```
MACHINE m0
      Describes a road intersections
      Conventions:
      o variables modelling the environment have names all
      in CAPITAL
      o variables describing the state of the controller are
      all LOWER CASES
VARIABLES
      EW
           Number of cars crossing the intersection in the
           east-west direction
       NS Number of cars crossing in the north-south direction
INVARIANTS
       inv1: EW \in \mathbb{N}
       inv2: NS \in \mathbb{N}
       inv3: EW = 0 \lor NS = 0
           YOUR INVARIANT HERE:
           we want to prevent cars from colliding
           in the intersection
EVENTS
Initialisation
      Initially, the intersection
      is empty
      begin
            act1: EW := 0
            act2: NS := 0
      end
Event ENTER_NORTH (ordinary) \hat{=}
     Environment phenomenon.
      You may have to edit this
      when
            grd1: EW = 0
      then
            act1: NS := NS + 1
      end
Event EXIT_SOUTH (ordinary) \hat{=}
      Environment phenomenon.
      You may have to edit this
      when
            grd1: NS > 0
      then
            act1: NS := NS - 1
      end
Event ENTER_EAST \langle \text{ordinary} \rangle =
      Environment phenomenon.
      You may have to edit this
      when
            grd1: NS = 0
      then
            \mathbf{act1} \colon EW := EW + 1
      end
Event EXIT_WEST ⟨ordinary⟩ \hat{=}
      Environment phenomenon.
      You may have to edit this
      when
            grd1: EW > 0
```

then

10.02.2018 22:19 Page 1 of 2

 $\mathbf{act1} \colon EW := EW - 1$

 \mathbf{END}

 \mathbf{end}

10.02.2018 22:19 Page 2 of 2