Section 1 - Overview

In this emotion recognition project, we have 29000 original training data and 6887 images in the test dataset that need to be predicted. We have explored different models such as RandomForest, DNN, CNN, and ResNet, along with various configurations to identify the most effective solution. The methodology involved initial data analysis, preprocessing, and subsequent model experimentation to test various model performances.

Key Findings:

- Random Forest: The model exhibited high training accuracy but performed poorly onvalidation, indicating overfitting.
 Tuning the 'min samples split' parameter improved validationaccuracy marginally.
- DNN: The performance of DNN slightly exceeded that of the Random Forest. A systematicapproach, as advised by the referenced literature, helped mitigate overfitting to some extent.
- CNN: The experiments with CNN indicated the delicate balance between neuron count andoverfitting, with a learning
 rate of around 0.001 providing optimal results. Increasing complexityvia additional layers did not significantly benefit
 ResNet's performance.
- ResNet: Adjustments to ResNet, such as modifying the number of layers and strides, hadnuanced effects on performance, with some configurations indicating potential overfitting.

The suggested model is ResNet without data augmentation, achieving 85% validationaccuracy and 0.58 Kaggle competition score. The analysis indicates that while dataaugmentation offers performance benefits, the trade-off against increased training time maynot be justified given project constraints.

```
In [1]: import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import tensorflow as tf
```

Section 2 - Method

2.1 - Load data & Explore the data

By looking at the first few examples of the training set, we noticed that the training set has been shuffled already (i.e., ids are disorder and class labels are intertwined), hence we may not need to perform dataset shuffling when splitting the data. We used function <code>count()</code> to see how many examples there are. In the meantime, we checked that there are no NULL values in the dataset; therefore, we do not need to drop any examples. Lastly, we explored the data type of the feature column **'pixels'** to get a picture of how to deal with it (i.e., object type -> numerical type).

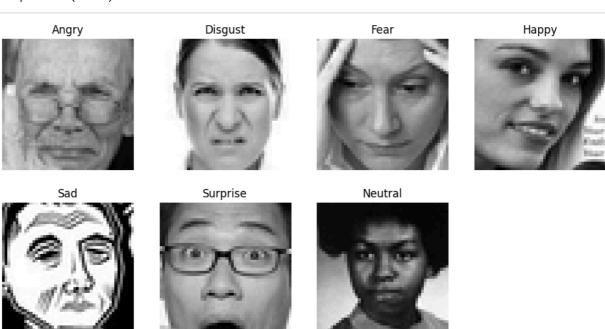
```
In [ ]: # Load data
    from google.colab import drive
        drive.mount('/content/drive')

        train_df = pd.read_csv('/content/drive/MyDrive/my_emotion_train.csv')
        test_df = pd.read_csv('/content/drive/MyDrive/my_emotion_test.csv')

In [ ]: # Explore the data set
        train_df.head(5) # View the first five examples of the training set
        train_df.count() # Check the number of examples
        train_df.isna().any() # Check if there is any NULL value exists
        train_df['pixels'].dtype # Check the data type of the feature column 'pixels'
```

We further explored the dataset by displaying examples (images). We picked one example from each class and plotted them together to have a comprehensive understanding of their characteristics. More importantly, we realised that it is feasible to rescale/resize/crop examples during the preprocessing stage because features of emotions (such as the eye area, cheek area, and mouth area) are mostly located around the centre or middle of images, which means only the information at the centre will be useful for our models, the others can be reduced.

```
In [4]: # Explore the data set (i.e., preview examples)
        emotions = {0: 'Angry', 1: 'Disgust', 2: 'Fear', 3: 'Happy', 4: 'Sad', 5: 'Surprise', 6: 'Neutral'}
        fig, axarr = plt.subplots(nrows=2, ncols=4, figsize=(12,6))
        axarr[-1, -1].axis('off')
        for label, emotion name in emotions.items():
            # Find the first example of each emotion
            example = train_df[train_df['emotion'] == label].iloc[0]
            # Split the pixel string into a list of integers
            pixels = list(map(int, example['pixels'].split(' ')))
            # Assuming it's a 48x48 image, reshape it
            image_array = np.array(pixels).reshape(48, 48)
            # Display the image with the emotion label
            i = 0 if label<4 else 1</pre>
            j = label % 4
            fig.add subplot(2, 4, label+1, title=emotion name)
            axarr[i,j].axis('off')
            plt.imshow(image_array, cmap='gray')
            plt.axis('off')
```



2.2 - Data preprocessing

The first thing we need to do for data preprocessing is convert the feature 'pixels' into a numerical type like an array of int, and then our model can use it to train.

```
In [5]: # Convert the feature 'pixels' from string into ndarray
X_train = np.array([np.fromstring(x, dtype=int, sep=' ') for x in train_df['pixels']])
y_train = train_df['emotion']
X_test = np.array([np.fromstring(x, dtype=int, sep=' ') for x in test_df['pixels']])
```

By using the functions min() & max(), we can see that the value range of the training data (pixel values) scales from 0 -> 255, which means we can scale it down to 0 -> 1 by dividing it by 255 and not change its distribution.

```
In [6]: X_train.min() # Check the minimum value
X_train.max() # Check the maximum value

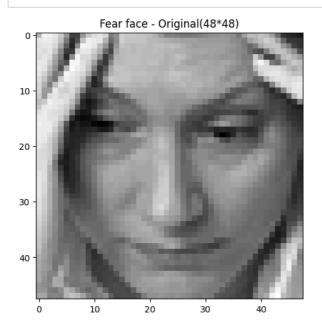
# Scale piexel values from 0 -> 255 to 0 -> 1
X_train = X_train/255
X_test = X_test/255
```

