

Bayesian Networks

Knowledge Representation

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- (Content adapted from Erman Acar)



Overview

1. Foundations

Degrees of Belief, Belief Dynamics, Independence, Bayes Theorem, Marginalization

2. Bayesian Networks

Graphs and their Independencies, Bayesian Networks, d-Separation

3. Tools for Inference

Factors, Variable Elimination, Elimination Order, Interaction Graphs, Graph pruning

4. Exact Inference in Bayesian Networks

Posterior Marginal, Maximum – A-Posteriori, Most Probable Explanation

Lecture 4: Exact Inference in Bayesian Networks

Lecture Overview

Posterior Marginals

Joint Marginal, Normalization, Computation

More About Factors

Maximizing-Out, Extended Factors

Most Likely Instantiations

Maximum A-Posteriori, Most Probable Explanation, Computation

Computing Posterior Marginals

Definition

We already saw how we can compute the prior marginal $\Pr(Q)$ with $Q \subseteq V$ via variable elimination.

Now we want to compute the distribution over Q given some evidence e via variable elimination

We call this the **posterior marginal** $P(Q|e)$.

Note that the prior marginal is just a special case of the posterior marginal where the evidence is empty.

Approach

Recall that $\Pr(A|B) = \frac{\Pr(A \wedge B)}{\Pr(B)}$, hence we can compute the posterior marginal through normalizing the joint marginal.

So for query variables Q and evidence e we compute $\Pr(Q|e) = \frac{\Pr(Q \wedge e)}{\Pr(e)}$

The overall approach is then as follows:

- Reduce all factors w.r.t. e
- Compute the joint marginal $\Pr(Q \wedge e)$
- Sum-out Q to obtain $\Pr(e)$
- Compute $\Pr(Q|e) = \frac{\Pr(Q \wedge e)}{\Pr(e)}$

Example

$$Q = \{C\}, e = \{A = \text{true}\}$$

$$\begin{aligned}\Pr(Q \wedge e) &= \sum_{A,B} (\Theta_A \Theta_{B|A} \Theta_{C|B})^e \\ &= \sum_{A,B} \Theta_A^e \Theta_{B|A}^e \Theta_{C|B}^e\end{aligned}$$

First, reduce all factors w.r.t. $A = \text{true}$:

| $A \mid \Theta_A^e$ | | $A \quad B \mid \Theta_{B A}^e$ | | | $B \quad C \mid \Theta_{C B}^e$ | | |
|---------------------|----|---------------------------------|-------|----|---------------------------------|-------|----|
| true | .6 | true | true | .9 | true | true | .3 |
| | | true | false | .1 | true | false | .7 |
| | | | | | false | true | .5 |
| | | | | | false | false | .5 |

Then we pick an ordering, say, first A then B resulting in $\Pr(Q \wedge e) = \sum_B \Theta_{C|B}^e \sum_A \Theta_A^e \Theta_{B|A}^e$

$A \rightarrow B \rightarrow C \quad G4$

| A | B | $\Theta_{B A}$ | B | C | $\Theta_{C B}$ |
|-------|-------|----------------|-------|-------|----------------|
| true | true | .9 | true | true | .3 |
| true | false | .1 | true | false | .7 |
| false | true | .2 | false | true | .5 |
| false | false | .8 | false | false | .5 |

| A | Θ_A |
|-------|------------|
| true | .6 |
| false | .4 |

Example – Continued

So given

| A | Θ_A^e | A | B | $\Theta_{B A}^e$ | B | C | $\Theta_{C B}^e$ |
|------|--------------|------|-------|------------------|-------|-------|------------------|
| true | .6 | true | true | .9 | true | true | .3 |
| | | true | false | .1 | true | false | .7 |
| | | | | | false | true | .5 |
| | | | | | false | false | .5 |

We can compute $\Pr(Q \wedge e) = \sum_B \Theta_{C|B}^e \sum_A \Theta_A^e \Theta_{B|A}^e$ via variable elimination.

| A | B | $\Theta_A^e \Theta_{B A}^e$ | B | $\sum_A \Theta_A^e \Theta_{B A}^e$ | B | C | $\Theta_{C B}^e \sum_A \Theta_A^e \Theta_{B A}^e$ | C | $\sum_B \Theta_{C B}^e \sum_A \Theta_A^e \Theta_{B A}^e$ |
|------|-------|-----------------------------|-------|------------------------------------|-------|-------|---|-------|--|
| true | true | .54 | true | .54 | true | true | .162 | true | .192 |
| true | false | .06 | false | .06 | true | false | .378 | false | .408 |
| | | | | | false | true | .030 | | |
| | | | | | false | false | .030 | | |

