displacement current is from changing electric field rather than flow of charges.

$$I_{\rm disp} = \epsilon_0 \frac{d\Phi_e}{dt} = \epsilon_0 \cdot A \frac{dE}{dt}$$
 
$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{\rm in}}{\epsilon_0} \quad \text{(Gauss's Law)}$$
 
$$\oint \vec{B} \cdot d\vec{A} = 0 \quad \text{(Gauss's Law for Magnetism)}$$
 
$$\oint \vec{E} \cdot d\vec{s} = -N \frac{d\Phi_m}{dt} \quad \text{(Faraday's Law)}$$
 
$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{\rm through} + \epsilon_0 \mu_0 \frac{d\Phi_e}{dt} \quad \text{(Ampere-Maxwell Law)}$$
 
$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \quad \text{(Lorentz Force Law)}$$
 
$$E(x,t) = E_0 \cos(kx - \omega t + \phi) \quad c = \frac{\omega}{k} = \frac{\omega \lambda}{2\pi} = f\lambda = \frac{E}{B}$$
 
$$I = \frac{P}{4\pi r^2} = \frac{c\epsilon_0 E_0^2}{2}$$

Average value for  $\sin \theta$  is  $\frac{1}{2}$ 

$$\langle S \rangle = \frac{1}{\mu_0} EB \sin \theta$$
 (**Poynting Vector** — energy flux of an EM wave)

Right-hand rule for electromagnetic waves: fingers point toward electric field, palm faces magnetic field, thumb points toward motion

$$\begin{split} I_{\text{transmitted}} &= \frac{1}{2} I_0 \quad \text{(unpolarized)} \quad I_{\text{transmitted}} = I_0 \cos^2 \theta \quad \text{(polarized)} \\ &\quad \varepsilon = \varepsilon_0 \cos \omega t \quad \omega = 2\pi f \quad X = \text{Reactance} \\ &\quad v_R = i_R R = V_{\text{max}} \sin \omega t \quad p = i\varepsilon \quad \text{(AC circuit)} \\ \text{Capacitor circuit} & \begin{cases} v_C = V_C \cos \omega t \quad q = C v_C \quad X_C = \frac{1}{\omega C} \quad I_C = \frac{V_C}{X_C} \\ i_C = -\omega C V_C \sin \omega t = \omega C V_C \cos(\omega t + \frac{\pi}{2}) \end{cases} \\ &\quad \omega_C = \frac{1}{RC} \quad \text{(RC Circuit)} \end{split}$$

An inductor is a coil of wire that generates a magnetic field when current flows through it and resist changes in current by inducing an emf opposite to the charge.

$$\begin{aligned} & \text{Inductor circuit} \begin{cases} i_L = I_L \cos(\omega t - \frac{\pi}{2}) \quad V = L \cdot \frac{dI}{dt} \\ X_L = \omega L \quad I_L = \frac{V_L}{X_L} \end{cases} \\ & \text{Series RLC Circuit} \begin{cases} Z = \sqrt{R^2 + (X_L - X_C)^2} \quad \text{(impedance)} \\ V = \sqrt{V_R^2 + (V_L - V_C)^2} \quad I_{\text{peak}} = \frac{\varepsilon_0}{Z} \\ \phi_{\text{between emf and current}} = \tan^{-1}\left(\frac{X_L - X_C}{R}\right) \\ \omega_0 = \frac{1}{\sqrt{LC}} = \text{resonance angular frequency} \end{cases}$$

Resonance frequency occurs when  $X_L=X_C$  and Z=R. If  $V_C>V_L$ , the circuit operates below resonance frequency. If  $V_L>V_C$ , the circuit operates above resonance frequency.

$$P_R = \frac{1}{2}I_R^2 R = I_{\rm rms}V_{\rm rms} \quad x_{\rm rms} = \frac{x}{\sqrt{2}}$$

$$P_{\rm source} = \frac{1}{2}I\varepsilon_0\cos\phi = I_{\rm rms}\varepsilon_{\rm rms}\cos\phi = P_{\rm max}\cos^2\phi$$

where  $\cos \phi$  is the power factor,  $\phi$  is the phase between current and emf, and  $P_{\rm max} = \frac{1}{2} I_{\rm max} \varepsilon_0$ .

- AC circuit with capacitor: current leads voltage by  $\frac{\pi}{2}$  (current reaches maximum  $\frac{T}{4}$  before voltage)
- AC circuit with inductor: current lags voltage by  $\frac{\pi}{2}$  (current reaches maximum  $\frac{T}{4}$  after voltage)
- AC circuit with resistor: current is in phase with voltage