

Chapter 2- Analysis of Algorithms

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Prepared by: Beimnet G.

If computers were infinitely fast and computer memory was free, would you have any reason to analyze algorithms?

Birthday Algorithm

Maintain a record of names and birthdays (initially empty)

Interview each student in some order

 If birthday exists in record, return found pair!

 Else add name and birthday to record

Return None if last student interviewed and no pairs are found

Correctness of an Algorithm: Example

Find max of two numbers:

```
max(a,b)
  If a >= b
    max=a
  Else max=b
  Return max
```

Find max value from array:

```
max(A)
  max=A[0]
  for i=1 to A.length-1
    if A[i] > max
      max=A[i]
  return max
```

Mathematical Induction

Proof By Mathematical Induction

When trying to prove a **given statement** for a set of natural numbers:

The first step, known as the **base case**, is to prove the given statement for the first natural number.

The second step, known as the **inductive step**, is to prove that, if the statement is assumed to be true for any one natural number, then it must be true for the next natural number as well.

Having proved these two steps, the rule of inference establishes the statement to be true for all natural numbers.

In addition to these two steps in the conventional mathematical induction, while proving correctness of algorithm we add a third step to check the **termination** of the algorithm.

Birthday Algorithm

Maintain a record of names and birthdays (initially empty)

Interview each student in some order

 If birthday exists in record, return found pair!

 Else add name and birthday to record

Return None if last student interviewed and no pairs are found

Birthday Algorithm- Inductive Hypothesis

At the start of the i^{th} interview, if birthday pairs exist in our input size n , they exist in the input subset $[i,n]$.

Base Case (n):

The simplest thing you can do. The smallest input you can accept.

What's our base case?

Birthday Algorithm

Maintain a record of names and birthdays (initially empty)

Interview each student in some order

 If birthday exists in record, return found pair!

 Else add name and birthday to record

Return None if last student interviewed and no pairs are found

Base Case

We've not interviewed any students, $i=1$

At the start of the i^{th} interview, if birthday pairs exist in our input size n , they exist in the input subset $[i,n]$.

Base Case

We've not interviewed any students, $i=1$

At the start of the 1st interview, if birthday pairs exist in our input size n , they exist in the input subset $[1,n]$. Which is the entire input size.

Inductive Step

We're about to interview student i .

At the start of the i^{th} interview, if birthday pairs exist in our input size n , they exist in the input subset $[i, n]$.

Inductive Step

We're about to interview student i .

What can happen during this interview?

2 possibilities

Inductive Step

We're about to interview student i .

1. Student i is a birthday pair with one of the students already interviewed
2. Student i has a new birthday we haven't recorded yet.

Inductive Step

We're about to interview student i .

1. Student i is a birthday pair with one of the students already interviewed so return birthday.*
2. Student i has a new birthday we haven't recorded yet so add birthday to records and interview students $i+1$.

Termination

We've interviewed all students. i.e $i=n+1$.

At the start of the i^{th} interview, if birthday pairs exist in our input size n , they exist in the input subset $[i,n]$.

Termination

We've interviewed all students. i.e $i=n+1$.

At the start of the $(n+1)^{\text{th}}$ interview, if birthday pairs exist in our input size n , they exist in the input subset $[n+1, n]$, which is an empty set and therefore we can conclude that birthday pairs don't exist in our input.

Loop Invariant

A loop invariant is a property of a program loop that is true before (and after) each iteration.

Knowing the loop invariant(s) is essential in understanding the effect of a loop.

It is what we will use to prove in the base case and the inductive step.

Correctness Proof

To show that an algorithm is correct, we must proof 3 things about the loop invariant.

Initialization: It is true prior to the first iteration of the loop.

Maintenance: If it is true before an iteration of the loop, it remains true before the next iteration.

Termination: When the loop terminates, the invariant gives us a useful property that helps show that the algorithm is correct.

