Inverse of matrix is:
$$\frac{1}{(z_{x_{1}}^{2}+1)^{2}-(z_{x_{1}}^{2})^{2}}$$
 $(z_{x_{1}}^{2}+1)^{2}-(z_{x_{1}}^{2})^{2}$ $(z_{x_{1}}^{2}+1)^{2}-(z_{x_{1}}^{2})^{2}$ $(z_{x_{1}}^{2}+1)^{2}-(z_{x_{1}}^{2})^{2}$ $(z_{x_{1}}^{2}+1)^{2}-(z_{x_{1}}^{2}$

b) As
$$J \rightarrow 0$$
 β_1 and $\beta_2 \rightarrow 0$
c) As $J \rightarrow 0$ β_1 and $\beta_2 \rightarrow 0$

$$\frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i y_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum \sum x_i} => \beta_1 + \beta_2 \rightarrow \frac{\sum x_i y_i}{\sum x_i} => \beta_1 + \beta_2 \rightarrow$$

 $\beta = (X^{T} \cdot X)^{-1} X^{T} y, X-non-roll don$ $A = (X^{T} \cdot X)^{-1} X^{T} y, X-non-roll don$ $A = (\beta | X) = E((X^{T} \cdot X)^{-1} \cdot X^{T} y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} E(y | X) = (X^{T} \cdot X)^{-1} \cdot X^{T} \cdot$ (XTX) 1XT (E(XB+alX)=(XTX) 1XT (XB+E(alX))=(XTX) 1xT (XB=B $(X^T, X)^{-1} X^T$, $S^2 \omega \cdot ((X^T X)^{-1} X^T)^T =$ 5. (XT.X) XT. EW. X.(XT.X) ~1 c) As now Wean be not itentity matrix => cost covariance between different error terms is can be non-zero => correlated Which breaks the assumption flaof homoscadastic and uncorrelated error terms reaccessory for standart (I application.

d)
$$Cov(y,\beta|X) = (ov(y,[X^T,X)^{-1}X^T,y|X) = Var(y)(x^T,X)^TX^T$$

 $Var(y|X) = (X^T,X)^{-1}X^T = Vor(\beta X + \alpha | X) \cdot X \cdot (X^T,X)^{-1} = S^* w \cdot X(X^T,X)^T$
 $X = \begin{pmatrix} 2 & 1 \\ -1 & 2 \\ 1 & 1 \end{pmatrix}$
 $X = \begin{pmatrix} 2 & 1 \\ -1 & 2 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 6 & 1 \\ 1 & 6 \end{pmatrix}$
 $X = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 6 & 1 \\ 1 & 6 \end{pmatrix}$
 $X = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 6 & 1 \\ 1 & 6 \end{pmatrix}$
 $X = \begin{pmatrix} 6 & 1 \\ 1 & 6 \end{pmatrix} = \begin{pmatrix} 6 & 1 \\ 1 & 6 \end{pmatrix} = \begin{pmatrix} 6 & 1 \\ 1 & 6 \end{pmatrix} = \begin{pmatrix} 6 & 1 \\ 1 & 6 \end{pmatrix} = \begin{pmatrix} 6 & 1 \\ 1 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 1 \end{pmatrix} \quad V_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \quad S_1 = S_2$
 $X = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 1 \end{pmatrix} \quad V_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad S_2 = S_3$
 $X = \begin{pmatrix} 6 & 1 \\ 1 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & -1 \end{pmatrix} \quad V_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad S_2 = S_3$
 $X = \begin{pmatrix} 6 & 1 \\ 1 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & -1 \end{pmatrix} \quad V_3 = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1$

```
import numpy as np
       import pandas
[12]
       0.0s
       # standartised matrix
       x=np.array([[4/3,-1/3],[-5/3,2/3],[1/3,-1/3]])
       # svd decomposition
       p=numpy.linalg.svd(x)
       u1=(p[0].T[0]).reshape(-1,1)
       vh=p[2][0].reshape(1,-1)
       s1=p[1][0]
       # Answer
       s1*u1@vh
     ✓ 0.0s
[71]
```

14 Kis KXn, wisnx1 a) L= ||Xw||2+ d(1-1w||2)= < Xw, Xw>+d(1-cw, w>)= (XW) - XW - 1 (1-wt-w) = W-X-X-W+d(1-W-W) b) $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ $\begin{cases} \frac{\partial L}{\partial w} = 0 \\ \frac{\partial L}{\partial w} = 0 \end{cases}$ (1) d(wt). X. X. W+ wt. X. X. dw d(d(wt) w + wt. dw)= 0

1 × n nxk kxn knx1 Scalar Scalar Scalar 24. X. X. X. du - 2 d w - dw = 0 wt Xt. X + dw = 0 => wt. Xt. X = d.wt & Granspose (X+XW= 1.W) FOC: [X6.X W= dag) XX=VZZVt) (ww=1 of From 6 we can notice that wis the eigenvector of xtx. with the eigenvalue of.
We also know that & w vector is normalised => it is the column vector of V So, in order to maximize $\|Xw\|^2 = w_{\perp}^t X^T X y = A w_{\perp}^t y = A$,

We need to choose eigenvector w_{\perp} which corresponds to the highest

eigenvalue, as $d_{1,2} d_{2,2} > \cdots > 0 = 0$ the first column of W corresponds to the highest eigenvalue = s it maximises the expression.