

DSBA CS224n 2021 Study

[Lecture 05] Language Models and RNNs [Lecture 06] Simple and LSTM RNNs



고려대학교 산업경영공학과

Data Science & Business Analytics Lab

발표자: 고유경



- 1 Language Model
- 2 RNN Language Model
- 3 Problem of RNN
- 4 LSTM
- 5 Conclusion



Description

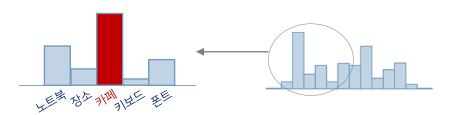


- 확률 분포를 기반으로 주어진 문맥(sequence) 이후에 위치할 단어 예측
 - 시퀀스의 결합 확률 by multiplication rule

$$P(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(T)}) = P(\mathbf{x}^{(1)}) \times P(\mathbf{x}^{(2)} | \mathbf{x}^{(1)}) \times \dots \times P(\mathbf{x}^{(T)} | \mathbf{x}^{(T-1)}, \dots, \mathbf{x}^{(1)})$$

$$= \prod_{t=1}^{T} P(\mathbf{x}^{(t)} | \mathbf{x}^{(t-1)}, \dots, \mathbf{x}^{(1)})$$

• $P(x^{(3)}| 코딩하기,좋은)$





N-gram LM, Neural LM

N-gram Language Model

P(코딩하기, 좋은, 카페, 추천)

uni-gram

P(코딩하기) P(좋은) P(카페) P(추천)

bi-gram

P(코딩하기) P(좋은|코딩하기) P(카페|좋은) P(추천|카페)

P(카페| 코딩하기,좋은 $) = \frac{count(코딩하기,좋은,카페)}{count(코딩하기,좋은)}$

- ✓ 이전에 등장한 n개의 단어를 바탕으로 예측
- ✓ count(빈도)를 기반으로 확률 계산
- ✓ (-) sparsity problem: n-gram chunk 문서 내 등장 x



N-gram LM, Neural LM

N-gram Language Model

P(코딩하기, 좋은, 카페, 추천)

uni-gram

P(코딩하기) P(좋은) P(카페) P(추천)

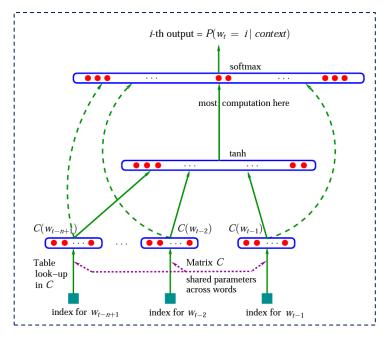
bi-gram

P(코딩하기) P(좋은|코딩하기) P(카페|좋은) P(추천|카페)

P(카페| 코딩하기,좋은 $) = \frac{count(코딩하기,좋은,카페)}{count(코딩하기,좋은)}$

- ✓ 이전에 등장한 n개의 단어를 바탕으로 예측
- ✓ count(빈도)를 기반으로 확률 계산
- ✓ (-) sparsity problem: n-gram chunk 문서 내 등장 x

Neural Language Model



A neural probabilistic language model (Bengio et al, 2003)

- ✓ 미리 지정한 window size 이전 단어를 바탕으로 예측
- ✓ word embedding: 단어의 distributed representation 학습
- ✓ (-) window size가 커지면 파라미터 수 증가 -> 연산 부담, 과적합 가능



N-gram LM, Neural LM

N-gram Language Model

P(코딩하기, 좋은, 카페, 추천)

uni-gram

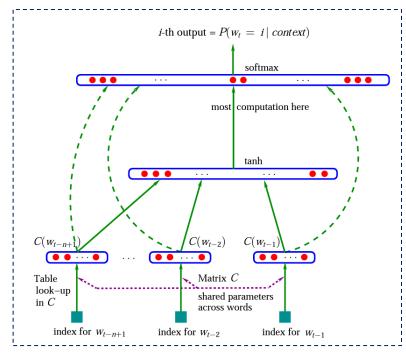
P(코딩하기) P(좋은) P(카페) P(추천)

bi-gram

P(코딩하기) P(좋은|코딩하기) P(카페|좋은) P(추천|카페)

P(카페| 코딩하기,좋은 $) = \frac{count(코딩하기,좋은,카페)}{count(코딩하기,좋은)}$

Neural Language Model



A neural probabilistic language model (Bengio et al, 2003)

