The 8051 Microcontroller

1.1 INTRODUCTION

The microcontroller incorporates all the features that are found in microprocessor. The microcontroller has built in ROM, RAM, Input Output ports, Serial Port, timers, interrupts and clock circuit. A microcontroller is an entire computer manufactured on a single chip. Microcontrollers are usually dedicated devices embedded within an application. For example, microcontrollers are used as engine controllers in automobiles and as exposure and focus controllers in cameras. In order to serve these applications, they have a high concentration of on-chip facilities such as serial ports, parallel input output ports, timers, counters, interrupt control, analog-to-digital converters, random access memory, read only memory, etc. The I/O, memory, and on-chip peripherals of a microcontroller are selected depending on the specifics of the target application. Since microcontrollers are powerful digital processors, the degree of control and programmability they provide significantly enhances the effectiveness of the application. The 8051 is the first microcontroller of the MCS-51 family introduced by Intel Corporation at the end of the 1970s. The 8051 family with its many enhanced members enjoys the largest market share, estimated to be about 40%, among the various microcontroller architectures.

The microcontroller has on chip peripheral devices. In this unit firstly we differentiate microcontroller from microprocessor then we will discuss about Hardware details of 8051 and then introduce the Assembly level language in brief.

Microcontrollers

 Microcontroller (MC) may be called computer on chip since it has basic features of microprocessor with internal ROM, RAM, Parallel and serial ports within single chip. Or we can say microprocessor with memory and ports is called as microcontroller. This is widely used in washing machines, vcd player, microwave oven, robotics or in industries.

- Microcontroller can be classified on the basis of their bits processed like 8bit MC, 16bit MC.
- 8 bit microcontroller, means it can read, write and process 8 bit data. Ex.
 8051 microcontroller. Basically 8 bit specifies the size of data bus. 8 bit microcontroller means 8 bit data can travel on the data bus or we can read, write process 8 bit data.

1.2 DIFFERENCE BETWEEN MICROCONTROLLER AND MICROPROCESSOR

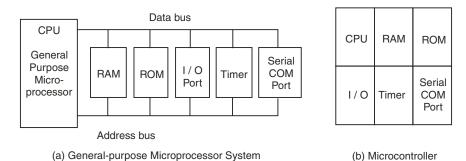


Fig. 1.1 Structure of microprocessor and microcontroller

It is very clear from figure that in microprocessor we have to interface additional circuitry for providing the function of memory and ports, for example we have to interface external RAM for data storage, ROM for program storage, programmable peripheral interface (PPI) 8255 for the Input Output ports, 8253 for timers, USART for serial port. While in the microcontroller RAM, ROM, I/O ports, timers and serial communication ports are in built. Because of this it is called as "system on chip". So in micro-controller there is no necessity of additional circuitry which is interfaced in the microprocessor because memory and input output ports are inbuilt in the microcontroller. Microcontroller gives the satisfactory performance for small applications. But for large applications the memory requirement is limited because only 64 KB memory is available for program storage. So for large applications we prefer microprocessor than microcontroller due to its high processing speed.

1.3 CRITERIA FOR SELECTION OF A MICROCONTROLLER IN EMBEDDED SYSTEM

Criteria for selection of microcontroller in any embedded system is as following:

- (a) Meeting the computing needs of task at hand efficiently and cost effectively
 - Speed of operation
 - Packing

- Power consumption
- Amount of RAM and ROM on chip
- No. of I/O pins and timers on chip
- (b) Availability of software development tools such as compiler, assembler and debugger.

1.4 MICROCONTROLLER 8051 ARCHITECTURE

It is 8-bit microcontroller, means MC 8051 can Read, Write and Process 8 bit data. This is mostly used microcontroller in the robotics, home appliances like mp3 player, washing machines, electronic iron and industries. Mostly used blocks in the architecture of 8051 are as follows:

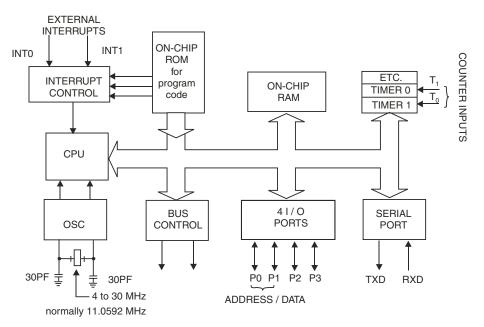


Fig. 1.2 8051 architecture

1.4.1 128 Byte RAM for Data Storage

MC 8051 has 128 byte Random Access memory for data storage. Random access memory is non volatile memory. During execution for storing the data the RAM is used. RAM consists of the register banks, stack for temporary data storage. It also consists of some special function register (SFR) which are used for some specific purpose like timer, input output ports etc. Normally microcontroller has 256 byte RAM in which 128 byte is used for user space which is normally Register

banks and stack. But other 128 byte RAM which consists of SFRs. We will discuss the RAM in detail in next section.

Now what is the meaning of 128 byte RAM. What are address range which is provided for data storage. We will discuss here.

We know that $128 \text{ byte} = 2^7 \text{ byte}$

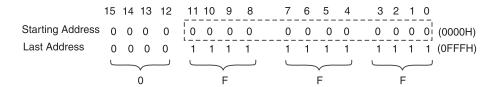
Since 2⁷ bytes so last 7 bits can be changed so total locations are from 00H to 7F H. This procedure of calculating the memory address is called as "*memory mapping*". We can save data on memory locations from 00H to 7FH. Means total 128 byte space from 00H to 7FH is provided for data storage.

1.4.2 4KB ROM

- In 8051, 4KB read only memory (ROM) is available for program storage. This is used for permanent data storage. Or the data which is not changed during the processing like the program or algorithm for specific applications.
- This is volatile memory; the data saved in this memory does not disappear after power failure.
- We can interface up to 64KB ROM memory externally if the application is large. These sizes are specified different by their companies.
- Address Range of PC: Address range of PC means program counter (which points the next instruction to be executing) can be moved between these locations or we can save the program from this location to this location. The address range can be calculated in the same way just like the RAM which is discussed in previous section.

$$4KB = 2^2 \cdot 2^{10} B \text{ (since } 1KB = 2^{10} B\text{)}$$

= $2^{12} Byte$



Address range of PC is 0000H to 0FFFH means total 4KB locations are available from 0000H to 0FFFH. At which we can save the program.

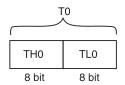
Difference between RAM and ROM

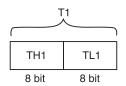
- RAM is used for data storage while ROM is used for program storage.
- Data of RAM can be changed during processing while data of ROM can't be changed during processing.
- We can take an example of calculator. If we want to perform addition of two numbers then we type the two numbers in calculator, this is saved in the RAM, but the Algorithms by which the calculation is performed is saved in the ROM. Data which is given by us to calculator can be changed but the algorithm or program by which calculation is performed can't be changed.

1.4.3 Timers and Counters

Timer means which can give the delay of particular time between some events. For example on or off the lights after every 2 sec. This delay can be provided through some assembly program but in microcontroller two hardware pins are available for delay generation. These hardware pins can be also used for counting some external events. How much times a number is repeated in the given table is calculated by the counter.

- In MC8051, two timer pins are available T0 and T1, by these timers we can give the delay of particular time if we use these in timer mode.
- We can count external pulses at these pins if we use these pins in counter
- 16 bits timers are available. Means we can generate delay between 0000H
- Two special function registers are available.





- If we want to load T0 with 16 bit data then we can load separate lower 8 bit in TL0 and higher 8 bit in TH0.
- In the same way for T1.
- TMOD, TCON registers are used for controlling timer operation.

1.4.4 Serial Port

- There are two pins available for serial communication TXD and RXD.
- Normally TXD is used for transmitting serial data which is in SBUF register, RXD is used for receiving the serial data.
- SCON register is used for controlling the operation.
- There are four modes of serial communication which has been discussed in next chapter.

1.4.5 Input Output Ports

- There are four input output ports available P0, P1, P2, P3.
- Each port is 8 bit wide and has special function register P0, P1, P2, P3 which are bit addressable means each bit can be set or reset by the Bit instructions (SETB for high, CLR for low) independently.
- The data at any port which is transmitting or receiving is in these registers.
- The port 0 can perform dual works. It is also used as Lower order address bus (A0 to A7) multiplexed with 8 bit data bus P0.0 to P0.7 is AD0 to AD7 respectively the address bus and data bus is demultiplex by the ALE signal and latch which is further discussed in details.
- Port 2 can be used as I/O port as well as higher order address bus A8 to A15.
- Port 3 also have dual functions it can be worked as I/O as well as each pin of P3 has specific function.

$$P3.0-RXD - \begin{cases} Serial~I/P~for~Asynchronous~communication\\ Serial~O/P~for~synchronous~communication. \end{cases}$$

P3.1 – TXD – Serial data transmit.