Example- Find max

Loop Invariant

after the i^{th} iteration max will contain the maximum value from the subarray $A[0:i]$

```
max(A)
```

```
    max=A[0]
```

```
    for i=1 to A.length-1
```

```
        if A[i] > max
```

```
            max=A[i]
```

```
    return max
```

Example- Find Max

Initialization

When $i=1$, max will contain the maximum value of the subarray $A[0:1] \Rightarrow A[0] \Rightarrow$ trivially true

```
max(A)
```

```
    max=A[0]
```

```
    for i=1 to A.length-1
```

```
        if A[i] >max
```

```
            max=A[i]
```

```
    return max
```

Example- Find Max

Maintenance

After the i th iteration max will contain the maximum value from the subarray $A[0:i]$; proof for $i+1$

Case 1: $A[i] > \text{max}$; max will be replaced with the new maximum value thus, max is the maximum value in the subarray $A[0:i+1]$

Case 2: $A[i] \leq \text{max}$; max will retain its previous value, max is the maximum value in the subarray $A[0:i+1]$

```
max(A)
```

```
max=A[0]
```

```
for i=1 to A.length-1
```

```
    if A[i] > max
```

```
        max=A[i]
```

```
return max
```


Example- Find Max

Termination

$i=n$

When $i=1$, max will contain the maximum value of the subarray $A[0:n]$
 $\Rightarrow A[0], A[1], A[2], \dots, A[n-1] \Rightarrow$ the whole array.

```
max(A)
```

```
    max=A[0]
```

```
    for i=1 to A.length-1
```

```
        if A[i] > max
```

```
            max=A[i]
```

```
    return max
```

Finding a Loop Invariant

A loop invariant often makes a statement depending on i and about the data seen so far.

Ask: what do you want to know at the end?

What do you know? What information do you gain after each iteration?

Checklist for your loop invariant

1. Have you stated your loop invariant explicitly when beginning?
2. Does your loop variable occur in your loop invariant statement ?
3. Does the loop invariant hold before the first iteration of the loop?
4. Is your invariant strong enough to conclude the right answer?
5. If you have multiple loops, is it clear for which loop you have defined the invariant?
6. Did you use the loop invariant in the maintenance and termination step?
7. Does your argument line up with what the algorithm is trying to do?

Example: Insertion Sort

23	1	10	5	3
----	---	----	---	---

23	1	10	5	3
----	---	----	---	---

1	23	10	5	3
---	----	----	---	---

1	23	10	5	3
---	----	----	---	---

1	10	23	5	3
---	----	----	---	---

1	10	23	5	3
---	----	----	---	---

1	10	23	5	3
---	----	----	---	---

1	5	10	23	3
---	---	----	----	---

1	3	5	10	23
---	---	---	----	----

INSERTION-SORT(A)

for $j=2$ to $A.length$

key = $A[j]$

$i = j-1$

while $i > 0$ and $A[i] > \text{key}$

$A[i+1] = A[i]$

$i = i-1$

$A[i+1] = \text{key}$

Example: Insertion Sort

Loop Invariant

At the j^{th} iteration the subarray $A[1:j]$ is sorted in a non-decreasing order.

```
INSERTION-SORT(A)
```

```
  for  $j=2$  to  $A.\text{length}$ 
```

```
     $\text{key} = A[j]$ 
```

```
     $i = j - 1$ 
```

```
    while  $i > 0$  and  $A[i] > \text{key}$ 
```

```
       $A[i+1] = A[i]$ 
```

```
       $i = i - 1$ 
```

```
     $A[i+1] = \text{key}$ 
```

Example: Insertion Sort

Initialization

$j=2$

When $j=2$, $A[1:2]$ is already sorted.

$A[1:2] \Rightarrow A[1] \Rightarrow$ sorted relative to itself

INSERTION-SORT(A)

for $j=2$ to $A.length$

$key = A[j]$

$i = j-1$

 while $i > 0$ and $A[i] > key$

$A[i+1] = A[i]$

$i = i-1$

$A[i+1] = key$

Example: Insertion Sort

Maintenance

At the j th iteration the subarray $A[1:j]$ is sorted in a non-decreasing order.

For the j th iteration, $A[j]$ is placed in its correct position in the subarray $A[1:j+1]$. Thus, the subarray $A[1:j+1]$ is relatively sorted.

INSERTION-SORT(A)

for $j=2$ to $A.length$

key = $A[j]$

$i = j-1$

while $i > 0$ and $A[i] > \text{key}$

$A[i+1] = A[i]$

$i = i-1$

$A[i+1] = \text{key}$

Example: Insertion Sort

Termination

$j = n + 1$

$A[1:n]$ is already sorted $\Rightarrow A[1]$,
 $A[2]$, $A[3]$... $A[n]$

\Rightarrow the whole array

INSERTION-SORT(A)

