Homework 2

- **Implement the stereo camera calibration explained in lecture 4**
  - Use the homework framework provided
  - Use the calibration data given
    - left1.bmp ~ left15.bmp, right1.bmp ~ right15.bmp
    - left1.txt ~ left15.txt, right1.txt ~ right15.txt, model.txt
    - Text files include corresponding points as follows:

$$x_1 \quad y_1 \quad \cdots \quad x_{10} \quad y_{10}$$
$$\vdots$$
$$x_{91} \quad y_{91} \quad \cdots \quad x_{100} \quad y_{100}$$

  - Show the performance by the reprojection of the target points on the bmp images