✓ 입력 길이가 고정되어(N, window size) 이전에 등장하는 모든 단어를 고려할 수 없음



Architecture

Output distribution

$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$

3 Hidden States

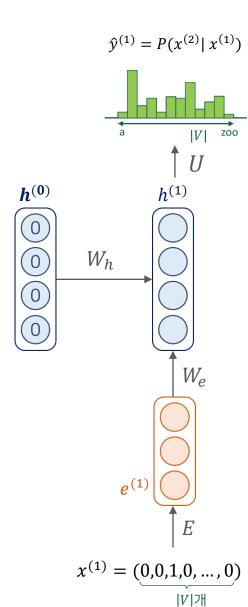
$$egin{align} m{h}^{(t)} &= \sigma \left(m{W}_h m{h}^{(t-1)} + m{W}_e e^{(t)} + m{b}_1
ight) \ m{W}_h &: (d_h imes d_h), \ m{W}_e &: (d_e imes d_h) \ \end{pmatrix}$$

② Word embedding

$$e^{(t)} = Ex^{(t)}$$
 $E: (|V| \times d_e)$

① Input word sequence

• 원핫 벡터 $oldsymbol{x}^{(t)} \in \mathbb{R}^{|V|}$





Architecture

Output distribution

$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$

3 Hidden States

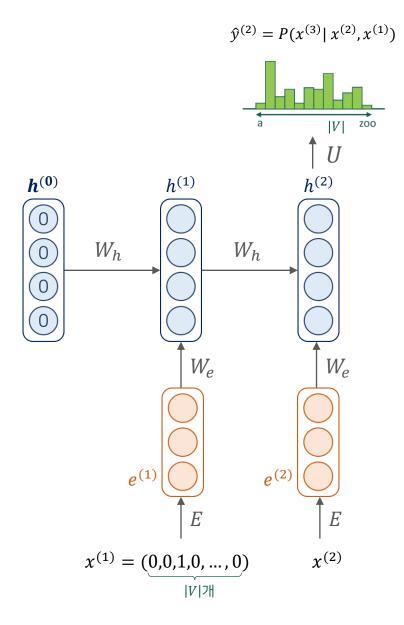
$$egin{aligned} m{h}^{(t)} &= \sigma \left(m{W}_h m{h}^{(t-1)} + m{W}_e e^{(t)} + m{b}_1
ight) \ m{W}_h &: (d_h imes d_h), \ m{W}_e &: (d_e imes d_h) \end{aligned}$$

② Word embedding

$$e^{(t)} = Ex^{(t)}$$
 $E: (|V| \times d_e)$

① Input word sequence

• 원핫 벡터 $oldsymbol{x}^{(t)} \in \mathbb{R}^{|V|}$





Architecture

④ Output distribution

$$\hat{oldsymbol{y}}^{(t)} = \operatorname{softmax}\left(oldsymbol{U}oldsymbol{h}^{(t)} + oldsymbol{b}_2
ight) \in \mathbb{R}^{|V|}$$

③ Hidden States

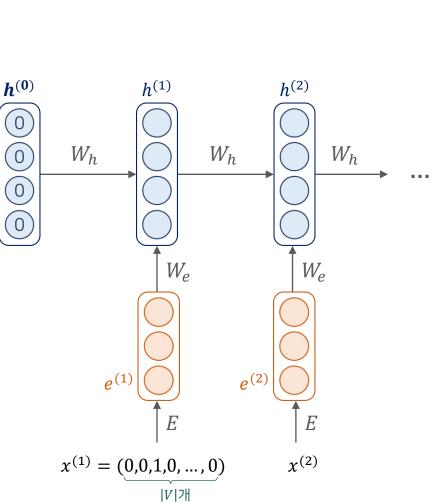
$$egin{aligned} m{h}^{(t)} &= \sigma \left(m{W}_h m{h}^{(t-1)} + m{W}_e e^{(t)} + m{b}_1
ight) \ m{W}_h &: (d_h imes d_h), \ m{W}_e &: (d_e imes d_h) \end{aligned}$$

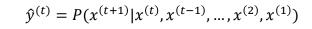
② Word embedding

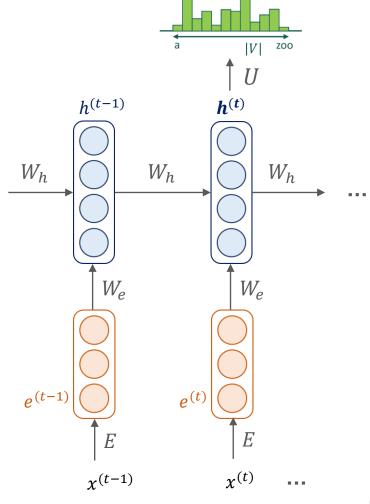
$$e^{(t)} = Ex^{(t)}$$
 $E: (|V| \times d_e)$