for $j = 2$ to $A.length$

$key = A[j]$

$i = j - 1$

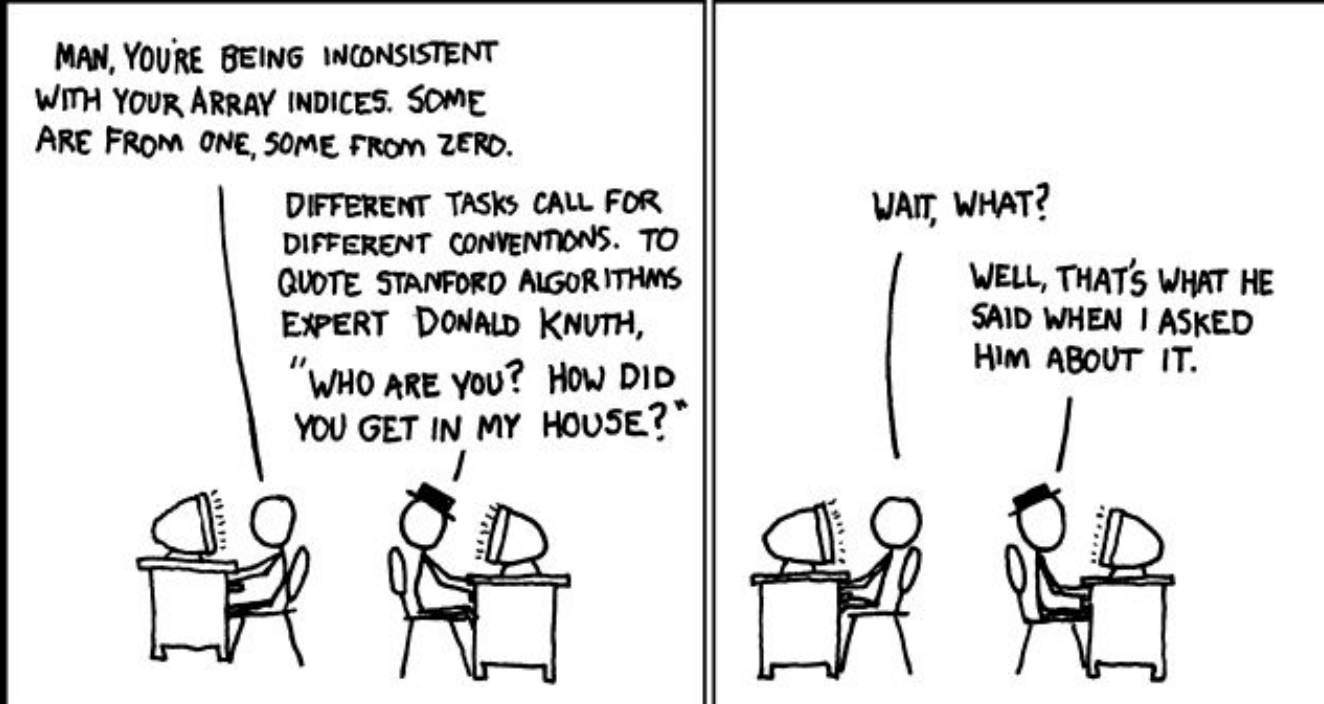
 while $i > 0$ and $A[i] > key$

$A[i + 1] = A[i]$

$i = i - 1$

$A[i + 1] = key$

`arr[0] != arr[1]`: which is it?



Example- Linear Search

Loop Invariant

at the i th iteration, if x is present in the array, it is present in the subarray $A[i:n]$

```
improved-linear-search(A)
  for i=0 to A.length-1
    if A[i]=x
      return i
  return -1
```

Example- Linear Search

Loop Invariant

at the i th iteration, x is not present
in the subarray $A[0:i]$

```
improved-linear-search(A)
  for i=0 to A.length-1
    if A[i]=x
      return i
  return -1
```

Example- Linear Search

Initialization

When $i=0$, if x is present in the array it is present in the subarray $A[0:n] \Rightarrow$ the whole array

```
improved-linear-search(A)
  for i=0 to A.length-1
    if A[i]=x
      return i
  return -1
```

Example- Linear Search

Maintenance

At the i th iteration, if x is in A , then it is present in the subarray $A[i:n]$

If $A[i] \neq x$, if x is in A it is present in the subarray $A[i+1:n]$

```
improved-linear-search(A)
```

```
  for  $i=0$  to  $A.length-1$ 
```

```
    if  $A[i]=x$ 
```

```
      return  $i$ 
```

```
  return  $-1$ 
```

Example- Linear Search

Termination

Case 1: $A[i]=x$, x is in $A[i:n]$

Case 2: $i=n$

When $i=n$, if x is present in A it is present in $A[n:n] \Rightarrow$ empty \Rightarrow therefore x is not in A

```
improved-linear-search(A)
```

```
  for i=0 to A.length-1
```

```
    if  $A[i]=x$ 
```

```
      return i
```

```
  return -1
```

Linear Search- Exercise

```
improved-linear-search(A)
```

```
    for i=0 to A.length-1
```

```
        if A[i]=x
```

```
            return i
```

```
return -1
```

Exercises

1. Use the alternative loop invariant stated earlier to prove the correctness of the algorithm
2. Modify this algorithm to a traditional linear search algorithm (one that stores the index of the matched value instead of returning right away) and prove the correctness of that algorithm.