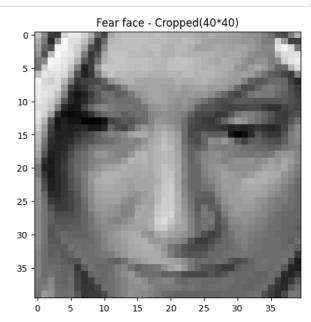
As mentioned earlier, we deployed a function called centerCropping used to crop the central area of images, which will reduce the image dimensions from 48×48 down to 40×40 for example. Another function named smallerDS, as its name says this function is used to produce a smaller dataset by cropping every image of that dataset.

```
In [7]: import math
        # Center crop an image down to a desired size (e.g., 40*40)
        def centerCropping(img, original_Size, target_Size):
          if original_Size == target_Size:
            return img
          image = img.reshape(original_Size, original_Size)
          pixels_ToRemove = (original_Size - target_Size) // 2
          cropped_image = image[pixels_ToRemove-1:original_Size-pixels_ToRemove-1,
                                pixels_ToRemove-1:original_Size-pixels_ToRemove-1]
          return cropped_image
        # Return a smaller dataset by reducing the size of each example
        def smallerDS(ds, desired_Size):
          cropped_DS = []
          for image in ds:
            original_Size = int(math.sqrt(len(image)))
            cropped_DS.append(centerCropping(image, original_Size, desired_Size).reshape(-1))
          return np.asarray(cropped DS)
```

Select one image and verify the effect of centre cropping. We can see that all those useful features are still retained, but the image size has been significantly reduced from 2304 pixels down to 1600 pixels. In other words, we have removed **704** less useful features for each example (there are 29000 examples in total), this is very useful to speed up model training!

```
In [8]: # Check the difference
        example = train_df[train_df['emotion'] == 2].iloc[0]
        img = np.array(list(map(int, example['pixels'].split(' '))))
        img_Size = int(math.sqrt(len(img)))
        img = img.reshape(img_Size, img_Size)
        cropped_img = centerCropping(img, img_Size, 40)
        f, axa = plt.subplots(nrows=1, ncols=2, figsize=(12,6));
        f.add_subplot(1,2,1, title=f"Fear face - Original({img_Size}*{img_Size})")
        axa[0].axis('off')
        plt.imshow(img, cmap="gray")
        f.add_subplot(1, 2, 2, title="Fear face - Cropped(40*40)")
        axa[1].axis('off')
        plt.imshow(cropped_img, cmap="gray")
        # Apply center cropping to the whole training & test set.
        cropped Size = 40
        X train = smallerDS(X train, cropped Size)
        X_test = smallerDS(X_test, cropped_Size)
```





2.3 - Data splitting

Since training and testing have already been split, this step is about to further split the current training set into a training and validation set, and we decided to use 20% of the original training set for validation.

2.4 - Data augmentation

After splitting the training and validation set, we applied data augmentation to every example of the training set ([1] described the process of applying data augmentation to the original dataset), which involved using Gaussian filters, adding noise, image rescaling and image rotation. We then merged the augmented dataset with the original training set, and shuffled it.

[1] https://www.linkedin.com/pulse/data-augmentation-python-vishwajit-sen/ (https://www.linkedin.com/pulse/data-augmentation-python-vishwajit-sen/)

```
In [10]: from skimage import transform
         from skimage import filters
         from skimage import util
         import random
         def augment Image(img):
           im = filters.gaussian(img)
           #im = filters.median(img)
           im = util.random noise(img)
           im = transform.rescale(img, 0.8)
           im = transform.rotate(img, 180)
           return im.reshape(-1)
         def larger_DS(img_DS, label_DS):
           augmented_DS = []
           newImgLabel_DS = []
           for pixels, emotion in zip(img_DS, label_DS):
             img_Size = int(math.sqrt(len(pixels)))
             augmented_DS.append(augment_Image(pixels.reshape(img_Size, img_Size)))
             newImgLabel_DS.append(emotion)
           merge_Imgs = np.concatenate([img_DS, augmented_DS])
           merge Labels = np.concatenate([label DS, newImgLabel DS])
           tmp = list(zip(merge Imgs, merge Labels))
           random.shuffle(tmp)
           larger_img_DS, larger_label_DS = zip(*tmp)
           return np.asarray(larger_img_DS), np.asarray(larger_label_DS)
```

Section 3 - Models

3.1 - Standard ML Baseline

For the standard ML baseline model, [1] showed a list of classification models supported by sklearn, and we decided to try Random Forest and KNN (K-Nearest Neibours) for this task because this task is a multilable classification where the majority of classifiers on that list are based on binary classification, which means we need to further apply the OvO (One versus One) or OvR (One versus Rest) strategy if we want to use them. On the other hand, time complexity is also something we are concerned about, [2] described the time complexity of different models, and the two we chose were less time-costly.