① Input word sequence

• 원핫 벡터 $oldsymbol{x}^{(t)} \in \mathbb{R}^{|V|}$

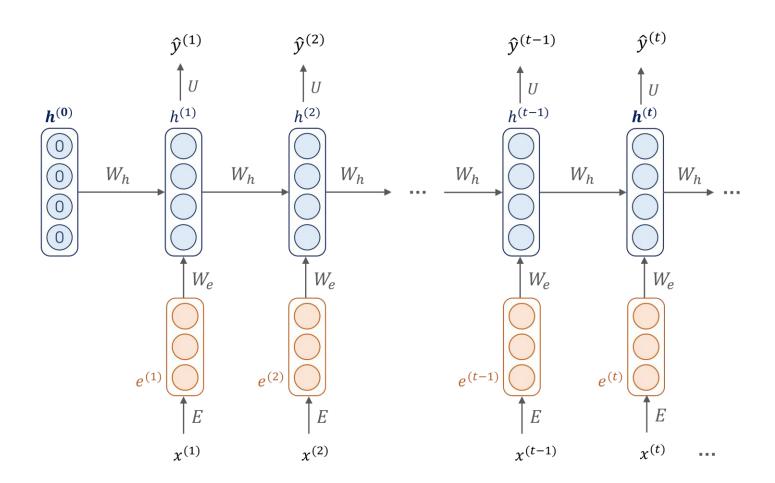








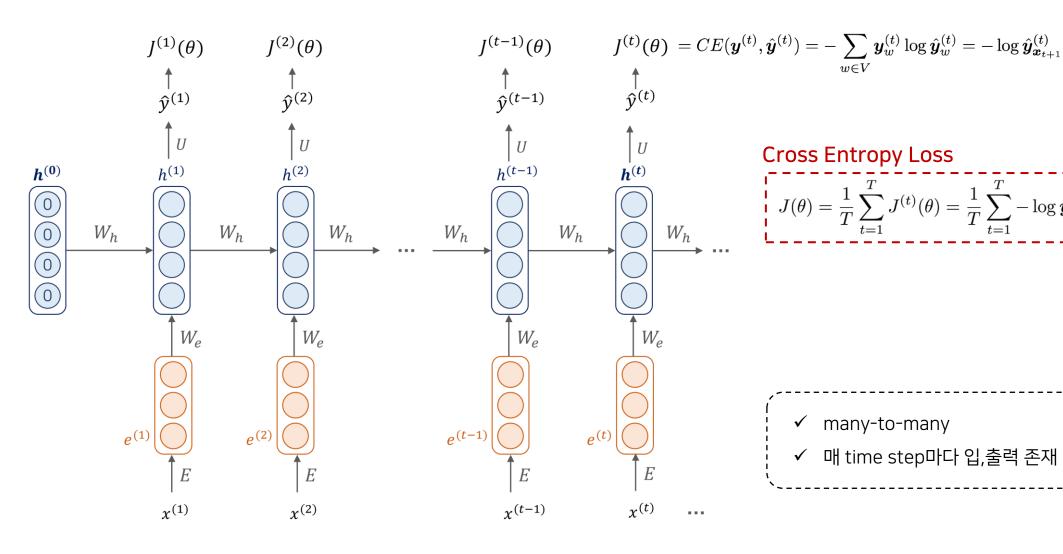
Loss Function



- ✓ many-to-many
- ✓ 매 time step마다 입,출력 존재



Loss Function



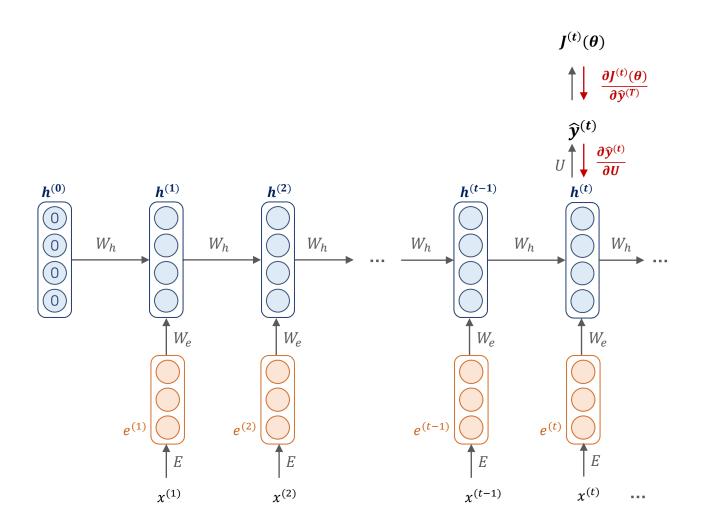
Cross Entropy Loss

$$J(\theta) = \frac{1}{T} \sum_{t=1}^{T} J^{(t)}(\theta) = \frac{1}{T} \sum_{t=1}^{T} -\log \hat{\boldsymbol{y}}_{\boldsymbol{x}_{t+1}}^{(t)}$$

