

eP16MyHDL

July 17, 2016

This file and it's support can be found @ <https://github.com/DRuffer/eP16MyHDL>

To run this in the interactive editor, type: **jupyter notebook eP16MyHDL.ipynb**.

To just run as a script, type: **runipy eP16MyHDL.ipynb**. This is not working at the moment.

To get PDF output, type: **jupyter nbconvert --to pdf eP16MyHDL.ipynb**. However, you have to setup Pandoc and LaTeX.

After runipy, **echo Exit Code is %ERRORLEVEL%** displays: **True** if the assert passes and **False** if it does not.

Note that it's called **\$LastExitCode** in PowerShell.

```
In [1]: import re
import sys
import time
import unittest
import subprocess
from myhdl import *
from random import randrange

print ("Current date and time %s" % time.strftime("%c") )

print ("Python version %s" % sys.version.replace("|", "\n\r"))
```

Current date and time 07/17/16 17:33:34

Python version 2.7.12

Continuum Analytics, Inc.

(default, Jun 29 2016, 11:07:13) [MSC v.1500 64 bit (AMD64)]

Starting from the MyHDL D flip-flop example at <http://www.myhdl.org/docs/examples/flipflops.html>

```
In [2]: def dff(led_0, sw_7, clk):

    @always(clk.posedge)
    def logic():
        led_0.next = sw_7

    return logic

def test_dff():

    q, d, clk = [Signal(bool(0)) for i in range(3)]

    dff_inst = dff(q, d, clk)

    @always(delay(10))
    def clkgen():
```

```

        clk.next = not clk

    @always(clk.negedge)
    def stimulus():
        d.next = randrange(2)

    return dff_inst, clkgen, stimulus

def simulate(timesteps):
    tb = traceSignals(test_dff)
    sim = Simulation(tb)
    sim.run(timesteps)

simulate(2000)

<class 'myhdl._SuspendSimulation': Simulated 2000 timesteps

```

I'm going to skip the simulation part, for the moment, because I'm more interested in the VHDL output

```

In [3]: q, d, clk = [Signal(bool(1)) for i in range(3)]

    for f in (toVHDL, toVerilog):
        f(dff, q, d, clk)

```

Now, we can tell Lattice Diamond to do its thing.

```

In [4]: p = subprocess.Popen('pnmainc ep16MyHDL.tcl', shell=True, \
                             stdout=subprocess.PIPE, \
                             stderr=subprocess.STDOUT)
    for line in p.stdout.readlines():
        line = re.sub(r'[^-]', '', line.strip())
        if ((-1 != line.find("WARNING")) or (-1 != line.find("ERROR"))):
            print (line)
    p.wait()

```

WARNING - par: The following clock signals will be routed by using generic routing resource and may suf

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Out[4]: 0

At this point, we should have some results on the serial port, but not until we get there.

Instead, led_0 turns on when sw_7 is pressed.

Good 1st test.