

# Advanced Algorithms

## Geometric Algorithm

### Graham Scan Algorithm

The **convex hull** of a set  $Q$  of points is the smallest convex polygon  $P$  for which each point in  $Q$  is either on the boundary of  $P$  or in its interior. We denote the convex hull of  $Q$  by  $CH(Q)$ .

Intuitively, we can think of each point in  $Q$  as being a nail sticking out from a board. The convex hull is then the shape formed by a tight rubber band that surrounds all the nails.

Graham's scan use a technique called "rotational sweep," processing vertices in the order of the polar angles they form with a reference vertex.

## Graham Scan Algorithm

**Graham's scan** solves the convex-hull problem by maintaining a stack  $S$  of candidate points.

Each point of the input set  $Q$  is pushed **once** onto the stack, and the points that are **not vertices of  $CH(Q)$**  are eventually **popped** from the stack.

When the algorithm terminates, stack  $S$  contains exactly the vertices of  $CH(Q)$ , in counterclockwise order of their appearance on the boundary.

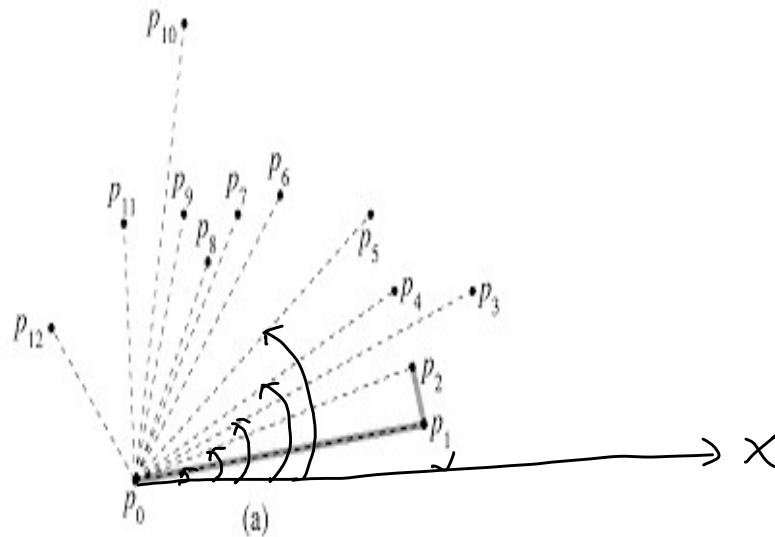
## Graham Scan Algorithm

```

1  let  $p_0$  be the point in  $Q$  with the minimum  $y$ -coordinate,
   or the leftmost such point in case of a tie
2  let  $\langle p_1, p_2, \dots, p_m \rangle$  be the remaining points in  $Q$ ,
   sorted by polar angle in counterclockwise order around  $p_0$ 
   (if more than point has the same angle, remove all but
   the one that is farthest from  $p_0$ )
3   $top[S] \leftarrow 0$ 
4  PUSH( $p_0, S$ )
5  PUSH( $p_1, S$ )
6  PUSH( $p_2, S$ )

