

## Exercise sheet 8

**Due date:** Monday, November 13, 2023, 23:59 CET (midnight).

### Problem 8.1 Inheritance

Specify the output of the following code (without running it!).

```
#include <iostream>

class A {
public:
    virtual void f() const { std::cout << "A::f "; }
    void g() const { std::cout << "A::g "; }
};

class B: public A {
public:
    void f() const { std::cout << "B::f "; }
    void g() { std::cout << "B::g "; }
};

class C: public B {
public:
    void f() { std::cout << "C::f "; }
    void g() const { std::cout << "C::g "; }
};

void func(A const& a) {
    a.f();
    a.g();
}

int main() {
    A a;
    B b;
    C c;

    a.f();
    a.g();

    b.f();
    b.g();

    c.f();
    c.g();

    func(a);
    func(b);
    func(c);

    std::cout << std::endl;
}
```

### Problem 8.2 Simpson integration with virtual functions

Implement a new version of your Simpson integration routine using virtual functions:

- Define an abstract base class with a pure virtual `operator()` for function objects in double precision.

- Write a free Simpson integrator function that takes the integrand as a reference to the abstract base class.
- Derive a concrete class from the abstract base class and implement the `operator()`.

### Problem 8.3 Benchmark of Simpson integrations

Benchmark the four different versions of the Simpson integration that you have already implemented:

- hard-coded function (Exercise sheet 1),
- function pointer (Exercise sheet 2),
- function template with function objects and type traits (Exercise sheet 4 and 5),
- derived function object (virtual function) (Exercise sheet 8).

We suggest using the optimization flags `-O3 -DNDEBUG -march=native`<sup>1</sup>. Additionally, you can try `-funroll-loops`.

Repeat the benchmarks for functions of different computational complexity:  $f_1(x) = 0$ ,  $f_2(x) = 1$ ,  $f_3(x) = x$ ,  $f_4(x) = x^2$ ,  $f_5(x) = \sin(x)$ , and  $f_6(x) = \sin(5x)$ . Discuss the results.

### Problem 8.4 Penna Model with Fishing

Read the paper by Moss de Oliveira, Penna, and Stauffer [Moss de Oliveira et al., Physica A 215, 298, 1995]<sup>2</sup>.

Implement a Penna simulation for a population of fish that is subject to systematic fishing. The goal is to observe how a slight increase in fishing may destroy an initially stable population. The following describes how you should modify your original Penna simulation:

1. At a time-step  $M_1$ , when the fish population is stable, introduce the concept of fishing. Here, each fish can die due to fishing (in addition to illness) with probability  $p_1$ . At a later time-step  $M_2 > M_1$  increase the fishing probability to  $p_2 > p_1$ .
2. Observe that the increase in fishing at time-step  $M_2$  destabilizes the fish population. Use simulation parameters from the paper:  $M = 1$ ,  $T = 3$ , genome length = 32,  $R = 7$ , pregnancy probability = 1,  $p_1 = 0.17$ ,  $p_2 = 0.22$ .
3. What happens if fishing is only allowed for the adult species?

As usual, you can base your code on the `Genome`, `Animal`, and `Population` classes from the lecture repository, but working on your own design might prove more rewarding.

In the paper a new parameter  $M_0$  is introduced which you can ignore.

<sup>1</sup>When using CMake, perform the benchmarks using the `Release` build type. The build type is controlled via the variable `CMAKE_BUILD_TYPE`. By default, the `Release` build type adds `-O3 -DNDEBUG` to the compiler flags.

<sup>2</sup>The paper is available at [https://doi.org/10.1016/0378-4371\(95\)00039-A](https://doi.org/10.1016/0378-4371(95)00039-A). You have to be inside the ETH network in order to download it.