Efficiency Analysis

Efficiency Analysis

Analyzing an algorithm has come to mean predicting the resources that the algorithm requires.

Occasionally, resources such as memory, communication bandwidth, or computer hardware are of primary concern, but most often it is computational time that we want to measure.

By analyzing several possible correct algorithms, we can identify the most efficient one.

How can we measure how fast an algorithm runs?

Model of Computation

Defines what our computer is allowed to do in constant time

In this course, to model the implementation technology , we will use the **RAM model** (aka WORD RAM).

RAM Model

This model defines some basic assumptions we're going to make about how our algorithms get executed.

In the RAM model, instructions are executed one after the other.

Assume operations (instructions) in real machines are available and each instruction takes a constant amount of time

Example: data movement, addition, multiplication, shift, control instructions....

Don't abuse this model by assuming unrealistic operations.

The RAM model assumes no memory hierarchy.

Pseudocode Conventions

Indentation indicates block structure.

The looping and control statements for, while, if-else have similar interpretation to their usage in C, C++, Java ...

Variables are assumed to be local unless stated otherwise

Comments are specified by using “//”

Time Complexity

The time it takes to execute an algorithm.

The sum of the time it take to execute every operation.

Elementary operations are assumed to take a single unit of time, these operations are summed to give the total time it takes to run an algorithm.

The running time for an algorithm is dependent on the input that is provided.

As the input size grows larger and larger so might the run time of an algorithm.

Time Complexity

The running time of an algorithm on a particular input is the number of primitive operations or “steps” executed.

The analysis is supposed to be as machine-independent as possible.

Assume a constant amount of time is required to execute each line in the algorithm.

One line may take a different amount of time than another line, but we assume that each execution of the i th line takes time c_i , where c_i is a constant.

Input Size: Fixed and Variable

Growth of Functions

How does the running time of an algorithm changes as input size gets very large?

For large enough inputs, the effects of the input size itself dominates the time it takes to perform identified fundamental steps.

When we look at input sizes large enough to make only the order of growth of the running time relevant, we are studying the **asymptotic efficiency**.

That is, we are concerned with how the running time of an algorithm increases with the size of the input as it increases without bound.

Asymptotic Notations

Standard notations for expressing the asymptotic analysis of algorithms.

A family of notations that describes the limiting behavior of a function when the argument tends towards a particular value or infinity.

In this course we will use these notations to describe the time complexity of algorithms. However these notations could be used to characterize some other aspects of algorithms or even functions that have nothing to do with algorithms.

