Homework2

Programmers

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Clear the Workspace

```
close all;
clear all;
clc;
```

Homework2_1_2

• In this task we want to make a psudo-integrated filter and use the function we made to filter input signal

Here we declare some variables and signals

```
h = 0.1 * ones(1, 10);
t = 0:1:199;
x = [ones(1, 25) zeros(1, 25)];
```

Here we make the input signal which its T is 50

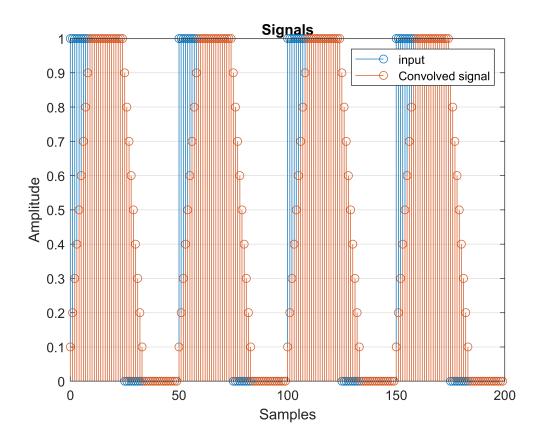
```
for i = 1:3
    x = [x ones(1, 25) zeros(1, 25)];
end
```

Here we make sure the length of y matches with input signal

```
y = myconv(x, h);
y = y(1:200);
```

Here we plot signals on each other

```
figure('Name', 'Convolution');
stem(t, x);
xlabel('Samples');
ylabel('Amplitude');
title('Signals');
grid on;
hold on;
stem(t, y);
legend('input', 'Convolved signal');
```



Homework2_1_3

• Here we do what we did prior for another filter, with myconv function

Now we declare variables and signals we want to use

```
h = [1];
for j = 1:14
    h = [h 0.75 ^ (j)];
end

h = 0.25 * h;
x = [ones(1, 25) zeros(1, 25)];
t = 0:1:199;

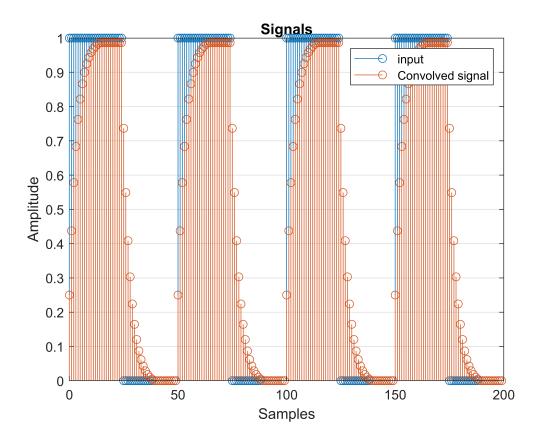
for i = 1:3
    x = [x ones(1, 25) zeros(1, 25)];
end
```

Here we make sure the length of y matches with input signal

```
y = myconv(x, h);
y = y(1:200);
```

Here we plot signals on each other

```
figure('Name', 'Convolution');
stem(t, x);
xlabel('Samples');
ylabel('Amplitude');
title('Signals');
grid on;
hold on;
stem(t, y);
legend('input', 'Convolved signal');
```



Homework2 1 4

• Here we do the same things as we did till now for another filter

We declare variables and signals now

```
x = [ones(1, 25) zeros(1, 25)];
t = 0:1:199;

for i = 1:3
    x = [x ones(1, 25) zeros(1, 25)];
end

y = myconv([1, -1], x);

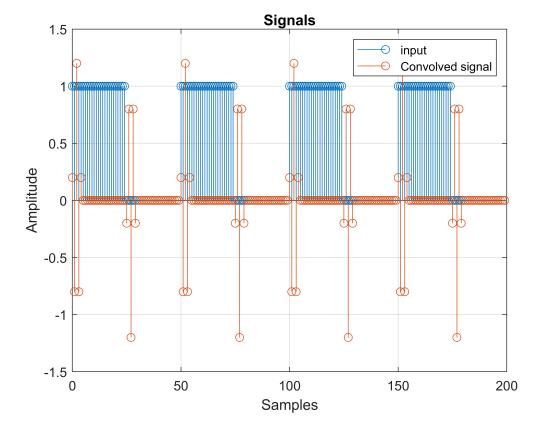
for i = 1:4
    y = myconv([1, -1], y);
```