From this, we can sum-out C to obtain $\Pr(e)$, for normalizing to obtain $\Pr(Q, e)$:

$$\Pr(a) = 0.6, \quad \Pr(c|a) = \frac{\Pr(c \wedge a)}{\Pr(a)} = \frac{0.192}{0.6} = 0.32, \quad \Pr(\neg c|a) = \frac{\Pr(\neg c \wedge a)}{\Pr(a)} = \frac{0.408}{0.6} = 0.68$$

More About Factors

Maximising-Out – Introduction

Before we saw how to eliminate a variable by summing it out:

| B | C | D | f_1 |
|-------|-------|-------|-------|
| true | true | true | .95 |
| true | true | false | .05 |
| true | false | true | .9 |
| true | false | false | .1 |
| false | true | true | .8 |
| false | true | false | .2 |
| false | false | true | 0 |
| false | false | false | 1 |

Sum-out D

| B | C | $\sum_D f_1$ |
|-------|-------|--------------|
| true | true | 1 |
| true | false | 1 |
| false | true | 1 |
| false | false | 1 |

For some applications, we want to only keep the instantiation with the maximum probability:

| B | C | D | f_1 |
|-------|-------|-------|-------|
| true | true | true | .95 |
| true | true | false | .05 |
| true | false | true | .9 |
| true | false | false | .1 |
| false | true | true | .8 |
| false | true | false | .2 |
| false | false | true | 0 |
| false | false | false | 1 |

max-out D

| B | C | $\max_D f_1$ |
|-------|-------|--------------|
| true | true | .95 |
| true | false | .9 |
| false | true | .8 |
| false | false | 1 |

Maximizing-Out – Formalization

Given a factor f over variables X **maximizing-out** $X \in X$ results in a new factor $(\max_X f)(Y) \stackrel{\text{def}}{=} \max_X f(X, Y)$ over variables $X \setminus X$.

Maximizing out is commutative:

$$\max_X \max_Y f = \max_Y \max_X f$$

If f_1, f_2 are factors and if variable X only appears in factor f_2 then:

$$\max_X f_1 f_2 = f_1 \max_X f_2$$

Extended Factors

When we maximize-out on normal factors, we lose the information on which instantiation maximized the probability.

With **extended factors**, we can keep this information which is necessary for certain queries.

For every maxed-out instantiation, the extended factor assigns a probability and the instantiation which led to the maximization:

| B | C | D | f_1 |
|-------|-------|-------|-------|
| true | true | true | .95 |
| true | true | false | .05 |
| true | false | true | .9 |
| true | false | false | .1 |
| false | true | true | .8 |
| false | true | false | .2 |
| false | false | true | 0 |
| false | false | false | 1 |

max-out D

| B | C | $\max_D f_1$ |
|-------|-------|----------------------|
| true | true | .95, $D=\text{true}$ |
| true | false | .9, $D=\text{true}$ |
| false | true | .8, $D=\text{true}$ |
| false | false | 1, $D=\text{false}$ |

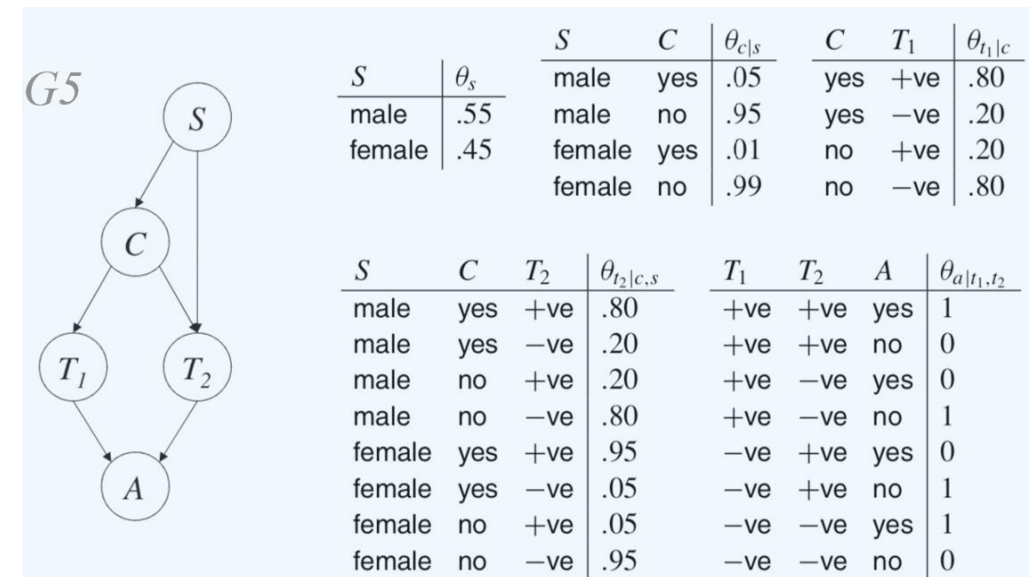
Most Likely Instantiations

Introduction

Example: S =sex, C =has condition, T_1, T_2 = Test results 1 and 2, A = tests agree.