- ✓ many-to-many
- ✓ 매 time step마다 입,출력 존재



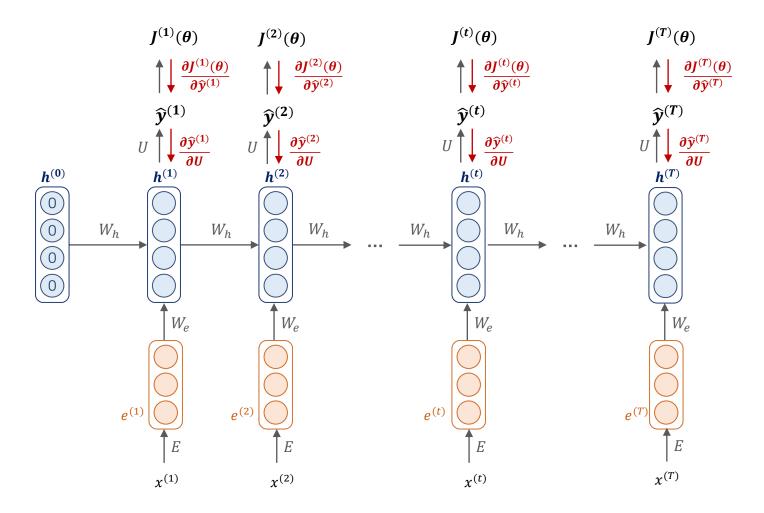
Back Propagation Through Time (BPTT) ①



$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$
 $m{h}^{(t)} = \sigma\left(m{W}_hm{h}^{(t-1)} + m{W}_em{e}^{(t)} + m{b}_1
ight)$



Back Propagation Through Time (BPTT) ①



$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$
 $m{h}^{(t)} = \sigma\left(m{W}_hm{h}^{(t-1)} + m{W}_em{e}^{(t)} + m{b}_1\right)$

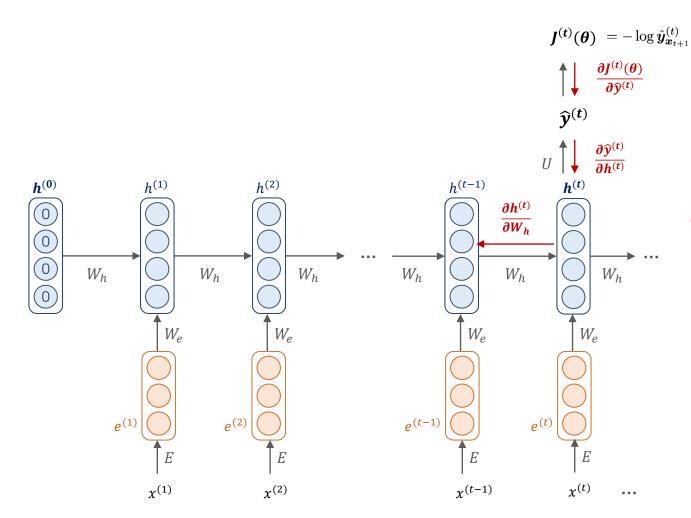
$$\frac{\partial J(\theta)}{\partial U} = \sum_{t=1}^{T} \frac{\partial J^{(t)}(\theta)}{\partial U}$$

$$U^{new} = U^{old} - \alpha \frac{\partial J(\theta)}{\partial U}$$



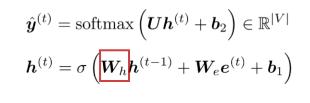
Back Propagation Through Time (BPTT) ②

$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$
 $m{h}^{(t)} = \sigma\left(m{W}_hm{h}^{(t-1)} + m{W}_em{e}^{(t)} + m{b}_1\right)$





