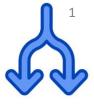
Performance and Scalability



Practical Concurrent and Parallel Programming VI Performance and Scalability

Jørgen Staunstrup

Agenda



- Performance versus scalability
- Scalability, speed-up and loss classification Example: QuickSort
- **Executors and Future Example: count Prime Factors**
- Hash maps, a scalability case study

Previously on PCPP



Week 3

Speedup for quicksort: 3.6 using 8 threads 2.9 using 4 threads

Speedup for counting primes: 3.9 using 8 threads 2.3 using 4 threads

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Performance and scalability

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Performance (of software)

- Latency: time till first result (response time)
- Throughput: results per second

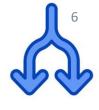
Scalability (one way to improve performance)

Improve throughput/latency by adding more resources

One may sacrifice performance for scalability Maybe OK to be slower on 1 core, if faster on 2 or 4 or ...

Goetz chapter 11

What limits performance?



Suggestions?

What limits performance?

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CPU-bound

- Eg. counting prime numbers
- To speed up, add more CPUs (cores) (exploitation)

Input/output-bound

- Eg. reading from network
- To speed up, use more tasks (inherent)

Synchronization-bound

- Eg. Algorithm using shared data structure
- To speed up, improve shared data structure (Much of this lecture)

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Quicksort



1	2	43	78	19	54	33	21	64	52	17	53	
1	2	43	78	19	54	33	21	64	52	17	53	
1	2	43 †	78	19	54	33	21	64	52	17 †	53	
1	2	17 †	78	19	54	33	21	64	52	43	53	
1	2	17	78 †	19	54	33	21 †	64	52	43	53	
1	2	17	21	19	33	54	78	64	52	43	53	

17 21 19 33 54 78 64 52 43 53

Two parts can be

sorted independently

Multi-threaded version of Quicksort



```
class Problem {
    public int[] arr;
    public int low, high;
    ...
}

thread thread thread ... thread }

class ProblemHeap {
    list<Problem> heap= new List<Problem>;
```

```
private static void qsort(Problem problem, ProblemHeap heap) {
  int[] arr= problem.arr;
  int a= problem.low;
  int.b= problem.high;
  ...
  heap.add(new Problem(arr, a, j); //qsort(arr, a, j);
  heap.add(new Problem(arr, i, b));//qsort(arr, i, b);
}
```

Java code for Quicksort (1)



```
public static void problemHeapStart(int threadCount, int pSize, int[] intArray) {
 ProblemHeap heap= new ProblemHeap(1);
 heap.add(new Problem(intArray, 0, pSize-1));
 for (int t=0; t<threadCount; t++) {</pre>
   threads[t] = new Thread( () -> { try {
       Problem newProblem= heap.getProblem();
       while (newProblem != null) { // when newProblem == null alg stops
         qsort(newProblem, heap);
         newProblem= heap.getProblem();
       }catch (InterruptedException exn) { } //needed because getProblem may wait
   });
```



We use Mark8Setup to measure runtime

```
Benchmark.Mark8Setup("Problem heap quicksort",
         String.format("%2d", threadCount),
         new Benchmarkable() {
           public void setup() {
             SearchAndSort.shuffle(intArray);
             problemHeapStart(threadCount, pSize, intArray);
           public double applyAsDouble(int i) {
             problemHeapFinish(threadCount, intArray); return 0.0;
   );
```

Code in: Week06: exercises/

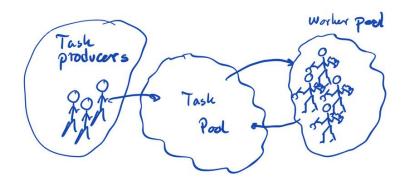
ProblemHeapSortingBenchmarkable.java

Java Executors (1)

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Motivation

- Threads are expensive to start executors reuse threads
- Problem heap breaking a problem down to smaller problems (tasks)



Task producers, and Workers are threads
Workers may themselves produce new tasks

The Task pool and Worker pool together is called an *Executor service*

Thread(runnable2).start();

new Thread(runnable3).start();

Threads are expensive!