We want to investigate 4 groups:
Female\male that have the condition or not.

Query: Given we only know that the tests agree for a person (A =true), which group does this person belong to?



In other words: what is the most likely instantiation of S and C given A =true?

Maximum A-Posteriori Query

Given a BN over variables V query variables $Q \subseteq V$, and an evidence e the **maximum a-posteriori query (MAP)** gives us the instantiation $\operatorname{argmax}_Q \Pr(Q, e)$ with a probability of $\max_Q \Pr(Q, e)$.

We can do this by first computing $P(Q, e)$ with variable elimination as before and then maximizing-out Q using extended factors.

In our example with $Q = \{S, C\}, A = \text{true}$, we get a MAP with $S=\text{male}$, $C=\text{no}$ with a probability of 0.49.

Most Probable Explanation

Often we are interested in the MAP of all variables except the evidence.

We call a MAP a **most probable explanation (MPE)**, if $Q = V \setminus E$, where E is the set of variables of the evidence.

We can compute it by maximizing-out all variables with extended factors.

In general, MPE is easier to compute than MAP. Hence, MPE is sometimes used to approximate MAP, but they might disagree.

Example 1 – MPE

What is the MPE given $J=\text{true}$, $O=\text{false}$.

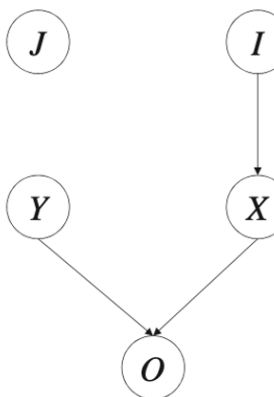
So we have to compute

$$MPE(e) = \max_V (\Theta_I^e \Theta_J^e \Theta_{Y|J}^e \Theta_{X|I,J}^e \Theta_{O|X,Y}^e)$$

We start by doing network pruning, resulting in:

| I | Θ_I^e | J | Θ_J^e | Y | Θ_Y^e |
|-------|--------------|-------|--------------|-------|--------------|
| true | .5 | true | .5 | true | .01 |
| false | .5 | false | .5 | false | .99 |

| I | X | $\Theta_{X I}^e$ | X | Y | O | $\Theta_{O XY}^e$ |
|-------|-------|------------------|-------|-------|-------|-------------------|
| true | true | .95 | true | true | false | .02 |
| true | false | .05 | true | false | false | .02 |
| false | true | .05 | false | true | false | .02 |
| false | false | .95 | false | false | false | .98 |

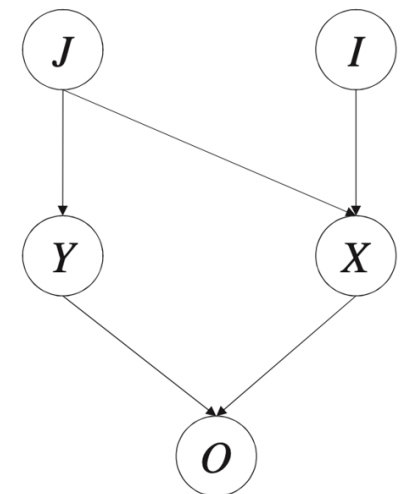


| I | Θ_I | J | Θ_J |
|-------|------------|-------|------------|
| true | .5 | true | .5 |
| false | .5 | false | .5 |

| J | Y | $\Theta_{Y J}$ |
|-------|-------|----------------|
| true | true | .01 |
| true | false | .99 |
| false | true | .99 |
| false | false | .01 |

| I | J | X | $\Theta_{X IJ}$ |
|-------|-------|-------|-----------------|
| true | true | true | .95 |
| true | true | false | .05 |
| true | false | true | .05 |
| true | false | false | .95 |
| false | true | true | .05 |
| false | true | false | .95 |
| false | false | true | .05 |
| false | false | false | .95 |

| X | Y | O | $\Theta_{O XY}$ |
|-------|-------|-------|-----------------|
| true | true | true | .98 |
| true | true | false | .02 |
| true | false | true | .98 |
| true | false | false | .02 |
| false | true | true | .98 |
| false | true | false | .02 |
| false | false | true | .02 |
| false | false | false | .98 |



