

CONVEXITY ADJUSTMENTS WITH A BIT OF MALLIAVIN

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Abstract

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1 Introduction

Mathematical finance aims to find a methodology to price consistently all the instruments quoted in the market. When working with fixed income derivatives, a classic research topic is the introduction of a price adjustment to achieve this. This adjustment is called convexity adjustment. It is non-linear and depends on the interest rate model.

There are several reasons to include this type of adjustment. One of them is to incorporate futures on the yield curve construction. Futures and other fixed-income instruments are quoted differently. The firsts are linear against the yield, but the others are not. Therefore, the changes in value and yield of different contracts are different. This difference will depend on the volatility and correlation of the yield curve.

But it is not the only one. The fixed-income market has several features changing the schedule of payments. For example, in a swap in arrears, the floating coupon fixing and payment are on the same date. Or in a CMS swap, the floating rate is linked to a rate longer than the floating length. Any customization of an interest rate product based on changing time, currency, margin, or collateral will require a convexity adjustment. Deep down, by making these changes, we are mixing the martingale measures.

Convexity adjustments have become popular again. Not only by the increase in volatility in the markets. In addition, as a consequence of the transition in risk-free rates from the IBOR (InterBank Offered Rates) indices to the ARR (Alternative Reference Rates) indices, also called RFR. Both indices try to represent the same thing, the risk-free rate, but they are fundamentally different. While the former represents the average rate at which Panel Banks believe they could borrow money, the latter is calculated backward based on transactions. Therefore, these new products need their corresponding convexity adjustment.

The first references on the convexity adjustment were ?, ? and ?, published almost simultaneously. A convexity formula for averaging contracts was found in ?. Flesaker derived a convexity adjustment for computing the expected Libor rate under the Ho-Lee model in a continuous and discrete setting in ?. ? used the Taylor expansion on the inverse function for calculating the convexity adjustment. In the following years, several improvements were made. For example, the convexity adjustment was extended to other payoffs in ?. ? improved the Taylor expansion. ?

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derived the convexity adjustment for the Hull-White model. Afterwards, we can find papers that extend the convexity adjustment to different payoffs, see ? or ?. Or by applying alternative techniques such as the change of measure in ?, a martingale approach in ? or the effects of stochastic volatility in ? and ?.

In the present paper, we find an alternative way to calculate the convexity adjustment for a general interest rate model. The idea is to use the Itô's representation theorem. Unfortunately, the theorem does not give an insight into how to calculate the elements therein. Therefore, it is necessary to introduce basic concepts of Malliavin calculus to apply the Clark-Ocone representation formula.

The structure of the paper is as follows. In Section 2, we give the basic preliminaries and our notation related to Interest Rates models. This notation will be used throughout the paper without being repeated in particular theorems unless we find it useful to do so in order to guide the reader through the results. In Section 3, we make an introduction to Malliavin calculus. In Section 4, In Section 5, In Section 6

2 Preliminaries and notation

3 Basic introduction to Malliavin calculus

Malliavin calculus is an infinite-dimensional calculus in a Gaussian space, that is, a stochastic calculus of variations. In other words, this is a theory that provides a way to calculate the derivatives of random variables defined in a Gaussian probability space with respect to the underlying noise. The initial objective of Malliavin was the study of the existence of densities of Wiener functionals such as solutions of stochastic differential equations. But, nowadays, it has become an important tool in stochastic analysis due to the increase in its applications. Some of these applications include stochastic calculus for fractional Brownian motion, central limit theorems for multiple stochastic integrals, and an extension of the Itô formula for anticipative processes, but especially mathematical finance. For example, we can apply Malliavin calculus for computing hedging strategies, Greeks, or obtain price approximations. See, for example, ? or ? for more general content.

In our case, we are interested in using the Malliavin calculus to apply the Clark-Ocone representation theorem. But, first of all, let's introduce some basic concepts.

Now, we introduce the derivative operator in the Malliavin calculus sense and the divergence operator to establish the notation that we use in the remainder of the paper.

Consider $W = \{W_t, t \in [0, T]\}$ a Brownian motion defined on a complete probability space $(\Omega, \mathcal{F}, \mathbb{P})$. Let $H = L^2([0, T])$ and denote by

$$W_t := \int_0^T t_s dW_s,$$

the Itô integral of a deterministic function $h \in H$, also known as Wiener integral. Let \mathcal{S} be the set of smooth random variables of the form

$$F = f(W_{t_1}, \dots, W_{t_n})$$

with $t_1, \dots, t_n \in [0, T]$ and f is infinitely differentiable bounded function.

