Moving Conductor

$$\Delta V = \varepsilon = vlB$$

$$I = \frac{\varepsilon}{R} = \frac{vlB}{R}$$

$$F_{\text{mag}} = F_{\text{pull}} = IlB = \frac{vl^2B^2}{R}$$

$$P_{\text{input}} = P_{\text{dissipated}} = I^2R = \frac{v^2l^2B^2}{R}$$

$$\Phi_m = \int \vec{B} \cdot d\vec{A}$$

 $\Phi_m = \vec{A} \cdot \vec{B} = |A||B|\cos\theta$ (uniform magnetic field)

- Increasing flux: The induced magnetic field points opposite the applied magnetic field.
- Decreasing flux: The induced magnetic field points in the same direction as the applied magnetic field.
- \bullet Steady flux: There is no induced magnetic field.

$$\begin{split} \varepsilon_{\rm induced} &= \frac{d\Phi_m}{dt} \\ I_{\rm induced} &= \frac{\varepsilon_{\rm induced}}{R} \\ E_{\rm inside} &= \frac{r}{2} \Big| \frac{dB}{dt} \Big| \quad \text{Solenoid} \\ \frac{V_2}{V_1} &= \frac{N_2}{N_1} \quad \text{Transformers} \end{split}$$

Inductors

$$L=rac{\Phi_m}{I}$$
 henry (H) Inductance
$$\Delta V_L=-Lrac{dI}{dt}$$

$$U_L=L\int_0^IIdI=rac{1}{2}LI^2$$

LC Circuits

$$I = -\frac{dQ}{dt}$$

$$Q(t) = Q_0 \cos \omega t$$

$$\omega = \frac{1}{\sqrt{LC}} \quad f = \omega/2\pi$$

LR Circuits

$$I = I_0 e^{-t/(L/R)}$$

$$\tau = \frac{L}{R} \quad \text{where current has decreased to } e^{-1}$$

Right-hand rule (wire)

- 1. Point thumb in the direction of current
- 2. Point fingers in the direction of magnetic field
- 3. Point palm in the face of force on wire

Right-hand rule (electromagnetic waves)

- 1. Point index finger in the direction of electric field
- 2. Point middle finger in the direction of magnetic field
- 3. Point thumb in the direction of motion

$$X_C = \frac{1}{2\pi f C}$$

where X_C is the capacitive reactance in ohms, f is the frequency, and C is the capacitance.