```

## Graham Scan Algorithm



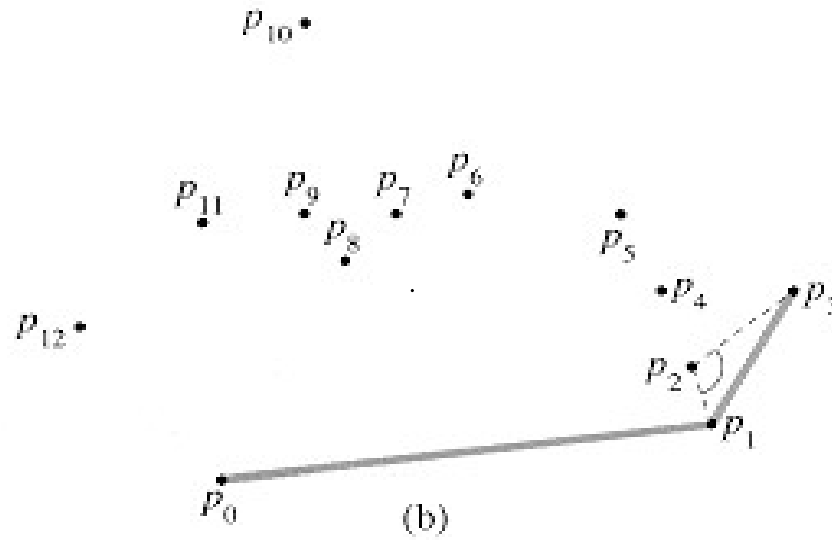
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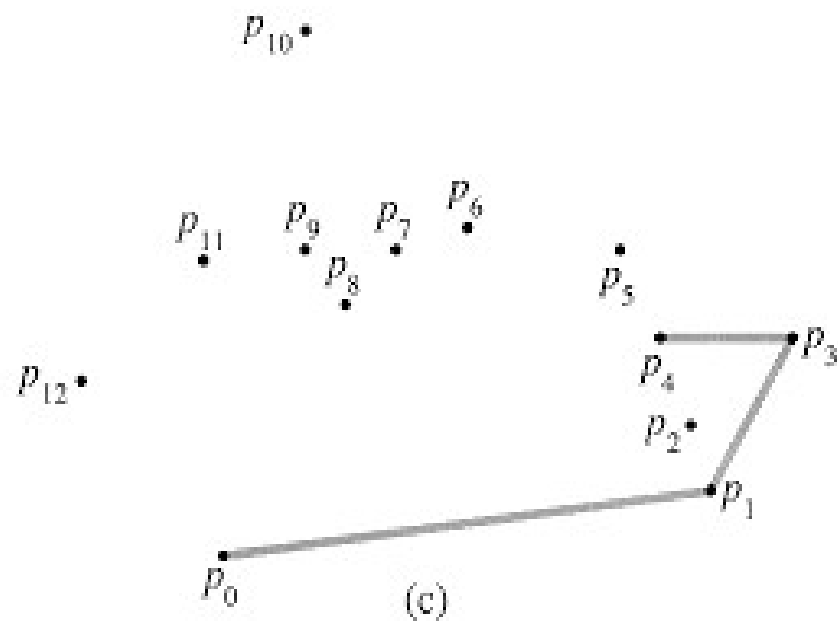
7  for  $i \leftarrow 3$  to  $m$ 
8      do while the angle formed by points NEXT-TO-TOP( $S$ ),
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9          do POP( $S$ )
10         PUSH( $S, p_i$ )
11  return  $S$ 