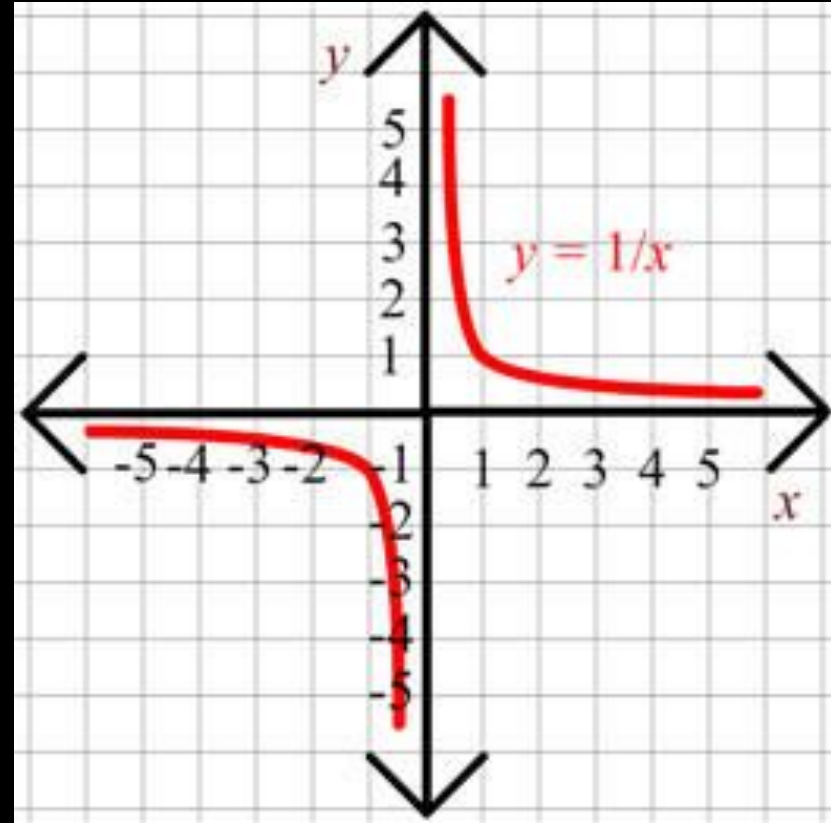
Asymptotic Behaviour

Point of interest: tail behaviour of the graph.

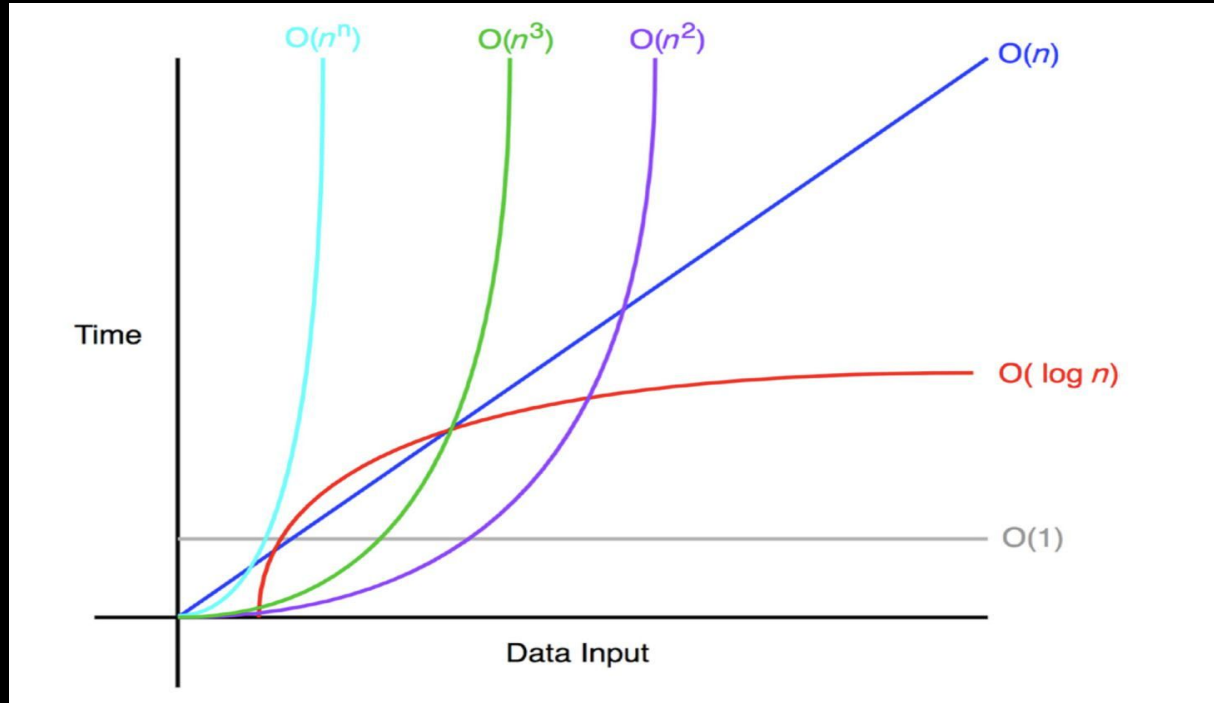
What is

$$\lim_{x \rightarrow \infty} \frac{1}{x}$$

How does the graph behave as x gets to very large values?



Graph Behaviours



Asymptotic Bounding

Gives a general characterization of different algorithms; a general description of how the algorithm performs as input grows large.

Bounding functions: constant time, linear time, logarithmic time, quadratic, polynomial, exponential ...

Start with $T(n)$ - a function describing the time an algorithm takes.

As n changes the value of $T(n)$ changes as well.

We want to bound this change. I.e. predict or bound the possibility of how this function changes as n changes (gets very large).