Back Propagation Through Time (BPTT) ②





 $h^{(0)}$

0

 $\frac{\partial h^{(1)}}{\partial W_h}$

 W_h

RNN Language Model

Back Propagation Through Time (BPTT) ②

 $\frac{\partial h^{(2)}}{\partial h^{(1)}}$

 W_h

 $x^{(1)}$

 $\frac{\partial h^{(3)}}{\partial h^{(2)}}$

 W_h

 W_e

 $x^{(2)}$

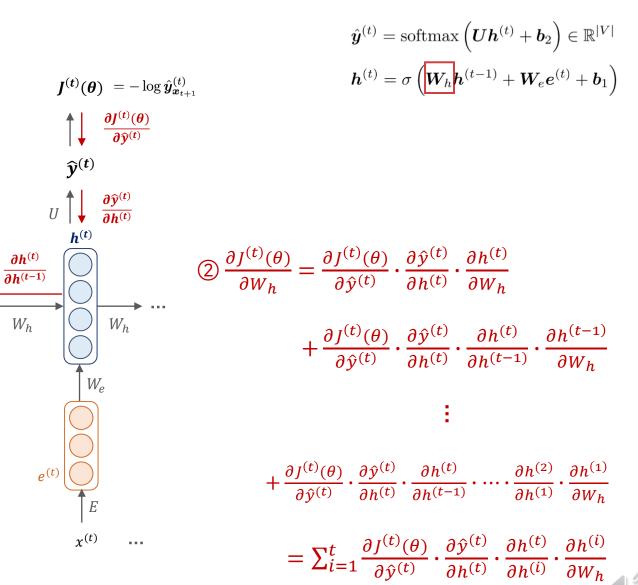
 $h^{(t-1)}$

 W_h

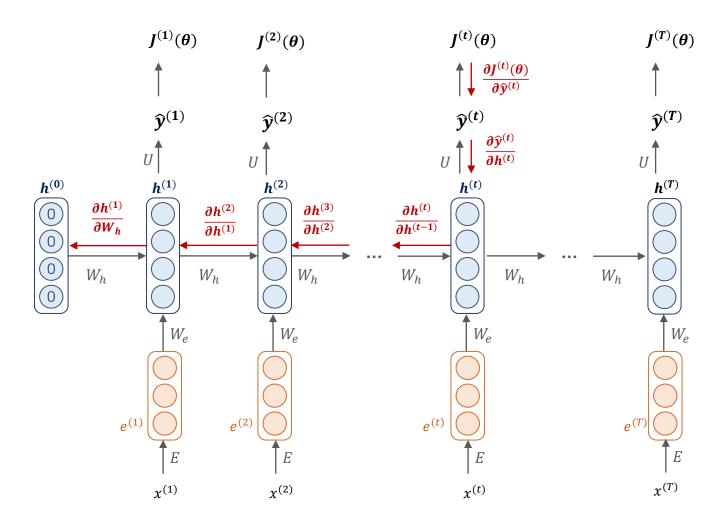
 $\partial h^{(t-1)}$

 $\overline{\partial h^{(t-2)}}$

 W_h



Back Propagation Through Time (BPTT) ②

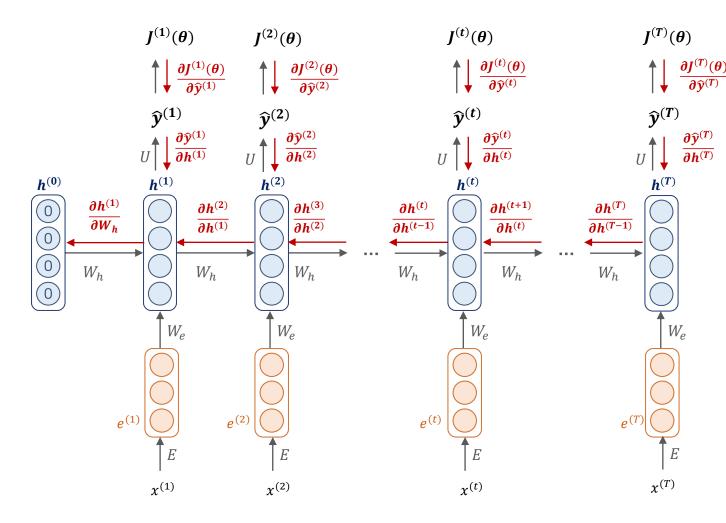


$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$
 $m{h}^{(t)} = \sigma\left(m{W}_hm{h}^{(t-1)} + m{W}_em{e}^{(t)} + m{b}_1\right)$

$$\frac{\partial J(\theta)}{\partial W_h} =$$



Back Propagation Through Time (BPTT) ②



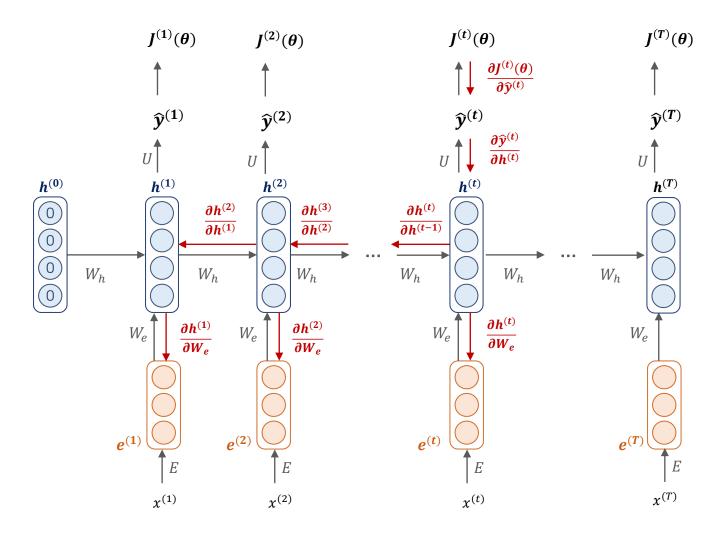
$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$
 $m{h}^{(t)} = \sigma\left(m{W}_hm{h}^{(t-1)} + m{W}_em{e}^{(t)} + m{b}_1\right)$