ExecutorService pool; pool.execute(runnable1);

Reuse of threads

pool.execute(runnable2);

pool.execute(runnable2); https://howtodoinjava.com/java/multi-threading/java-fixed-size-thread-pool-executor-example/

Quicksort example



```
class runProblemHeap extends Thread {
 private final ExecutorService pool;
 public runProblemHeap(...) { pool = Executors.newFixedThreadPool(poolSize); }
 @Override
 public void run() {
   pool.execute( new solveProblem( new Problem(...), pool, c) );
class solveProblem implements Runnable {
 @Override
 public void run() { qsort(...); }
 // Quicksort
 public static void qsort(..., ExecutorService pool) { ... }
```

Quicksort using Executors



```
class solveProblem implements Runnable {
private ExecutorService pool;
private static int threshold;
public solveProblem(ExecutorService pool, int threshold, ...) { }
 @Override
public void run() { qsort(pool, ... ); }
public static void qsort(ExecutorService pool, ...) {
 if (a < b) { ... }
  if ((j-a)>=threshold) pool.execute(new solveProblem(pool,threshold));
  else { SearchAndSort.qsort(..., a, j); }
  if ((b-i)>= threshold) pool.execute(new solveProblem(pool,threshold));
  else { SearchAndSort.qsort(..., i, b); }
                    Code in Week06: Exercises .../QuicksortExecutor.java
```

Performance of Executor Quicksort



```
Executor quicksort 1 98003405.0 ns
Executor quicksort 2 53568593.9 ns
Executor quicksort 4 36397241.3 ns
Executor quicksort 8 21714103.7 ns
Executor quicksort 16 22237307.4 ns
Executor quicksort 32 22510681.9 ns
```

Speedup = 4.5

A bit better than using native Threads (slide 3)

Quicksort



1	2	43	78	19	54	33	21	64	52	17	53
1	2	43	78	19	54	33	21	64	52	17	53
1	2	43 †	78	19	54	33	21	64	52	17 †	53
1	2	17 †	78	19	54	33	21	64	52	43	53
1	2	17	78 †	19	54	33	21 †	64	52	43	53

1 2 17 21 19 54 33 78 64 52 43 53

17 21 19 33 54 78 64 52 43 53 sorted independently

Two parts can be

What limits scalability?



Example: growing a crop

- 4 months growth + 1 month harvest if done by 1 person
- Growth (sequential) cannot be speeded up
- Using 30 people to harvest, takes 1/30 month = 1 day
- Speed-up using many harvesters: 5/(4+1/30) = 1.24 times faster

Amdahl's law (Goetz 11.2)

```
F = sequential fraction of problem = 4/5 = 0.8
```

$$N = number of threads (people) = 30$$

Speed-up
$$\leq 1/(F+(1-F)/N) = 1/(0.8+0.2/30) = 1.24$$

Other types of "loss" limiting scalability



Starvation loss

Separation loss (best threshold)

Saturation loss (locking common data structure)

Braking loss

Møller-Nielsen, P and Staunstrup, J, Problem-heap. A paradigm for multiprocessor algorithms. *Parallel Computing*, 4:63-74, 1987

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Termination in Executors



```
class solveProblem implements Runnable {
  public void run() { qsort(p, ...); }
}
class solveProblem implements Runnable {
    public void run() { qsort(p, ...); }
}
```

```
class solveProblem implements Runnable {
  public void run() { qsort(p, ...); }
}
```

```
//main (thread)
  setUpQS( ... ) // creates thread
  finishQS( ... ) //wait for all threads to finish
}
```

Need for a signal from the threads to the main thread !!!

Shut down



The ExecutorService has methods to help in shutting down.

```
// Executor body
...
...
pool.shutdown();
```

The challenge is: when to shut down?