The table below demonstrates the performance of Random Forest and KNN under baseline conditions (all parameters were set to default):

	Random Forest	K-Nearest Neibours		
Accuracy (Training)	0.999	0.563		
Accuracy (Validation)	0.443	0.348		

As we can see, Random Forest performs much better than KNN on both training and validation set, hence we decided to use Random Forest classifier as the Standard ML baseline model for this task. We then performed a very basic grid search, which aims to search for the optimal value from (2, 5, 10) for the hyperparameter 'min_samples_split' of Random Forest, and the metric we use is the accuracy on the validation set. We observed that the validation accuracy is increased to **0.447** when min_samples_split = 5, and the accuracy goes down when min_samples_split = 10.

[1] https://scikit-learn.org/stable/auto_examples/classification/plot_classifier_comparison.html (https://scikit-learn.org/stable/auto_examples/classification/plot_classifier_comparison.html)

[2] https://medium.com/analytics-vidhya/time-complexity-of-ml-models-4ec39fad2770 (https://medium.com/analytics-vidhya/time-complexity-of-ml-models-4ec39fad2770)

```
In [11]: from sklearn.ensemble import RandomForestClassifier
         from sklearn.neighbors import KNeighborsClassifier
         from sklearn.metrics import accuracy score
         # Evaluate the performance of Random Forest and KNN on training and validation set.
         def show_clf_performance(model, X_train, y_train, X_valid, y_valid):
           model.fit(X_train, y_train)
           # Predict training data
           train pred = model.predict(X train)
           # Predict validation data
           val_pred = model.predict(X_valid)
           train_score = round(accuracy_score(y_train, train_pred), 3)
           val_score = round(accuracy_score(y_valid, val_pred), 3)
           return train_score, val_score
         # Uncomment this to get the result described
         # rf = RandomForestClassifier(random state=42)
         # knn = KNeighborsClassifier()
         # train_acc, val_acc = show_clf_performance(rf, X_train_partial, y_train_partial, X_val, y_val)
         # print("RF: Training accuracy -", round(train_acc,3), " Validation accuracy -", round(val_acc, 3))
         # train_acc, val_acc = show_clf_performance(knn, X_train_partial, y_train_partial, X_val, y_val)
         # print("KNN: Training accuracy -", round(train_acc,3), " Validation accuracy -", round(val_acc, 3)
         def easy_Search():
           for min_samples in [2, 5, 10]:
             # Since we are comparing models, so we need to set their random_state consistent
             good_rf = RandomForestClassifier(min_samples_split=min_samples, random_state=42)
             train_acc, val_acc = show_clf_performance(good_rf, X_train_partial, y_train_partial, X_val, y_v
             print(f"RF_MinSampleSplit_{min_samples}: Training accuracy -", round(train_acc,3), " Validation
         # Uncomment this to get the result described
         # easy_Search()
```

3.2 - Deep NN Models

We have experimented with the Deep Neural Network using 6 different configurations, regarding the selection of the optimiser, activation function, and kernel intialisation strategy of dense layers. The architecture these configurations used are the same: 5 layers (1 input, 3 hiddens, 1 output), the number of neurons of hidden layers are (500, 300, 100), and Dropout regularisation and Batch Normalisation are applied to each hidden layer. All configurations were trained by 10 epochs, other training hyperparameters were set as default.

```
    DNN_1: Optimiser = AdamW, Activation = ReLU, Kernel_Initialiser = he_normal
    DNN_2: Optimiser = AdamW, Activation = ReLU, Kernel_Initialiser = Default
    DNN_3: Optimiser = AdamW, Activation = Swish, Kernel_Initialiser = Default
    DNN_4: Optimiser = NAG, Activation = ReLU, Kernel_Initialiser = he_normal
    DNN_5: Optimiser = NAG, Activation = ReLU, Kernel_Initialiser = Default
    DNN 6: Optimiser = NAG, Activation = Swish, Kernel_Initialiser = Default
```

Note: The default of kernel initialiser is "glorot uniform", NGA - Nesterov Accelerated Gradient

	DNN_1	DNN_2	DNN_3	DNN_4	DNN_5	DNN_6
Accuracy (Training)	0.45	0.463	0.453	0.363	0.372	0.377
Accuracy (Validation)	0.40	0.402	0.397	0.354	0.356	0.362

```
In [12]: # Deep NN means a MLP model, where number of layers more than 3
         # 1 input layer + more than 1 hidden layers + 1 output layer
         def diff_Config_DNN(a, kernel="glorot_uniform"):
          # We are comparing models, set random seed consistent
          tf.keras.utils.set random seed(42)
          happy_dnn = tf.keras.Sequential([
            # Input layer
            tf.keras.layers.Input(shape=[1600,]),
            #tf.keras.layers.Flatten(),
             # 1st Hidden Layer
            tf.keras.layers.Dropout(rate=0.2),
            tf.keras.layers.Dense(500, kernel_initializer=kernel),
            tf.keras.layers.BatchNormalization(),
             tf.keras.layers.Activation(a),
             # 2nd Hidden Layer
            tf.keras.layers.Dropout(rate=0.2),
            tf.keras.layers.Dense(300, kernel initializer=kernel),
            tf.keras.layers.BatchNormalization(),
            tf.keras.layers.Activation(a),
             # 3rd Hidden Layer
            tf.keras.layers.Dropout(rate=0.2),
            tf.keras.layers.Dense(100, kernel_initializer=kernel),
            tf.keras.layers.BatchNormalization(),
            tf.keras.layers.Activation(a),
             # Output layer
            tf.keras.layers.Dense(7, activation="softmax")])
          return happy_dnn
         def get_DNN_performance(model, opt, X_train, y_train, X_val, y_val, epochs_num):
          model.compile(loss="sparse categorical crossentropy", optimizer=opt, metrics=["accuracy"])
          model.fit(X_train, y_train, epochs=epochs_num, validation_data=(X_val, y_val), verbose=0)
          train_acc = model.evaluate(X_train, y_train, verbose=0)
          val_acc = model.evaluate(X_val, y_val, verbose=0)
          return train_acc[1], val_acc[1]
 In [ ]: # Get the performance of each configuration defined.
```