$$\frac{\partial J(\theta)}{\partial W_h} = \sum_{t=1}^{T} \frac{\partial J^{(t)}(\theta)}{\partial W_h}$$

$$W_h^{new} = W_h^{old} - \alpha \frac{\partial J(\theta)}{\partial W_h}$$



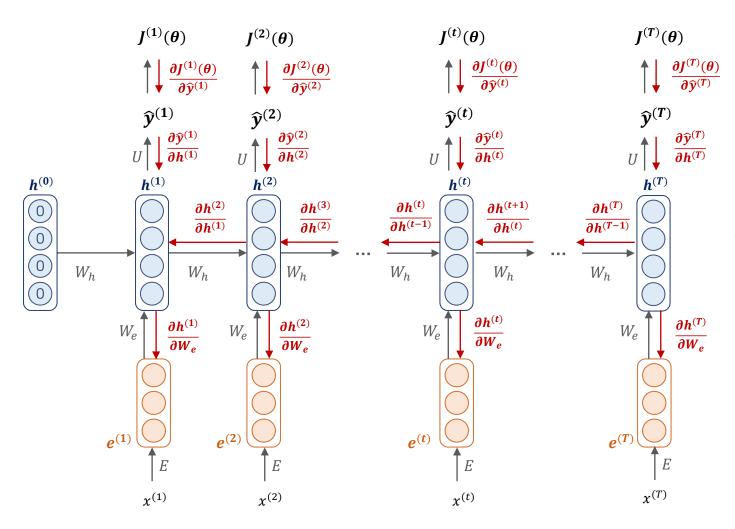
Back Propagation Through Time (BPTT) ③



$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$
 $m{h}^{(t)} = \sigma\left(m{W}_hm{h}^{(t-1)} + m{W}_em{e}^{(t)} + m{b}_1\right)$



Back Propagation Through Time (BPTT) ③



$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$
 $m{h}^{(t)} = \sigma\left(m{W}_hm{h}^{(t-1)} + m{W}_em{e}^{(t)} + m{b}_1\right)$

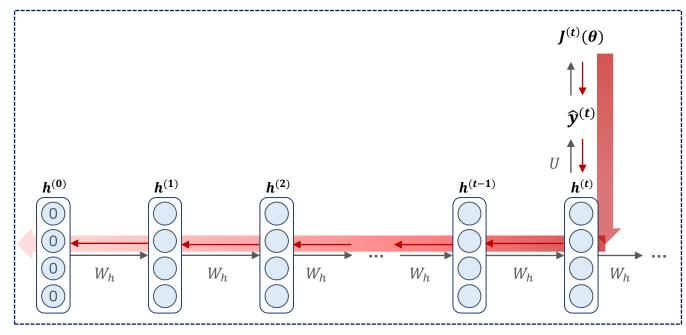
$$\frac{\partial J(\theta)}{\partial W_e} = \sum_{t=1}^{T} \frac{\partial J^{(t)}(\theta)}{\partial W_e}$$

$$W_e^{new} = W_e^{old} - \alpha \frac{\partial J(\theta)}{\partial W_e}$$



Problem of RNN

① Vanishing/Exploding Gradients



$$\hat{m{y}}^{(t)} = \operatorname{softmax}\left(m{U}m{h}^{(t)} + m{b}_2\right) \in \mathbb{R}^{|V|}$$
 $m{h}^{(t)} = \sigma\left(m{W}_hm{h}^{(t-1)} + m{W}_em{e}^{(t)} + m{b}_1\right)$
 $= m{S}^{(t)}$

$$\frac{\partial h^{(t)}}{\partial h^{(t-1)}} = \frac{\partial h^{(t)}}{\partial s^{(t)}} \cdot \frac{\partial s^{(t)}}{\partial h^{(t-1)}} = \frac{\partial h^{(t)}}{\partial s^{(t)}} \cdot W_h$$