The derivative of a random variable F , $D_s F$, is defined as the stochastic process given by

$$D_s F = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(W_{t_1}, \dots, W_{t_n}) 1_{[0, t_i]}(s), \quad s \in [0, T].$$

The iterated derivative operator of a random variable F is defined by

$$D_{s_1, \dots, s_m}^m F = D_{s_1} \cdots D_{s_m} F, \quad s_1, \dots, s_m \in [0, T].$$

? stated that these operators are closable from $L^p(\Omega)$ into $L^p(\Omega; L^2[0, T])$ for any $p \geq 1$, and we denote by $\mathbb{D}^{n,p}$ the closure of \mathcal{S} with respect to the norm

$$\|F\|_{n,p} := \left(E[F]^p + \sum_{i=1}^n E \|D^i F\|_{L^2([0, T]^i)}^p \right)^{\frac{1}{p}}.$$

We define δ as the adjoint of derivative operator D , also referred to as the Skorohod integral. The domain of δ , denoted by $Dom \delta$, is the set of elements $u \in L^2([0, T] \times \Omega)$ such that there exists $\delta(u) \in L^2(\Omega)$ satisfying the duality relation

$$E[\delta(u)F] = E \left[\int_0^T (D_s F) u_s ds \right].$$

The operator δ is an extension of the Itô integral in the sense that the set $L_a^2([0, T] \times \Omega)$ of square integrable and adapted processes is included in $Dom \delta$ and the operator δ restricted to $L_a^2([0, T] \times \Omega)$ coincides with the Itô stochastic integral.

For any $u \in Dom \delta$, we will use the following notation

$$\delta(u) = \int_0^T u_s dW_s.$$

The representation of functionals of Brownian motion by stochastic integrals, also known as martingale representation, has been widely studied over the years. It states that if F is a square-integrable random variable, there exists a unique adapted process φ in $L^2(\Omega \times [0, T]; \mathbb{R}^d)$ such that

$$F = E[F] + \sum_{i=1}^n \int_0^T \varphi_s^i dW_s^i.$$

In other words, there exists a unique martingale representation or, more precisely, the integrand φ in the representation exists and is unique in $L^2(\Omega \times [0, T]; \mathbb{R}^d)$.

Unfortunately, it is not easy to find an analytic representation of the process φ . Here, the Malliavin calculus helps us to find a solution. When the random variable F is Malliavin differentiable, the process φ appearing in Itô's representation theorem, is given by

$$\varphi^i = E \left[D_t^{W^i} F | \mathcal{F}_s^W \right].$$

In fact,

$$F = E[F] + \sum_{i=1}^n \int_0^T E \left[D_t^{W^i} F | \mathcal{F}_s^W \right] dW_s^i \quad (1)$$

is the Clark-Ocone representation formula.

4 Convexity Adjustment

... tengo que pensar que poner aqui como intro

4.1 HJM framework

In order to compute the convexity adjustment, we need to assume some dynamic on the estimation curve and discount curve. In order to avoid problems with a stochastic basis between both curves, we will suppose a not stochastic basis i.e, we will suppose the next representation for the forward rate curve $f_E(t, T)$

$$f_E(t, T) = f_{ois}(t, T) + s(t, T). \quad (2)$$

Where $s(t, T) = f_E(0, T) - f_{ois}(0, T)$ i.e we suppose the basis between curves that we get from the market in time $t = 0$. On other hand, $f_{ois}(t, T)$ is the OIS forward rate curve and whose dynamic under the \mathbb{Q} -measure will be a single factor HJM dynamic i.e

$$\begin{aligned} df_{ois}(t, T) &= \sigma(t, T)\nu(t, T)dt + \sigma(t, T)dW_t^{\mathbb{Q}} \\ f_{ois}(0, T) &= -\partial_T \log(P_{ois}(0, T)) \end{aligned} \quad (3)$$

where $\nu(t, T) = \int_t^T \sigma(t, s)ds$ and $\sigma(t, T)$ is a positive function for all $t, T > 0$. In order to have a Markovian representation of the HJM model, It is usual to assume that volatility function is separable, i.e