Here we make sure the length of y matches with input signal

```
y = 1/5 * y;
y = y(1:200);
```

Here we plot signals on each other

```
figure('Name', 'Convolution');
stem(t, x);
xlabel('Samples');
ylabel('Amplitude');
title('Signals');
grid on;
hold on;
stem(t, y);
legend('input', 'Convolved signal');
```



Homework2_2

- Main purpose of this task is filtering of noisy signals
- In this part we want to make signals and then plot it

Now first we declare signals and variables below

```
M = 100;
```

```
n1 = 0:1:200;

n = 0:1:100;

w = 0.54 - 0.46 * sin(2 * pi * n / M);

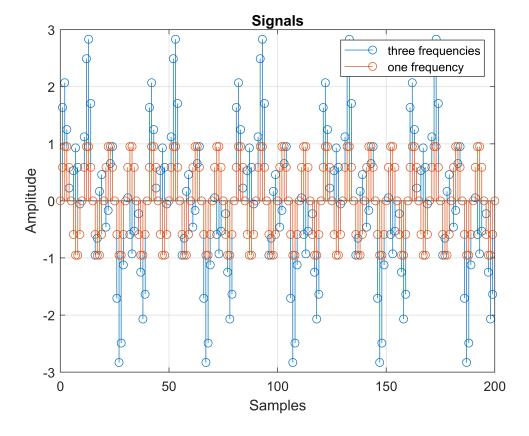
h = w .* (0.25 * sinc(0.25 * (n - M / 2)) - 0.15 * sinc(0.15 * (n - M / 2)));

s = sin(0.2 * pi * n1);

x = s + sin(0.05 * pi * n1) + sin(0.35 * pi * n1);
```

Now we plot our signal with and without interferenced signals

```
figure('Name', 'signals');
stem(n1, x);
xlabel('Samples');
ylabel('Amplitude');
title('Signals');
grid on;
hold on;
stem(n1, s);
legend('three frequencies', 'one frequency');
```

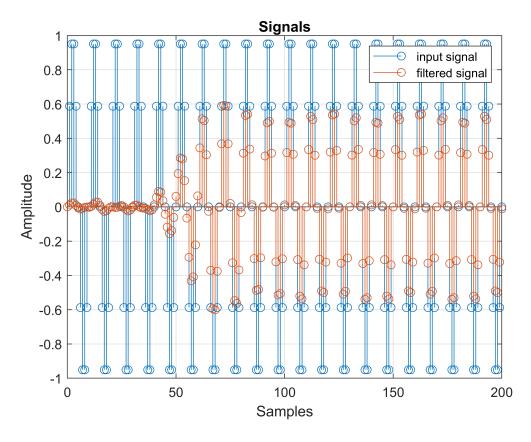


Homework2_2_2:

Here we filter signal, and plot signals on each other

```
t = -50:50;
y = filter(h, 1, x);
figure('Name', 'signals');
stem(n1, s);
xlabel('Samples');
ylabel('Amplitude');
```

```
title('Signals');
grid on;
hold on;
stem(n1, y);
legend('input signal', 'filtered signal');
```



Homework2 2 3:

• Here we make a filter with "filterDesigner" toolbox and then filter our signal with it.

Here we used Eliptic filter

```
FD = Filter_Designer;
y1 = FD.filter(x);
```

Now we plot signals on each other

```
figure('Name', 'signals_2');
stem(n1, s);
xlabel('Samples');
ylabel('Amplitude');
title('Signals');
grid on;
hold on;
stem(n1, y1);
legend('input signal', 'filtered signal_2');
```

