Topic 05 **Computational Complexity**

資料結構與程式設計 **Data Structure and Programming**

10/23/2019

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Why should we care?

- ◆ The most classic example is the "sorting algorithm"
- ◆ With straightforward "selection sort"

```
selectionSort(arr, n) {
  for (i = 0 \text{ to } n - 1)
    for (j = i+1 \text{ to } n-1)
      if (arr[i] > arr[j])
        swap(arr[i], arr[j]);
```

- Best case: original list is in ascending order
 - \rightarrow n + n(n 1) / 2 "for" conditions
 - \rightarrow (n-1)(n-2)/2 "if" comparison operations
- Worst case: original list is in descending order
 - \rightarrow Best case + (n-1)(n-2)/2 "swap" operations
 - → assume (1 swap ~= 3 copies)
- → How fast can you sort a n-element array?

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Knowing the language basics, and having the basic idea of software engineering,

the next big thing for writing a good program is to consider the computational complexity

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```
A Better Sorting Algorithm
```

```
/*** Merge Sort ***/
// for easier explanation, index = [1, size]
// tmpArr has the same size as arr
mergeSort(arr, n) {
  for (i = 1 \text{ to } n; i *= 2) {
    mergeSub(arr, tmpArr, n, i);
     mergeSub(tmpArr, arr, n, i);
mergeSub(arr, resArr, n, i) {
  for (j = 1 \text{ to } n - 2*i +1; j += 2*i)
    mergeArr(arr, resArr, j, j+i-1, j+2*i-1);
  if ((j+i-1) < n) // Remaining (< 2*i) or (< i) elements
     mergeArr(arr, resArr, j, j+i-1, n);
   else copyArr(resArr, arr, j, n);
mergeArr(arr, resArr, n1, n2, n) {    // merge 2 ordered arrays for (i1 = n1 to n2, i2 = n2+1 to n, r = i1; ++r)
     resArr[r] = (arr[i1] <= arr[i2])? arr[i1++] : arr[i2++];
   (i1 > n2)? copyArr(resArr, arr, i2, n)
            : copyArr(resArr, arr, i1, n2);
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```

Merge Sort Analysis

- ◆ Note: the best and worst case complexities are about the same
- ◆ Approximately ---
 - n function calls
 n*log₂n "for" evaluations
 n*log₂n "if" comparisons
 n*log₂n copies

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Comparison: Selection vs. Merge Sort

- Time complexity
 - Selection sort
 - OK for low n
 - Becomes quadric when n gets large
 - Merge sort
 - Much better than bubble sort for large n
- ◆ Space tradeoff
 - Selection sort needs just 1 extra element space
 - Merge sort needs extra n-element space (tmpArr)
 - There are other merge sort algorithms that require just 1 extra space, but the performance is not as well

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Comparison: Selection vs. Merge Sort

Assume

1. "for", "if", "copy" operation: 1 time unit

2. Function call: 10 time units

◆ Selection: (n² - n + 1) ~ (3*n² - 5*n + 4) / 2 Merge: n*log₂n + 10*n

n	10	100	1000	10K	1M
Selection	91	10K	1M	100M	1T
	127	15K	1.5M	150M	1.5T
Merge	140	1.7K	20K	240K	30M
S/M	0.91	8.8	75	625	50K

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FYI, there are many interesting videos for "sorting algorithms"

- ◆ (e.g.) The folk dance series
 - Quick sort:

http://www.youtube.com/watch?v=ywWBy6J5gz8

 Merge sort: http://www.youtube.com/watch?v=XaqR3G_NVoo&fe ature=related

Bubble sort:

http://www.youtube.com/watch?v=lyZQPjUT5B4&feat ure=related

 Insertion sort: http://www.youtube.com/watch?v=ROalU379l3U&feat ure=related

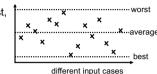
 Shell sort: http://www.youtube.com/watch?v=CmPA7zE8mx0&fe ature=related

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Measurement of Complexity

◆ As we can see, the performance runtime/memory for an algorithm may vary on best, worst, and average cases



♦ Which case is more important?

♦ Worst case?

 Yes, prepare for the raining days... a robust program should be able to handle such cases

♦ Average case?

