HW5 report

Group 5

0516222 許芳瑀 0516209 呂淇安 0516326陳廷達

1. Introduction

In this homework, we try to build a classifier to categorize images into one of 15 scene types. We tried different methods from task 1 to task 3 to get better results.

In task 1, we implemented tiny images representation, then use brute force method to find k-nearest neighbor and decide the type of test image.

In task 2, we try the combination of bag of SIFT representation and nearest neighbor classifier, the accuracy of classification rise to about 50%.

In task 3, nearest neighbor classifier is replaced with linear SVM classifier.

2. Implementation procedure

Task1:

I. resize the picture as 16*16

```
def Resize_Normal(Img_list):
    Result = []

for ImgClass in Img_list:
    img, Class_ = ImgClass

Rsz = cv2.resize( img, dsize=(16, 16) )
    temp = [ pixel for row in Rsz for pixel in row ]
    #normalize
    Nmlz = [ float(pixel) / sum(temp) for pixel in temp ]

Result.append( (Nmlz, Class_) )
return Result
```

II. Use k nearest neighbor algorithm, it means that given a test instance i, find the k closest neighbors and their labels. Predict i's label as the majority of the labels of the k nearest neighbors

```
9 def euclidean_distance(row1, row2):
      distance = 0.0
      if len(row1) != len(row2):
      print("not equal", len(row1), len(row2))
      for i in range(len(row1)-1):
          distance += (row1[i] - row2[i])**2
      return math.sqrt(distance)
16
18 # Locate the most similar neighbors
19 def GetNeighbors(train, test_row, num_neighbors):
       distances = list()
       for (train_row, Class_) in train:
           dist = euclidean distance(row1 = test row, row2 = train row)
           distances.append((Class_, dist))
      distances.sort(key = lambda y: y[1])
24
      neighbors = list()
      for i in range(num_neighbors):
           neighbors.append(distances[i][0])
      return neighbors
28
68 ## NN
   for k in range(1,11): #testing on different k
      iter_ = 0 #counter of image
      right = 0
                         #counter of right prediction
      for (test_row, Class_) in RN_test_list:
           iter_ += 1
           neighbors = GetNeighbors(train = RN_train_list, test_row = test_row, num_neighbors = k)
           output_values = [row for row in neighbors]
           prediction = max(set(output_values), key = output_values.count)
           if prediction == Class :
               right += 1
       Result.append((k, right / (float(iter_))))
82
      print(k, iter_, right, right / float(iter_))
```

Task2:

find SIFT keypoints of all train pictures

```
# find kp
print("finding keypoints of training data")
train_kp = []
]for i in train_list:
    img, img_class = i
    sift = cv2.xfeatures2d.SIFT_create()
    kp, descriptors = sift.detectAndCompute(img, None)
    train_kp.append(descriptors)
train_kp = np.concatenate(train_kp, axis=0)
```

II. function *k_means(data, k, threas)* build cluster of all train key points, we use k=34, threas = 1000 in task 2

it returns k centers of k clusters.

```
while(abs error > threas):
   # cluster 為有k個空list的list
    cluster = []
    for i in range(k):
        cluster.append([])
    # classify pts
    for pt in data:
        classIdx = -1
       min distance = float("inf")
        for idx, c in enumerate(center):
            #print(pt)
            #print(c)
            new_distance = distance(pt, c)
            if new distance < min distance:
                classIdx = idx
                min distance = new distance
        cluster[classIdx].append(pt)
   print('k cluster, k=', k)
    for C in cluster:
       print(len(C))
    cluster = np.array(cluster)
```

while the error is bigger than threshold, we repeatedly classify all points into k clusters and compute new center of each cluster.

III. build histogram of train pictures

```
train_histogram = []
for i in train_list:
    img, img_class = i
    sift = cv2.xfeatures2d.SIFT_create()
    kp, descriptors = sift.detectAndCompute(img, None)
    train_histogram.append((build_histogram(descriptors, center), img_class))
```

```
input: descriptor of a picture, centers of k-cluster output: histogram of the picture

histogram = np.zeros(center.shape[0])
for kp in descriptor:

label = -1

min_distance = float("inf")

for idx, c in enumerate(center):

dis = distance(kp, c)

if dis < min_distance:

lable = idx

min_distance = dis

histogram[lable] += 1

return histogram
```

