Let $\mathcal{L}=(x_1,...,x_n)$ – training data with labels (y_1,y_n) and \mathcal{U} – set of examples models doesn't know labels for. Let f – function, interpolating training dataset, with minimum norm (this condition is gotten from the experiments – such models usually have good interpolating properties. Let's define $f_t^u(x)$ - as minimum-norn function that interpolates training data combined with the point $u \in \mathcal{U}$ with label t. The label t(u) we will choose by one of these ways:

$$t^{(1)}(u) = argmin_{t \in \{-1,1\}} || f_t^u(x) ||, \ t^{(2)}(u) = \begin{cases} +1 \text{ if } f(u) \ge 0, \\ -1 \text{ if } f(u) < 0 \end{cases}$$
 (1)

Defined t(u), let $f^u(x) = f^u_{t(u)}(x)$. Introduce also score-functions:

$$score^{(1)}(u) = ||f^{u}(x)||, \ score^{(2)}(u) = ||f^{u}(x) - f(x)||,$$
 (2)

In the first case the most score get the least smooth function, in the second case – the function, that differs the most from previous one. We expect that point with the largest score is the most imformative.

Then the next point for labeling is

$$u^* = argmax_{u \in \mathcal{U}} score(u).$$

In (1) μ (2) we intentionally do not define specific norm for variety of *score*-functions. If these norms are the same and we chose the first *score*-function, then the new point u^* can be determined by

$$||f^{u^*}(x)|| = \max_{u \in \mathcal{U}} \min_{t \in \{-1,1\}} ||f_t^u(x)||.$$
(3)