SYSTEM PROGRAMMING

CHAPTER ONE: INTRODUCTION

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CONTENTS

- Basic terminology
- System software and machine architecture
- The Simplified Instructional Computer (SIC)
 - SIC and SIC/XE Machine architecture
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 - Instruction sets
 - I/O
 - Programming Examples

BASIC TERMINOLOGY

- System: Group of related things that works towards common goal.
 - An organized collection of parts(sub systems) are integrated together to accomplish goal
 - E.g. computer(made from integrated components like I/O, cpu, storage etc.)
- Program/Software: executable sw runs on a machine like computer
 - Consists a compiled code that can run directly from the computer's operating system.
- Types of software: there are two types
 - Application SW
 - System SW

CON...

Application Software

- A set of programs written in a specific programming language to solve a particular problem.
- It is independent of the machine on which it is operated.
- Concerned mainly with the solution of the problem and makes use of the computer software as a tool.
- Purpose of supporting or improving the user's work with a software (it gives services for user)
- The focus is on the application

• Example:

- Word processing :MS word, WordPad
- Database :Oracle, MS Access
- Spreadsheet :Excel, Apple Numbers
- Multimedia :Real Player, Media Player
- Presentation Graphics :MS PowerPoint

CON... System Software

- It is software designed to provide a platform for other software.
 - A set of programs that creates the environment to facilitate working of an application software.
 - Able effective execution of application Software
 - Acts as an intermediary between computer hardware and application programs.
 - Controls the computer system and enhances its performance.
 - Focus is on the system.
 - Machine dependent(Instruction Set, Instruction Format, Addressing Mode)
 - However, general design and logic of an assembler and compiler, code optimization techniques are machine independent
- System programming means development of computer programs that allow the entire system to function as a single unit.

EXAMPLES OF SYSTEM SOFTWARE

• Operating **systems:** like macOS, Linux, Android and Microsoft Windows, computational science **software**, game engines, industrial automation,

• Text Editor

- Allows user to create/modify a file having only plain text.
- Edit contents to get an immediate visual feedback
- Notepad (Microsoft)

Compiler

- Translates high level language to machine language.
- Source code into data, that computer can understand.
- Source code to object code
 - ADA, BASIC, Fortran, Pascal
 - C, C++, C#
 - Open Source like java

Linker

Gathers 1 or more objects codes generated by the compiler
 & combines into a single EXE

CON...

- Loader
 - Loads object code into memory for execution
- Debugger
 - Tests & debugs errors
 - Code run on Instruction Set Simulator (ISS)
 - DEBUG Microsoft DOS built-in debugger
 - Nemiver Graphical C/C++ debugger
 - Ups Fortran, C
 - VB Watch Visual Basic
 - Jswat Open source Java
 - Xdebug PHP

Assembler

- Assembly language to machine language
- Mnemonics to machine code, Produces executable machine code

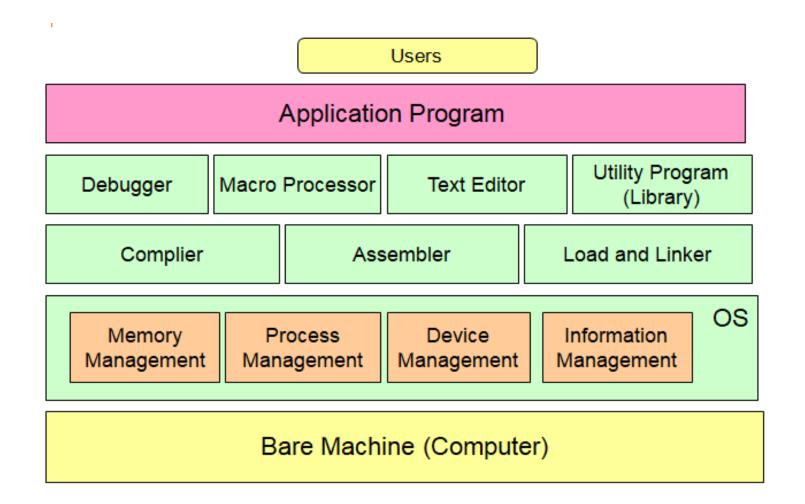
Interpreter

High level language to machine language

NEED FOR SYSTEM SOFTWARE

- Controls some of the aspects of operation of computers.
 - File operation
 - I/O operation
 - Memory management
 - Etc.