$$\sigma(t, T) = h(t)g(T). \quad (4)$$

with g is a time-dependent positive function and h is a general non-negative process. It is easy to show (see Andreasen 2001), that in this case (3)

$$r_{ois}(t) = f_{ois}(t, t) = f_{ois}(0, t) + x_t, \quad (5)$$

where

$$\begin{aligned} dx_t &= (-k_t x_t + y_t)dt + \eta_t dW_t^{\mathbb{Q}} \\ dy_t &= (\eta_t^2 - 2k_t y_t)dt, \end{aligned} \quad (6)$$

with

$$\begin{aligned} \eta_t &= g(t)h(t, x_t, y_t) \\ k_t &= -\frac{\partial_t g(t)}{g(t)} \end{aligned}$$

Then with a little bit of algebra and we use Itô formula we can show the next representation formula for $P_{ois}(t, T)$

$$P_{ois}(t, T) = \frac{P_{ois}(0, T)}{P_{ois}(0, t)} \exp \left(-G(t, T)x_t - \frac{1}{2}G^2(t, T)y_t \right) \quad (7)$$

where $G(t, T) = \int_t^T \exp \left(-\int_t^u k_s ds \right) du$. We must observe, that under the representation (2) we have that

$$P_E(t, T) = H(t, T)P_{ois}(t, T) \quad (8)$$

where $H(t, T) = \exp \left(-\int_t^T s(t, u)du \right)$.

4.2 FRAs Vs futures

The cashflows in FRAs and futures are computing under different measures and consequently we have to adjust the futures price quote to transform them to FRAs price quote. As usual, we will define the forward rate in time t_0 between t_1 and t_2 under the forward curve E as

$$L_E(t_0, t_1, t_2) = \frac{\left(\frac{P_E(t_0, t_1)}{P_E(t_0, t_2)} - 1 \right)}{\delta_{t_1, t_2}} \quad (9)$$

where $P_E(t, T)$ is the discount factor for the curve E from t to T and δ_{t_1, t_2} is the year fraction between t_1 and t_2 . We must observe that $L_E(t, t_1, t_2)$ is a martingale under the forward measure \mathbb{Q}^{t_2} . Let us define the future rate

$$\hat{L}_E(t, t_1, t_2) = \mathbb{E}_t^{\mathbb{Q}}(L_E(t_0, t_1, t_2)), \quad (10)$$

where the measure \mathbb{Q} is the measure associated to the numeraire $B_t = \exp\left(\int_0^t r_{ois,s} ds\right)$ with $r_{ois,t}$ the risk free short rate. From (9) and (10), we will define the convexity adjustment as

$$CA(t, t_0, t_1, t_2) = \mathbb{E}_t^{\mathbb{Q}}(L_E(t_0, t_1, t_2)) - \mathbb{E}_t^{\mathbb{Q}^{t_2}}(L_E(t_0, t_1, t_2)) = \mathbb{E}_t^{\mathbb{Q}}(L_E(t_0, t_1, t_2)) - L_E(t_0, t_1, t_2)$$

With view to get a general representation formula of the convexity adjustment for the futures, we will use (1) to $L_E(t_0, t_1, t_2)$ i.e

$$L_E(t_0, t_1, t_2) = \mathbb{E}_t^{\mathbb{Q}}(L_E(t_0, t_1, t_2)) + \int_0^{t_0} \mathbb{E}_s(D_s L_E(t_0, t_1, t_2)) dW_s^{\mathbb{Q}} \quad (11)$$

therefore, if we take $\mathbb{E}^{\mathbb{Q}^{t_2}}(\cdot)$ in the last equation, then we get

$$CA(t, t_0, t_1, t_2) = -\mathbb{E}^{\mathbb{Q}^{t_2}}\left(\int_0^{t_0} \mathbb{E}_s(D_s L_E(t_0, t_1, t_2)) dW_s^{\mathbb{Q}}\right).$$