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## Graham Scan Algorithm



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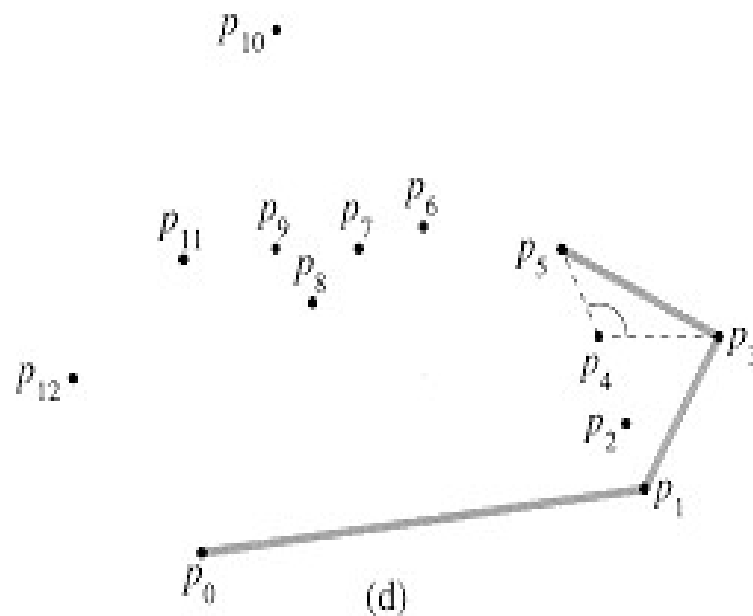
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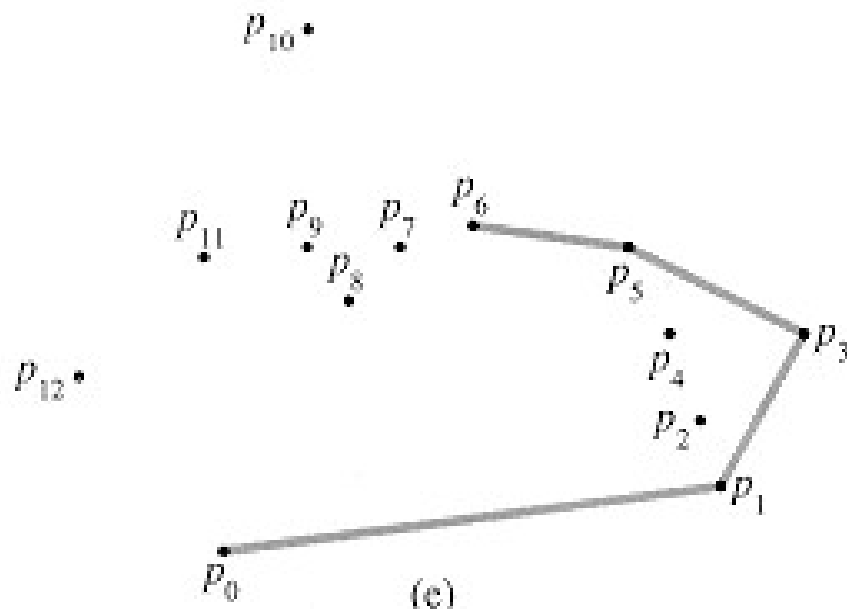