Asymptotic Notations

- Big Oh (O) Notation
- Big Omega (Ω) Notation
- Theta (Θ) Notation
- Small Oh (o) Notation
- Small Omega (ω) Notation

Boundes: Upper Bound

Big-Oh (O)

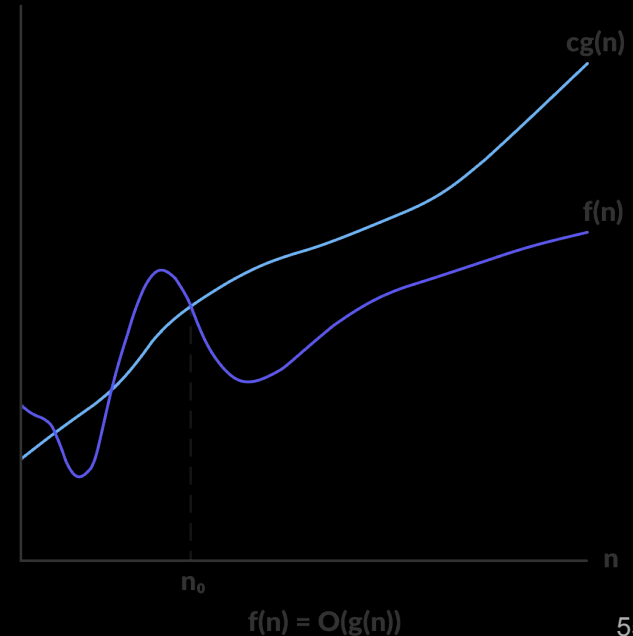
Bounds a function from above.

Mathematically:

$$f(n) = O(g(n)) \text{ iff}$$

for every $n \geq n_0$ where $n_0 \geq 1$ and $c > 0$

$$f(n) \leq c g(n)$$



Boundes: Lower Bound

Big-Omega (Ω)

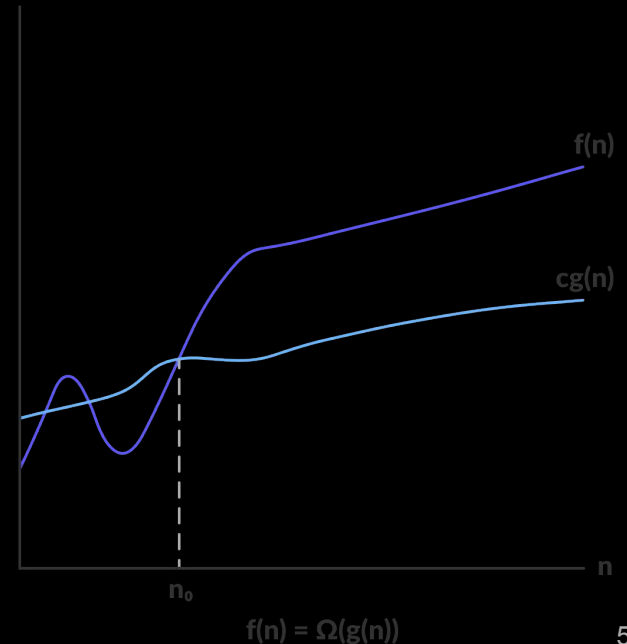
Bounds a function from below.

Mathematically:

$$f(n) = \Omega(g(n)) \text{ iff}$$

for every $n \geq n_0$ where $n_0 \geq 1$ and $c > 0$

$$f(n) \geq c g(n)$$



Boundes: Exact Bound

Theta (Θ)

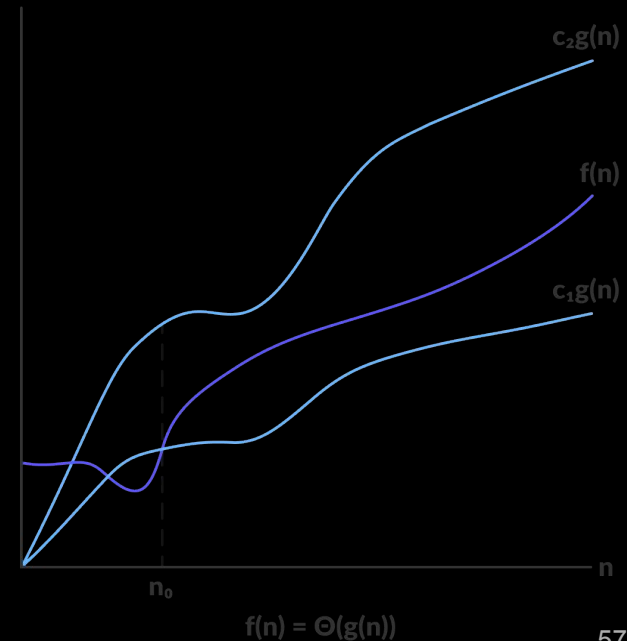
Bounds a function from both above and below.