P3.2 – INTO – External Interrupt 0.

P3.3 – INT1 – External Interrupt 1.

P3.4 - T0 - Clock input for counter 0.

P3.5 – T1 – Clock input for counter 1.

P3.6 – WR – Signal for writing to external memory.

P3.7 – RD – Signal for reading from external memory.

When external memory is interfaced with 8051 then P0 and P2 can't be worked as I/O port they works as address bus and data bus, otherwise they can be accessed as I/O ports.

1.4.6 Oscillator

- It is used for providing the clock to MC8051 which decides the speed or baud rate of MC.
- We use crystal which frequency vary from 4MHz to 30 MHz, normally we use 11.0592 MHz frequency.

1.4.7 Interrupts

- Interrupts are defined as requests because they can be refused (masked) if they are not used, that is when an interrupt is acknowledged. A special set of events or routines are followed to handle the interrupts. These special routines are known as interrupt handler or interrupt service routines (ISR). These are located at a special location in memory.
- INTO and INT1 are the pins for external interrupts.

1.5 PIN DIAGRAM OF 8051

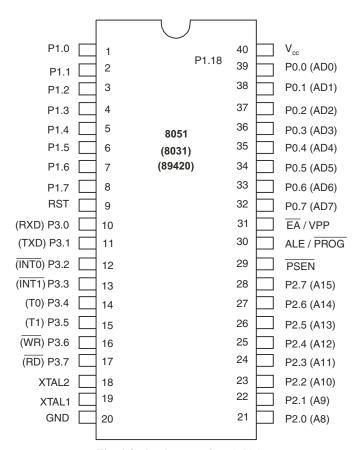


Fig. 1.3 Pin diagram of MC 8051

Description of each pin is discussed here:

- $V_{CC} \rightarrow 5V$ supply $VSS \rightarrow GND$
- XTAL2/XTALI are for oscillator input
- Port 0 32 to 39 AD0/AD7 and P0.0 to P0.7
- Port 1 1 to 8 P1.0 to P1.7
- Port 2 21 to 28 P2.0 to P2.7 and A 8 to A15
- Port 3 10 to 17 P3.0 to P3.7
- P 3.0 RXD Serial data input SBUF
- P 3.1 TXD Serial data output SBUF
- P 3.2 INTO External interrupt 0 TCON 0.1
- P 3.3 INT1 External interrupt 1 TCON 0.3
- P 3.4 T0 External timer 0 input TMOD

- P 3.5 T1 External timer 1 input TMOD
- P $3.6 \overline{WR}$ External memory write cycle Active LOW
- P 3.7 RD External memory read cycle Active LOW
- RST for Restarting 8051
- ALE Address latch enable
 - 1 Address on AD 0 to AD 7
 - 0 Data on AD 0 to AD 7
- PSEN Program store enable

1.6 ARCHITECTURE OF 8051

Figure 1.4 shows the architecture block diagram of 8051.

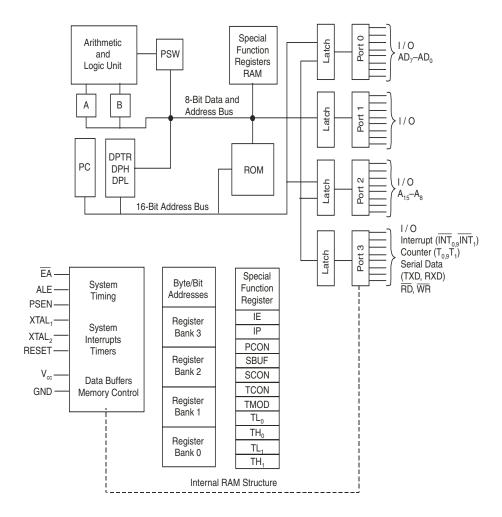


Fig. 1.4 Architectural block diagram of microcontroller 8051

Each block will be discussed step by step:

1.6.1 ALU — Arithmetic Logical Unit

This unit is used for the arithmetic calculations.