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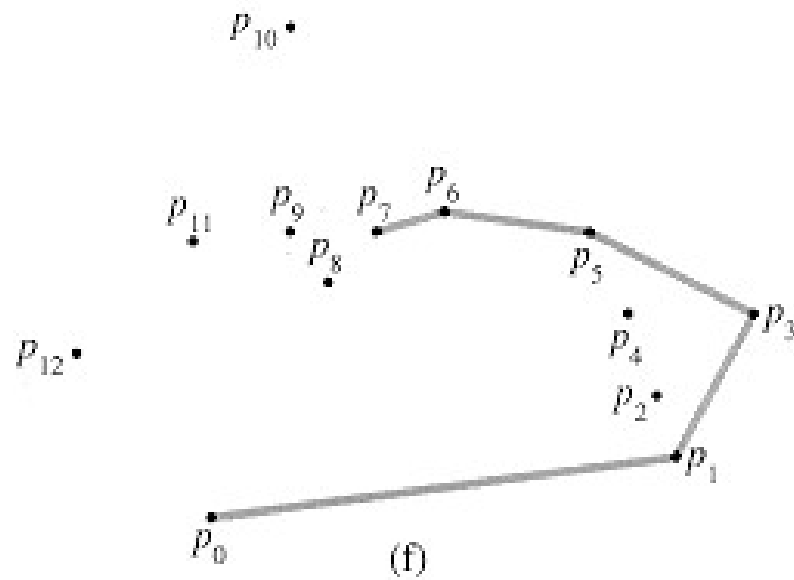
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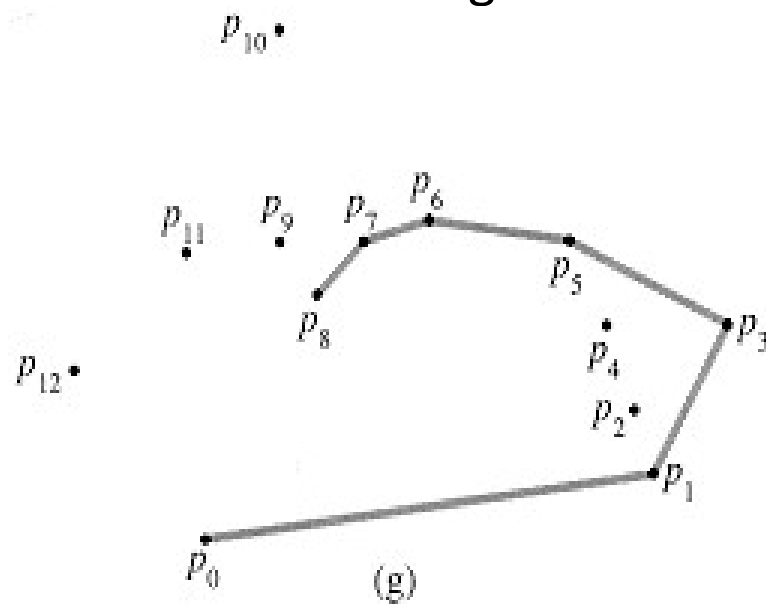
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