From (3) and since $f_{ois}(t, T)$ is a \mathbb{Q}^T martingale, we have that

$$dW^{\mathbb{Q}^{t_2}} = dW^{\mathbb{Q}} + \nu(t, T)dt.$$

Therefore, if we apply Girsanov's theorem to switch to measure \mathbb{Q}^{t_2} , we get that

$$CA(t, t_0, t_1, t_2) = \mathbb{E}^{\mathbb{Q}^{t_2}}\left(\int_0^{t_0} \mathbb{E}_s(D_s L_E(t_0, t_1, t_2)) \nu(s, t_2) ds\right) \quad (12)$$

where $\nu(t, T)$ has been defined in (3). Now, from the definition of $L_E(t, T)$ we have that

$$D_s L_E(t_0, t_1, t_2) = \frac{H(t_0, t_1)}{\delta_{t_1, t_2} H(t_0, t_2)} D_s \left(\frac{P_{ois}(t_0, t_1)}{P_{ois}(t_0, t_2)} \right).$$

If we use the representation formula (7) we get that

$$D_s \left(\frac{P_{ois}(t_0, t_1)}{P_{ois}(t_0, t_2)} \right) = \frac{(\partial_x P_{ois}(t_0, t_1) P_{ois}(t_0, t_2) - \partial_x P_{ois}(t_0, t_2) P_{ois}(t_0, t_1))}{P_{ois}^2(t_0, t_2)} D_s x_{t_0}$$

therefore

$$D_s L_E(t_0, t_1, t_2) = \frac{H(t_0, t_1)}{\delta_{t_1, t_2} H(t_0, t_2)} \frac{(\partial_x P_{ois}(t_0, t_1) P_{ois}(t_0, t_2) - \partial_x P_{ois}(t_0, t_2) P_{ois}(t_0, t_1))}{P_{ois}^2(t_0, t_2)} D_s x_{t_0}.$$

From (6) y we define $\beta(s, t, x, y) = \exp\left(-\int_s^t k_u\right) \eta(s, x, y)$ we have that

$$D_s x_{t_0} = \beta(s, t_0, x_s, y_s) M(s, t_0)$$

where $M(s, t_0) = \exp\left(-\frac{\int_s^{t_0} (\partial_x \beta(u, t_0, x_s, y_s))^2 du}{2} + \int_s^{t_0} \partial_x \beta(u, t_0, x_s, y_s) dW_u^{\mathbb{Q}}\right)$. Then, we have that

$$\begin{aligned} D_s L_E(t_0, t_1, t_2) &= \frac{H(t_0, t_1)}{\delta_{t_1, t_2} H(t_0, t_2)} \frac{(\partial_x P_{ois}(t_0, t_1) P_{ois}(t_0, t_2) - \partial_x P_{ois}(t_0, t_2) P_{ois}(t_0, t_1))}{P_{ois}^2(t_0, t_2)} \beta(s, t_0, x_s, y_s) M(s, t_0) \\ &= \frac{P_E(0, t_1)}{\delta_{t_1, t_2} P_E(0, t_2)} (G(t_0, t_2) - G(t_0, t_1)) \beta(s, t_0, x_s, y_s) M(s, t_0). \end{aligned}$$

It is a common practice, freeze the state variables of the model to achieve some approximations. We can approximate x_s and y_s the next way

$$\begin{aligned} x_s &\approx x_0 \\ y_s &\approx y_0 + \int_0^s \exp\left(-2 \int_u^s k_{u'} du'\right) \eta(u, x_0, y_0) du \end{aligned}$$

Therefore,

$$\mathbb{E}_s(D_s L_E(t_0, t_1, t_2)) = \frac{P_E(0, t_1)}{\delta_{t_1, t_2} P_E(0, t_2)} (G(t_0, t_2) - G(t_0, t_1)) \beta(s, t_0, x_0, \hat{y}_s) \quad (13)$$

where $\hat{y}_s = y_0 + \int_0^s \exp\left(-2 \int_u^s k_{u'} du'\right) \eta(u, x_0, y_0) du$. Now, from (12) and (13) we have the next approximation for the convexity adjustmet for future

$$CA(t, t_0, t_1) \approx \frac{P_E(0, t_1)}{\delta_{t_1, t_2} P_E(0, t_2)} (G(t_0, t_2) - G(t_0, t_1)) \int_0^{t_0} \beta(s, t_0, x_0, \hat{y}_s) ds. \quad (14)$$

Example 4.1. *Hull-White model*

Example 4.2. *Ho-Lee model*

4.3 OIS futures

4.4 CMSs

5 Numerical Results

6 Conclusion