In the Quicksort example a counter (=size of problem heap) was used to determine when to shutdown

Solution 1: shared counter



```
class countProblems{
  private int c= 1; // counting active threads + problems in heap
  synchronized void incr() { c++; }
  synchronized void decr() { c--; }
  synchronized void reset() { c= 1; }
  synchronized boolean isZero() { return c==0; }

  // The semaphore finished signals termination to main thread
  public Semaphore finished= new Semaphore(0);
}
```

Using the counter



```
public static void qsort(.., countProblems c) {
if (a < b) {
  if ((j-a) \ge threshold) {
    c.incr();
   pool.execute(new solveProblem(new Problem(arr, a, j), pool, c) );
                         How can we be sure that no other
  if ((b-i) >= 1000)
    c.incr();
                        threads are active?
   pool.execute (new sol.
  c.decr(); // problem 
                          _ decrement c
  if (c.isZero()) { signal termination pool.shutdown(); }
```

Termination in Executors



```
class solveProblem implements Runnable {
  public void run() { qsort(p, ...); }
  class solveProblem implements Runnable {
    public void run() { qsort(p, ...); }
}
```

```
public void run() { qsort(p, ...); }

//main (thread)
```

```
setUpQS( ... ) // creates thread
finishQS( ... ) //wait for all threads to finish
}
```

```
private static void finishQS(countProblems c) {
  try {    c.finished.acquire(); }
  catch (java.lang.InterruptedException e) { ... ); }
}
```

class solveProblem implements Runnable {

Solution 2: Future



```
get
\mathsf{T}_1
                           start
                                                                           return result
```

```
T2:
  public Future<Integer> calculate(Integer input) {
    return executor.submit(() -> {
      ... // compute result
     return result;
    });
T1:
  Future<Integer> future = T2.calculate( ); // start
  future.get();
```



Code in Week06: LectureCode .../futureExample.java

Runnable vs. Callable



Both are used to specify the code of a thread.

- Runnable cannot return a result
- Callable returns a result (via a Future)

As illustrated by the Quicksort example, Runnables may use shared data (e.g., to deliver a result)

Futures are an example of message passing

countPrimes

```
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```

```
private static long countParallelN(int range, int taskCount) {
  List<Callable<Long>> tasks= new ArrayList<Callable<Long>>();
  for (int t= 0; t<taskCount; t++) {</pre>
    final int from= ...,
              to= ...;
    tasks.add(() -> {
      long count = 0; // Task-local counter
      for (int i=from; i<to; i++) if (isPrime(i)) count++;</pre>
      return count;
    });
  long result = 0;
  try {
    List<Future<Long>> futures = executor.invokeAll(tasks);
    for (Future<Long> fut : futures)
      result += fut.get();
    } catch ...
    return result;
```

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Scalability of Java Collections



A *collection* is simply an object that groups multiple elements into a single unit

Package: java.util

Examples: ArrayList, HashMap, TreeSet, ...

https://docs.oracle.com/javase/tutorial/collections/intro/index.html

Methods: add, remove, size, contains, ...

Many of the classes have synchronized/concurrent implementations

https://www.baeldung.com/java-synchronized-collections

Example: synchronized ArrayList



```
import java.util.*;
public class syncCollectionExample {
 public static void main(String[] args) {    new syncCollectionExample(); }
 public String getLast(ArrayList<String> 1) {
    int last= 1.size()-1;
    return l.get(last);
 public static void delete(ArrayList<String> 1) {
    int last= 1.size()-1;
    1.remove(last);
 public syncCollectionExample() {
    ArrayList<String> a= new ArrayList<String>();
    a.add("A"); ...
    Collection<String> synColl = Collections.synchronizedCollection(a);
```

Goetz p. 80

Thread-safety (from week 4)



It is very important to note that:

Program where all classes are thread-safe ⇒ thread-safe <u>program</u>

Making the synchronized ArrayList thread safe