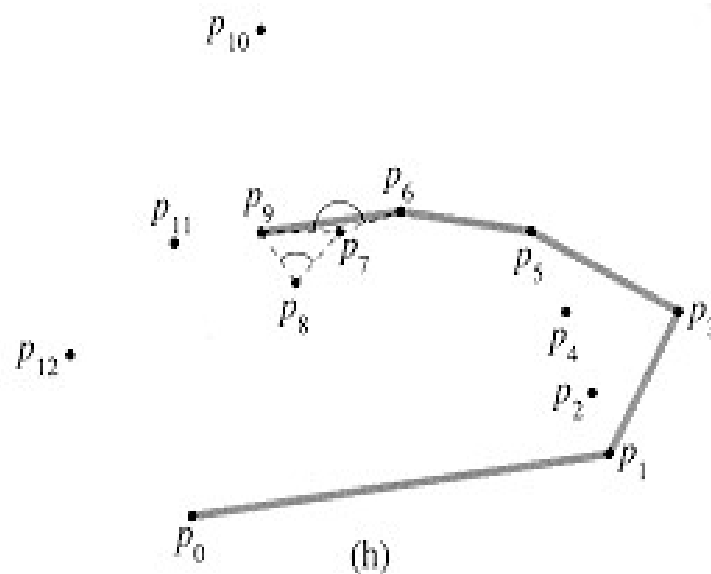
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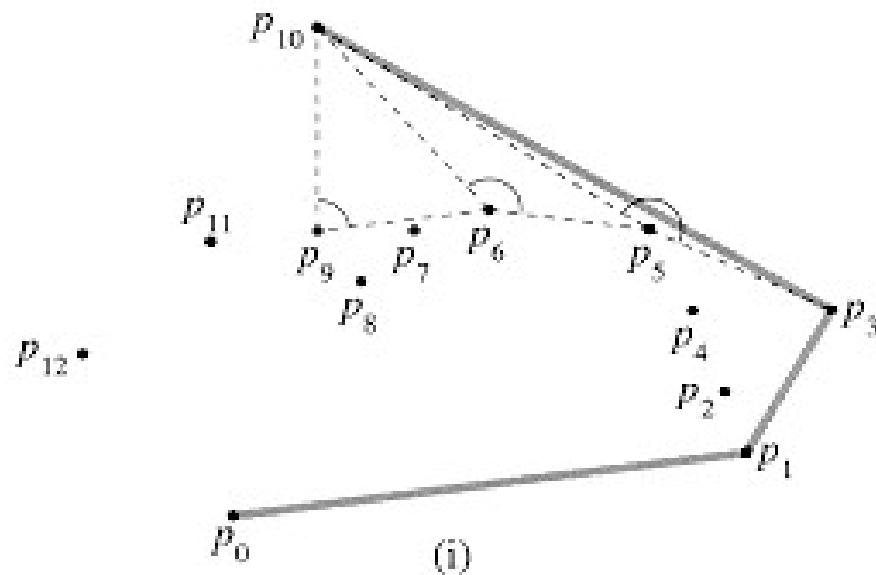
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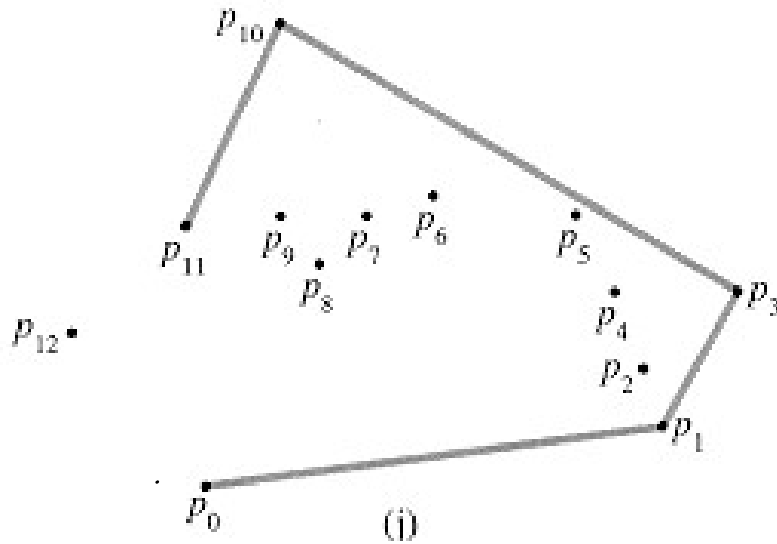