1.6.2 A-Accumulator

This register is used for arithmetic operations. This is also bit addressable and 8 bit register.

1.6.3 B-Register

This register is used in only two instructions MUL AB and DIV AB. This is also bit addressable and 8 bit register.

1.6.4 PC-Program Counter

- Points to the address of next instruction to be executed from ROM
- It is 16 bit register means the 8051 can access program address from 0000H to FFFFH. A total of 64KB of code. 16 bit register means.

Initial value	0000	0000	$0\ 00\ 0$	0000	(0000H)
Final value	1111	1111	1 1 1 1	1111	(FFFFH)

- Initially PC has 0000H
- ORG instruction is used to initialize the PC ORG 0000H means PC initialize by 0000H
- · PC is incremented after each instruction.

ROM 0000H 7D **Example:** 25 0001H **Mnemonics** Machine codes MOV R5, #25H 7D 25 74 0002H MOV A, #00H 74 00 00 0003H ADD A, R5 2D HERE: SJMP HERE; 80 FE 0004H 2D • When 7D is accessed then PC locate the 0005H 80 0001H (next instruction to be executed) • When 00 is accessed then PC locate the 0006H FΕ 0004H (next instruction to be executed)

Fig. 1.5 ROM locations

1.6.5 ROM Memory Map in 8051

- \rightarrow 4KB, 8KB, 16KB, 32KB, 64KB on chip ROM is available.
- → Max ROM space is 64 KB because 16 bit address line is available in 8051.
- → Starting address for ROM is 0000H (because PC which points the ROM is 16 bit wide).

Ex. For AT89C51 find the address range of ROM. Sol.

4KB ROM = 2^2 . 2^{10} = 2^{12} B So 12 bits can be changed.

(0000H) 0000 0000 0000 0000 (Starting Address) (0FFFH) 0000 1111 1111 1111 (Max Address) Memory address from 0000H to 0FFFH.

1.6.6 8051 Flag Bits and PSW Register

- → Used to indicate the Arithmetic condition of ACC.
- → Flag register in 8051 is called as program status word (PSW). This special function register PSW is also bit addressable and 8 bit wide means each bit can be set or reset independently.

PSW0.7	PSW0.6	PSW0.5	PSW0.4	PSW0.3	PSW0.2	PSW0.1	PSW0.0
CY	AC	F0	RS1	RS0	OV	_	Р

FLAG Register

There are four flags in 8051

- $P \rightarrow Parity flag \rightarrow PSW 0.0$
 - 1 odd number of 1 in ACC
 - 0 even number of 1 in ACC
- OV(PSW 0.2) → overflow flag → this is used to detect error in signed arithmetic operation. This is similar to carry flag but difference is only that carry flag is used for unsigned operation.

•	RS1(PSW0.4)	RS0(PSW0.3)	Register Bank Select
	0	0	Bank 0
	0	1	Bank 1
	1	0	Bank 2
	1	1	Bank 3

for selecting Bank 1, we use following commands

SETB PSW0.3 (means RS0=1)

CLR PSW0.4 (means RS1=0)

Initially by default always Bank 0 is selected.

- $F0 \rightarrow$ user definable bit
- AC → Auxiliary carry flag → when carry is generated from D3 to D4, it is set to 1, it is used in BCD arithmetic.

				1			1			
	0	0	0	0	1	1	1	0		(0EH
+	0	1	0	1	1	0	1	0		(5AH
-	0	1	1	0	1	0	0	0	_	(38H)

Since carry is generated from D3 to D4, so AC is set.

• $CY \rightarrow carry flag \rightarrow Affected after 8 bit addition and subtraction. It is used$ to detect error in unsigned arithmetic opr. We can also use it as single bit storage.

```
SETB C
                      \rightarrow for cy = 1
CLR C
                      \rightarrow for cy = 0
```

1.6.7 Structure of RAM or 8051 Register Bank and Stack

- → 128 byte RAM is available in 8051
- \rightarrow 128 byte = 2^7 B



Address range of RAM is 00H to 7FH.