```
import java.util.*;
public class syncCollectionExample {
  public static void main(String[] args) {    new syncCollectionExample(); }
  public String getLast(ArrayList<String> 1) {
    synchronized(1) {
      int last= l.size()-1;
      return l.get(last);
  public static void delete(ArrayList<String> 1) {
    synchronized(1) {
      int last= l.size()-1;
      1.remove(last);
  public syncCollectionExample() {
```

Goetz p. 80

What if the data structure is huge?



and used by many threads?

for example:

a bank

Facebook updates

•••

Would not work if everything I "synchronized"

What can we do?

Reduce locking !!

Example: A huge HashMap

Key value pairs: <k1, v1>, <k2, v2>, ...

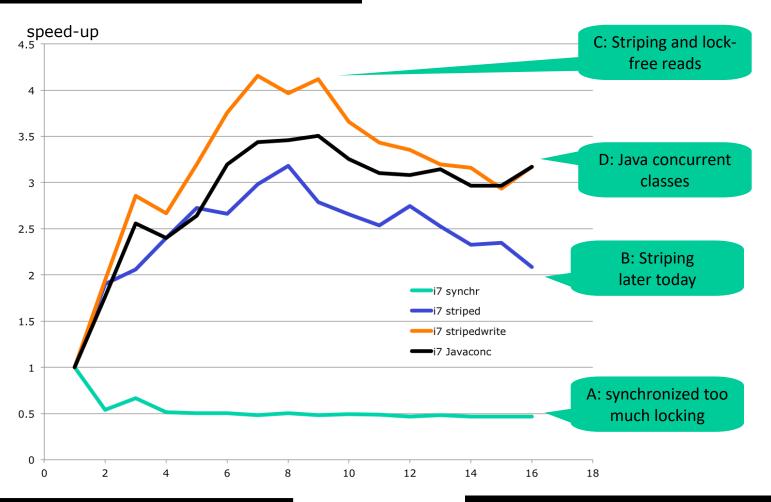
```
class HashMap<K,V> {
    ... // datastructure
    public V get(K k) { ... }
    public V put(K k, V v) { ... }
    public boolean containsKey(K k) { ... }
    public int size() { return cachedSize; }
    public V remove(K k) { ... }
    ...
}
```

How to make it thread-safe?

Key	Value	
Peter	20487612	
Anna	51251218	
Lena	34458318	
Holger	89545010	
Lisa	94959500	

Scaling a HashMap

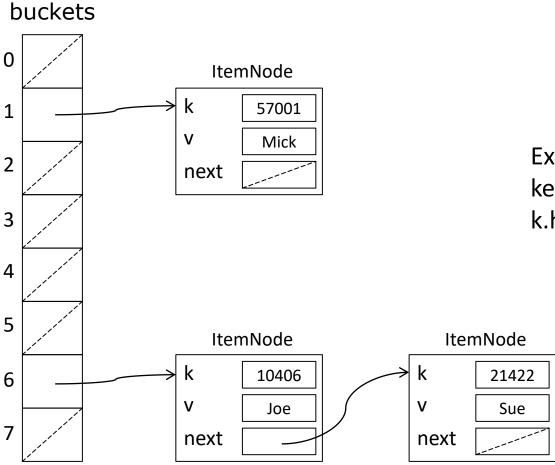




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HashMap implementation

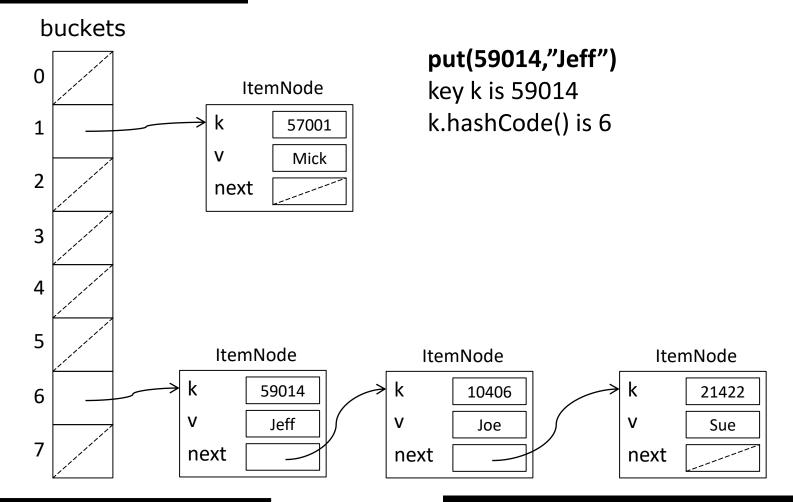




Example get(10406) key k is 10406 k.hashCode() is 6

HaspMap put





Synchronized implementation

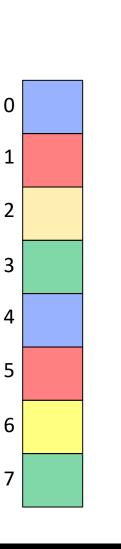