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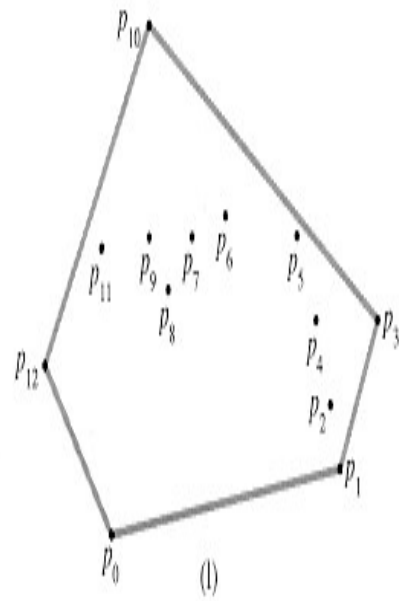
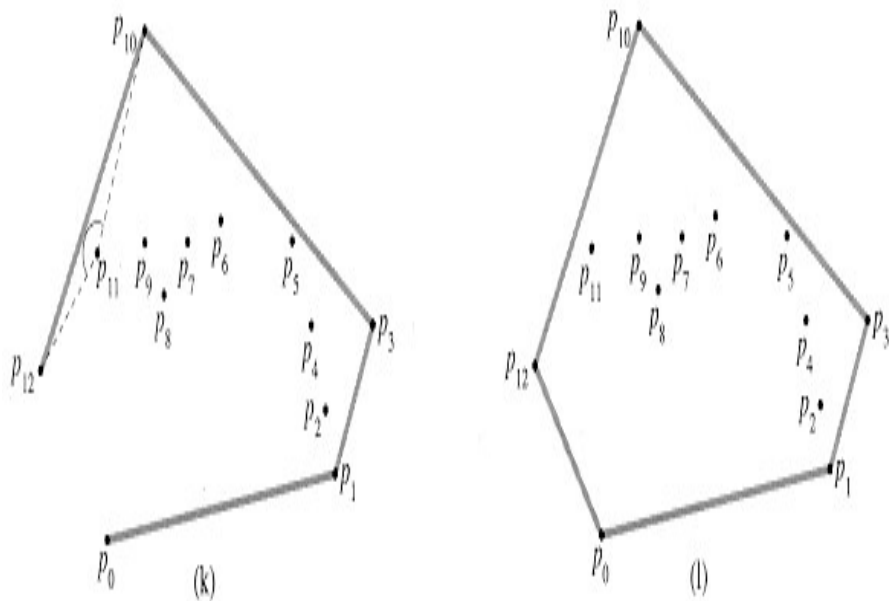
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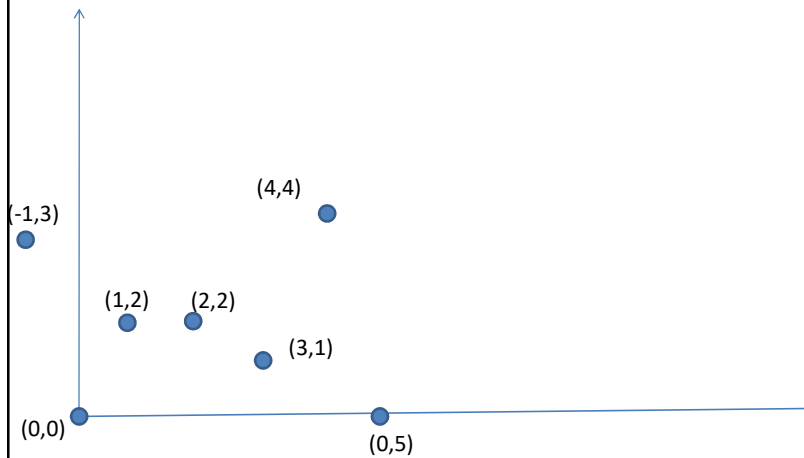
## Graham Scan Algorithm