3.3 - Complex NN Moldes

Note: The complex models created below have used a different data splitting strategy.

```
In [ ]: # Data Agumentation
        from skimage import filters, util, transform
        import numpy as np
        from tensorflow import keras
        def augment image(img):
            im = img.copy()
            im = filters.gaussian(im)
            # im = util.random noise(im)
            im = transform.rotate(im, 180)
            return im
        X train augmented = []
        y_train_augmented = []
        for img, label in zip(X_train_re, y_train):
            X_train_augmented.append(img) # add orginal img and it's label
            y_train_augmented.append(label)
            augmented_img = augment_image(img) # get the augmented imh
            X_train_augmented.append(augmented_img) # add to the list
            y train augmented.append(label) # augmented imas have the same label
        X_train_augmented = np.array(X_train_augmented)
        y_train_augmented = np.array(y_train_augmented)
        print("Original:", X_train_re.shape)
        print("Augmented:", X_train_augmented.shape)
```

CNN (Convolutional Neural Network)

```
In [ ]: cnnmodel = keras.models.Sequential([
            keras.layers.Conv2D(64, (3,3), activation="relu", padding="same", input_shape=[48, 48, 1]),
            #keras.layers.Dropout(0.2),
            keras.layers.MaxPooling2D(2,2),
            keras.layers.Conv2D(128, (3,3), activation="relu", padding="same"),
            keras.layers.Conv2D(128, (3,3), activation="relu", padding="same"),
            #keras.layers.Dropout(0.2),
            keras.layers.MaxPooling2D(2,2),
            keras.layers.Conv2D(256, (3,3), activation="relu", padding="same"),
            keras.layers.Conv2D(256, (3,3), activation="relu", padding="same"),
            #keras.layers.Dropout(0.2),
            keras.layers.MaxPooling2D(2,2),
            keras.layers.Flatten(),
            keras.layers.Dense(512, activation="relu"), # more neuron
            #keras.layers.Dropout(0.2),
            keras.layers.Dense(256, activation="relu"), # more neuron
            #keras.layers.Dropout(0.2),
            keras.layers.Dense(10, activation="sigmoid")
        ])
        optimizer = keras.optimizers.Adam(learning_rate=0.001)
        cnnmodel.compile(loss="sparse_categorical_crossentropy", optimizer=optimizer, metrics=["accuracy"])
        cnnmodel.summary()
In [ ]: cnnhistory = cnnmodel.fit(X train re, y train,
                       batch size=32,
        # cnnhistory_aug=cnnmodel.fit(X_train_augmented, y_train_augmented,
                         batch size=64,
                      epochs=10,
                      validation_data=(X_valid, y_valid)
                      #, class weight=class weights dict
                      )
In [ ]: |# use encoded label evaluate model
        test_scores = cnnmodel.evaluate(X_valid, y_valid, verbose=1)
        print('Test loss:', test_scores[0])
        print('Test accuracy:', test_scores[1])
In [ ]: plt.figure(figsize=(9,6))
        plt.subplot(2,1,1)
        plt.plot(cnnhistory.history['loss'])
        plt.plot(cnnhistory.history['val_loss'], 'ro')
        # plt.plot(cnnhistory_aug.history['loss'])
        # plt.plot(cnnhistory_aug.history['val_loss'], 'ro')
        plt.title('CNN Loss')
        plt.grid(True)
        plt.subplot(2,1,2)
        plt.plot(cnnhistory.history['accuracy'])
        plt.plot(cnnhistory.history['val_accuracy'], 'ro')
        # plt.plot(cnnhistory_aug.history['accuracy'])
        # plt.plot(cnnhistory_aug.history['val_accuracy'], 'ro')
        plt.title('CNN Accuracy')
        plt.grid(True)
```

```
In [ ]: # Prediction using trained model
        train predictions = cnnmodel.predict(X train re)
        # train predictions = cnnmodel.predict(X train augmented)
        # Converts predictions from probabilities to category labels
        train y pred = np.argmax(train predictions, axis=1)
        # Create a DataFrame to view the prediction results
        train_predictions_df = pd.DataFrame({
             _.
'actual_label': y_train,
              'actual_label': y_train_augmented,
            'predicted_label': train_y_pred
        })
        # Check prediction result
        print(train predictions df)
        # use sklearn calculate accuracy
        from sklearn.metrics import accuracy score
        train_accuracy = accuracy_score(y_train, train_y_pred)
        #train_accuracy = accuracy_score(y_train_augmented, train_y_pred)
        print(f"Train Accuracy: {train_accuracy}")
```