SYSTEM SOFTWARE CONCEPT



System software and machine architecture

- One characteristic in which most system_software differ from application_software is machine dependency.
 - e.g. assembler translate mnemonic instructions into machine code
 - e.g. compilers must generate machine language code
 - e.g. operating systems are directly concerned with the management of nearly all of the resources of a computing system
- Some aspects of system software that do not directly depend upon the type of computing system
 - e.g. general design and logic of an assembler and compiler
 - e.g. code optimization techniques

THE SIMPLIFIED INSTRUCTIONAL COMPUTER (SIC)

- SIC is a hypothetical computer system introduced in System Software.
 - It includes the hardware features most often found on real machines while avoiding unusual or irrelevant complexities
 - Since it is difficult to learn system programming on real computer system SIC introduced.

Two versions of SIC

- SIC standard model
- SIC/XE (extra equipments or extra expensive)
 - SIC program can be executed on SIC/XE (upward compatible)
- The two versions has been designed to be upward compatible.
 - Object program for the standard SIC machine will execute properly on SIC/XE system.

SIC Machine Architecture

- Memory
 - Memory consists of 8-bit, 3 consecutive bytes form a word (24 bits), SIC is designed as a 24-bit machine. Total of 32768 bytes (32 KB) in the computer memory.
 - A word is addressed by is lowest numbered byte (i.e., addressing starts at byte 0).
- Register: SIC machines have 5 registers

Register	Number	Known as	Use
A	0	Accumulator	Arithmetic operations
X	1	Index register	Addressing
L	2	Linkage register	jumping to specific memory addresses and storing return addresses
PC	8	Program counter	Contains the address of the next instruction to execute
SW	9	Status word	Contains a variety of information, such as carry or overflow flags

- Register: is a temporary storage area built into a CPU, **registers** are used to pass data from memory to the processor
- Flags: is a value that acts as a signal for a function or process

Data Formats

- Integers are stored as 24-bit binary numbers
- 2's complement for negative values
- 8-bit ASCII for characters
- No floating point hardware in standard SIC

Instruction Formats

- 24-bit format
- x indicates indexed addressing mode

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opcode X address

Addressing modes

- 2 addressing modes available
 - Indicated by x bit in the instruction

Mode	Indication	Target address calculation
Direct	$\mathbf{x} = 0$	TA = address
Indexed	x = 1	TA = address + (x)

• (x) represents the contents of register x

Instruction Set

- **load and store**: To move or store data from accumulator to memory or vice-versa example : LDA, LDX, STA, STX ...
- Arithmetic operations: ADD, SUB, MUL, DIV, etc.
 - Used to perform operations on accumulator and memory and store result in accumulator (register A)
- comparison: COMP
 - compares the value in register A with a word in memory, this instruction sets a condition code CC to indicate the result
- conditional jump instructions: JLT, JEQ, JGT
 - these instructions test the setting of condition code CC and jump accordingly
- subroutine linkage: JSUB, RSUB
 - \bullet JSUB jumps to the subroutine, placing the return address in register L
 - RSUB returns by jumping to the address contained in register
 - a **subroutine** is a sequence of program instructions that performs a specific task

Input and Output

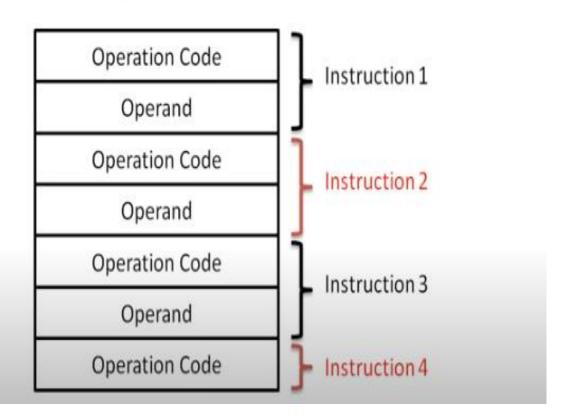
- Input and output are performed by transferring 1 byte at a time to or from the rightmost 8 bits of register A
- **The Test Device** (TD): instruction tests whether the addressed device is ready to send or receive a byte of data
- "Less Than " if device is ready; "Equal" if device is busy.
- Read Data (RD)
 - read a byte from the device to register A
- Write Data (WD)
 - write a byte from register A to the device

MACHINE CODE INSTRUCTION

- Machine code is a set of instructions executed directly by a computer's central processing unit
- Each **instruction** performs a very specific task, such as a load, a jump, or an ALU operation on a unit of data in a CPU register or memory.
- Machine code instruction usually consists operation code(op code) & operands
- Some instructions consists only operation code
- Op code is a mnemonic used to refer to a microprocessor instruction in assembly language
- Operand is A quantity to which an operator is applied (in 3 x, the operands of the subtraction operator are 3 and x).
- All operation code and operands are binary code

Con...