$$\frac{\partial J^{(t)}(\theta)}{\partial W_h} = \frac{\partial J^{(t)}(\theta)}{\partial \hat{y}^{(t)}} \cdot \frac{\partial \hat{y}^{(t)}}{\partial h^{(t)}} \cdot \frac{\partial h^{(t)}}{\partial W_h} + \frac{\partial J^{(t)}(\theta)}{\partial \hat{y}^{(t)}} \cdot \frac{\partial \hat{y}^{(t)}}{\partial h^{(t)}} \cdot \frac{\partial h^{(t)}}{\partial h^{(t)}} \cdot \frac{\partial h^{(t)}}{\partial h^{(t-1)}} \cdot \frac{\partial h^{(t-1)}}{\partial W_h} \cdot \dots + \frac{\partial J^{(t)}(\theta)}{\partial \hat{y}^{(t)}} \cdot \frac{\partial \hat{y}^{(t)}}{\partial h^{(t)}} \cdot \frac{\partial h^{(t)}}{\partial h^{(t-1)}} \cdot \dots \cdot \frac{\partial h^{(2)}}{\partial h^{(1)}} \cdot \frac{\partial h^{(1)}}{\partial W_h}$$

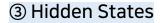
동일한 가중치(W_h) 공유

- \triangleright W_h 가 작을 수록(< 1) 반복적으로 곱해지는 값이 0에 가까워져 gradient vanishing
- \blacktriangleright W_h 가 클 수록(> 1) 반복적으로 곱해지는 값이 기하급수적으로 커져 gradient exploding

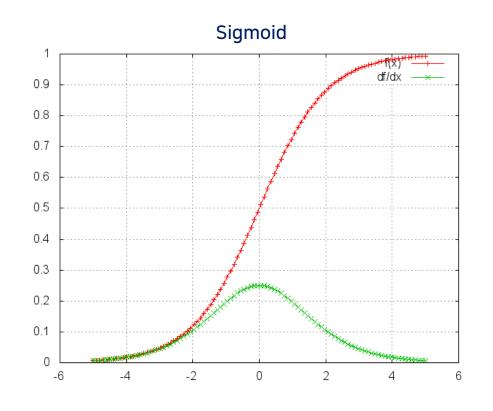


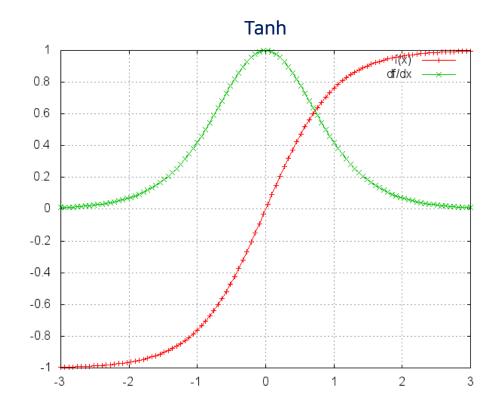
Problem of RNN

Sigmoid vs. Tanh



$$oldsymbol{h}^{(t)} = \sigma \left(oldsymbol{W}_h oldsymbol{h}^{(t-1)} + oldsymbol{W}_e oldsymbol{e}^{(t)} + oldsymbol{b}_1
ight)$$



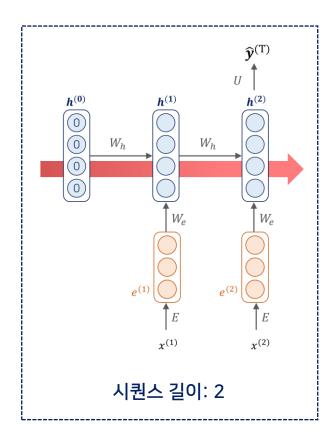


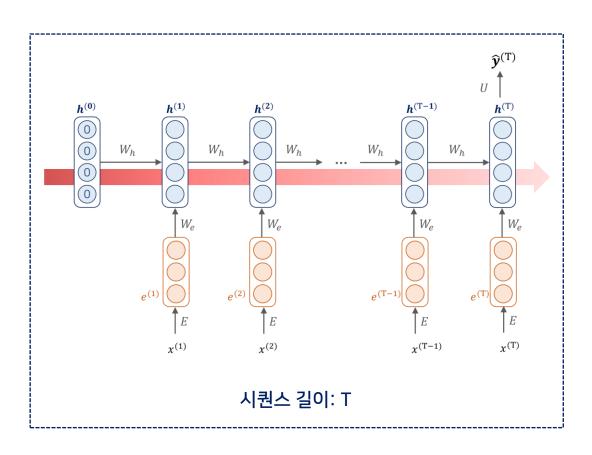
- ✓ Sigmoid: 기울기 0에서 약 0.25 사이
- ✓ Tanh: 기울기 0에서 1 사이 -> gradient vanishing에 더 강함



Problem of RNN

② Long Term Dependency (장기 의존성)