Mathematically:

$f(n) = \Theta(g(n))$ iff

for every $n \geq n_0$ where $n_0 \geq 1$ and $c_1, c_2 > 0$

$c_1 g(n) \leq f(n) \leq c_2 g(n)$



Example

Let's design a sorting algorithm.

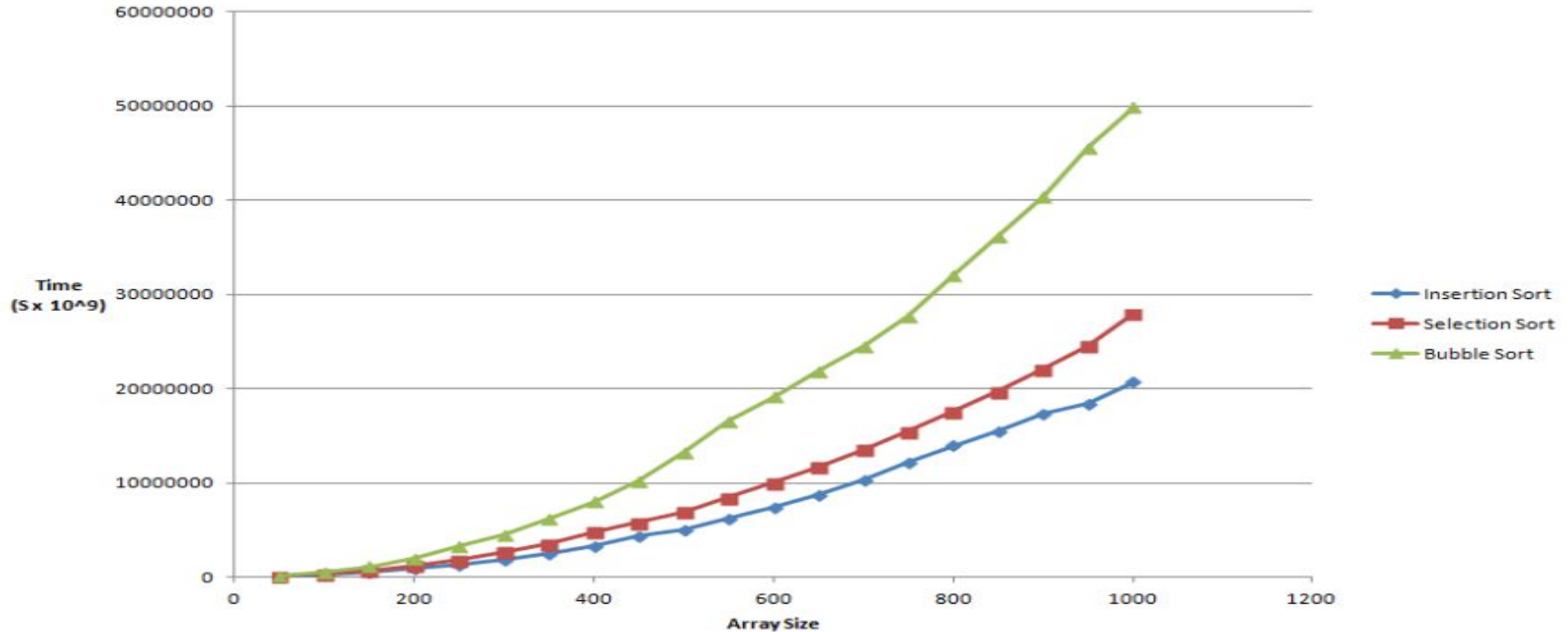
Problem Statement :

Input: A sequence of n numbers $\{a_1, a_2, a_3 \dots a_n\}$

Output: A permutation (reordering) $\{a_i, a_{ii}, a_{iii}, \dots, a_m\}$ of the input sequence such that $\{a_i \leq a_{ii} \leq a_{iii} \leq \dots \leq a_m\}$

There are a number of known sorting algorithms: Insertion sort, selection sort, bubble sort, merge sort...

Sorting Algorithms



Sorting Algorithm: Insertion Sort

INSERTION-SORT(A)

```
1   for j=2 to A.length
2       key= A[j]
3       // Insert A[j] into the sorted sequence A[1....j-1]
4       i= j-1
5       while i>0 and A[i] > key
6           A[i+1]=A[i]
7           i=i-1
8       A[i+1]=key
```

Sorting Algorithm: Insertion Sort

Given the previous algorithm to sort an array, let us analyze the time complexity of insertion sort.