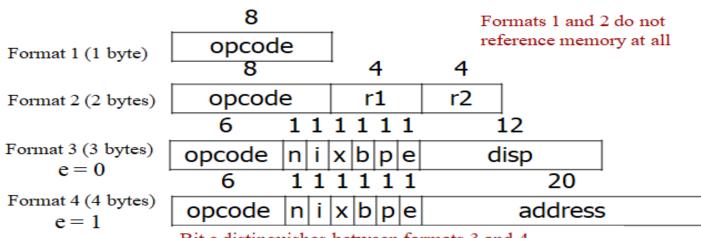
A machine code program consists of a sequence of Op Codes and Operands stored in the computers memory (e.g. RAM)



- Memory
 - Larger Memory
 - 2^{20} bytes (1 megabyte) in the computer memory
 - Leads to change in instruction formats & addressing modes
- Registers
 - Additional registers provided

Mnemonic	Number	Use
В	3	Base register – used for addressing
S	4	General purpose register – no special use
Т	5	General purpose register – no special use
F	6	Floating point accumulator (48 bits instead 24 bits)

- Data format
 - 24-bit binary number for integer, 2's complement for negative values
 - 48-bit floating-point data type
 - The exponent is between 0 and 2047
 - value represented = $f^*2^{\text{(exponent-1024)}}$, f is fraction b/n 0 &1
- Instruction format



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- Format 1: Consists of 8 bits of allocated memory to store instructions. Don't refer memory location
- Format 2: Consists of 16 bits of allocated memory to store 8 bits of instructions and two 4-bits segments to store operands(source and destination register)
- Format 3: Consists of 6 bits to store an instruction, 6 bits of flag values, and 12 bits of displacement.
- Format 4: Only valid on SIC/XE machines, consists of the same elements as format 3, but instead of a 12-bit displacement, stores a 20-bit address.
- Both format 3 and format 4 have six-bit flag values in them, consisting of the following flag bits:
 - **n**: Indirect addressing flag
 - i: Immediate addressing flag
 - x: Indexed addressing flag
 - **b**: Base address-relative flag
 - p: Program counter-relative flag
 - e: Extended for Format 4 instruction flag

- Addressing modes
 - Base relative (n=1, i=1, b=1, p=0)
 - Program-counter relative (n=1, i=1, b=0, p=1)
 - **Direct** (n=1, i=1, b=0, p=0)
 - Immediate (n=0, i=1, x=0)
 - Indirect (n=1, i=0, x=0)
 - Indexing (both n & i = 0(SIC) or 1(SIC/EX), x=1)
 - Extended (e=1) for format 4 and e=0 for format 3
 - Note: Indexing cannot be used with immediate or indirect addressing.

SIC/XE MACHINE...

Base Relative Addressing Mode

$$n=1$$
, $i=1$, $b=1$, $p=0$ TA=(B)+disp (0 \leq disp \leq 4095)

Program-Counter Relative Addressing Mode

n=1, i=1, b=0, p=1 TA=(PC)+disp (-2048 \leq disp \leq 2047)

SIC/XE MACHINE...

Direct Addressing Mode

$$n=1$$
, $i=1$, $b=0$, $p=0$ TA=(X)+disp (with index addressing mode)

SIC/XE MACHINE...

Immediate Addressing Mode

opcode	0	1	0			disp
n=0, i=1, x=0				TA = disp		

Indirect Addressing Mode

$$n=1$$
, $i=0$, $x=0$

Con...