• Yes, it may be the most commonly happened.

Best case?

• Yes, if it happens, we should take the advantage of it.

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Example: Pattern Generation Problem

- ◆ Given
 - m logic functions F₁(x₁, x₂,..., x_n), F₂,..., F_m, where x₁, x₂,..., x_n are the common input variables
 - → n-input / m-output circuit
 - Expected output values on { F₁, F₂,..., F_m }
- Find
 - An assignment to { x₁, x₂,..., x_n } which satisfies the output function values
- ◆ Algorithms
 - Complete: may take 2ⁿ operations
 - Random: may find it in a few tries; worst case still 2ⁿ
 - → Try "random" for a few patterns first

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An Engineering Approach

- Think of the "cache" mechanism in a computer's memory hierarchy
 - → Don't leave the low-hanging fruits on the tree
 - → Try the simple algorithm for the good cases first
 - → Turn to complex method only when it gets complicated
- ◆ Engineering approach
 - 1. Try super fast dirty approach
 - 2. Use heuristic to handle mostly common cases
 - 3. Turn to a complete algorithm for the remaining difficult cases, if necessary

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Overhead??

- ◆ In the cache memory case
 - Let hit rate = h,.....(0.0 < h < 1.0)
 memory access time = t,
 cache access time = c*t,.....(0.0 < c < 1.0)
 - Ave access time = $h^*c^*t + (1 h)^*(1 + c)^*t$

$$= t + (c - h) * t$$

- → Has overhead if "c > h" (any intuitive explanation?)
- Similarly, this can apply to our engineering approach
- Moreover, if the partial result obtained in the quick step can be reused in the later steps
 - → Possibly to guarantee "overhead-free"
 - → Usually used when there're many repeated problems
 - \rightarrow Best case: $t h^*(1 c) * t$ (why?)

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Importance of Complexity Analysis

- ◆ A good "algorithm" should
 - 1. Be able to finish the task with the fewest operations
 - 2. Use as little memory as possible

However, the above two objectives are usually mutually conflicting, so ---

- ◆ A good "program" should
 - Be able to strike the balance between runtime and memory complexities
 - Have multiple strategies to handle best, average, and worst cases

But, how do we "measure" the complexity of a program?

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Quantitative Complexity Measurement

- How to describe the complexity of an algorithm/program?
 - Number of (normalized) operations
- Number of operations in terms of what?
 - Input size, number of objects, etc
- But the performance varies case by case, and usually needs infinite sampling to determine the best/average/worst cases
 - → Describe the complexity in a range?
 - → Use "upper" or "lower" bound !!

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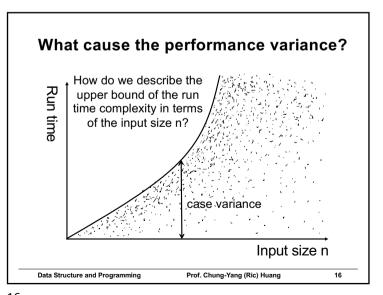
Program Complexity Measurement

- Intuitively, measured by number of instructions
 - (For asymptotic measurement) Should we care about the runtime difference between different instructions? (Not really, why??)
- 1. Analyze the control paths
 - What are the best and worst program flow
- 2. Focus on the looping statements with nonconstant range variables
- 3. Use rules of sum and product to derive the asymptotic measurements

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Asymptotic Notation (O, Ω, Θ)

♦ Big 'oh' O

(bounded above by / no worse than / grows as or slower)

- f(n) = O(g(n)) iff there exist positive constants c and n_0 such that $f(n) \le cg(n)$ for all $n, n \ge n_0$
- e.g. $4n^2 + 2n + 3 \rightarrow O(n^2)$, let c = 5
- Omega Ω

(bounded below by / no better than / grows as or faster)

- $f(n) = \Omega(g(n))$ iff there exist positive constants c and n_0 such that $f(n) \ge cg(n)$ for all $n, n \ge n_0$
- e.g. $4n^2 + 2n + 3 \rightarrow \Omega(n^2)$, let c = 4
- ♦ Theta Θ (bounded above and below by)
 - $f(n) = \Theta(g(n))$ iff there exist positive constants c_1 , c_2 , and n_0 such that $c_1g(n) \le f(n) \le c_2g(n)$ for all n, $n \ge n_0$
 - e.g. $4n^2 + 2n + 3 \rightarrow \Theta(n^2)$, let $c_1 = 4$, $c_2 = 5$

