

PID Controller

Compiling

Once the install for uWebSocketIO is complete, the main program can be built and run by doing the following from the project top directory.

1. `./build.sh` - build project
2. `./clean.sh` - clean build folder
3. `./run.sh` - connect pid to Term2 simulator

Follows the correct algorithm

I completed todos in such files:

- `main.cpp`
- `PID.cpp`
- I also added `prev_cte` field to PID class in the `PID.h` file.

Results