- PC-relative simple addressing: (PC) + disp
- Base-relative indexed simple addressing: (B) + disp + (X)
- PC-relative indirect addressing: **(PC) + disp**
- Immediate addressing: disp
- Indirect addressing :disp

- Instruction Set
 - new registers: LDB, STB, etc.
 - floating-point arithmetic: ADDF, SUBF, MULF, DIVF
 - register move: RMO
 - register-register arithmetic: ADDR, SUBR, MULR, DIVR
 - supervisor call: SVC
 - generates an interrupt for OS
- Input/output
 - SIO, TIO, HIO: start, test, halt the operation of I/O device

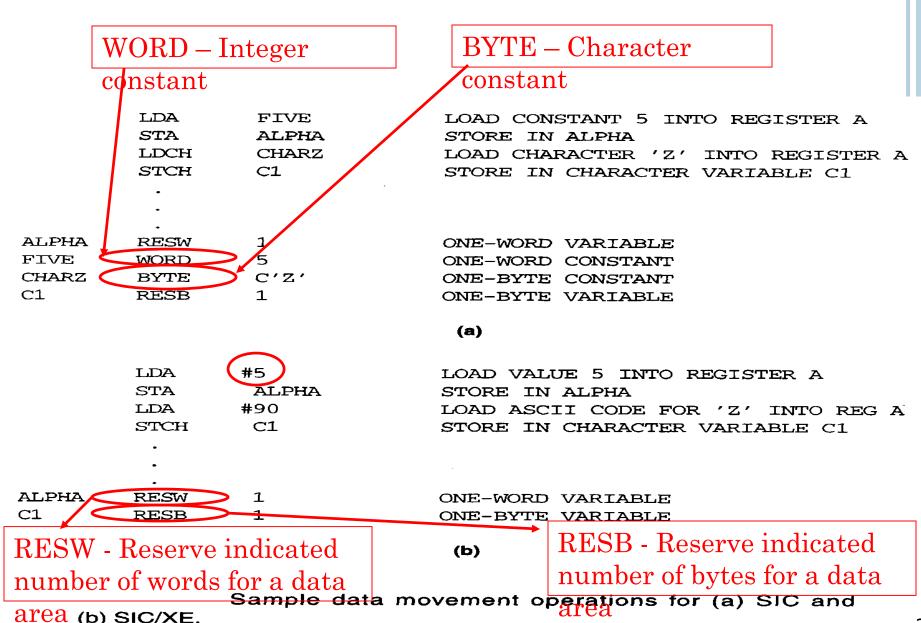
SIC ASSEMBLY SYNTAX

- SIC uses a special assembly language with its own operation codes that hold the hex values needed to assemble and execute programs.
- A sample program is provided below to get an idea of what a SIC program might look like.
- The first column represents a forwarded symbol that will store its location in memory.
- The second column denotes either a SIC instruction (opcode) or a constant value (BYTE or WORD).
- The third column takes the symbol value obtained by going through the first column and uses it to run the operation specified in the second column.
- This process creates an object code, and all the object codes are put into an object file to be run by the SIC machine.

SIC AND SIC/XE PROGRAMMING EXAMPLES

- Data movement operations
- Arithmetic operations
- Looping and indexing operations
- Data input and output operations

PROGRAMMING EXAMPLES



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PROGRAMMING EXAMPLES

	LDA	ALPHA	LOAD ALPHA INTO REGISTER A
	ADD	INCR	ADD THE VALUE OF INCR
	SUB	ONE	SUBTRACT 1
	STA	BETA	STORE IN BETA
	LDA	GAMMA	LOAD GAMMA INTO REGISTER A
	ADD	INCR	ADD THE VALUE OF INCR
	SUB	ONE	SUBTRACT 1
	STA	DELTA	STORE IN DELTA
ONE	WORD	1	ONE-WORD CONSTANT
· WHIRE			ONE-WORD VARIABLES
ALPHA	RESW	1	
BETA	RESW	1	T MAN A A THE WORLD
GAMMA	RESW	1	BETA← (ALPHA + INCR - 1)
DELTA	RESW	1	DELTA← (GAMMA + INCR - 1)
INCR	RESW	1	

Fig: Arithmetic operations

SIC

SIC PROGRAMMING EXAMPLE LOOP

	LDA	ZERO	initialize index value to 0
	STA	INDEX	
ADDLP	LDX	INDEX	load index value to reg X
	LDA	ALPHA,X	load word from ALPHA into reg A
	ADD	BETA, X	
	STA	GAMMA, X	store the result in a word in GAMMA
	LDA	INDEX	
	ADD	THREE	add 3 to index value
	STA	INDEX	
	COMP	K300	compare new index value to 300
	JLT	ADDLP	loop if less than 300
	• • •		
	• • •		
INDEX	RESW	1	
ALPHA	RESW	100	array variables—100 words each
BETA	RESW	100	
GAMMA	RESW	100	
ZERO	WORD	0	one-word constants
THREE	WORD	3	
K300	WORD	300	