ResNet (Residual Network)

```
In []: !pip install np_utils
import numpy as np
from keras.utils import np_utils

# change input data to RGB images
X_train_rgb = np.repeat(X_train_re, 3, axis=-1)
X_valid_rgb = np.repeat(X_valid, 3, axis=-1)
# X_train_rgb_aug = np.repeat(X_train_augmented, 3, axis=-1)
# X_valid_rgb = np.repeat(X_valid, 3, axis=-1)

# define number of classes and input_shape
num_classes = 7
input_shape = (48, 48, 1)

# If y_train and y_valid are not one-hot encodings, they need to be converted first
y_train_oh = np_utils.to_categorical(y_train, num_classes)
y_valid_oh = np_utils.to_categorical(y_valid, num_classes=7)
# y_train_aug_oh = np_utils.to_categorical(y_train_augmented, num_classes)
```

```
In [35]: class ResidualUnit(keras.layers.Layer):
             def __init__(self, filters, strides=1, activation="relu", **kwargs):
                 super().__init__(**kwargs)
                 self.activation = keras.activations.get(activation)
                 self.main_layers = [
                     keras.layers.Conv2D(filters, 3, strides=strides,
                                           padding="same", use_bias=False),
                     keras.layers.BatchNormalization(),
                     self.activation,
                     keras.layers.Conv2D(filters, 3, strides=1,
                                           padding="same", use_bias=False),
                     keras.layers.BatchNormalization()]
                 self.skip_layers = []
                 if strides > 1:
                     self.skip_layers = [
                          keras.layers.Conv2D(filters, 1, strides=strides,
                                               padding="same", use_bias=False),
                     keras.layers.BatchNormalization()]
             def call(self, inputs):
                 Z = inputs
                 for layer in self.main_layers:
                     Z = layer(Z)
                 skip Z = inputs
                 for layer in self.skip_layers:
                     skip_Z = layer(skip_Z)
                 return self.activation(Z + skip_Z)
 In [ ]: Resmodel = keras.models.Sequential()
         Resmodel.add(keras.layers.Conv2D(64, 7, strides=2, input_shape=[48, 48, 3],
                                           padding="same", use bias=False))
         Resmodel.add(keras.layers.BatchNormalization())
         Resmodel.add(keras.layers.Activation("elu"))
         Resmodel.add(keras.layers.MaxPool2D(pool_size=3, strides=2, padding="same"))
         prev_filters = 64
         for filters in [64] * 3 + [128] * 4 + [256] * 6 + [512] * 3:
             strides = 1 if filters == prev filters else 2
             Resmodel.add(ResidualUnit(filters, strides=strides))
             prev_filters = filters
         Resmodel.add(keras.layers.GlobalAvgPool2D())
         # Resmodel.add(keras.layers.Dropout(0.05))
         Resmodel.add(keras.layers.Flatten())
         Resmodel.add(keras.layers.Dense(7, activation="softmax"))
         # compile model
         Resmodel.compile(optimizer=keras.optimizers.Adam(learning rate=0.001), loss='categorical crossentro
         Resmodel.summary()
 In [ ]:  # model train basic
         Res_history_book = Resmodel.fit(X_train_rgb, y_train_oh, batch_size=32, epochs=10,
         # Res_history_aug = Resmodel.fit(X_train_rgb_aug, y_train_aug_oh, batch_size=64, epochs=10,
                   #steps per epoch=200,
                   validation data=(X valid rgb, y valid oh),
                   #validation steps=100,
                   #class_weight=class_weights_dict
                   )
```

```
In [ ]: # use encoded label evaluate model
        test_scores = Resmodel.evaluate(X_valid_rgb, y_valid_oh, verbose=1)
        print('Test loss:', test_scores[0])
        print('Test accuracy:', test_scores[1])
```

```
In [ ]: plt.figure(figsize=(9,6))
        plt.subplot(2,1,1)
        plt.plot(Res_history_book .history['loss'])
        plt.plot(Res_history_book .history['val_loss'], 'ro')
        # plt.plot(Res_history_aug .history['loss'])
        # plt.plot(Res_history_aug .history['val_loss'], 'ro')
        plt.title('ResNet Loss')
        plt.grid(True)
        plt.subplot(2,1,2)
        plt.plot(Res_history_book .history['accuracy'])
        plt.plot(Res_history_book .history['val_accuracy'], 'ro')
        # plt.plot(Res_history_aug .history['accuracy'])
        # plt.plot(Res_history_aug .history['val_accuracy'], 'ro')
        plt.title('ResNet Accuracy')
        plt.grid(True)
In [ ]: X_test_rgb = np.repeat(X_test_re, 3, axis=-1)
```

```
In [ ]: X_test_rgb = np.repeat(X_test_re, 3, axis=-1)
    predictions_Res = Resmodel.predict(X_test_rgb)
    y_pred_res = np.argmax(predictions_Res, axis=1)
```

```
In [ ]: # Prediction using trained model
        train predictionsres = Resmodel.predict(X train rgb)
        # train predictionsres = Resmodel.predict(X train rgb aug)
        # Converts predictions from probabilities to category labels
        train_y_predres = np.argmax(train_predictionsres, axis=1)
        # Create a DataFrame to view the prediction results
        train_predictions_res = pd.DataFrame({
             actual_label': y_train,# y_train_augmented,
            'predicted_label': train_y_predres
        })
        # Check prediction result
        print(train_predictions_res)
        # use sklearn calculate accuracy
        from sklearn.metrics import accuracy score
        train_accuracy = accuracy_score(y_train, train_y_predres)
        # train_accuracy = accuracy_score(y_train_augmented, train_y_predres)
        print(f"Train Accuracy: {train_accuracy}")
```

```
In [ ]: # predictions_df_res = pd.DataFrame(y_pred_res, columns=['emotion'])
# predictions_df_res['id'] = test_df.iloc[:, 0].values

# # Reorder the columns to have 'id' first
# predictions_df_res = predictions_df_res[['id', 'emotion']]

# # Output the DataFrame
# print(predictions_df_res)

# # Save this to a CSV file
# predictions_df_res.to_csv('emotions_predictions_Res.csv', index=False)
```

The Result for CNN and ResNet parameter testing is shown below, we also use a randomsearch method to cross validate and confirm our testing result, which help us decide and confirm the final configurations for the two models.