IV. for test data, find SIFT key points and build the histogram

```
# testing
print("finding keypoints of test data")
test_kp = []

for i in test_list:
    img, img_class = i
    sift = cv2.xfeatures2d.SIFT_create()
    kp, descriptors = sift.detectAndCompute(img, None)
    test_kp.append(descriptors)
test_kp = np.concatenate(test_kp, axis=0)

print("generating histogram of testing data")
test_histogram = []

for i in test_list:
    img, img_class = i
    sift = cv2.xfeatures2d.SIFT_create()
    kp, descriptors = sift.detectAndCompute(img, None)
    test_histogram.append((build_histogram(descriptors, center), img_class))
```

V. use function GetNeighbors(train, test_row, num_neighbors) in task 1, find k nearest neighbors of each test picture and classify them.

Task3:

I. use the train_histogram got in step2 with support vector machine algorithm, The objective of the svm algorithm is to find a hyperplane in an N-dimensional space that distinctly classifies the data points. In this step, we use libsvm package to simply the process. First we create the data in specified type.

II. Use grid.py in libsym to find best parameters

```
C:\Users\user\anaconda3\envs\cv2_v3.4\Lib\libsvm\windows>python grid.py train_data gnuplot executable not found [local] 5 -7 47.2667 (best c=32.0, g=0.0078125, rate=47.2667) [local] -1 -7 32.0667 (best c=32.0, g=0.0078125, rate=47.2667) [local] 5 -1 45.8667 (best c=32.0, g=0.0078125, rate=47.2667) [local] -1 -1 46.0 (best c=32.0, g=0.0078125, rate=47.2667)
```

III. Train model with best parameters

```
C:\Users\user\anaconda3\envs\cv2_v3.4\Lib\libsvm\windows>svm-train.exe -c 8.0 -g 0.03125 train100

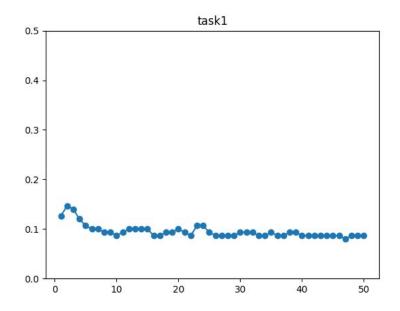
*
optimization finished, #iter = 103
nu = 0.087297
obj = -74.153030, rho = 1.615177
nSV = 33, nBSV = 6
*.*
optimization finished, #iter = 202
nu = 0.262965
obj = -272.800453, rho = 0.943790
nSV = 75, nBSV = 37
*.*
optimization finished, #iter = 215
nu = 0.368263
obj = -418.702488, rho = 3.551816
nSV = 99, nBSV = 57
```

3. Experimental results

Task1:

k=1~10 accuracy

line chart of different k, we get best accuracy when k = 2



Task2:

```
21 150 72 0.48
22 150 75 0.5
23 150 75 0.5
24 150 73 0.486666666666667
25 150 71 0.47333333333333333
26 150 70 0.466666666666667
27 150 72 0.48
28 150 72 0.48
29 150 69 0.46
30 150 72 0.48
31 150 70 0.466666666666667
32 150 72 0.48
33 150 73 0.486666666666667
34 150 76 0.506666666666667
35 150 73 0.4866666666666667
36 150 72 0.48
37 150 71 0.47333333333333333
38 150 70 0.466666666666667
39 150 72 0.48
40 150 71 0.473333333333333333
```

Task3:

The best result is 48%

C:\Users\user\anaconda3\envs\cv2_v3.4\Lib\libsvm\windows>svm-predict.exe test100.txt train100.txt.model t.out Accuracy = 48% (72/150) (classification)

4. Discussion

- 1. Since the training data is much more bigger than any other homeworks before, it spends much time to train the model. So we store the histogram of Bag of SIFT representation of every pictures when we finished task 2. So we can just load the file in task 3, which saves much time.
- 2. At first we only have 3 vocabularies in bags of SIFT, thus the result is bad. After adding more vocabularies ,the result get better.
- 3. The best accuracy of part 3 is 48%, which doesn't hit the goal. We have tried many methods(add vocabularies, scale data.....) but it still fail.

5. Conclusion

After finishing this homework, we know more about the model in machine learning. There are a lot of theory in computer vision can be used in many applications. The algorithms about classifier to

categorize images and the experience of this homework will help us a lot in the future.

6. Work assignment plan between team members.

陳廷達:33%

許芳瑀:33%

呂淇安:33%