The time taken to execute the insertion sort depends on:

- Input size

- Input sort status: how sorted is the input array already?

The run time of a program is represented as a function of the input size.

What exactly we mean by input size depends on the problem area under study. It could be the number of items in the input, the total number of bits needed to represent the input or two numbers that describe the input rather than one.

Insertion Sort: Running Time

INSERTION-SORT(A)		cost	times
1	for j=2 to A.length	C1	n
2	key= A[j]	C2	n-1
3	// Insert A[j] into the sorted sequence A[1....j-1]	C3=0	n-1
4	i= j-1	C4	n-1
5	while i>0 and A[i] > key	C5	$\sum_{i=2}^n t_j$
6	A[i+1]=A[i]	C6	$\sum_{i=2}^n (t_j-1)$
7	i=i-1	C7	$\sum_{i=2}^n (t_j-1)$
8	A[i+1]=key	C8	n-1

Insertion Sort: Running Time

$$T(n) = C_1n + C_2(n - 1) + C_4(n - 1) + C_5 \sum_{j=2}^n t_j + C_6 \sum_{j=2}^n (t_j - 1) + C_7 \sum_{j=2}^n (t_j - 1) + C_8(n - 1)$$

Insertion Sort: Running Time

Best Case: array is already sorted

$$T(n) = C_1n + C_2(n-1) + C_4(n-1) + C_5(n-1) + C_8(n-1)$$

$$T(n) = (C_1 + C_2 + C_4 + C_5 + C_8)n - (C_2 + C_4 + C_5 + C_8)$$

Worst Case: array is in a reverse order

$$T(n) = c_1n + c_2(n-1) + c_4(n-1) + c_5\left(\frac{n(n+1)}{2} - 1\right) + c_6\left(\frac{n(n-1)}{2}\right) + c_7\left(\frac{n(n-1)}{2}\right) + c_8(n-1)$$

$$T(n) = (C_5/2 + C_6/2 + C_7/2)n^2 + (C_1 + C_2 + C_4 + C_5/2 - C_6/2 + C_7/2 + C_8)n - (C_2 + C_4 + C_5 + C_8)$$

Insertion Sort: Order of Growth

These formulas could be simplified to represent an abstraction of the running time. This is done by ignoring any constants.

For further simplification, we only consider the **rate of growth**.

This would be the leading term in the running time equation. The leading term is chosen because as the input size gets very large, the other terms quickly become insignificant.

This expressions is known as the theta notation(Θ).

One algorithm is said to be more efficient than another if its worst case running time has a lower order of growth.

Insertion Sort: Order of Growth

Best Case: array is already sorted

$$T(n) = (C_1 + C_2 + C_4 + C_5 + C_8)n - (C_2 + C_4 + C_5 + C_8)$$

$$T(n) = \Theta(n)$$

Worst Case: array is in a reverse order

$$T(n) = (C_5^2 + C_6^2 + C_7^2)n^2 + (C_1 + C_2 + C_4 + C_5^2 - C_6^2 + C_7^2 + C_8)n - (C_2 + C_4 + C_5 + C_8)$$

$$T(n) = \Theta(n^2)$$

Best Case vs Worst Case vs Average Case

The worst case is the longest running time for an algorithm.

For the duration of this course, we will always use the worst case of a problem to analyze the time complexity of an algorithm. Why?

- The worst-case running time of an algorithm gives us an upper bound on the running time for any input.
- For some algorithms, the worst case occurs fairly often.
- The “average case” is often roughly as bad as the worst case. What we consider to be “average” is also hard to define. And it is also expensive to calculate.

Sorting Algorithm: Bubble Sort

BUBBLE-SORT(A)

```
1      for i=n downto 2
2          for j=1 to i-1
3              if A[j]> A[j+1]
4                  temp= A[j+1]
5                  A[j+1]=A[j]
6                  A[j]=temp
```

Bubble Sort: Running Time

	BUBBLE-SORT(A)	cost	time
1	for i=n down to 2	c1	n
2	for j=1 to i-1	c2	$\sum_{i=2}^n i$
3	if A[j]> A[j+1]	c3	$\sum_{i=2}^n i-1$
4	temp= A[j+1]	c4	$\sum_{i=2}^n t_i$
5	A[j+1]=A[j]	c5	$\sum_{i=2}^n t_i$
6	A[j]=temp	c6	$\sum_{i=2}^n t_i$