

# Chenda Duan

Los Angeles, CA 90024 | 310-254-5864 | [chenda@ucla.edu](mailto:chenda@ucla.edu)  
[linkedin.com/in/chenda-d](https://www.linkedin.com/in/chenda-d) | [github.com/Dadaism6](https://github.com/Dadaism6) | [chendaduan.com](https://chendaduan.com)

## Education

### University of California, Los Angeles (UCLA)

2022.09 – Expected 2024.06

Master of Science in Computer Science

Los Angeles, CA

- **GPA: 4.0/4.0**
- **Teaching Assistant:** CS174A: Intro to Computer Graphics, lectured more than 50 students.

### University of California, Los Angeles (UCLA)

2019.09 – 2022.06

Bachelor of Science in Computer Science

Los Angeles, CA

- **GPA: 4.0/4.0** | **Honor:** Summa Cum Laude, Dean's Honors List
- **Learning Assistant:** CS32: Intro to Computer Science, lectured more than 50 students.
- **Core Courses:** Algorithms, Computer Organization, Operating Systems, Computer Architecture, Network, Programming Languages, Database, Software Engineering, Computer Vision, NLP, Machine Learning

## Technical Skills

Language: Python, C++, Java, Shell, MATLAB  
Database & Deployment: MySQL, GCP, Docker

Front End: JavaScript, HTML/CSS, React  
Others: Robotics, CV, ML, NLP

## Work / Research Experience

### UCLA Prof. Bolei Zhou's Group

2022.03 – Present

Student Researcher

Los Angeles, CA

- Currently developing an improved version of the Human-in-the-loop Reinforcement Learning (RL). The trained agent can master driving tasks in **less than 30 minutes** on a home PC, saving **more than 90%** of the training time compared to traditional RL methods such as SAC, using **Python(PyTorch)**.
- Developing more photorealistic simulation environment for training RL autopilot agent using UE4 and Airsim.

### UCLA Structure-Computer Interaction Lab

2020.06 – 2022.6

Undergraduate Researcher

Los Angeles, CA

- Developed a 2D **LiDAR** robotic navigation algorithm for a road identification system and improved the navigation accuracy by **30%** (compared with multi-Ransac) for the robot while maintaining a low cost (less than \$100). The road identification system was deployed on a low-cost autonomous weed-control agri-robot, using **C++** and **Python**.
- Created an inverse learning approach to train a model to generate the physical parameters (such as diameter) for the **soft robot** and increase the efficiency of collecting the parameters by **90%**, using **Python (Tensorflow)**.

### UCLA Center for Neurobehavioral Genetics

2020.06 – 2022.6

Undergraduate Researcher

Los Angeles, CA

- Processed RNA sequence data and performed PCA, data visualization etc, using **Python** and **R**.
- Proved that Low-coverage RNA sequencing is an effective approach in Expression quantitative trait loci studies and can save the cost by **more than 50%**. Learn more details via the paper "*Powerful eQTL mapping through low-coverage RNA sequencing*".

## Course Project

### Online Text Generation Server

2022.3 - 2022.6

- Built a NGINX standard web server with REST API capabilities using **C++** and **Boost** Library.
- Constructed a CI/CD Pipeline on GCP: Detailed log info, test coverage monitoring using Google Test, and code review using gerrit. Setup a monitor dashboard to record up-time and request latency.
- Source code: <https://github.com/Dadaism6/UCLA-CS130-Googolplex>

### Online Basketball-shooting Game

2021.10 - 2021.12

- Designed and implemented an online basketball-shooting game with advanced graphic features, including shadow, texture, and reflections, using **JavaScript** and **WebGL**.
- Demo: <https://basketball-shooting.herokuapp.com>

### Egglendar Online Calendar

2020.10 - 2020.12

- Developed an online student calendar specially for international students, with features of importing and converting calendars, adding school course schedules, and finding classmates.
- Using Material-UI for designing and **React** for the front-end framework, and **MySQL** as the database.