→ In MC8051, 128 byte visible or user accessible RAM is available which is shown in figure. Extra 128B RAM which is not user accessible. 80H to FFH used for storage of SFR (special function register)

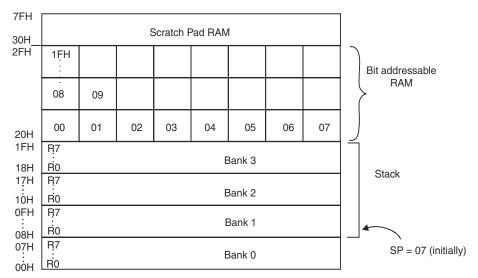


Fig. 1.6 Structure of RAM

→ Four Register Banks

- → There are four register banks, in each register bank there are eight 8 bit register available from R0 to R7
- \rightarrow By default Bank 0 is selected. For Bank 0, R0 has address 00H

R1 has address 01H

.....

R7 has address 07H

For Bank 1, R0 has address 08H

R1 has address 09H

R7 has address 0FH

For selecting banks we use RS0 and RS1 bit of PSW.

 \rightarrow R0 to R7 registers are byte addressable means.

7	6	5	4	3	2	1	0	
0	0	0	0	0	0	0	0	R0

If we want to set the bit 3 of R0 then we can't use SETB R0.3 We use MOV R0, #08H;

For changing single bit we can modify all the other bits of R0.

- → Locations 20H to 2FH is bit addressable RAM means each bit from 00H to FFH in this we can set or reset CF rather than changing whole byte.
- → Locations 30H to 7FH is used as scratch pad means we can use this space for data reading and writing or for data storage.

1.6.8 Stack in 8051

→ RAM locations from 08H to 1FH can be used as stack. Stack is used to store the data temporarily.

Stack is last in first out (LIFO)

- \rightarrow Stack pointer (SP) \rightarrow
- 8bit register
- It indicate current RAM address available for stack or it points the top of stack
- Initially by default at 07H because first location of stack is 08H.
- After each PUSH instruction the SP is incremented by one while in MC after PUSH instruction SP is decremented.
- After each POP instruction the SP is decremented.

Example:

MOV R6,#25H;

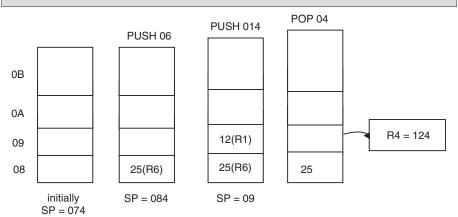
MOV R1,#12H;

MOV R4,#OF3H;

PUSH 06H;

PUSH 01H;

POP 04H;



- → if we want to use more than 24byte (08H to 1FH) of stack. We can change SP to point RAM address 30H to 7FH by MOV SP,
 - → Any value from 30 to 7FH

1.6.8.1 Conflicting of Register Banks and Stack

- → We know locations from 08H to 1FH is used as stack and it is also used as register bank.
- → If in the program, we use the Register Bank 1 to 3 and also use the stack then conflicts exist and error can be possible.
 - For removing this situation we use the stack from location 30H to 7FH by shifting SP to 2FH.

MOV SP,#2FH;

1.6.9 DPTR → Data Pointer in 8051

- \rightarrow 16 bit register, it is divided into two parts DPH and DPL.
- → DPH for Higher order 8 bits, DPL for lower order 8 bits.
- → DPTR, DPH, DPL these all are SFRs in 8051.

1.6.10 Special Function Register

- → (See Fig.) RAM scratch pad, there is extra 128 byte RAM which is used to store the SFRs
- → Following figure shows special function bit address, all access to the four I/O ports CPU register, interrupt control register, timer/counter, UART, power control are performed through registers between 80H and FFH.