CNN:

O1414.													
								Vithout Augmentation			With Augmentation		
CNN Model Name	Neurons -	Convolution Kernel	Dropout Layer .	Learning Rate	others	· Batch siz·	epoc*	val loss 💌	val accuracy -	train accurac .	val loss 1	val accuracy ·	train accurac .
Base Model	64/128/128/256/256	3x3	/	0.001	sigmoid	907	10	0.263487846	0.906400025	0.911413793	0.410396039	0.852999985	0.852793103
Dropout 0.1	64/128/128/256/256	3x3	0.1	0.001	sigmoid	907	10	0.503224254	0.836799979	0.83437931	0.478080511	0.843200028	0.822706897
Dropout 0.2	64/128/128/256/256	3x3	0.2	0.001	sigmoid	907	10	0.810014784	0.713800013	0.718103448	0.704277813	0.756600022	0.72962069
Dropout 0.01	64/128/128/256/256	3x3	0.1	0.001	sigmoid	907	10	0.305680037	0.895600021	0.898586207	0.16304712	0.9454	0.941327586
Learning rate 0.0001	64/128/128/256/256	3x3	/	0.0001	sigmoid	907	10	0.139325827	0.961399972	0.963	0.136919707	0.962400019	0.958534483
Learning rate 0.0005	64/128/128/256/256	3x3	/	0.0005	sigmoid	907	10	0.090847857	0.972000003	0.971	0.098051913	0.967199981	0.961396552
less neuron	32/64/64/128/128	3x3	/	0.001	sigmoid	907	10	0.193727329	0.932600021	0.934517241	0.21217373	0.9296	0.932741379
more neuron	128/256/256/512/512	3x3	/	0.001	sigmoid	907	10				0.945241379	0.946799994	0.945241379
more neuron 2	128/256/256/512/512	3x3	/	0.0005	sigmoid	907	10	0.124078549	0.960200012	0.961689655	0.091518432	0.973399997	0.967189655
Convolution Kernel 1x1	64/128/128/256/256	1x1	/	0.001	sigmoid	907	10	1.185786963	0.561200023	0.561517241	1.148819208	0.568400025	0.550396552
Convolution Kernel 5x5	64/128/128/256/256	5x5	/	0.001	sigmoid	907	10				0.254776776	0.916800022	0.908775862
Less Layers	64/128/128	3x3	/	0.001	sigmoid	907	10	0.06673713	0.980599999	0.981275862		0.978799999	0.97387931
Softmax dense	64/128/128/256/256	3x3	/	0.001	softmax	907	10	0.257800817	0.912800014	0.915344828	0.203037485	0.9296	0.925086207
Class weight fit	64/128/128/256/256	3x3	/	0.001	class_weight	907	10	0.933292985	0.657599986	0.665310345	0.44716236	0.844799995	0.819258621

ResNet:

ResNet Model Name	Stacked residual blocks	Total Stacked residual blocks	total convolutional layers	strides	batch size	activation	Dropout Layer	Learning Rate	others	apach	val loss	val accuracy	train accuracy	val loss	val accuracy	train accuracy
Basic Model	3x64/ 4x128/ 6x256/ 3x512	16	32	2	907	softmax	/	0.001	1	10	0.589377224	0.8028	0.805310345	0.361628681	0.871999979	0.846051724
Dropout 0.5	3x64/ 4x128/ 6x256/ 3x512	16	32	2	907	softmax	0.5	0.001	1	10	0.919224203	0.666888822	0.668862869	8.768413961	0.700800002	0.675810345
Dropout 0.05	3x64/ 4x128/ 6x256/ 3x512	16	32	2	907	softmax	0.05	0.001	1	10	0.709842682	0.734200001	0.746172414	8.414416701	0.859200001	0.826775862
Learning 0.01	3x64/ 4x128/ 6x256/ 3x512	16	32	2	907	softmax	/	0.01	1	10	1.169068456	0.559599996	0.564137931	0.886719823	0.681599975	0.632913793
Learning 0.0001	3x64/ 4x128/ 6x256/ 3x512	16	32	2	907	softmax	/	0.0001	1	10	0.349148273	0.875999987	0.875793103	8.278108269	0.984799998	0.882241379
Less Residual Blocks	2x64/ 3x128/ 5x256/ 2x512	12	28	2	907	softmax	/	0.001	1	10	0.346478611	0.876600027	0.878068966	8.256178826	8.912	0.893396552
More Residual Blocks	4x64/ 5x128/ 7x256/ 4x512	20	40	2	907	softmax	/	0.001	1	10	0.698319077	0.745000005	0.745586207	0.9076	8.6988	0.635448276
strides 1	3x64/ 4x128/ 6x256/ 3x512	16	32	1	907	softmax	/	0.001	1	10	0.870984256	0.67839998	0.678448276	0.608731806	0.764800012	0.774672414
strides 3	3x64/ 4x128/ 6x256/ 3x512	16	32	3	907	softmax	/	0.001	1	10	1.224826813	0.548799992	0.546137931	1.289328771	8.555999994	0.505465517
Class weight	3x64/ 4x128/ 6x256/ 3x512	16	32	2	907	softmax	/	0,001	Class weight	10	1.251818895	0.537199974	0.531793103	8,83885275	0.697888827	0.648551724

Section 4 - Results

4.1 - Performance comparison

The tables below present the performance of each model created under the circumstance with/without data augmentation applied. The **Mean** and **Standard Deviation (Std)** are obtained by training the model several times and using a different data or parameters each time:

-RF and DNN = 5 times, random seed.