Gamma[] = Alpha[] + Beta[]

SIC PROGRAMMING EXAMPLE I/O

Input and output

INLOOP	TD JEQ RD STCH	INDEV INLOOP INDEV DATA	test input device loop until device is ready read one byte into register A
OUTLP	TD JEQ LDCH WD	OUTDEV OUTLP DATA OUTDEV	test output device loop until device is ready write one byte to output device
INDEV OUTDEV DATA	BYTE BYTE RESB	X'F1' X'05' 1	input device number output device number

SIC/EX PROGRAMMING EXAMPLES

Arithmetic operation.

 $\begin{array}{c} \text{BETA} \leftarrow \text{(ALPHA + INCR - 1)} \\ \text{DELTA} \leftarrow \text{(GAMMA + INCR - 1)} \end{array}$

LDS	INCR
LDA	ALPHA
ADDR	S,A
SUB	#1
STA	BETA
LDA	GAMMA
ADDR	S,A
SUB	#1
STA	DELTA

LOAD VALUE OF INCR INTO REGISTER S
LOAD ALPHA INTO REGISTER A
ADD THE VALUE OF INCR
SUBTRACT 1
STORE IN BETA
LOAD GAMMA INTO REGISTER A
ADD THE VALUE OF INCR
SUBTRACT 1
STORE IN DELTA

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ONE WORD VARIABLES

ALPHA	RESW	1
BETA	RESW	1
GAMMA	RESW	1
DELTA	RESW	1
TNCR	RESW	1

This program will execute faster because it need not load INCR from memory each time when INCR is needed.

SIC/EX Programming Examples

Looping and indexing

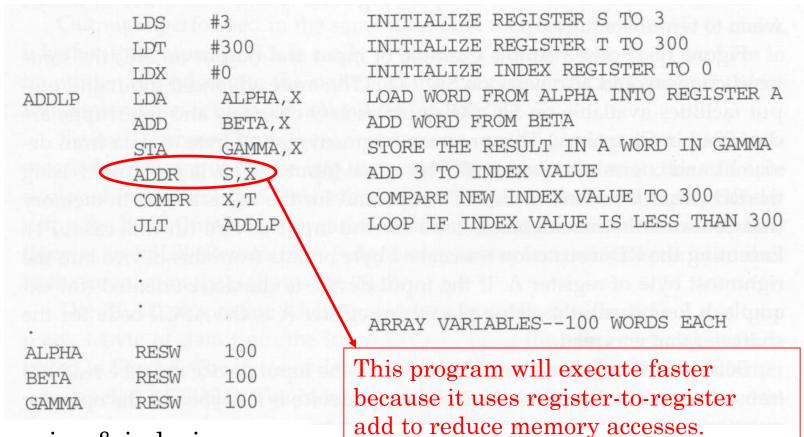


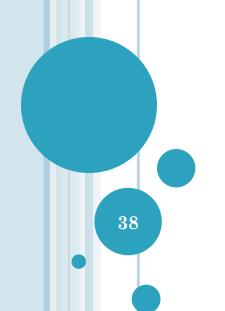
Fig: Looping & indexing SIC/XE

SIC/EX Programming Examples

Input /output

	JSUB	READ	CALL READ SUBROUTINE
at enterior			
	end resett		
· Indiana in the			SUBROUTINE TO READ 100-BYTE RECORD
READ	LDX	#0	INITIALIZE INDEX REGISTER TO 0
	LDT	#100	INITIALIZE REGISTER T TO 100
RLOOP	TD	INDEV	TEST INPUT DEVICE
	JEQ	RLOOP	LOOP IF DEVICE IS BUSY
	RD	INDEV	READ ONE BYTE INTO REGISTER A
	STCH	RECORD, X	STORE DATA BYTE INTO RECORD
	TIXR	T	ADD 1 TO INDEX AND COMPARE TO 100
	JLT	RLOOP	LOOP IF INDEX IS LESS THAN 100
	RSUB		EXIT FROM SUBROUTINE
	opinom		
	ROUNDE		
INDEV	BYTE	X'F1'	INPUT DEVICE NUMBER
RECORD	RESB	100	100-BYTE BUFFER FOR INPUT RECORD

Fig: Subroutine call & record input operations



THANK YOU!

Question?