Kevin Bradner
PS8 Writeup

Please see control_movie.mp4 for the video of this code in action.

This package primarily develops waypoints corresponding to a motion down the 2nd floor of Glennan. Code for linear steering is copied here so that parameters can be altered for the lab later, but the code is unchanged except for name.

rosrun odom_tf odom_tf_demo was used with this code, in addition to the commands explicitly mentioned in the instructions.

This works well, and it will be interesting to see it on the physical robot.