-CNN and ResNet = 15 times with different parameters to compare the impact of parameters on the models' performance.

- The final configuration for the Random Forest classifier is min_samples_split=5, and the others are set as default.
- The final configuration for the DNN is **Hidden layers**: (500, 300, 100), **Optimizer = AdamW**, **Activation = ReLU**, **Kernel_Initializer = Default Dropout rate = 0.2**, **epoch = 50**, and the others are set as default.
- The final configuration for CNN model is Learning Rate = 0.0005, Dense Size=512, Neuron= 128/128/256/512.
- The final configuration for ResNet is Learning Rate = 0.0001, Stacked Residual Blocks = 3x64/ 4x128/ 6x256/ 3x512, Strids=2, Activation=elu.

With Data Augmentation

	Random Forest	DNN	CNN	ResNet
Mean (Training)	0.999	0.576	0.8778	0.7536
Std (Training)	0	0	0.1271	0.1282
Mean (Validation)	0.418	0.423	0.8869	0.7838
Std (Validation)	0.008	0	0.1204	0.1158
Accurcy (Kaggle)	0.43	0.45	0.52	0.548

Without Data Augmentation

	Random Forest	DNN	CNN	ResNet
Mean (Training)	0.999	0.676	0.8597	0.7296
Std (Training)	0	0	0.1377	0.1311
Mean (Validation)	0.443	0.443	0.8577	0.7276
Std (Validation)	0.003	0	0.1385	0.1294
Accurcy (Kaggle)	0.45	0.46	0.515	0.55

```
In [ ]: # Results of Standard ML Baseline ML: Random Forest
        import statistics
        # Training and validation set used. Calculating the mean and std of a model's accuracy
        # (i.e., train the same model 5 times, then using different random seed each time)
        def get_train_val_performance(new_X_train_partial, new_y_train_partial, X_val, y_val, command):
          # Create a list of different random seeds
          random\_seed = [13, 22, 30, 42, 78]
          train_scores = []
          val_scores = []
          if command == "ML":
            for seed in random seed:
              rf = RandomForestClassifier(min_samples_split=5, random_state=seed)
              train_acc, val_acc = show_clf_performance(rf, new_X_train_partial,
                                                         new y train partial, X val, y val)
              train scores.append(train acc)
              val scores.append(val acc)
            print("Mean(Training):", round(statistics.mean(train_scores),3),
                  "Std(Training):", round(statistics.stdev(train scores),3))
            print("Mean(Validation):", round(statistics.mean(val_scores),3),
                   "Std(Validation):", round(statistics.stdev(val_scores),3))
          else:
            for seed in random_seed:
              tf.keras.utils.set_random_seed(seed)
              optimiser = tf.keras.optimizers.AdamW(learning_rate=0.001)
              our_DNN = diff_Config_DNN("relu", None)
              train_acc, val_acc = get_DNN_performance(our_DNN, optimiser, new_X_train_partial,
                                                       new_y_train_partial, X_val, y_val, epochs_num=50)
              train scores.append(train acc)
              val_scores.append(val_acc)
            print("Mean(Training):", round(statistics.mean(train_scores),3),
                  "Std(Training):", round(statistics.stdev(train_scores),3))
            print("Mean(Validation):", round(statistics.mean(val_scores),3),
                   "Std(Validation):", round(statistics.stdev(val_scores),3))
        # The entire training set used. Generate a CSV file containing predictions on real test set
        def get_test_prediction(whole_X_train, whole_y_train, real_test, command):
          if command == "ML":
            # The score on the Kaggle should be reproducible, therefore random state should be fixed
            final rf = RandomForestClassifier(min samples split=5, random state=42)
            final_rf.fit(whole_X_train, whole_y_train)
            predictions = final_rf.predict(real_test)
            predictions_ML = pd.DataFrame(predictions, columns=['emotion'])
            predictions_ML['id'] = test_df.iloc[:, 0].values
            predictions_ML = predictions_ML[['id', 'emotion']]
            predictions_ML.to_csv('emotions_predictions_ML.csv', index=False)
          else:
            tf.keras.utils.set_random_seed(42)
            final_DNN = diff_Config_DNN("relu", None)
            optimiser = tf.keras.optimizers.AdamW(learning_rate=0.001)
            final_DNN.compile(loss="sparse_categorical_crossentropy", optimizer=optimiser, metrics=["accura")
            final_DNN.fit(whole_X_train, whole_y_train, epochs=50, verbose=0)
            predictions = final_DNN.predict(X_test)
            y_pred = np.argmax(predictions, axis=1)
            predictions_DNN = pd.DataFrame(y_pred, columns=['emotion'])
            predictions_DNN['id'] = test_df.iloc[:, 0].values
            predictions_DNN = predictions_DNN[['id', 'emotion']]
            predictions DNN.to csv('emotions predictions DNN.csv', index=False)
```

```
In [ ]: # Test the performance with data augmentation applied.
        def augmented DS performance(command):
          augmented_X_train_partial, augmented_y_train_partial = larger_DS(X_train_partial, y_train_partial
          augmented_X_train, augmented_y_train = larger_DS(X_train, y_train)
          if command == "ML":
            get train val performance(augmented X train partial, augmented y train partial, X val, y val, "
            get_test_prediction(augmented_X_train, augmented_y_train, X_test, "ML")
            get_train_val_performance(augmented_X_train_partial, pd.Series(augmented_y_train_partial), X_va
            get_test_prediction(augmented_X_train, pd.Series(augmented_y_train), X_test, "DNN")
        # Test the performance without data augmentation applied
        def normal_DS_performance(command):
          if command == "ML":
            get_train_val_performance(X_train_partial, y_train_partial, X_val, y_val, "ML")
            get test prediction(X train, y train, X test, "ML")
            get_train_val_performance(X_train_partial, y_train_partial, X_val, y_val, "DNN")
            get test prediction(X train, y train, X test, "DNN")
```

```
In [ ]: # Get the performance of the Random forest and DNN presented in the table above

# The following will give the performance of the final random forest, including
# the mean and std of training accuracy and the mean and std of validation accuracy.
# The predictions on real test set will be stored into a CSV file.
# Recommend: Run the following code line by line, otherwise the CSV file will replace.

# augmented_DS_performance("ML") # With using augmented data
# normal_DS_performance("ML") # Without using augmented data
# augmented_DS_performance("DNN")
# normal_DS_performance("DNN")
```