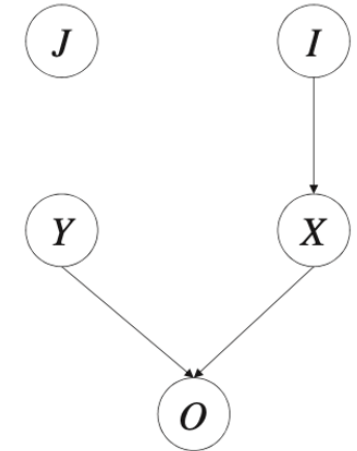
Example 1 - Continued

Assuming elimination order J,I,X,Y,O:

| I | Θ_I^e |
|-------|--------------|
| true | .5 |
| false | .5 |

| J | Θ_J^e |
|-------|--------------|
| true | .5 |
| false | .5 |

| Y | Θ_Y^e |
|-------|--------------|
| true | .01 |
| false | .99 |



| I | X | $\Theta_{X I}^e$ |
|-------|-------|------------------|
| true | true | .95 |
| true | false | .05 |
| false | true | .05 |
| false | false | .95 |

| X | Y | O | $\Theta_{O XY}^e$ |
|-------|-------|-------|-------------------|
| true | true | false | .02 |
| true | false | false | .02 |
| false | true | false | .02 |
| false | false | false | .98 |

$$\max_V(\Theta_I^e \Theta_J^e \Theta_Y^e \Theta_{X|I}^e \Theta_{O|XY}^e) = \max_O \left(\max_Y \left(\max_X \left(\max_I (\Theta_I^e \Theta_{X|I}^e) \Theta_{O|XY}^e \right) \Theta_Y^e \right) \right) \max_J (\Theta_J^e)$$

| | $\max_J \Theta_J^e$ | | X | $\max_I \Theta_I^e \Theta_{X I}^e$ | | Y | O | $\max_X \left(\max_I \Theta_I^e \Theta_{X I}^e \right) \Theta_{O XY}^e$ | | Y | O | $\left(\max_X \left(\max_I \Theta_I^e \Theta_{X I}^e \right) \Theta_{O XY}^e \right) \Theta_Y^e$ | |
|--------|---------------------|-----------------------------|---------------|------------------------------------|---|---------------|---|--|---|---|--|--|--|
| \top | .5 | $J = \text{true}$ | true false | .475 .475 | $I = \text{true}$ $I = \text{false}$ | true false | false false | .0095 .4655 | $I = \text{true}, X = \text{true}$ $I = \text{false}, X = \text{false}$ | true false | false false | .000095 .460845 | $I = \text{true}, X = \text{true}$ $I = \text{false}, X = \text{false}$ |
| I | X | $\Theta_I^e \Theta_{X I}^e$ | | X | Y | O | $\left(\max_I \Theta_I^e \Theta_{X I}^e \right) \Theta_{O XY}^e$ | | | | | | |
| true | true | .475 | \top | true | true | false | .0095 | $I = \text{true}$ | | | | | |
| true | false | .025 | \top | true | false | false | .0095 | $I = \text{true}$ | | | | | |
| false | true | .025 | \top | false | true | false | .0095 | $I = \text{false}$ | | | | | |
| false | false | .475 | \top | false | false | false | .4655 | $I = \text{false}$ | | | | | |
| | | | | | | | | | O | $\max_Y \left(\max_X \left(\max_I \Theta_I^e \Theta_{X I}^e \right) \Theta_{O XY}^e \right) \Theta_Y^e$ | | | |
| | | | | | | | | | false | .460845 | $I = \text{false}, X = \text{false}, Y = \text{false}$ | | |
| | | | | | | | | | $\max_O \left(\max_Y \left(\max_X \left(\max_I \Theta_I^e \Theta_{X I}^e \right) \Theta_{O XY}^e \right) \Theta_Y^e \right)$ | | | | |
| \top | | | | | | | | | .460845 | $I = \text{false}, X = \text{false}, Y = \text{false}, O = \text{false}$ | | | |

| | $\max_O \left(\max_Y \left(\max_X \left(\max_I \Theta_I^e \Theta_{X I}^e \right) \Theta_{O XY}^e \right) \Theta_Y^e \right) \left(\max_J \Theta_J^e \right)$ |
|--------|--|
| \top | .2304225 $J = \text{true}, I = \text{false}, X = \text{false}, Y = \text{false}, O = \text{false}$ |