Direct Address				Bit Address					Hardware register symbol
F04	F7	F6	F5	F4	F3	F2	F1	F0	B* - B Register
E04	E7	E6	E5	E4	E3	E2	E1	E0	Acc* - Accumulator
D04	D7	D6	D5	D4	D3	D2	D1	D0	PSW* - Program status word
B84	BF	BE	BD	вс	BB	ВА	В9	B8	IP* - Interrupt priority
B04	В7	B6	B5	B4	ВЗ	B2	B1	B0	P3* - Port 3
A84	AF	ΑE	AD	AC	AB	AA	A9	A8	IE* - Interrupt Enable
A04	A7	A6	A5	A4	А3	A2	A1	A0	P2* - Port 2
984	9F	9E	9D	9C	9B	9A	99	98	SCON* - Serial control
904	97	96	95	94	93	92	91	90	P1* - Port 1
884	8F	8E	8D	8C	8B	8A	89	88	TCON* - Timer control
804	87	86	85	84	83	82	81	80	P0* - Port 0

Special Function Register

Byte Addressable SFR with byte address

SP - Stack printer - 81H

DPTR - Data pointer 2 bytes

DPL - Low byte - 82H

DPH - High byte - 83H

TMOD - Timer mode control - 89H

THO - Timer 0 Higher order bytes - 8CH

TL0 - Timer 0 Low order bytes - 8AH

TH1 - Timer 1 High bytes = 80H

TL1 - Timer 1 Low order byte = 86H

SBUF - Serial data buffer = 99H

PCON - Power control - 87H.

1.7 INTRODUCTION TO ASSEMBLY LEVEL LANGUAGE

[Label:] mnemonic [operands] [;comment]

Mnemonics \rightarrow assembly level instructions are called mnemonic like MOV R5 Operands \rightarrow on which the operation is performed.

Example:

Loop: MOVR1, #25H; transfer 25H into R1

Label mnemonics operand comments

- \rightarrow two instructions which are used to start and terminate program.
- $ORG \rightarrow this$ instruction indicate the origin of program ORG 3000H
 - \rightarrow means program starts from 3000H locⁿ.
 - → this instruction hasn't take any memory space. It is used to show the starting address of program.
- END → this instruction show the END of program or it is used to terminate the program.

Example:

ORG 0H; Again: MOV R5, # 25H; transistor 25H to R5 ADD A, R5; Add the R5 with Acc SJMP Again; END;

1.8 ASSEMBLY AND RUNNING 8051 PROGRAM

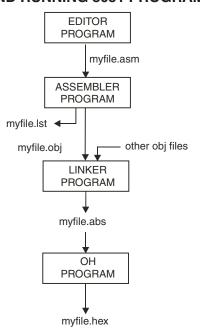


Fig. 1.7 Flow chart

Steps:

- Type your program in editor of software widely used editors are notepad.
- · Save this file with file name . asm \ depending on assembler file name . src notepad produce ASCII file.

- "ASM" source file contains program code assembler converts the instruction into machine code and produces "obj" file and "1st file" (object file and link file).
 - → Linker program takes one or more object files and produces an absolute object file with extension "abs".
 - \rightarrow "abs" file is used by 8051 trainer that have a monitor program.
 - \rightarrow "abs" file is fed into a program code called "OH" (object to Hex converter).

Which create a file with extension "Hex" that is ready to burn into ROM

→ 1st file contains all opcode and address as well as error that assembler detected.

REVIEW QUESTIONS

- 1. Differentiate between microprocessor and microcontroller. Draw and explain the block diagram of 8051. (RTU-EC-2010)
- 2. What do you mean by memory map? How the address range of ROM is defined? Write the address range for following memory:
 - (a) 8KB ROM

- (b) 64 KB ROM
- 3. Differentiate between RAM and ROM. Draw the structure of RAM in 8051. If we want to use the stack from location 30H to 7FH then what is the procedure for it?
- 4. What do you mean by bit addressability and byte addressability? Explain with the help of example. What is the procedure for eliminating the conflict of register bank and stack?
- 5. Why is the coding done in assembly language instead of being written in machine codes directly by programmer? What are different components in instruction? (RTU-EC-2010)
- 6. What are the different ways of classifying the types of microcontroller and list the alternate uses of each pin available in 8051 when used in expanded mode? (RTU-EC-2010)
- 7. What are the pointers in 8051? Explain the use of each pointer. Explain the stack feature in 8051. (RTU-EC-2010)
- 8. How the P0 and P2 are used for data bus and address bus and also used as Input Output Port?
- 9. What is the difference of stack according to operation in 8051, 8085?
- 10. Differentiate PSW in 8051 and 8085 also write difference between carry flag and OV flag.
- 11. Explain the use of SFR available in 8051 also write different types of SFR.
- 12. What are the registers available in 8051? What are the functions of 8051 registers?
- 13. What is a memory map? Why is it needed?