```
static class ItemNode<K,V> {
  private final K k;
  private V v;
  private ItemNode<K,V> next;
  public ItemNode(K k, V v, ItemNode<K,V> next) { ... }
}
```

```
class SynchronizedMap<K,V> {
  private ItemNode<K,V>[] buckets; // guarded by this
  private int cachedSize; // guarded by this
  public synchronized V get(K k) { ... }
  public synchronized boolean containsKey(K k) { ... }
  public synchronized int size() { return cachedSize; }
  public synchronized V put(K k, V v) { ... }
  public synchronized V remove(K k) { ... }
}
```

Improving scalability

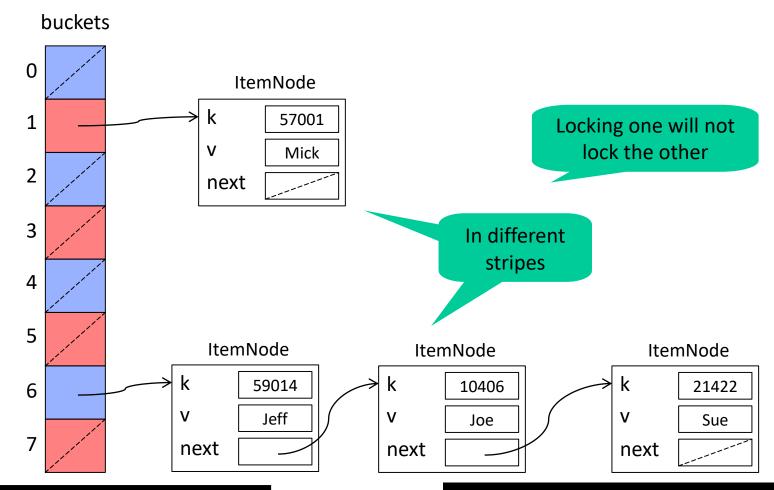
- Guarding the table with a single lock works
- -... but does not scale well (actually **very** badly)
- Idea: Each bucket could have its own lock
- In practice
- -use fewer, to illustrate we use 4, locks
- -guard every 4th bucket with the same lock
- -locks[0] guards bucket 0, 4, 8, ... (stripe 0)
- -locks[1] guards bucket 1, 5, 9, ... (stripe 1) et
- -two operations will work on different stripes
- -hence will take different locks
- Less lock contention, better scalability



-With high probability

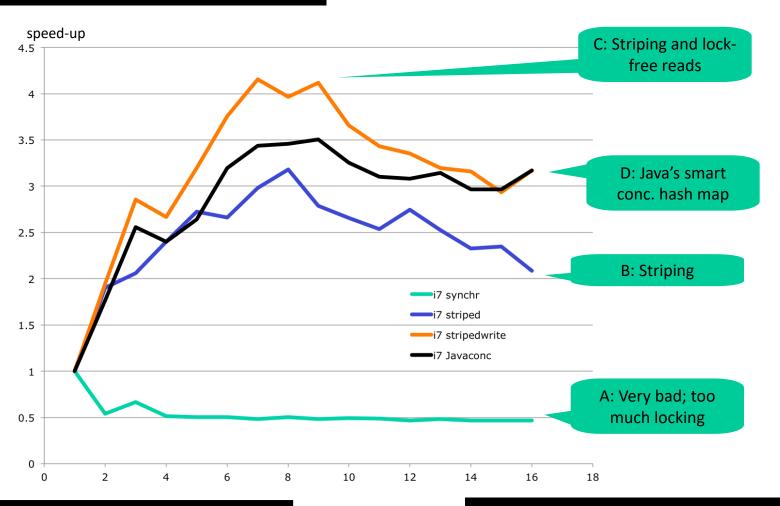
Bucket idea





Reducing locking





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Ultimate scalability



A web-shop, Facebook, ...

We must give up thread safety,

but still maintain some sort of consistency

Week 13