Example 2 – Compute MAP

We want to know the most likely instantiation of $Q = \{I, J\}$ given $O = \text{true}, \pi = O, Y, X, I, J$

$$\text{So we compute } MAP(Q, e) = \max_Q (\Sigma_{V \setminus Q} \Theta_I^e \Theta_J^e \Theta_{Y|J}^e \Theta_{X|IJ}^e \Theta_{O|X,Y}^e) \\ = \max_Q \Pr(Q, e)$$

“First sum-out $V \setminus Q$, then maximize-out Q ”

We can compute the marginal $\Pr(I, J, e)$ as before resulting in:

| I | J | f_1 | |
|-------|-------|--------|---|
| true | true | .93248 | T |
| true | false | .97088 | T |
| false | true | .07712 | T |
| false | false | .97088 | T |

| I | f_2 | |
|-------|-------|---|
| true | .5 | T |
| false | .5 | T |

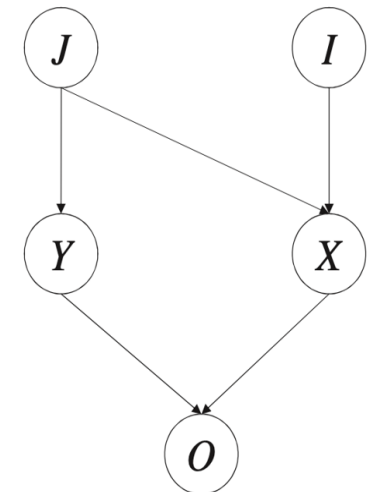
| J | f_3 | |
|-------|-------|---|
| true | .5 | T |
| false | .5 | T |

| I | Θ_I | J | Θ_J |
|-------|------------|-------|------------|
| true | .5 | true | .5 |
| false | .5 | false | .5 |

| J | Y | $\Theta_{Y J}$ |
|-------|-------|----------------|
| true | true | .01 |
| true | false | .99 |
| false | true | .99 |
| false | false | .01 |

| I | J | X | $\Theta_{X IJ}$ |
|-------|-------|-------|-----------------|
| true | true | true | .95 |
| true | true | false | .05 |
| true | false | true | .05 |
| true | false | false | .95 |
| false | true | true | .05 |
| false | true | false | .95 |
| false | false | true | .05 |
| false | false | false | .95 |

| X | Y | O | $\Theta_{O XY}$ |
|-------|-------|-------|-----------------|
| true | true | true | .98 |
| true | true | false | .02 |
| true | false | true | .98 |
| true | false | false | .02 |
| false | true | true | .98 |
| false | true | false | .02 |
| false | false | true | .02 |
| false | false | false | .98 |



Example 2 – Continued

| I | J | f_1 | |
|-------|-------|--------|---|
| true | true | .93248 | T |
| true | false | .97088 | T |
| false | true | .07712 | T |
| false | false | .97088 | T |

| I | f_2 | | J | f_3 | |
|-------|-------|---|-------|-------|---|
| true | .5 | T | true | .5 | T |
| false | .5 | T | false | .5 | T |

Now we are left with computing

$$\max_{I,J} \Pr(I,J,e) = \max_{I,J} f_1 f_2 f_3 = \max_J (\max_I f_1 f_2) f_3$$

| I | J | $f_1 f_2$ | |
|-------|-------|-----------|---|
| true | true | .466240 | T |
| true | false | .485440 | T |
| false | true | .038560 | T |
| false | false | .485440 | T |

| J | $(\max_I f_1 f_2) f_3$ | |
|-------|------------------------|-------------------|
| true | .233120 | $I = \text{true}$ |
| false | .242720 | $I = \text{true}$ |

| J | $\max_I f_1 f_2$ | |
|-------|------------------|-------------------|
| true | .466240 | $I = \text{true}$ |
| false | .485440 | $I = \text{true}$ |

| | $\max_J (\max_I f_1 f_2) f_3$ | |
|---|-------------------------------|-------------------------------------|
| T | .242720 | $I = \text{true}, J = \text{false}$ |

The MAP of I and J given $O = \text{true}$ is: $I = \text{true}, J = \text{false}$

Lecture 4 – Summary

- We introduced extended factors and how to maximize them out.
- We saw how to compute posterior marginals.
“What is the probability of an earthquake when the alarm is ringing.”
- We saw how to compute maximum a-posteriori queries.
“What is the most likely state of the alarm given someone is calling the police.”
- We saw how to compute most probable explanations.
“What is the most probable explanation of a ringing alarm.”