## Gram Scan Algorithm

Explain working of Graham scan algorithm **step by step** and generate Convex Hull for given set of points.

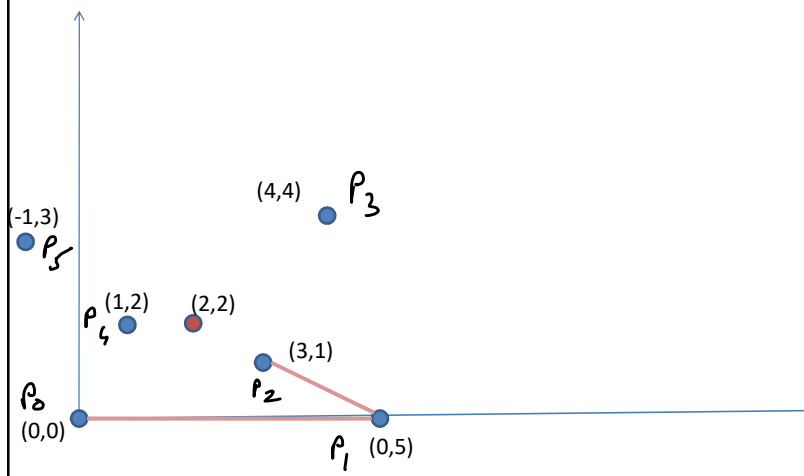
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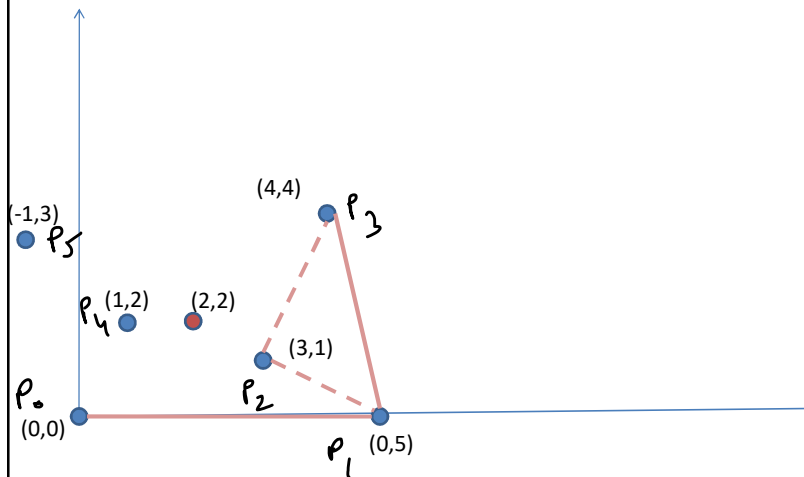
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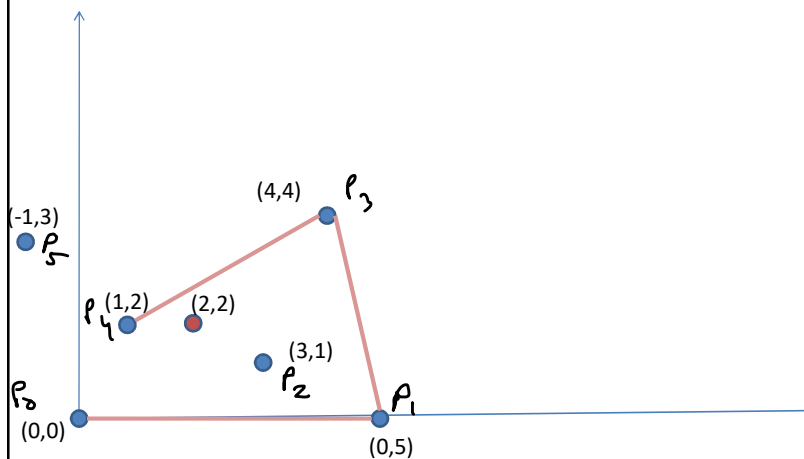
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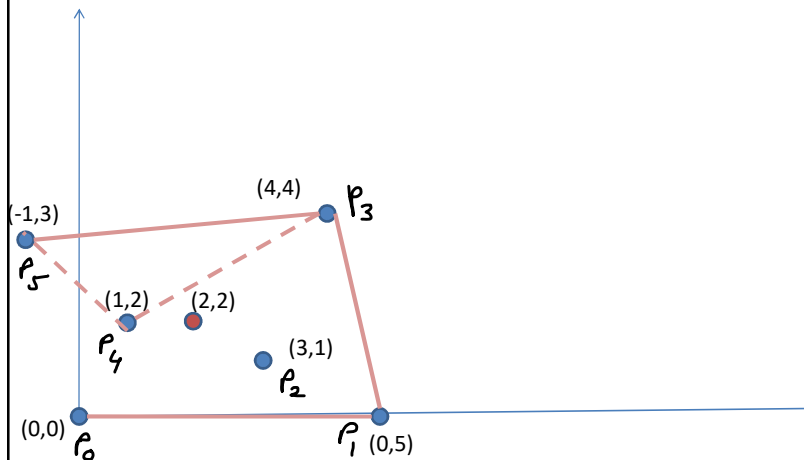
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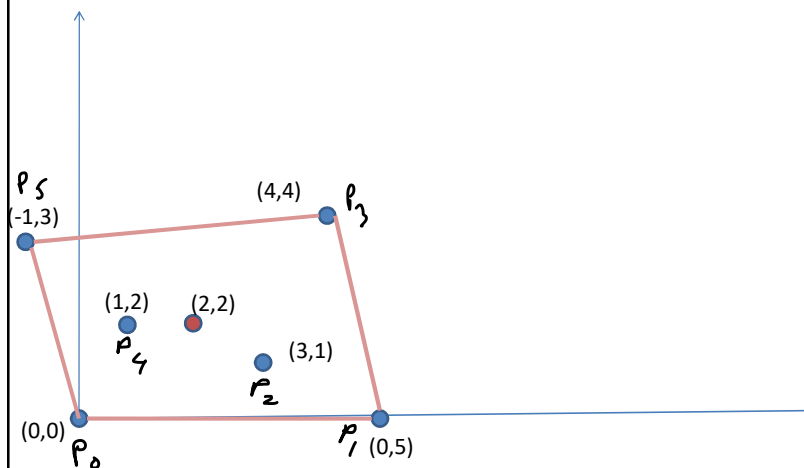
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## Time Complexity

the running time of GRAHAM-SCAN is  $O(n \lg n)$ , where  $n = |Q|$ .