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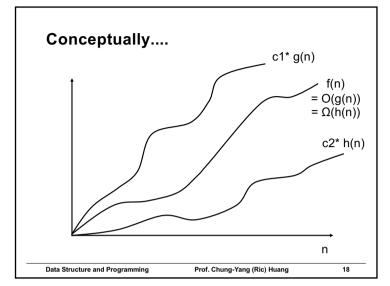
Properties about (O, Ω, Θ)

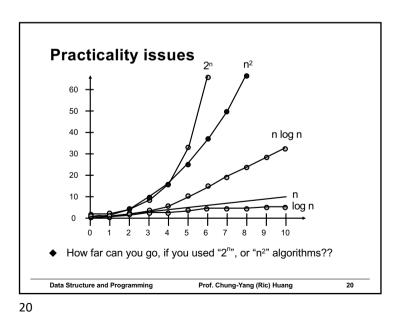
- 1. f(n) = O(g(n)) iff $g(n) = \Omega(f(n))$
- 2. $f(n) = \Theta(g(n))$ iff f(n) = O(g(n)) and $f(n) = \Omega(g(n))$
- 3. Let p(n) be a polynomial function with degree d
 - \Rightarrow p(n) = $\Theta(n^d)$ = $O(n^d)$ = $\Omega(n^d)$
- 4. Let c be any non-negative constant integer
 - \rightarrow p(n) = O(cⁿ) for c > 1
 - → e.g. Use a polynomial time heuristic algorithm to solve an exponential complexity problem
- 5. $\log^{\kappa} n = O(n)$ for any power k

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When we say some program has the complexity O(...) or $\Omega(...)$

> Does O(...) mean the worst case and $\Omega(...)$ mean the best case?

> > Not really...

→ Complexity of an algorithm vs.

Performance measurement of a case

- 1. Input size or number of objects
- 2. Input values
- Non-determined reason

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Example of Complexity Analysis

```
void magicSquare(int** square, int n)
   // n must be odd
   int i, j, k, 1;
   for (i = 0; i < n; i++)
      for (int j = 0; j < n; j++)
    square[i][j] = 0;</pre>
   square[0][(n-1) / 2] = 1;
   key = 2; i = 0; j = (n - 1) / 2;
   while (key <= n * n) {
      if (i - 1 < 0) k = n - 1; else k = i - 1;
      if (j - 1 < 0) k = n - 1; else l = j - 1;
      if (squre[k][1] != 0) i = (i + 1) % n;
      else { i = k; j = 1; }
      square[i][j] = key;
      key++;
◆ Complexity = O(n²) (why ??)
```

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Example of Complexity Analysis

```
int binarySearch(int* a, const int x, const int n)
   int left = 0, right = n - 1;
   while (left <= right) {
      int middle = (left + right) / 2;
      switch (compare(x, a[middle]) {
         case '>': left = middle + 1; break;
         case '<': right = middle - 1; break;</pre>
         case '=': return middle;
   return NOT FOUND;
♦ Complexity = \Theta(\log n) (why??)
                                                  22
```

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Example of Complexity Analysis

```
void permuteGen(char* a, const int k, const int n)
  if (k == n - 1) {
      for (int i = 0; i < n; i++)
        cout << a[i] << " ";
      cout << endl:
      for (int i = k; i < n; i++) {
         swap(a[k], a[i]);
         permuteGen(a, k + 1, n);
         swap(a[k], a[i]);
  Complexity = \Theta(n(n!)) (why??)
```

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Summary

- Important to analyze the complexity of your program
 - If the best, or average cases have much smaller complexity
 - → Use some special routines to handle them first
 - If the worst case is equal or greater than O(n²), and n can be big
 - → Provide options to terminate your program gracefully
- ◆ For complicated problems, time and space complexities are usually complementary
 - Must take care of both at the same time

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