4.2 - Short summary

For this task (Emotion recognition), we have experimented a standard ML random forest classifier model, a deep neural network with 3 hidden layers, a complex NN model based on CNN (Convolutional Neural Network) architecture, and another complex NN model based on ResNet (Residual Network) architecture.

- For the random forest model, we tried to fine-tune the hyperparameter min_samples_split and we found that the model accuracy increased when we tuned this hyperparameter from 2 (the default value) to 5, but the model accuracy started going down when this hyperparameter up to 10. Also, it was trivial to notice that by increasing the number of decision trees of the random forest, the model's performance would be improved; however, we did not go for that because it was very computationally expansive. At the end, the training accuracy of Random Forest reached 99% that was greatly exceed its testing score, which this was severely overfitting.
- For DNNs, due to the same concern we had with Random Forest, we did not choose to fine-tune parameters like number of layers and number of neurons. The guideline about setting DNN configuration was referred from [1]. The performance of the DNN model performed slightly better than the Random Forest, the extend of overfitting is reduced.
- In testing CNN, key findings include the trade-off between increased neuron count and higher accuracy against longer training and potential overfitting. Learning rates around 0.001 were optimal, and large convolution kernels risked overfitting. More layers did not necessarily improve ResNet performance, suggesting limits to complexity benefits.
- For ResNet, using fewer, efficiently designed layers maintained accuracy and indicated overfitting with too many
 layers. Strides of 1 captured detail without improving accuracy, while strides of 3 reduced it due to lost information.
 Class weight adjustments and sigmoid activation in dense layers had a marginal positive impact on accuracy,
 whereas ELU activation was effective against vanishing gradients.

[1] "Hands-on Machine Learning With Scikit-Learn, Keras and TensorFlow: Concepts, Tools, and Techniques to Build Intelligent Systems", 3rd edition, page 293-294

Section 5 - Summery and Next Steps for Enhanced Emotion Recognition

Project Summery

Our final decision for this project is to utilize a ResNet model without applying data augmentation in above configuration. Which give us a **85% validation accuracy** based on the first 5000 image, and **0.58 in kaggle** competation.

Given this scenario, the decision to disuse data augmentation in favor of a standard ResNet model is justified by the relative gains in performance V.S. the increased training duration. In this project, a 7% improvement in performance might not warrant doubling the training time, particularly when we have limited time and computational resources. Furthermore, the existing accuracy without augmentation already meets the project requirements, the additional time and resources required for a small increase might not be considered cost-effective.

The ResNet model is recommended not only because it has the best performance overall, but also ResNet is a deep network and capable to learn complex patterns effectively. As a task like this emotional recognition, ResNet has an inherent structure to help mitigate the vanishing gradient problem, enabling training of much deeper networks without compromising on the ability to learn.

Enhancement for Next Step

Due to the project limit, our data preprocessing is only include sample data augmentation. For the problem of emotion recognition, we chould have better data processing methods. For example, the class distribution in the training data is not balanced, which we take into account, but since we focus on finding the best parameters, including class weight parameter slows down our training epoch. Possible follow-up measures are:

- **-Synthetic Data Generation:** We can try techniques like SMOTE (Synthetic Minority Over-sampling Technique) to generate new, synthetic examples of the underrepresented classes.
- **-Advanced Preprocessing:** Spend more time on data preprocessing, such as feature engineering or extraction, to identify key features that are indicative of specific emotions.
- **-Combined Models Methods:** Combine multiple models, particularly those trained on different resampled subsets of the data, to improve the final prediction.

By implementing these methods, we are confident that we can improve the prediction performance.