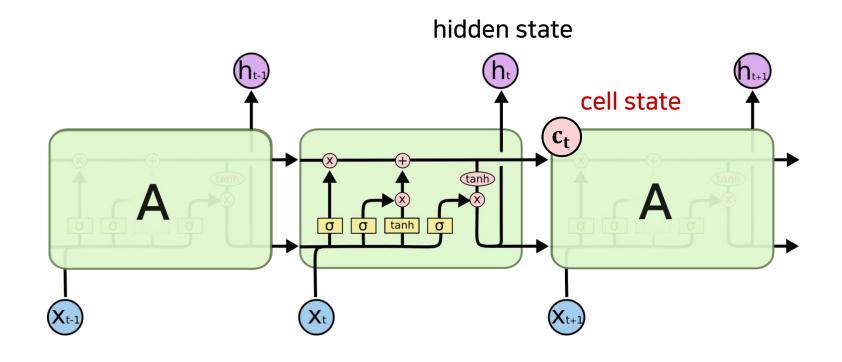


▶ input sequence 길이가 긴 경우, 시퀀스 초반의 정보가 후반 time step의 hidden state를 도출하는데까지 전달되기 어려움 -> Long term dependency를 잘 반영하지 못함



LSTM: Long Short-Term Memory RNN

RNN with Separate Memory



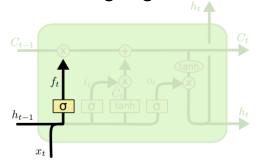
- ① hidden state를 통해 short term memory를 조절하고 cell state를 통해 long term memory 보존
- ② **forget, input, output, 3개의 gate**를 통해 매 time step의 cell state와 hidden state, input에서 취할 정보의 양 결정



LSTM: Long Short-Term Memory RNN

Architecture

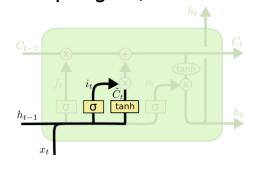
1) forget gate



$$f_t = \sigma(W_f h^{(t-1)} + U_f x^{(t)} + b_f)$$

• 입력 정보(새로운 입력 시퀀스와 이전 시점의 hidden state)에 시그모이드를 취함

② input gate, new cell content



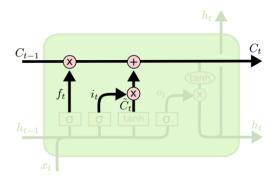
$$i_t = \sigma(W_i h^{(t-1)} + U_i x^{(t)} + b_i)$$

• input gate: 입력 정보에 시그모이드를 취함

$$\widetilde{C}_t = \tanh(W_c h^{(t-1)} + U_c x^{(t)} + b_c)$$

• new cell content: 입력 정보에 tanh를 취함

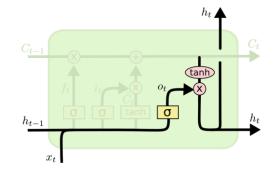
3 Cell state



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

- forget gate: 이전 시점의 cell state에서 어느 정도의 정보를 가져갈 것인지 결정
- input gate: 입력 정보에서 장기 기억으로 가져갈 정보의 양 결정
- element wise product

④ Output gate, hidden state



$$o_t = \sigma(W_o h^{(t-1)} + U_o x^{(t)} + b_o)$$

• output gate: 입력 정보에 시그모이드를 취함

$$h_t = o_t * tanh(C_t)$$

hidden state: 현재 입력과 대비해서
 장기 기억에서 어느 정도의 정보를 단기
 기억으로 사용할지 결정



LSTM: Long Short-Term Memory RNN

Architecture

① forget gate

$$f_t = \sigma(W_f h^{(t-1)} + U_f x^{(t)} + b_f)$$

② input gate

$$i_t = \sigma(W_i h^{(t-1)} + U_i x^{(t)} + b_i)$$

③ Output gate

$$o_t = \sigma(W_o h^{(t-1)} + U_o x^{(t)} + b_o) \longrightarrow h_t = o_t * \tanh(C_t)$$

new cell content

$$\widetilde{C}_t = \tanh(W_c h^{(t-1)} + U_c x^{(t)} + b_c)$$

$$C_t = f_t * C_{t-1} + i_t * \widetilde{C}_t \quad \text{Cell state (장기 기억)}$$

 p_t * tanh (C_t) hidden state (단기 기억)



- ✓ Language Model : 확률 분포를 기반으로 주어진 문맥(sequence) 이후에 위치할 단어 예측
 - N-gram LM: 이전에 등장하는 N개의 단어 chunck를 바탕으로 다음에 올 단어 예측 (sparsity problem)
 - Neural LM: 이전에 등장하는 window size만큼의 단어를 바탕으로 다음에 올 단어 예측
 - input length 에 제한 -> 모든 문맥 고려 불가능

✓ RNN

- input length 에 제한이 없는 sequential neural network
- gradient vanishing /exploding
- long term dependency problem

✓ LSTM

- cell state를 통해 long term memory 보존
- 3개의 gate를 통해 정보의 flow 조절



감사합니다