Line 1 takes  $O(n)$  time.

Line 2 takes  $O(n \lg n)$  time, using merge sort or heapsort to sort the polar angles and the cross-product method to compare angles. (Removing all but the farthest point with the same polar angle can be done in a total of  $O(n)$  time.)

Lines 3-6 take  $O(1)$  time.

Because  $m \leq n - 1$ , the **for** loop of lines 7-10 is executed at most  $n - 3$  times. Since **PUSH** takes  $O(1)$  time, each iteration takes  $O(1)$  time exclusive of the time spent in the **while** loop of lines 8-9, and thus overall the **for** loop takes  $O(n)$  time exclusive of the nested **while** loop.

## Time Complexity

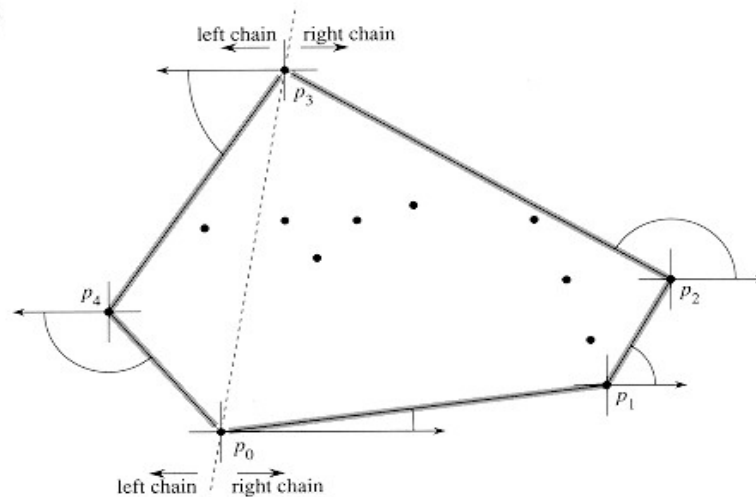
We use the **aggregate method** to show that the **while** loop takes  $O(n)$  time overall.

For  $i = 0, 1, \dots, m$ , each point  $p_i$  is pushed onto stack  $S$  exactly once.

At least three points-- $p_0$ ,  $p_1$ , and  $p_m$ --are never popped from the stack, so that in fact at most  $m - 2$  **POP** operations are performed in total. Each iteration of the **while** loop performs one **POP**, and so there are at most  $m - 2$  iterations of the **while** loop altogether.

Since the test in line 8 takes  $O(1)$  time, each call of **POP** takes  $O(1)$  time, and  $m \leq n - 1$ , the total time taken by the **while** loop is  $O(n)$ . Thus, the running time of GRAHAM-SCAN is  $O(n \lg n)$ .

## Jarvis's march Approach



## Jarvis's march Approach

Jarvis's march builds a sequence  $H = p_0, p_1, \dots, p_{h-1}$  of the vertices of  $CH(Q)$ .

We start with  $p_0$ . The next convex hull vertex  $p_1$  has the least polar angle with respect to  $p_0$ . (In case of ties, we choose the point farthest from  $p_0$ .)

Similarly,  $p_2$  has the least polar angle with respect to  $p_1$ , and so on. When we reach the highest vertex, say  $p_k$  (breaking ties by choosing the farthest such vertex), we have constructed the **right chain** of  $CH(Q)$ .

To construct the **left chain**, we start at  $p_k$  and choose  $p_{k+1}$  as the point with the least polar angle with respect to  $p_k$ , but *from the negative x-axis*. We continue on, forming the left chain by taking polar angles from the negative x-axis, until we come back to our original vertex  $p_0$ .

## Jarvis's march Approach

**Jarvis's march** computes the convex hull of a set  $Q$  of points by a technique known as **package wrapping** (or **gift wrapping**). The algorithm runs in time  $O(nh)$ , where  $h$  is the number of vertices of  $CH(Q)$ .

When  $h$  is  $O(\lg n)$ , Jarvis's march is asymptotically faster than Graham's scan.