





MediCar – How vehicles can navigate around using LLMs

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1) Project Description

2) Approach

3) Results







## PROJECT DESCRIPTION







#### Intelligent Hospital Logistics

Advanced transport logistics platform for vehicles on clinic premises

Handling of demands and unpredictable events

Simulation environment – University Hospital in Freiburg

Al based routing algorithms + integration of Large Language Models

Contribution to the future of Hospital Logistics



Improvement of selflearning routing systems







#### Visualization with moving vehicles

#### **Connection of LLM and Graph**



Compared different shortest path algorithms (a\*, Dijkstra, Bellman-Ford)

**Evaluation Metric: Euclidean Distance**=> Comparison of Algorithms







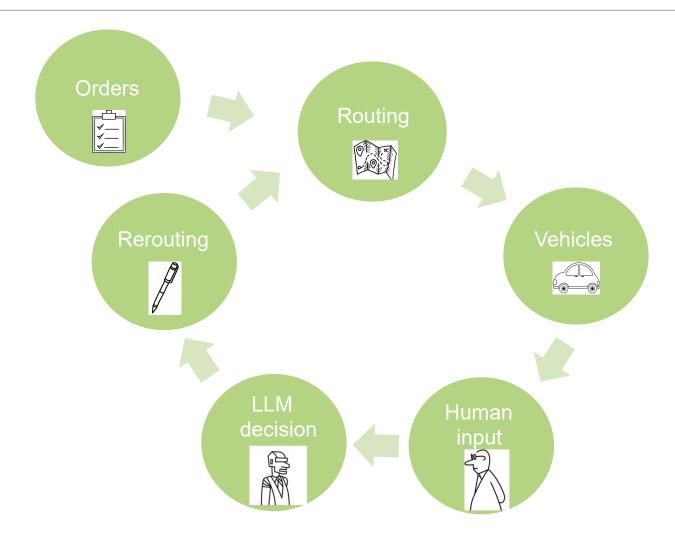
## **APPROACH**



#### Workflow



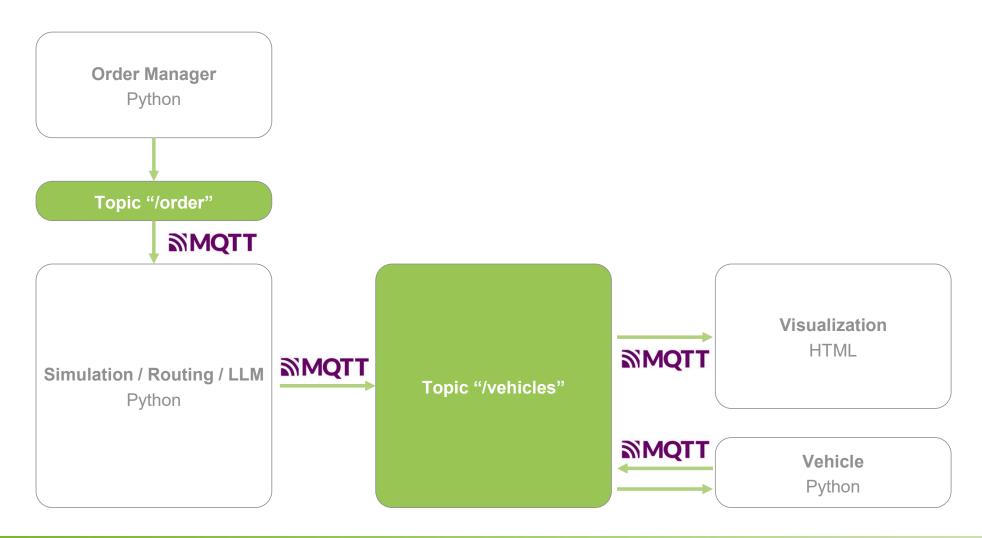


















# **RESULTS**







### LLaMA2

- Meta Model
- Open-Source
- Very high latency
- Has difficulty in understanding prompts with a large number of tokens

### **OpenAl Zero Shot**

- OpenAl Model
- Relies on preexisting knowledge and only the context is given
  - Task-diverse
- A small number of tokens is used

## **OpenAl Few Shot**

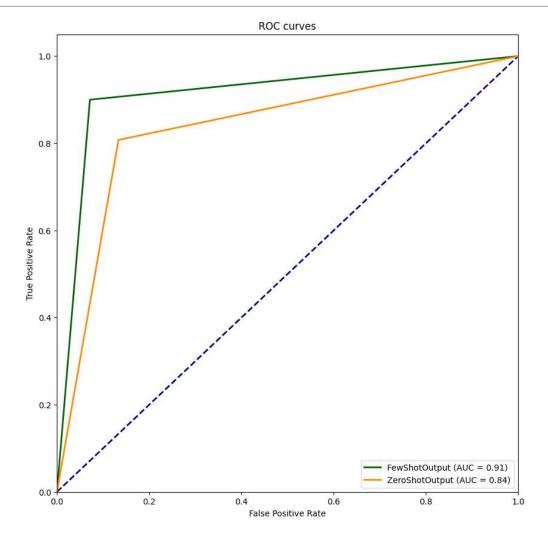
- OpenAl Model
- Giving context and a few examples of expected output to certain inputs
- More fine-tuned for certain Tasks
- Larger amount of tokens used











Ranking	Model	Accuracy
1	OpenAl Few Shot	0.9151
2	OpenAl Zero Shot	0.8393
3	LLama2	-



LLama2 not sufficient for our task

















## **NEXT STEPS**







Reroute moving vehicles too



**Expand current map** 



LLM Finetuning & try LLAMA again



Setup open source models on Uni server





Different vehicle/ order priorities

**Dynamic edge weights** 



**Prompt input from Vehicles** 









# Thank You For Your Attention!

# Do You Have Any Questions?

