M-10*i*D/8L







			Motion range (°)						Maximum speed (°/s)								
Controlled axes	Repeatability (mm)	Mechanical weight (kg)	J1	J2	73	J4	J5	J6	J1	J2	J3	J4	J5	Ј6	J4 Moment/ Inertia (Nm/kgm²)	J5 Moment/ Inertia (Nm/kgm²)	J6 Moment/ Inertia (Nm/kgm²)
6	± 0.03*	180	340 (370)	235	455	380	360	900	210	210	220	430	450	720	16.1/0.63	16.1/0.63	5.9/0.061

	170deg 5-M8 depth 10 25 45 50 68,5 50 68,5 50 68,5
	Motion range of the J5 axis rotation center J5 axis rotation center J5 axis rotation center 2-M8 depth12 123.9 400
Motion range may be restricted according to the mounting angle!	1882 2032

Robot	M-10 <i>i</i> D/8L
Robot footprint [mm]	343 x 343
Mounting position Floor	•
Mounting position Upside down	•
Mounting position Angle	•
Controller	R-30 <i>i</i> B Plus
Open air cabinet	-
Mate cabinet	0
A-cabinet	•
B-cabinet	0
iPendant Touch	•
Electrical connections	
Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	1
Integrated services	
Integrated signals on upper arm In/Out	8/8
Integrated air supply	1
Environment	
Acoustic noise level [dB]	57.4
Ambient temperature [° C]	0-45
Protection	
Body standard/optional	IP54
Wrist & J3 arm standard/optional	IP67